# Research Article <br> Existence and Multiplicity Results for Degenerate Elliptic Equations with Dependence on the Gradient 

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We study the existence of positive solutions for a class of degenerate nonlinear elliptic equations with gradient dependence. For this purpose, we combine a blowup argument, the strong maximum principle, and Liouville-type theorems to obtain a priori estimates.

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## 1. Introduction

We consider the following nonvariational problem:

$$
-\Delta_{m} u=f(x, u, \nabla u)-a(x) g(u, \nabla u)+\tau \quad \text { in } \Omega, \quad u=0 \quad \text { on } \partial \Omega, \quad(P)_{\tau}
$$

where $\Omega$ is a bounded domain with smooth boundary of $\mathbb{R}^{N}, N \geq 3$. $\Delta_{m}$ denotes the usual $m$-Laplacian operators, $1<m<N$ and $\tau \geq 0$. We will obtain a priori estimate to positive solutions of problem $(P)_{\tau}$ under certain conditions on the functions $f, g, a$. This result implies nonexistence of positive solutions to $\tau$ large enough.

Also we are interested in the existence of a positive solutions to problem $(P)_{0}$, which does not have a clear variational structure. To avoid this difficulty, we make use of the blow-up method over the solutions to problem $(P)_{\tau}$, which have been employed very often to obtain a priori estimates (see, e.g., $[1,2]$ ). This analysis allows us to apply a result due to [3], which is a variant of a Rabinowitz bifurcation result. Using this result, we obtain the existence of positive solutions.

Throughout our work, we will assume that the nonlinearities $f$ and $g$ satisfy the following conditions.
$\left(\mathrm{H}_{1}\right) f: \Omega \times \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a nonnegative continuous function.
$\left(\mathrm{H}_{2}\right) g: \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a nonnegative continuous function.
$\left(\mathrm{H}_{3}\right)$ There exist $L>0$ and $c_{0} \geq 1$ such that $u^{p}-L|\eta|^{\alpha} \leq f(x, u, \eta) \leq c_{0} u^{p}+L|\eta|^{\alpha}$ for all $(x, u, \eta) \in \Omega \times \mathbb{R} \times \mathbb{R}^{N}$, where $p \in\left(m-1, m_{*}-1\right)$ and $\alpha \in(m-1, m p /(p+1))$. Here, we denote $m_{*}=m(N-1) /(N-m)$.
$\left(\mathrm{H}_{4}\right)$ There exist $M>0, c_{1} \geq 1, q>p$, and $\beta \in(m-1, m p /(p+1))$ such that $|u|^{q}-$ $M|\eta|^{\beta} \leq g(u, \eta) \leq c_{1}|u|^{q}+M|\eta|^{\beta}$ for all $(u, \eta) \in \mathbb{R} \times \mathbb{R}^{N}$.
We also assume the following hypotheses on the function $a$.
$\left(\mathrm{A}_{1}\right) a: \bar{\Omega} \rightarrow \mathbb{R}$ is a nonnegative continuous function.
$\left(\mathrm{A}_{2}\right)$ There is a subdomain $\Omega_{0}$ with $C^{2}$-boundary so that $\overline{\Omega_{0}} \subset \Omega, a \equiv 0$ in $\overline{\Omega_{0}}$, and $a(x)>0$ for $x \in \Omega \backslash \overline{\Omega_{0}}$.
$\left(\mathrm{A}_{3}\right)$ We assume that the function $a$ has the following behavior near to $\partial \Omega_{0}$ :

$$
\begin{equation*}
a(x)=b(x) d\left(x, \partial \Omega_{0}\right)^{\gamma}, \tag{1.1}
\end{equation*}
$$

$x \in \Omega \backslash \overline{\Omega_{0}}$, where $\gamma$ is positive constant and $b(x)$ is a positive continuous function defined in a small neighborhood of $\partial \Omega_{0}$.
Observe that particular situations on the nonlinearities have been considered by many authors. For instance, when $a \equiv 0$ and $f$ verifies $\left(\mathrm{H}_{3}\right)$, Ruiz has proved that the problem $(P)_{0}$ has a bounded positive solution (see [2] and reference therein). On the other hand, when $f(x, u, \eta)=u^{p}$ and $g(x, u, \eta)=u^{q}, q>p$ and $m<p$, and $a \equiv 1$, a multiplicity of results was obtained by Takeuchi [4] under the restriction $m>2$. Later, Dong and Chen [5] improve the result because they established the result for all $m>1$. We notice that the Laplacian case was studied by Rabinowitz by combining the critical point theory with the Leray-Schauder degree [6]. Then, when $m \geq p$, since $(f(x, u)-g(x, u)) / u^{m-1}$ becomes monotone decreasing for $0<u$, we know that the solution to $(P)_{0}$ is unique (as far as it exists) from the Díaz and Saá's uniqueness result (see [7]). For more information about this type of logistic problems, see $[1,8-13]$ and references cited therein.

Our main results are the following.
Theorem 1.1. Let $u \in C^{1}(\Omega)$ be a positive solution of problem $(P)_{\tau}$. Suppose that the conditions $\left(H_{1}\right)-\left(H_{4}\right)$ and the hypotheses $\left(A_{1}\right)-\left(A_{3}\right)$ are satisfied with $\gamma \neq m(q-p) /(1-m+p)$. Then, there is a positive constant $C$, depending only on the function $a$ and $\Omega$, such that

$$
\begin{equation*}
0 \leq u(x)+\tau \leq C \tag{1.2}
\end{equation*}
$$

for any $x \in \Omega$.
Moreover, if $\gamma=m(q-p) /(1-m+p)$, then there exists a positive constant $c_{1}=c_{1}(p, \alpha$, $\left.\beta, N, c_{0}\right)$ such that the conclusion of the theorem is true, provided that $\inf _{\partial \Omega_{0}} b(x)>c_{1}$.

Observe that this result implies in particular that there is no solution for $0<\tau$ large enough. By using a variant of a Rabinowitz bifurcation result, we obtain an existence result for positive solutions.

Theorem 1.2. Under the hypotheses of Theorem 1.1, the problem $(P)_{0}$ has at least one positive solution.

## 2. A priori estimates and proof of Theorem 1.1

We will use the following lemma which is an improvement of Lemma 2.4 by Serrin and Zou [14] and was proved in Ruiz [2].

Lemma 2.1. Let u be a nonnegative weak solution to the inequality

$$
\begin{equation*}
-\Delta_{m} u \geq u^{p}-M|\nabla u|^{\alpha}, \tag{2.1}
\end{equation*}
$$

in a domain $\Omega \subset \mathbb{R}^{N}$, where $p>m-1$ and $m-1 \leq \alpha<m p /(p+1)$. Take $\lambda \in(0, p)$ and let $B\left(\cdot, R_{0}\right)$ be a ball of radius $R_{0}$ such that $B\left(\cdot, 2 R_{0}\right)$ is included in $\Omega$.

Then, there exists a positive constant $C=C\left(N, m, q, \alpha, \lambda, R_{0}\right)$ such that

$$
\begin{equation*}
\int_{B(\cdot, R)} u^{\lambda} \leq C R^{(N-m \lambda) /(p+1-m)}, \tag{2.2}
\end{equation*}
$$

for all $R \in\left(0, R_{0}\right]$.
We will also make use of the following weak Harnack inequality, which was proved by Trudinger [15].

Lemma 2.2. Let $u \geq 0$ be a weak solution to the inequality $\Delta_{m} u \leq 0$ in $\Omega$. Take $\lambda \in\left[1, m_{*}-\right.$ 1) and $R>0$ such that $B(\cdot, 2 R) \subset \Omega$. Then there exists $C=C(N, m, \lambda)$ (independent of $R$ ) such that

$$
\begin{equation*}
\inf _{B(\cdot, R)} u \geq C R^{-N / \lambda}\left(\int_{B(\cdot, 2 R)} u^{\lambda}\right)^{1 / \lambda} \tag{2.3}
\end{equation*}
$$

The following lemma allows us to control the parameter $\tau$ in the Blow-Up analysis. (See Section 2.1.)

Lemma 2.3. Let $u$ be a solution to the problem $(P)_{\tau}$. Then there is a positive constant $k_{0}$ which depends only on $\Omega_{0}$ such that

$$
\begin{equation*}
\tau \leq k_{0}\left(\max _{x \in \overline{\bar{\Omega}}} u\right)^{m-1} \tag{2.4}
\end{equation*}
$$

Proof. Since $u$ is a positive solution, the inequality holds if $\tau=0$. Now if $\tau>0$, then from $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{A}_{2}\right)$ we get

$$
\begin{equation*}
-\Delta_{m} u=f(x, u, \nabla u)-a(x) g(u, \nabla u)+\tau \geq \tau \quad \forall x \in \Omega_{0} . \tag{2.5}
\end{equation*}
$$

Let $v$ be the positive solution to

$$
\begin{gather*}
-\Delta_{m} v=1 \quad \text { in } \Omega_{0} \\
v=0 \quad \text { on } \partial \Omega_{0} \tag{2.6}
\end{gather*}
$$

and $w=(\tau / 2)^{1 /(m-1)} v$ in $\Omega_{0}$, then it follows that $-\Delta_{m} w=\tau / 2<-\Delta_{m} u$ in $\Omega_{0}$ and $u>w$ on $\partial \Omega_{0}$. Thus, using the comparison lemma (see [16]), we obtain $u \geq w$ in $\Omega_{0}$. Therefore,
there is a positive constant $k_{0}$ such that

$$
\begin{equation*}
\tau \leq k_{0} u^{m-1} \tag{2.7}
\end{equation*}
$$

at the maximum point of $v$ and the conclusion follows.
2.1. A priori estimates. We suppose that there is a sequence $\left\{\left(u_{n}, \tau_{n}\right)\right\}_{n \in \mathbb{N}}$ with $u_{n}$ being a $C^{1}$-solution of $(P)_{\tau_{n}}$ such that $\left\|u_{n}\right\|+\tau_{n} \xrightarrow[n \rightarrow \infty]{ } \infty$. By Lemma 2.3, we can assume that there exists $x_{n} \in \Omega$ such that $u_{n}\left(x_{n}\right)=\left\|u_{n}\right\|=: S_{n} \xrightarrow[n \rightarrow \infty]{ }$. Let $d_{n}:=d\left(x_{n}, \partial \Omega\right)$, we define $w_{n}(y)=S_{n}^{-1} u_{n}(x)$, where $x=S_{n}^{-\theta} y+x_{n}$ for some positive $\theta$ that will be defined later. The functions $w_{n}$ are well defined at least $B\left(0, d_{n} S_{n}^{\theta}\right)$, and $w_{n}(0)=\left\|w_{n}\right\|=1$. Easy computations show that

$$
\begin{align*}
-\Delta_{m} w_{n}(y)=S_{n}^{1-(\theta+1) m}[ & f\left(S_{n}^{-\theta} y+x_{n}, S_{n} w_{n}(y), S_{n}^{1-\theta} \nabla w_{n}(y)\right)  \tag{2.8}\\
& \left.-a\left(S_{n}^{-\theta} y+x_{n}\right) g\left(S_{n} w_{n}(y), S_{n}^{1-\theta} \nabla w_{n}(y)\right)+\tau_{n}\right] .
\end{align*}
$$

From our conditions on the functions $f$ and $g$, the right-hand side of (2.8) reads as

$$
\begin{align*}
& S_{n}^{1-(\theta+1) m}\left[f\left(S_{n}^{-\theta} y+x_{n}, S_{n} w_{n}(y), S_{n}^{1-\theta} \nabla w_{n}(y)\right)\right. \\
& \left.-a\left(S_{n}^{-\theta} y+x_{n}\right) g\left(S_{n} w_{n}(y), S_{n}^{1-\theta} \nabla w_{n}(y)\right)+\tau_{n}\right] \\
& \leq S_{n}^{1-(\theta+1) m+q}\left[c_{0} S_{n}^{p-q} w_{n}(y)^{p}+M S_{n}^{(1-\theta) \alpha-q}\left|\nabla w_{n}(y)\right|^{\alpha}\right. \\
& \left.-a\left(S_{n}^{-\theta} y+x_{n}\right)\left(w_{n}(y)^{q}-g_{0} S_{n}^{\beta(1-\theta)-q}\left|\nabla w_{n}(y)\right|^{\beta}\right)\right]+S_{n}^{1-(\theta+1) m} \tau_{n} . \tag{2.9}
\end{align*}
$$

We note that from Lemma 2.3 we have $S_{n}^{1-(\theta+1) m} \tau_{n} \leq c_{0} S_{n}^{1-(\theta+1) m} S_{n}^{m-1} \underset{n \rightarrow \infty}{\longrightarrow} 0$.
We split this section into the following three steps according to location of the limit point $x_{0}$ of the sequence $\left\{x_{n}\right\}_{n}$.
(1) $x_{0} \in \bar{\Omega} \backslash \overline{\Omega_{0}}$. Here, up to subsequence, we may assume that $\left\{x_{n}\right\}_{n} \subset \Omega \backslash \overline{\Omega_{0}}$. We define $\delta_{n}^{\prime}=\min \left\{\operatorname{dist}\left(x_{n}, \partial \Omega\right), \operatorname{dist}\left(x_{n}, \partial \Omega_{0}\right)\right\}$ and $B=B\left(0, \delta_{n}^{\prime} S_{n}^{\theta}\right)$ if $\operatorname{dist}\left(x_{0}, \partial \Omega\right)>0$, or $\delta_{n}^{\prime}=$ $\operatorname{dist}\left(x_{n}, \partial \Omega_{0}\right)$ and $B=B\left(0, \delta_{n}^{\prime} S_{n}^{\theta}\right) \cap \Omega$ if $\operatorname{dist}\left(x_{0}, \partial \Omega\right)=0$. Then, $w_{n}$ is well defined in $B$ and satisfies

$$
\begin{equation*}
\sup _{y \in B} w_{n}(y)=w_{n}(0)=1 \tag{2.10}
\end{equation*}
$$

Now, taking $\theta=(q+1-m) / m$ in (2.9) and applying regularity theorems for the $m$ Laplacian operator, we can obtain estimates for $w_{n}$ such that for a subsequence $w_{n} \rightarrow w$, locally uniformly, with $w$ be a $C^{1}$-function defined in $\mathbb{R}^{N}$ or in a halfspace, if dist $\left(x_{0}, \partial \Omega\right)$ is positive or zero, satisfying

$$
\begin{equation*}
-\Delta_{m} w \leq-a\left(x_{0}\right) w^{q}, \quad w \geq 0, w(0)=\max w=1 \tag{2.11}
\end{equation*}
$$

which is a contradiction with the strong maximum principle (see [17]).
(2) $x_{0} \in \Omega_{0}$. In this case, up to subsequence we may assume that $\left\{x_{n}\right\}_{n} \subset \Omega_{0}$. Let $d_{n}=$ $\operatorname{dist}\left(x_{n}, \partial \Omega_{0}\right)$ and $\theta=(1+p-m) / m$. Then, $w_{n}$ is well defined in $B\left(0, d_{n} S_{n}^{\theta}\right)$ and satisfies

$$
\begin{equation*}
\sup _{y \in B\left(0, d_{n} S_{n}^{\theta}\right)} w_{n}(y)=w_{n}(0)=1 . \tag{2.12}
\end{equation*}
$$

On the other hand, for any $n \in \mathbb{N}$, we have $a\left(S_{n}^{-\theta} y+x_{n}\right)=0$ and

$$
\begin{equation*}
-\Delta_{m} w_{n}(y)=S_{n}^{1-(\theta+1) m}\left[f\left(S_{n}^{-\theta} y+x_{n}, S_{n} w_{n}(y), S_{n}^{1-\theta} \nabla w_{n}(y)\right)+\tau_{n}\right] \tag{2.13}
\end{equation*}
$$

From the hypothesis $\left(\mathrm{H}_{4}\right)$,

$$
\begin{align*}
-\Delta_{m} w_{n}(y) & =S_{n}^{1-(\theta+1) m}\left[f\left(S_{n}^{-\theta} y+x_{n}, S_{n} w_{n}(y), S_{n}^{1-\theta} \nabla w_{n}(y)\right)+\tau_{n}\right] \\
& \geq w_{n}(y)^{p}-M S_{n}^{\alpha(1-\theta)+1-(\theta+1) m}\left|\nabla w_{n}(y)\right|^{\alpha}+\tau_{n} S_{n}^{1-(\theta+1) m} . \tag{2.14}
\end{align*}
$$

From our choice of the constants $\alpha$ and $\theta$, we have $\alpha(1-\theta)+1-(\theta+1) m=\alpha(2 m-(1+$ $p)) / m-p<0$, that is, $S_{n}^{\alpha(1-\theta)+1-(\theta+1) m}\left|\nabla w_{n}(y)\right|^{\alpha}$ and $\tau_{n} S_{n}^{1-(\theta+1) m}$ tend to 0 as $n$ goes to $\infty$. This implies that for a subsequence $w_{n}$ converges to a solution of $-\Delta_{m} v \geq v^{p}, v \geq 0$ in $\mathbb{R}^{N}, v(0)=\max v=1$. This is a contradiction with [14, Theorem III].
(3) $x_{0} \in \partial \Omega_{0}$. Let $\delta_{n}=d\left(x_{n}, z_{n}\right)$, where $z_{n} \in \partial \Omega_{0}$. Denote by $\nu_{n}$ the unit normal of $\partial \Omega_{0}$ at $z_{n}$ pointing to $\Omega \backslash \Omega_{0}$.

Up to subsequences, We may distinguish two cases: $x_{n} \in \partial \Omega_{0}$ for all $n$ or $x_{n} \in \Omega \backslash \partial \Omega_{0}$ for all $n$.
Case $1\left(x_{n} \in \partial \Omega_{0}\right.$ for all $n$ ). In this case, $x_{n}=z_{n}$. For $\varepsilon$ sufficiently small but fixed take $\tilde{x}_{n}=z_{n}-\varepsilon v_{n}$. Then we have the following.
Claim 1. For any large $n$ we have

$$
\begin{equation*}
u_{n}\left(\tilde{x}_{n}\right)<\frac{S_{n}}{4} . \tag{2.15}
\end{equation*}
$$

Proof of Claim 1. In other cases, define for all $n$ sufficiently large, passing to a subsequence if necessary, the following functions

$$
\begin{equation*}
\tilde{w}_{n}(y)=S_{n}^{-1} u_{n}\left(\tilde{x}_{n}+S_{n}^{-(p+1-m) / m} y\right), \tag{2.16}
\end{equation*}
$$

which are well defined at least in $B\left(0, \varepsilon S_{n}^{(p+1-m) / m}\right), w_{n}(0) \geq 1 / 4$ and $\sup _{B\left(0, \varepsilon S_{n}^{(p+1-m) / m}\right)} \widetilde{w}_{n} \leq 1$.
Arguing as in the previous case $x_{0} \in \Omega_{0}$, we arrive to a contradiction.
Now, by continuity, for any large $n$ there exist two points in $\Omega_{0} x_{n}^{*}=x_{n}-t_{n}^{*} \nu_{n}$ and $x_{n}^{* *}=x_{n}-t_{n}^{* *} v_{n}, 0<t_{n}^{*}<t_{n}^{* *}<\varepsilon$ such that

$$
\begin{equation*}
u_{n}\left(x_{n}^{*}\right)=\frac{S_{n}}{2}, \quad u_{n}\left(x_{n}^{* *}\right)=\frac{S_{n}}{4} . \tag{2.17}
\end{equation*}
$$

Claim 2. There exists a number $\tilde{\delta}_{n} \in\left(0, \min \left\{d\left(x_{n}, x_{n}^{*}\right), d\left(x_{n}^{*}, x_{n}^{* *}\right)\right\}\right)$ such that $S_{n} / 4<$ $u_{n}(x)<S_{n}$ for all $x \in B\left(x_{n}^{*}, \tilde{\delta}_{n}\right)$. Moreover, there exists $y_{n}$ satisfying $d\left(x_{n}^{*}, y_{n}\right)=\widetilde{\delta}_{n}$ and either $u_{n}\left(y_{n}\right)=S_{n} / 4$ or else $u_{n}\left(y_{n}\right)=S_{n}$.

## 6 Boundary Value Problems

Proof of Claim 2. Define $\widetilde{\delta}_{n}=\sup \left\{\delta>0: S_{n} / 4<u_{n}(x)<S_{n}\right.$ for all $\left.x \in B\left(x_{n}^{*}, \delta\right)\right\}$. It is easy to prove that $\tilde{\delta}_{n}$ is well defined. Thus, the continuity of $u_{n}$ ensures the existence of $y_{n}$.

Now we will obtain an estimate from below of $\widetilde{\delta}_{n} S_{n}^{(p+1-m) / m}$.
Claim 3. There exists a positive constant $c=c\left(p, \alpha, \beta, N, c_{0}\right)$ such that

$$
\begin{equation*}
\tilde{\delta}_{n} S_{n}^{(p+1-m) / m} \geq c \tag{2.18}
\end{equation*}
$$

for any $n$ sufficiently large.
Proof of Claim 3. Assume, passing to a subsequence if necessary, that $\tilde{\delta}_{n} S_{n}^{(p+1-m) / m}<1$ for any $n$. We have that the functions $\widetilde{w}_{n}(y)=S_{n}^{-1} u_{n}\left(x_{n}^{*}+S_{n}^{-(p+1-m) / m} y\right)$ are well defined in $B(0,1)$ for $n$ sufficiently large and satisfy

$$
\begin{equation*}
-\Delta_{m} \tilde{w}_{n} \leq c_{0} \tilde{w}_{n}^{p}+\left|\nabla \tilde{w}_{n}\right|^{\alpha}+\left|\nabla \tilde{w}_{n}\right|^{\beta} . \tag{2.19}
\end{equation*}
$$

Applying Lieberman's regularity (see [18]), we obtain that there exists a positive constant $k=k\left(p, \alpha, \beta, N, c_{0}\right)$ such that $\left|\nabla \widetilde{w}_{n}\right| \leq k$ in $B(0,1)$. Assume for example that $u_{n}\left(y_{n}\right)=S_{n} / 4$. By the generalized mean value theorem, we have

$$
\begin{equation*}
\frac{1}{4}=\frac{1}{2}-\frac{1}{4}=\widetilde{w}_{n}(0)-\widetilde{w}_{n}\left(S_{n}^{\theta}\left(y_{n}-x_{n}^{*}\right)\right) \leq\left|\nabla \widetilde{w}_{n}(\xi)\right| \widetilde{\delta}_{n} S_{n}^{\theta} \tag{2.20}
\end{equation*}
$$

Claim 4. For any $n$ sufficiently large, we have $B\left(x_{n}^{*}, \tilde{\delta}_{n}\right) \subset B\left(\tilde{x}_{n}, \varepsilon\right)$.
Proof of Claim 4. Take $x \in B\left(x_{n}^{*}, \widetilde{\delta}_{n}\right)$, by Claim 2 we get

$$
\begin{align*}
d\left(x, \tilde{x}_{n}\right) & \leq d\left(x, x_{n}^{*}\right)+d\left(x_{n}^{*}, \tilde{x}_{n}\right)<\tilde{\delta}_{n}+d\left(x_{n}^{*}, \tilde{x}_{n}\right) \\
& \leq d\left(x_{n}, x_{n}^{*}\right)+d\left(x_{n}^{*}, \tilde{x}_{n}\right)=d\left(x_{n}, \tilde{x}_{n}\right) \leq \varepsilon . \tag{2.21}
\end{align*}
$$

So, $x \in B\left(\tilde{x}_{n}, \varepsilon\right)$.
Let $\lambda$ be a number such that $N(p+1-m) / m<\lambda<p$ (this is possible because $p<$ $m_{*}-1$ ). By Claims 3 and 4, and by Lemma 2.2, we get

$$
\begin{align*}
\left(\inf _{B\left(\tilde{x}_{n}, \delta / 2\right)} u_{n}\right)^{\lambda} & \geq c \varepsilon^{-N} \int_{B\left(\tilde{x}_{n}, \varepsilon\right)} u_{n}^{\lambda} \geq \int_{B\left(x_{n}^{*}, \tilde{\delta}_{n}\right)} u_{n}^{\lambda}  \tag{2.22}\\
& \geq C \widetilde{\delta}_{n}^{N} S_{n}^{\lambda} / 4 \geq C_{1} S_{n}^{N(m-1-p) / m+\lambda} \underset{n \rightarrow \infty}{\longrightarrow} \infty
\end{align*}
$$

Therefore, the last inequality tells us that

$$
\begin{equation*}
\int_{B\left(\tilde{x}_{n}, \varepsilon / 2\right)} u_{n}^{\lambda} \underset{n \rightarrow \infty}{ } \infty \tag{2.23}
\end{equation*}
$$

which contradicts Lemma 2.1.
Now, we will analyze the other case.

Case $2\left(x_{n} \in \Omega \backslash \partial \Omega_{0}\right.$ for all $\left.n\right)$. Define $2 d=\operatorname{dist}\left(x_{0}, \partial \Omega\right)>0$. Since $\Omega_{0}$ has $C^{2}$-boundary as in [19], we have

$$
\begin{gather*}
d\left(x_{n}+S_{n}^{-\theta} y, \partial \Omega_{0}\right)=\left|\delta_{n}+S_{n}^{-\theta} v_{n} \cdot y+o\left(S_{n}^{-\theta}\right)\right|, \\
a\left(x_{n}+S_{n}^{-\theta} y\right)= \begin{cases}b\left(x_{n}+S_{n}^{-\theta} y\right) S_{n}^{-\gamma \theta}\left|\delta_{n} S_{n}^{\theta}+v_{n} \cdot y+o(1)\right|^{\gamma}, & \text { if } x_{n}+S_{n}^{-\theta} y \in \Omega \backslash \Omega_{0}, \\
0, & \text { if } x_{n}+S_{n}^{-\theta} y \in \Omega_{0} .\end{cases} \tag{2.24}
\end{gather*}
$$

We define $b_{n}\left(x_{n}+S_{n}^{-\theta} y\right)=S_{n}^{\gamma \theta} a\left(x_{n}+S_{n}^{-\theta} y\right)$.
For $n$ large enough, $w_{n}$ is well defined in $B\left(0, d S_{n}^{\theta}\right)$ and we get

$$
\begin{equation*}
\sup _{y \in B\left(0, d S_{n}^{\theta}\right)} w_{n}(y)=w_{n}(0)=1 . \tag{2.25}
\end{equation*}
$$

By (2.9), we obtain

$$
\begin{align*}
&-\Delta_{m} w_{n}(y) \leq S_{n}^{1-(\theta+1) m+q}[ c_{0} S_{n}^{p-q} w_{n}(y)^{p}+M S_{n}^{(1-\theta) \alpha-q}\left|\nabla w_{n}(y)\right|^{\alpha} \\
&\left.-b_{n}\left(x_{n}+S_{n}^{-\theta} y\right) S_{n}^{-\gamma \theta}\left(w_{n}(y)^{q}-g_{0} S_{n}^{\beta(1-\theta)-q}\left|\nabla w_{n}(y)\right|^{\beta}\right)\right] \\
&+S_{n}^{1-(\theta+1) m} \tau_{n} . \tag{2.26}
\end{align*}
$$

Now we need to consider the following cases.
If $0<\gamma<m(q-p) /(1-m+p)$, we choose $\theta=(1-m+q) /(\gamma+m)$.
We first assume that $\left\{\delta_{n} S_{n}^{\theta}\right\}_{n \in \mathbb{N}}$ is bounded. Up to subsequence, we may assume that $\delta_{n} S_{n}^{\theta} \xrightarrow[n \rightarrow \infty]{\longrightarrow} d_{0} \geq 0$, from (2.26) we get

$$
\begin{align*}
-\Delta_{m} w_{n}(y) \leq & S_{n}^{\gamma \theta}\left[c_{0} S_{n}^{p-q} w_{n}(y)^{p}+M S_{n}^{(1-\theta) \alpha-q}\left|\nabla w_{n}(y)\right|^{\alpha}\right. \\
& \left.\quad-b_{n}\left(x_{n}+S_{n}^{-\theta} y\right) S_{n}^{-\gamma \theta}\left(w_{n}(y)^{q}-g_{0} S_{n}^{\beta(1-\theta)-q}\left|\nabla w_{n}(y)\right|^{\beta}\right)\right]+S_{n}^{1-(\theta+1) m} \tau_{n} \\
= & c_{0} S_{n}^{p-q+\gamma \theta} w_{n}(y)^{p}+M S_{n}^{\gamma \theta+(1-\theta) \alpha-q}\left|\nabla w_{n}(y)\right|^{\alpha} \\
& -b_{n}\left(x_{n}+S_{n}^{-\theta} y\right)\left(w_{n}(y)^{q}-g_{0} S_{n}^{\beta(1-\theta)-q}\left|\nabla w_{n}(y)\right|^{\beta}\right)+S_{n}^{1-(\theta+1) m} \tau_{n} . \tag{2.27}
\end{align*}
$$

Thus, up to a subsequence, we may assume that $w_{n}$ converges to a $C^{1}$ function $w$ defined in $\mathbb{R}^{N}$ and satisfying $w \geq 0, w(0)=\max w=1$ in $\mathbb{R}^{N}$, and

$$
-\Delta_{m} w(y) \leq \begin{cases}-b\left(x_{0}\right)\left|d_{0}+\nu_{0} \cdot y\right|^{\gamma} w^{q}(y), & \text { if } v_{0} \cdot y>\sigma  \tag{2.28}\\ 0, & \text { if } \nu_{0} \cdot y<\sigma\end{cases}
$$

where $\sigma=-d_{0}$ if $x_{n} \in \Omega \backslash \bar{\Omega}_{0}$ or $\sigma=d_{0}$ if $x_{n} \in \bar{\Omega}_{0}$ and $\nu_{0}$ is a unitary vector in $\mathbb{R}^{N}$. This is impossible by the strong maximum principles.

Suppose now that $\left\{\delta_{n} S_{n}^{\theta}\right\}$ is unbounded, we may assume that $\beta_{n}=\left(\delta_{n}^{-1} S_{n}^{-\theta}\right)^{\gamma / m}$ $\xrightarrow[n \rightarrow \infty]{\longrightarrow} 0$ for any $r>0$. Let us introduce $z=y / \beta_{n}$ and $v_{n}(z)=w_{n}\left(\beta_{n} z\right)$, using (2.26) we see that $v_{n}$ satisfies

$$
\left.\begin{array}{rl}
-\Delta_{m} v_{n}(z) \leq & \beta_{n}^{m} S_{n}^{\gamma \theta}[
\end{array} c_{0} S_{n}^{p-q} v_{n}(z)^{p}+M S_{n}^{(1-\theta) \alpha-q} \beta_{n}^{-\alpha}\left|\nabla v_{n}(z)\right|^{\alpha}\right)
$$

On the other hand,

$$
\begin{equation*}
\beta_{n}^{m} b_{n}\left(x_{n}+S_{n}^{-\theta} \beta_{n} z\right)=b\left(x_{n}+S_{n}^{-\theta} \beta_{n} z\right)\left[1+\beta_{n}^{(m+\gamma) / \gamma} v_{n} \cdot z+o\left(\beta_{n}^{m / \gamma}\right)\right]^{\gamma} \xrightarrow[n \rightarrow \infty]{\longrightarrow} b\left(x_{0}\right) \tag{2.30}
\end{equation*}
$$

Thus, since $\gamma<m(q-p) /(1-m+p)$ and our choice of $\theta$ and $\beta_{n}$, it is easy to see that $S_{n}^{\gamma \theta+p-q}, S_{n}^{\gamma \theta+(1-\theta) \alpha-q} \beta_{n}^{m-\alpha}$ and $S_{n}^{\beta(1-\theta)-q} \beta_{n}^{m-\beta}$ tend to 0 as $n$ goes to $+\infty$. Therefore, we obtain a limit function $v$ that satisfies $-\Delta_{m} v \leq-b\left(x_{0}\right) v^{q}, v \geq 0, v(0)=\max v=1$ in $\mathbb{R}^{N}$ which is again impossible.

If $\gamma=m(q-p) /(1-m+p)$, in this case, by our assumptions on the function $b$, we obtain for $\theta=(1-m+p) / m$

$$
\begin{align*}
-\Delta_{m} w_{n}(y) \leq & c_{0} w_{n}(y)^{p}+M S_{n}^{(1-\theta) \alpha-p}\left|\nabla w_{n}(y)\right|^{\alpha} \\
& -b_{n}\left(x_{n}+S_{n}^{-\theta} y\right)\left(w_{n}(y)^{q}-g_{0} S_{n}^{\beta(1-\theta)-q}\left|\nabla w_{n}(y)\right|^{\beta}\right)+S_{n}^{1-(\theta+1) m} \tau_{n} \tag{2.31}
\end{align*}
$$

Arguing as in the proof of Claim 3 in the above case $x_{n} \in \partial \Omega_{0}$ for all $n$, we may assume that $\delta_{n} S_{n} \theta \geq d_{0}=d_{0}\left(p, \alpha, \beta, N, c_{0}\right)>0$. Therefore, the limit $w$ of the sequence $w_{n}$ satisfies

$$
\begin{equation*}
-\Delta_{m} w(y) \leq c_{0} w(y)^{p}-b\left(x_{0}\right)\left|d_{0}-\left|\nu_{0} \cdot y+o(1)\right|\right|^{\gamma} w(y)^{q} . \tag{2.32}
\end{equation*}
$$

Now, evaluating in $x=0$, the last inequality reads as

$$
\begin{equation*}
-\Delta_{m} w(0) \leq c_{0}-b\left(x_{0}\right) d_{0}^{\gamma}<0 \tag{2.33}
\end{equation*}
$$

provided that $b\left(x_{0}\right)>c_{0} / d_{0}^{\gamma}$. This contradicts the strong maximum principle.
If $\gamma>m(q-p) /(1-m+p)$, we choose $\theta=(p-m+1) / m$, then we get

$$
\begin{align*}
-\Delta_{m} w_{n}(y) \geq & w_{n}(y)^{p}-M S_{n}^{(1-\theta) \alpha-p}\left|\nabla w_{n}(y)\right|^{\alpha} \\
& -S_{n}^{q-p-\gamma \theta} b_{n}\left(x_{n}+S_{n}^{-\theta} y\right)\left(g_{1} w_{n}(y)^{q}+g_{2} S_{n}^{\beta(1-\theta)-q}\left|\nabla w_{n}(y)\right|^{\beta}\right)+S_{n}^{1-(\theta+1) m} \tau_{n} \tag{2.34}
\end{align*}
$$

Arguing as seen before, that is, $\left\{\delta_{n} S_{n}^{-\theta}\right\}$ is whether bounded or unbounded, we obtain that the limit equation of the last inequality becomes

$$
\begin{equation*}
-\Delta_{m} v \geq v^{p}, \quad v \geq 0 \text { in } \mathbb{R}^{N}, v(0)=\max v=1, \tag{2.35}
\end{equation*}
$$

which is a contradiction with [14, Theorem III].

## 3. Proof of Theorem 1.2

The following result is due to Azizieh and Clément (see [3]).
Lemma 3.1. Let $\mathbb{R}^{+}:=[0,+\infty)$ and let $(E,\|\cdot\|)$ be a real Banach space. Let $G: \mathbb{R}^{+} \times E \rightarrow E$ be continuous and map bounded subsets on relatively compact subsets. Suppose moreover that $G$ satisfies the following:
(a) $G(0,0)=0$,
(b) there exists $R>0$ such that
(i) $u \in E,\|u\| \leq R$, and $u=G(0, u)$ imply that $u=0$,
(ii) $\operatorname{deg}(\operatorname{Id}-G(0, \cdot), B(0, R), 0)=1$.

Let $J$ denote the set of the solutions to the problem

$$
\begin{equation*}
u=G(t, u) \tag{P}
\end{equation*}
$$

in $\mathbb{R}^{+} \times E$. Let $\mathfrak{C}$ denote the component (closed connected maximal subset with respect to the inclusion) of J to which $(0,0)$ belongs. Then if

$$
\begin{equation*}
\mathfrak{C} \cap(\{0\} \times E)=\{(0,0)\}, \tag{3.1}
\end{equation*}
$$

then $\mathfrak{C}$ is unbounded in $\mathbb{R}^{+} \times E$.
Proof of Theorem 1.2. First, we consider the following problem:

$$
\begin{gather*}
-\Delta_{m} u=f\left(x, u^{+}, \nabla u^{+}\right)-a(x) g\left(u^{+}, \nabla u^{+}\right)+\tau \quad \text { in } \Omega, \\
u=0 \quad \text { on } \partial \Omega, \tag{P}
\end{gather*}
$$

and let $u$ be a nontrivial solution to the problem above, then $u$ is nonnegative and so is solution for the problem $(P)_{\tau}$. In fact, suppose that $U=\{x \in \Omega: u(x)<0\}$ is nonempty. Then $u$ is a weak solution to

$$
\begin{gather*}
-\Delta_{m} u=\tau \geq 0 \quad \text { in } U, \\
u=0 \quad \text { on } \partial U . \tag{3.2}
\end{gather*}
$$

Using Lemma 2.3, we obtain that $u(x) \geq 0$, which is a contradiction with the definition of $U$.

Consider $T: L^{\infty}(\Omega) \rightarrow C^{1}(\bar{\Omega})$ as the unique weak solution $T(v)$ to the problem

$$
\begin{gather*}
-\Delta_{m} T(v)=v \quad \text { in } \Omega, \\
T(v)=0 \quad \text { on } \partial \Omega . \tag{3.3}
\end{gather*}
$$

It is well known that the function $T$ is continuous and compact (e.g., see [3, Lemma 1.1]).

Next, denote by $G(\tau, u):=T\left(f\left(x, u^{+}, \nabla u^{+}\right)-a(x) g\left(u^{+}, \nabla u^{+}\right)+\tau\right)$, then $G: \mathbb{R}^{+} \times C^{1}(\bar{\Omega})$ $\rightarrow C^{1}(\bar{\Omega})$ is continuous and compact. Now, we will verify the hypotheses of Lemma 3.1. It is clear that $G(0,0)=0$. On the other hand, consider the compact homotopy $H(\lambda, u)$ : $[0,1] \times C^{1}(\bar{\Omega}) \rightarrow C^{1}(\bar{\Omega})$ given by $H(\lambda, u)=u-\lambda G(0, u)$. We will show that

$$
\begin{equation*}
\text { if } u \text { is a nontrivial solution to } H(\lambda, u)=0 \text {, then }\|u\|>R>0 \text {. } \tag{3.4}
\end{equation*}
$$

This fact implies that condition (i) of (b) holds. Moreover, (3.4) also implies that $\operatorname{deg}(H(\lambda, \cdot) B(0, R), 0)$ is well defined since there is not solution on $\partial B(0, R)$. By the invariance property of the degree, we have

$$
\begin{equation*}
\operatorname{deg}(\operatorname{Id}-\lambda G(0, \cdot), B(0, R), 0)=\operatorname{deg}(\operatorname{Id}, B(0, R), 0)=1, \quad \forall \lambda \in(0,1] \tag{3.5}
\end{equation*}
$$

and (ii) of (b) holds.
In order to prove (3.4), note that $H(\lambda, u)=0$ implies that $u$ is a solution to the problem

$$
\begin{gather*}
-\Delta_{m} u=\lambda\left(f\left(x, u^{+}, \nabla u^{+}\right)-a(x) g\left(u^{+}, \nabla u^{+}\right)\right) \quad \text { in } \Omega, \\
u=0 \quad \text { on } \partial \Omega . \tag{3.6}
\end{gather*}
$$

Multiplying (3.6) by $u$, integrating over $\Omega$ the equation obtained, and applying Hölder's and Poincare's inequalities, we have that

$$
\begin{align*}
\int_{\Omega}|\nabla u|^{m} \leq & c_{0} \int_{\Omega} u^{p+1}+M_{1}\left[\int_{\Omega}|\nabla u|^{\alpha} u+\int_{\Omega}|\nabla u|^{\beta} u\right] \\
\leq & C\left(\int_{\Omega}|\nabla u|^{m}\right)^{(p+1) / m}+M_{1}\left(\int_{\Omega}|\nabla u|^{m}\right)^{\alpha / m}\left(\int_{\Omega} u^{m /(m-\alpha)}\right)^{(m-\alpha) / m} \\
& +M_{1}\left(\int_{\Omega}|\nabla u|^{m}\right)^{\beta / m}\left(\int_{\Omega} u^{m /(m-\beta)}\right)^{(m-\beta) / m} \\
\leq & C\left(\int_{\Omega}|\nabla u|^{m}\right)^{(p+1) / m}+C_{1}\left(\int_{\Omega}|\nabla u|^{m}\right)^{(\alpha+1) / m}+C_{1}\left(\int_{\Omega}|\nabla u|^{m}\right)^{(\beta+1) / m} . \tag{3.7}
\end{align*}
$$

This inequality implies that $\int_{\Omega}|\nabla u|^{m}>c>0$. Hence, we have $\|u\|>R>0$.
Now, we note that Theorem 1.1 and $C^{1, \rho}$ estimates imply that the component $\mathfrak{C}$ which contains $(0,0)$ is bounded. So, applying Lemma 3.1, we obtain that $\mathfrak{C} \cap\left(\{0\} \times C^{1}(\bar{\Omega})\right) \neq$ $(0,0)$. Therefore, we have a positive solution $u$ to the problem $(P)_{0}$.

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