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Parabolic problems with data measure

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Abstract

The article deals with the existence of solutions of some unilateral problems in the Orlicz-Sobolev spaces framework when the right-hand side is a Radon measure.

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1 Introduction

We deal with boundary value problems

$$\begin{cases} u \geq \psi & \text{a.e. in } Q = \Omega \times [0, T], \\ \frac{\partial u}{\partial t} + \mathcal{A}(u) = \mu & \text{in } Q, \\ u = 0 & \text{on } \partial Q = \partial \Omega \times [0, T], \\ u(x, 0) = u_0(x) & \text{in } \Omega, \end{cases} \quad (\mathcal{P})$$

where

$$\mathcal{A}(u) = -\operatorname{div}(a(\cdot, t, u, \nabla u)),$$

$T > 0$ and Ω is a bounded domain of \mathbf{R}^N , with the segment property. $a : \Omega \times \mathbf{R} \times \mathbf{R}^N \rightarrow \mathbf{R}^N$ is a Carathéodory function (that is, measurable with respect to x in Ω for every (t, s, ξ) in $\mathbf{R} \times \mathbf{R} \times \mathbf{R}^N$, and continuous with respect to (s, ξ) in $\mathbf{R} \times \mathbf{R}^N$ for almost every x in Ω) such that for all $\xi, \xi^* \in \mathbf{R}^N$, $\xi \neq \xi^*$,

$$a(x, t, s, \xi) \xi \geq \alpha M(|\xi|) \quad (1.1)$$

$$[a(x, t, s, \xi) - a(x, t, s, \xi^*)][\xi - \xi^*] > 0, \quad (1.2)$$

$$|a(x, t, s, \xi)| \leq c(x, t) + k_1 \bar{P}^{-1} M(k_2 |s|) + k_3 \bar{M}^{-1} M(k_4 |\xi|), \quad (1.3)$$

where $c(x, t)$ belongs to $E_{\bar{M}}(Q)$, $c \geq 0$, P is an N -function such that $P \ll M$ and k_i ($i = 1, 2, 3, 4$) belongs to \mathbf{R}^+ and α to \mathbf{R}_*^+ .

$$\mu \in M_b^+(Q), \quad u_0 \in M_b^+(\Omega), \quad (1.4)$$

$$\psi \in L^\infty(\Omega) \cap W_0^1 E_M(\Omega). \quad (1.5)$$

There have obviously been many previous studies on nonlinear differential equations with nonsmooth coefficients and measures as data. The special case was cited in the references (see [1, 2]).

It is noteworthy that the articles mentioned above differ in significant way, in the terms of the structure of the equations and data. In [1], when $f \in L^1(0, T; L^1(\Omega))$ and $u_0 \in L^1(\Omega)$. The authors have shown the existence of solutions u of the corresponding equation of the problem (\mathcal{P}) , $u \in L^q(0, T; W_0^{1,q}(\Omega))$ for every q such that $q < p - \frac{N}{N+1}$ which is more restrictive than the one given in the elliptic case $\left(q < \frac{N(p-1)}{N-1}\right)$.

In this article, we are interested with an obstacle parabolic problem with measure as data. We give an improved regularity result of the study of Boccardo et al. [1].

In [1], the authors have shown the existence of a weak solutions for the corresponding equation, the function $a(x, t, s, \xi)$ was assumed to satisfy a polynomial growth condition with respect to u and ∇u . When trying to relax this restriction on the function $a(\cdot, s, \xi)$, we are led to replace the space $L^p(0, T; W^{1,p}(\Omega))$ by an inhomogeneous Sobolev space $W^{1,x}L_M$ built from an Orlicz space L_M instead of L^p , where the N -function M which defines L_M is related to the actual growth of the Carathéodory's function.

For simplicity, one can suppose that there exist $\alpha > 0$, $\beta > 0$ such that

$$a(x, t, u, \nabla u) = a(x, t, u) \frac{M(|\nabla u|)}{|\nabla u|^2} \nabla u \text{ and } \alpha \leq -a(x, t, s) \leq \beta.$$

2 Preliminaries

Let $M : \mathbf{R}^+ \rightarrow \mathbf{R}^+$ be an N -function, i.e. M is continuous, convex, with $M(t) > 0$ for $t > 0$, $\frac{M(t)}{t} \rightarrow 0$ as $t \rightarrow 0$ and $\frac{M(t)}{t} \rightarrow \infty$ as $t \rightarrow \infty$. Equivalently, M admits the representation: $M(t) = \int_0^t a(\tau) d\tau$ where $a : \mathbf{R}^+ \rightarrow \mathbf{R}^+$ is non-decreasing, right continuous, with $a(0) = 0$, $a(t) > 0$ for $t > 0$ and $a(t) \rightarrow \infty$ as $t \rightarrow \infty$. The N -function \overline{M} conjugate to M is defined by $\overline{M}(t) = \int_0^t \bar{a}(\tau) d\tau$, where $\bar{a} : \mathbf{R}^+ \rightarrow \mathbf{R}^+$ is given by $\bar{a}(t) = \sup\{s : a(s) \leq t\}$ (see [3,4]).

The N -function M is said to satisfy the Δ_2 condition if, for some $k > 0$:

$$M(2t) \leq kM(t) \quad \text{for all } t \geq 0, \quad (2.1)$$

when this inequality holds only for $t \geq t_0 > 0$, M is said to satisfy the Δ_2 condition near infinity.

Let P and Q be two N -functions. $P \ll Q$ means that P grows essentially less rapidly than Q ; i.e., for each $\varepsilon > 0$,

$$\frac{P(t)}{Q(\varepsilon t)} \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

Let Ω be an open subset of \mathbf{R}^N . The Orlicz class $\mathcal{L}_M(\Omega)$ (resp. the Orlicz space $L_M(\Omega)$) is defined as the set of (equivalence classes of) real-valued measurable functions u on Ω such that

$$\int_{\Omega} M(u(x)) dx < +\infty \quad \left(\text{resp. } \int_{\Omega} M\left(\frac{u(x)}{\lambda}\right) dx < +\infty \text{ for some } \lambda > 0 \right).$$

Note that $L_M(\Omega)$ is a Banach space under the norm $\|u\|_{M,\Omega} = \inf \left\{ \lambda > 0 : \int_{\Omega} M \left(\frac{u(x)}{\lambda} \right) dx \leq 1 \right\}$ and $\mathcal{L}_M(\Omega)$ is a convex subset of $L_M(\Omega)$.

The closure in $L_M(\Omega)$ of the set of bounded measurable functions with compact support in $\overline{\Omega}$ is denoted by $E_M(\Omega)$. The equality $E_M(\Omega) = L_M(\Omega)$ holds if and only if M satisfies the Δ_2 condition, for all t or for t large according to whether Ω has infinite measure or not.

The dual of $E_M(\Omega)$ can be identified with $L_{\overline{M}}(\Omega)$ by means of the pairing $\int_{\Omega} u(x)v(x)dx$, and the dual norm on $L_{\overline{M}}(\Omega)$ is equivalent to $\|\cdot\|_{\overline{M},\Omega}$. The space $L_M(\Omega)$ is reflexive if and only if M and \overline{M} satisfy the Δ_2 condition, for all t or for t large, according to whether Ω has infinite measure or not.

We now turn to the Orlicz-Sobolev space. $W^1L_M(\Omega)$ (resp. $W^1E_M(\Omega)$) is the space of all functions u such that u and its distributional derivatives up to order 1 lie in $L_M(\Omega)$ (resp. $E_M(\Omega)$). This is a Banach space under the norm $\|u\|_{1,M,\Omega} = \sum_{|\alpha| \leq 1} \|D^{\alpha}u\|_{M,\Omega}$. Thus, $W^1L_M(\Omega)$ and $W^1E_M(\Omega)$ can be identified with subspaces of the product of $N + 1$ copies of $L_M(\Omega)$. Denoting this product by ΠL_M , we will use the weak topologies $\sigma(\Pi L_M, \Pi E_{\overline{M}})$ and $\sigma(\Pi L_M, \Pi L_{\overline{M}})$. The space $W_0^1E_M(\Omega)$ is defined as the (norm) closure of the Schwartz space $\mathcal{D}(\Omega)$ in $W^1E_M(\Omega)$ and the space $W_0^1L_M(\Omega)$ as the $\sigma(\Pi L_M, \Pi E_{\overline{M}})$ closure of $\mathcal{D}(\Omega)$ in $W^1L_M(\Omega)$. We say that u_n converges to u for the modular convergence in $W^1L_M(\Omega)$ if for some $\lambda > 0$, $\int_{\Omega} M \left(\frac{D^{\alpha}u_n - D^{\alpha}u}{\lambda} \right) dx \rightarrow 0$ for all $|\alpha| \leq 1$. This implies convergence for $\sigma(\Pi L_M, \Pi L_{\overline{M}})$. If M satisfies the Δ_2 condition on \mathbf{R}^+ (near infinity only when Ω has finite measure), then modular convergence coincides with norm convergence.

Let $W^{-1}L_{\overline{M}}(\Omega)$ (resp. $W^{-1}E_{\overline{M}}(\Omega)$) denote the space of distributions on Ω which can be written as sums of derivatives of order ≤ 1 of functions in $L_{\overline{M}}(\Omega)$ (resp. $E_{\overline{M}}(\Omega)$). It is a Banach space under the usual quotient norm.

If the open set Ω has the segment property, then the space $\mathcal{D}(\Omega)$ is dense in $W_0^1L_M(\Omega)$ for the modular convergence and for the topology $\sigma(\Pi L_M, \Pi L_{\overline{M}})$ (cf. [5,6]). Consequently, the action of a distribution in $W^{-1}L_{\overline{M}}(\Omega)$ on an element of $W_0^1L_M(\Omega)$ is well defined.

For $k > 0$, $s \in \mathbf{R}$, we define the truncation at height k , $T_k(s) = [k - (k - |s|)_+] \text{sign}(s)$.

The following abstract lemmas will be applied to the truncation operators.

Lemma 2.1 [7] *Let $F : \mathbf{R} \rightarrow \mathbf{R}$ be uniformly lipschitzian, with $F(0) = 0$. Let M be an N -function and let $u \in W_0^1L_M(\Omega)$ (resp. $W_0^1E_M(\Omega)$).*

Then $F(u) \in W_0^1L_M(\Omega)$ (resp. $W_0^1E_M(\Omega)$). Moreover, if the set of discontinuity points of F' is finite, then

$$\frac{\partial}{\partial x_i} F(u) = \begin{cases} F'(u) \frac{\partial u}{\partial x_i} & \text{a.e. in } \{x \in \Omega : u(x) \notin D\} \\ 0 & \text{a.e. in } \{x \in \Omega : u(x) \in D\} \end{cases}$$

Let Ω be a bounded open subset of \mathbf{R}^N , $T > 0$ and set $Q = \Omega \times]0, T[$. Let $m \geq 1$ be an integer and let M be an N -function. For each $\alpha \in \mathbf{I}\mathbf{N}^N$, denote by D_x^{α} the distributional derivative on Q of order α with respect to the variable $x \in \mathbf{R}^N$. The

inhomogeneous Orlicz-Sobolev spaces are defined as follows

$$W^{m,x}L_M(Q) = \{u \in L_M(Q) : D_x^\alpha u \in L_M(Q) \forall |\alpha| \leq m\} \quad W^{m,x}E_M(Q) = \{u \in E_M(Q) : D_x^\alpha u \in E_M(Q) \forall |\alpha| \leq m\}$$

The last space is a subspace of the first one, and both are Banach spaces under the norm $\|u\| = \sum_{|\alpha| \leq m} \|D_x^\alpha u\|_{M,Q}$. We can easily show that they form a complementary system when Ω satisfies the segment property. These spaces are considered as subspaces of the product space $\Pi L_m(Q)$ which have as many copies as there are α -order derivatives, $|\alpha| \leq m$. We shall also consider the weak topologies $\sigma(\prod L_M, \prod E_M)$ and $\sigma(\prod L_M, \prod L_M)$. If $u \in W^{m,x}L_M(Q)$, then the function $t \mapsto u(t) = u(t, \cdot)$ is defined on $[0, T]$ with values in $W^m L_M(\Omega)$. If, further, $u \in W^{m,x}E_M(Q)$ then the concerned function is a $W^m E_M(\Omega)$ -valued and is strongly measurable. Furthermore, the following imbedding holds: $W^{m,x}E_M(Q) \subset L^1(0, T; W^m E_M(\Omega))$. The space $W^{m,x}L_M(Q)$ is not in general separable, if $u \in W^{m,x}L_M(Q)$, we cannot conclude that the function $u(t)$ is measurable on $[0, T]$. However, the scalar function $t \mapsto \|u(t)\|_{M,\Omega}$, is in $L^1(0, T)$. The space $W_0^{m,x}E_M(Q)$ is defined as the (norm) closure in $W^{m,x}E_M(Q)$ of $\mathcal{D}(\Omega)$. We can easily show as in [6] that when Ω has the segment property, then each element u of the closure of $\mathcal{D}(\Omega)$ with respect of the weak $*$ topology $\sigma(\prod L_M, \prod E_M)$ is limit, in $W^{m,x}L_M(Q)$, of some subsequence $(u_i) \subset \mathcal{D}(Q)$ for the modular convergence; i.e., there exists $\lambda > 0$ such that for all $|\alpha| \leq m$,

$$\int_Q M\left(\frac{D_x^\alpha u_i - D_x^\alpha u}{\lambda}\right) dx dt \rightarrow 0 \text{ as } i \rightarrow \infty,$$

this implies that (u_i) converges to u in $W^{m,x}L_M(Q)$ for the weak topology $\sigma(\prod L_M, \prod L_M)$. Consequently, $\overline{\mathcal{D}(Q)}^{\sigma(\prod L_M, \prod E_M)} = \overline{\mathcal{D}(Q)}^{\sigma(\prod L_M, \prod L_M)}$, and this space will be denoted by $W_0^{m,x}L_M(Q)$.

Furthermore, $W_0^{m,x}E_M(Q) = W_0^{m,x}L_M(Q) \cap \prod E_M$. Poincaré's inequality also holds in $W_0^{m,x}L_M(Q)$, i.e., there is a constant $C > 0$ such that for all $u \in W_0^{m,x}L_M(Q)$ one has $\sum_{|\alpha| \leq m} \|D_x^\alpha u\|_{M,Q} \leq C \sum_{|\alpha| = m} \|D_x^\alpha u\|_{M,Q}$. Thus both sides of the last inequality are equivalent norms on $W_0^{m,x}L_M(Q)$. We have then the following complementary system:

$$\begin{pmatrix} W_0^{m,x}L_M(Q) & F \\ W_0^{m,x}E_M(Q) & F_0 \end{pmatrix}$$

F being the dual space of $W_0^{m,x}E_M(Q)$. It is also, except for an isomorphism, the quotient of $\prod L_M$ by the polar set $W_0^{m,x}E_M(Q)^\perp$, and will be denoted by $F = W^{-m,x}L_M(Q)$, and it is shown that $W^{-m,x}L_M(Q) = \left\{f = \sum_{|\alpha| \leq m} D_x^\alpha f_\alpha : f_\alpha \in L_M(Q)\right\}$. This space will be equipped with the usual quotient norm $\|f\| = \inf \sum_{|\alpha| \leq m} \|f_\alpha\|_{M,Q}$ where the infimum is taken on all possible decompositions $f = \sum_{|\alpha| \leq m} D_x^\alpha f_\alpha$, $f_\alpha \in L_M(Q)$. The space F_0 is then given by $F_0 = \left\{f = \sum_{|\alpha| \leq m} D_x^\alpha f_\alpha : f_\alpha \in E_M(Q)\right\}$ and is denoted by $F_0 = W^{-m,x}E_M(Q)$.

We can easily check, using Lemma 4.4 of [6], that each uniformly lipschitzian mapping F , with $F(0) = 0$, acts in inhomogeneous Orlicz-Sobolev spaces of order 1: $W^{1,x}L_M(Q)$ and $W_0^{1,x}L_M(Q)$.

3 Main results

First, we give the following results which will be used in our main result.

3.1 Useful results

Hereafter, we denote by \mathcal{X}_N the real number defined by $\mathcal{X}_N = NC_N^{1/N}$, C_N is the measure of the unit ball of \mathbf{R}^N , and for a fixed $t \in [0, T]$, we denote $\mu(\theta) = \text{meas}\{(x, t) : |u(x, t)| > \theta\}$.

Lemma 3.1 [8] *Let $u \in W_0^{1,x}L_M(Q)$, and let fixed $t \in [0, T]$, then we have*

$$-\mu'(\theta) \geq -\frac{1}{\mathcal{X}_N \mu(\theta)^{1-\frac{1}{N}}} S \left(-\frac{1}{\mathcal{X}_N \mu(\theta)^{1-\frac{1}{N}}} \frac{d}{d\theta} \int_{\{|u|>\theta\}} M(|\nabla u|) dx \right), \forall \theta > 0$$

and where S is defined by

$$\frac{1}{S(s)} = \sup\{t : B(t) \leq s\}, \quad B(s) = \frac{M(s)}{s}.$$

Lemma 3.2 *Under the hypotheses (1.1)-(1.3), if f, u_0 are regular functions and $f, u_0 \geq 0$, then there exists at least one positive weak solution of the problem*

$$\begin{cases} \frac{\partial u}{\partial t} + \mathcal{A}(u) = f & \text{in } Q, \\ u = 0 & \text{on } \partial Q, \\ u(x, 0) = u_0(x) & \text{in } \Omega. \end{cases} \quad (E)$$

such that

$$\frac{\partial u}{\partial t} \geq 0, \quad \text{a.e. } t \in (0, T).$$

Proof

Let u be a continuous function, we say that u satisfies (*) if: there exists a continuous and increasing function β such that $\|u(t) - u(s)\|_2 \leq \beta(\|u_0\|_2)|t - s|$, where $u_0(x) = u(x, 0)$.

Let $X := \left\{ u \in W_0^{1,x}L_M(Q) \cap L^2(Q) \text{ s.t. } u \text{ satisfies } (*) \text{ and } \frac{du}{dt} \in L^\infty(0, T, L^2(\Omega)) \right\}$.

Let us consider the set $\mathcal{C} = \{v \in X : v(t) \in C, \quad \frac{\partial v}{\partial t} \geq 0 \text{ a.e. } t \in (0, T)\}$, where C is a closed convex of $W_0^1L_M(\Omega)$. It is easy to see that \mathcal{C} is a closed convex (since all its elements satisfy (*)).

We claim that the problem

$$\begin{cases} u \in \mathcal{C} \cap L^2(Q) \\ \frac{\partial u}{\partial t} + \mathcal{A}(u) = f & \text{in } Q, \\ u = 0 & \text{on } \partial Q, \\ u(x, 0) = u_0 & \text{in } \Omega. \end{cases} \quad (E')$$

has a weak solution which is unique in the sense defined in [9].

Indeed, let us consider the approximate problem

$$\begin{cases} \frac{\partial u_n}{\partial t} + \mathcal{A}(u_n) + nT_n(\Phi(u_n)) = f & \text{in } \Omega, \\ u_n(\cdot, 0) = u_0 & \text{in } \Omega. \end{cases} \quad (E'')$$

where the functional Φ is defined by $\Phi : X \rightarrow \mathbf{R} \cup \{+\infty\}$ such that

$$\Phi(v) := \begin{cases} 0 & \text{if } v \in \mathcal{C}, \\ +\infty & \text{otherwise.} \end{cases}$$

The existence of such $u_n \in X$ was ensured by Kacur et al. [10].

Following the same proof as in [9], we can prove the existence of a solution u of the problem (E') as limit of u_n (for more details see [9]).

Lemma 3.3 *Let $v \in W_0^{1,x}L_M(Q)$ such that $\frac{\partial v}{\partial t} \in W^{-1,x}L_{\overline{M}}(Q) + L^1(Q)$ and $v \geq \psi$, $\psi \in L^\infty(\Omega) \cap W_0^1E_M(\Omega)$.*

Then, there exists a smooth function (v_j) such that

$$v_j \geq \psi,$$

$v_j \rightarrow v$ for the modular convergence in $W_0^{1,x}L_M(Q)$,

$$\frac{\partial v_j}{\partial t} \rightarrow \frac{\partial v}{\partial t} \text{ for the modular convergence in } W^{-1,x}L_{\overline{M}}(Q) + L^1(Q).$$

For the proof, we use the same technique as in [11] in the parabolic case.

3.2 Existence result

Let M be a fixed N -function, we define K as the set of N -function D satisfying the following conditions:

i) $M(D^{-1}(s))$ is a convex function,

$$ii) \int_0^\infty D \circ B^{-1} \left(\frac{1}{r^{1-1/N}} \right) dr < +\infty, B(t) = \frac{M(t)}{t},$$

iii) There exists an N -function H such that $H \circ \overline{M}^{-1} \circ M \leq D$ and $\overline{H} \leq D$ near infinity.

Theorem 3.1 *Under the hypotheses (1.1)-(1.5), The problem (P) has at least one solution u in the following sense:*

$$\begin{cases} u \geq \psi \text{ a.e. in } Q \\ T_k(u) \in W_0^{1,x}L_M(Q), u \in W_0^{1,x}L_D(Q) \quad \forall D \in K \\ - \int_Q u \frac{\partial \varphi}{\partial t} + \int_Q a(\cdot, u, \nabla u) \nabla \varphi dx dt - \int_\Omega \varphi du_0 = \int_Q \varphi d\mu, \end{cases}$$

for all $\phi \in D(\mathbf{R}^{N+1})$ which are zero in a neighborhood of $(0, T) \times \partial \Omega$ and $\{T\} \times \Omega$.

Remark 3.1 (1) *If $\psi = -\infty$ in the problem (P), then the above theorem gives the same regularity as in the elliptic case.*

(2) *An improved regularity is reached for all N -function satisfying the conditions (i)-(ii)-(iii).*

$$\text{For example, } u \in W_0^{1,x}L_D(Q), D(t) = \frac{t^q}{\text{Log}^\sigma(e+t)}, \text{ for all } q < \frac{N(p-1)}{N-1}, \sigma > 1.$$

In the sequel and throughout the article, we will omit for simplicity the dependence on x and t in the function $a(x, t, s, \zeta)$ and denote $\epsilon(n, j, \mu, s, m)$ all quantities (possibly different) such that

$$\lim_{m \rightarrow \infty} \lim_{s \rightarrow \infty} \lim_{\mu \rightarrow \infty} \lim_{j \rightarrow \infty} \lim_{n \rightarrow \infty} \varepsilon(n, j, \mu, s, m) = 0,$$

and this will be in the order in which the parameters we use will tend to infinity, that is, first n , then j , μ , s , and finally m . Similarly, we will write only $\varepsilon(n)$, or $\varepsilon(n, j)$,... to mean that the limits are made only on the specified parameters.

3.2.1 A sequence of approximating problems

Let (f_n) be a sequence in $D(Q)$ which is bounded in $L^1(Q)$ and converge to μ in $M_b(Q)$.

Let (u_0^n) be a sequence in $D(\Omega)$ which is bounded in $L^1(\Omega)$ and converge to u_0 in $M_b(\Omega)$.

We define the following problems approximating the original (P) :

$$\begin{cases} \frac{\partial u_n}{\partial t} + \mathcal{A}(u_n) - nT_n((u_n - \psi)^-) = f_n & \text{in } Q, \\ u_n = 0 & \text{on } \partial Q \\ u_n(\cdot, 0) = u_0^n & \text{in } \Omega. \end{cases} \quad (P_n)$$

Lemma 3.4 *Under the hypotheses (1.1)-(1.3), there exists at least one solution u_n of the problem (P_n) such that $\frac{\partial u_n}{\partial t} \geq 0$ a.e. in Q .*

For the proof see Lemma 3.2.

3.2.2 A priori estimates

Lemma 3.5 *There exists a subsequence of (u_n) (also denoted (u_n)), there exists a measurable function u such that:*

$$\begin{aligned} u &\geq \psi, T_k(u) \in W_0^{1,x}L_M(Q) \text{ for all } k > 0 \\ u_n &\rightharpoonup u \text{ weakly in } W_0^{1,x}L_D(Q) \text{ for all } D \in K. \end{aligned}$$

Proof:

Recall that $u_n \geq 0$ since $f_n \geq 0$.

Let $h > 0$ and consider the following test function $v = T_h(u_n - T_k(u_n))$ in (P_n) , we obtain

$$\ll \frac{\partial u_n}{\partial t}, v \gg + \alpha \int_{\{k < |u_n| \leq k+h\}} M(|\nabla u_n|) dx dt - n \int_Q T_n((u_n - \psi)^-) v dx dt \leq \int_Q f_n v dx dt$$

We have

$$\ll \frac{\partial u_n}{\partial t}, T_h(u_n - T_k(u_n)) \gg = \int_{\Omega} \int_0^{u_n(x,T)} T_h(s - T_k(s)) - \int_{\Omega} \int_0^{u_0^n} T_h(s - T_k(s)).$$

So,

$$- \int_Q nT_n((u_n - \psi)^-) \frac{T_h(u_n - T_k(u_n))}{h} dx dt \leq C.$$

Now, let us fix $k > \|\psi\|_{\infty}$, we deduce the fact that:
 $nT_n(u_n - \psi)(u_n - k)\chi_{\{u_n \leq \psi\}}\chi_{\{k < u_n \leq k+h\}} \geq 0$.

Let h to tend to zero, one has

$$n \int_Q T_n((u_n - \psi)^-) dx dt \leq C. \quad (3.1)$$

Let us use as test function in $(P_n), v = T_k(u_n)$, then as above, we obtain

$$\int_Q M(|\nabla T_k(u_n)|) \leq C_1 k. \quad (3.2)$$

Then $(T_k(u_n))_n$ is bounded in $W_0^{1,x}L_M(Q)$, and then there exist some $\omega_k \in W_0^{1,x}L_M(Q)$ such that

$T_k(u_n) \rightharpoonup \omega_k$, weakly in $W_0^{1,x}L_M(Q)$ for $\sigma(\prod L_M, \prod E_M^-)$, strongly in $E_M(Q)$ and a.e in Q .

Let consider the C^2 function defined by

$$\mu_k(s) \begin{cases} s & |s| \leq k/2 \\ k \operatorname{sign}(s) & |s| \geq k \end{cases}$$

Multiplying the approximating equation by $\eta'_k(u_n)$, we get $\frac{\partial \eta_k(u_n)}{\partial t} - \operatorname{div}(a(\cdot, u_n, \nabla u_n) \eta'_k(u_n)) + a(\cdot, u_n, \nabla u_n) \eta''_k(u_n) = f_n \eta'_k(u_n) + n(T_n((u_n - \psi)^-)) \eta'_k(u_n)$ in the distributions sense. We deduce then that $\eta_k(u_n)$ being bounded in $W_0^{1,x}L_M(Q)$ and $\frac{\partial \eta_k(u_n)}{\partial t}$ in $W^{-1,x}L_{\overline{M}}(Q) + L^1(Q)$. By Corollary 1 of [12], $\eta_k(u_n)$ is compact in $L^1(Q)$.

Following the same way as in [2], we obtain for every $k > 0$,

$$T_k(u_n) \rightharpoonup T_k(u), \text{ weakly in } W_0^{1,x}L_M(Q) \text{ for } \sigma(\prod L_M, \prod E_M^-), \text{ strongly in } L^1(Q) \text{ and a.e in } Q. \quad (3.3)$$

Using now the estimation (3.1) and Fatou's lemma to obtain

$$(u - \psi)^- = 0 \text{ and so } u \geq \psi.$$

Let fixed a $t \in [0, T]$. We argue now as for the elliptic case, the problem becomes:

$$\frac{\partial u_n}{\partial t} - \operatorname{div}(a(\cdot, u_n, \nabla u_n)) = f_n + nT_n((u_n - \psi)^-) \quad \text{in } \Omega. \quad (P'_n)$$

We denote $g_n := nT_n((u_n - \psi)^-)$.

Let ϕ be a truncation defined by

$$\varphi(\xi) = \begin{cases} 0 & 0 \leq \xi \leq \theta \\ \frac{1}{h}(\xi - \theta) & \theta < \xi < \theta + h \\ 1 & \xi \geq \theta + h \\ -\varphi(-\xi) & \xi < 0 \end{cases} \quad (3.4)$$

for all $\theta, h > 0$.

Using $v = \phi(u_n)$ as a test function in the approximate elliptic problem (P'_n) , we obtain by using the same technique as in [8]

$$-\frac{d}{d\theta} \int_{\{|u_n| > \theta\}} M(|\nabla u_n|) dx \leq C \int_{\{|u_n| \geq \theta\}} (f_n + g_n - \frac{\partial u_n}{\partial t}) dx. \quad (3.5)$$

here and below C denote positive constants not depending on n .

By using Lemma 3.1, we obtain (supposing $-\mu'(\theta) > 0$ which does not affect the proof) and following the same way as in [8], we have for $D \in K$,

$$-\frac{d}{d\theta} \int_{\{|u_n|>\theta\}} D(|\nabla u_n|) dx \leq (-\mu'(\theta)) D \circ B^{-1} \left(\left(-\frac{1}{\mathcal{X}_{N\mu}(\theta)^{1-\frac{1}{N}}} \frac{d}{d\theta} \int_{\{|u_n|>\theta\}} M(|\nabla u_n|) dx \right) \right). \quad (3.6)$$

Let denote $k(t, s) := \int_0^s u_{n*}(t, \rho) d\rho$, then

$$\frac{\partial k}{\partial t}(t, s) = \int_0^s \frac{\partial u_{n*}(t, \rho)}{\partial t} d\rho, \quad \int_{u_n > \theta} \frac{\partial u_n}{\partial t} dx = \frac{\partial k}{\partial t}(t, \mu(\theta)).$$

Using Lemma 3.1, denoting $F(t, \mu(\theta)) := \int_0^{\mu(\theta)} (f_{n*} + g_{n*})(\rho) d\rho$ one has

$$1 \leq \frac{-\mu'(\theta)}{\mathcal{X}_{N\mu}(\theta)^{1-\frac{1}{N}}} B^{-1} \left(\frac{1}{\mathcal{X}_{N\mu}(\theta)^{1-\frac{1}{N}}} \left[F(t, \mu(\theta)) - \frac{\partial k}{\partial t}(t, \mu(\theta)) \right] \right).$$

Remark also that $F(t, s) \geq \frac{\partial k}{\partial t}(t, s)$ and using Lemma 3.2, we have $\left| \frac{\partial k}{\partial t}(t, s) \right| \leq F(t, s)$.

Combining the inequalities (3.5) and (3.6) we obtain,

$$-\frac{d}{d\theta} \int_{\{|u_n|>\theta\}} D(|\nabla u_n|) dx \leq (-\mu'(\theta)) D \circ B^{-1} \left(-\frac{1}{\mathcal{X}_{N\mu}(\theta)^{1-\frac{1}{N}}} \left[F(t, \mu(\theta)) - \frac{\partial k}{\partial t}(t, \mu(\theta)) \right] \right). \quad (3.7)$$

and since the function $\theta \rightarrow \int_{\{|u_n|>\theta\}} D(|\nabla u_n|) dx$ is absolutely continuous, we get

$$\begin{aligned} \int_{\Omega} D(|\nabla u_n|) dx &= \int_0^{+\infty} \left(-\frac{d}{d\theta} \int_{\{|u_n|>\theta\}} D(|\nabla u_n|) dx \right) dt \\ &\leq \frac{1}{C'} \int_0^{C'|\Omega|} D \circ B^{-1} \left(\left(\frac{C}{s^{1-1/N}} \right) \right) ds \text{ (using 3.1 and 3.7).} \end{aligned}$$

Then, the sequence (u_n) is bounded in $W_0^{1,x} L_D(Q)$ and we deduce that $u \in W_0^{1,x} L_D(Q)$ for all N -function $D \in K$.

3.3 Almost everywhere convergence of the gradients

Lemma 3.6 *The subsequence (u_n) obtained in Lemma 3.5 satisfies:*

$$\nabla u_n \rightarrow \nabla u \text{ a.e. in } Q.$$

Proof:

Let $m > 0$, $k > 0$ such that $m > k$. Let ρ_m be a truncation defined by

$$\rho_m(s) = \begin{cases} 1 & |s| \leq m, \\ m+1-|s| & m < |s| < m+1, \\ 0 & |s| \geq m+1. \end{cases}$$

$$R_m(s) = \int_0^s \rho_m(t) dt \text{ and } \omega_{\mu,j} = T_k(v_j)_{\mu}.$$

where $v_j \in D(Q)$ such that $v_j \geq \psi$ and $v_j \rightarrow T_k(u)$ with the modular convergence in $W_0^{1,x} L_M(Q)$ (for the existence of such function see [11] since $\psi \in L^\infty(\Omega) \cap W_0^1 E_M(\Omega)$).

ω_μ is the mollifier function defined in Landes [13], the function $\omega_{\mu,j}$ have the following properties:

$$\begin{cases} \frac{\partial \omega_{\mu,j}}{\partial t} = \mu(T_k(v_j) - \omega_{\mu,j}), \omega_{\mu,j}(0) = 0, |\omega_{\mu,j}| \leq k, \\ \omega_{\mu,j} \rightarrow T_k(u)_\mu \text{ in } W_0^{1,x}L_M(Q) \text{ for the modular convergence with respect to } j, \\ T_k(u)_\mu \rightarrow T_k(u) \text{ in } W_0^{1,x}L_M(Q) \text{ for the modular convergence with respect to } \mu. \end{cases}$$

Set $v = (T_k(u_n) - \omega_{\mu,j}) \rho_m(u_n)$ as test function, we have

$$\begin{aligned} & \ll \frac{\partial u_n}{\partial t}, v \gg \\ & + \int_Q a(\cdot, u_n, \nabla u_n)(\nabla T_k(u_n) - \nabla \omega_{\mu,j}) \rho_m(u_n) \end{aligned} \quad (1)$$

$$\begin{aligned} & + \int_Q a(\cdot, u_n, \nabla u_n) \nabla u_n (T_k(u_n) - \omega_{\mu,j}) \rho'_m(u_n) \\ & = \int_Q f_n v dx dt + n \int_Q T_n((u_n - \psi)^-) v dx dt \\ & =: (3) + (4). \end{aligned} \quad (2)$$

Let us recall that for $u_n \in W_0^{1,x}L_M(Q)$, there exists a smooth function $u_{n\sigma}$ (see [14]) such that

$$\begin{aligned} u_{n\sigma} & \rightarrow u_n \text{ for the modular convergence in } W_0^{1,x}L_M(Q), \\ \frac{\partial u_{n\sigma}}{\partial t} & \rightarrow \frac{\partial u_n}{\partial t} \text{ for the modular convergence in } W^{-1,x}L_{\overline{M}}(Q) + L^1(Q). \end{aligned}$$

$$\begin{aligned} & \ll \frac{\partial u_n}{\partial t}, v \gg = \lim_{\sigma \rightarrow 0+} \int_Q (u_{n\sigma})'(T_k(u_{n\sigma}) - \omega_{\mu,j}) \rho_m(u_{n\sigma}) \\ & = \lim_{\sigma \rightarrow 0+} \left(\int_Q (R_m(u_{n\sigma}) - T_k(u_{n\sigma}))'(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx dt + \int_Q (T_k(u_{n\sigma}))'(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx dt \right) \\ & = \lim_{\sigma \rightarrow 0+} \left[\int_\Omega (R_m(u_{n\sigma}) - T_k(u_{n\sigma}))(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx \right]_0^T \\ & - \int_Q (R_m(u_{n\sigma}) - T_k(u_{n\sigma}))(T_k(u_{n\sigma}) - \omega_{\mu,j})' dx dt \\ & + \int_Q (T_k(u_{n\sigma}))'(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx dt =: I_1 + I_2 + I_3. \end{aligned}$$

Remark also that,

$$\begin{aligned} R_m(u_{n\sigma}) & \geq T_k(u_{n\sigma}) \text{ if } u_{n\sigma} < k \text{ and } R_m(u_{n\sigma}) > k = T_k(u_{n\sigma}) \geq |\omega_{\mu,j}| \text{ if } u_{n\sigma} \geq k. \\ I_1 & = \int_\Omega (R_m(u_{n\sigma})(T) - T_k(u_{n\sigma})(T))(T_k(u_{n\sigma})(T) - \omega_{\mu,j}(T)) dx \\ I_1 & \geq \int_{u_{n\sigma}(T) \leq k} (R_m(u_{n\sigma})(T) - T_k(u_{n\sigma})(T))(T_k(u_{n\sigma})(T) - \omega_{\mu,j}(T)) dx \end{aligned}$$

and it is easy to see that $\limsup_{\sigma \rightarrow 0+} I_1 \geq \varepsilon(n, j, \mu)$.

Concerning I_2 ,

$$\begin{aligned} I_2 & = - \int_{u_{n\sigma} \leq k} (R_m(u_{n\sigma}) - T_k(u_{n\sigma}))(T_k(u_{n\sigma}) - \omega_{\mu,j})' dx dt + \int_{u_{n\sigma} > k} (R_m(u_{n\sigma}) - T_k(u_{n\sigma}))(\omega_{\mu,j})' dx dt \\ & =: I_2^1 + I_2^2. \end{aligned}$$

As in I_1 , we obtain $I_2^1 \geq \varepsilon(n, j, \mu)$,

and

$$I_2^2 = \int_{u_{n\sigma} > k} (R_m(u_{n\sigma}) - T_k(u_{n\sigma}))(\omega_{\mu,j})' dx dt \geq \mu \int_{u_{n\sigma} > k} (R_m(u_{n\sigma}) - T_k(u_{n\sigma}))(T_k(v_j) - T_k(u_{n\sigma}))' dx dt,$$

thus by using the fact that $(R_m(u_{n\sigma}) - T_k(u_{n\sigma}))(T_k(u_{n\sigma}) - \omega_{\mu,j})\mathcal{X}_{u_{n\sigma} > k} \geq 0$.

$$\text{So, } \limsup_{\sigma \rightarrow 0^+} I_2^2 \geq \mu \int_{u_n > k} (R_m(u_n) - T_k(u_n))(T_k(v_j) - T_k(u_n))' dx dt = \varepsilon(n, j).$$

About I_3 ,

$$\begin{aligned} I_3 &= \int_Q (T_k(u_{n\sigma}))'(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx dt \\ &= \int_Q (T_k(u_{n\sigma}) - \omega_{\mu,j})'(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx dt + \int_Q (\omega_{\mu,j})'(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx dt. \end{aligned}$$

Set $\Phi(s) = s^2/2$, $\Phi \geq 0$, then

$$\begin{aligned} I_3 &= \left[\int_{\Omega} \Phi(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx \right]_0^T + \mu \int_Q (T_k(v_j) - \omega_{\mu,j})(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx dt \\ &\geq \varepsilon(n, j, \mu) + \mu \int_Q (T_k(v_j) - T_k(u_{n\sigma}))(T_k(u_{n\sigma}) - \omega_{\mu,j}) dx dt \text{ (as in } I_2). \end{aligned}$$

So,

$$\begin{aligned} \limsup_{\sigma \rightarrow 0^+} I_3 &\geq \varepsilon(n, j, \mu) + \mu \int_Q (T_k(v_j) - T_k(u_n))(T_k(u_n) - \omega_{\mu,j}) dx dt \\ &= \varepsilon(n, j, \mu) + \mu \int_Q (T_k(v_j) - T_k(u))(T_k(u) - \omega_{\mu,j}) dx dt + \varepsilon(n), \end{aligned}$$

and easily we deduce, $\limsup_{\sigma \rightarrow 0^+} I_3 \geq \varepsilon(n, j, \mu)$.

Finally we conclude that: $\ll \frac{\partial u_n}{\partial t}, (T_k(u_n) - \omega_{\mu,j})\rho_m(u_n) \gg \geq \varepsilon(n, j, \mu)$.

We are interested now with the terms of (1)-(4).

About (1):

$$\begin{aligned} &\int_Q a(\cdot, u_n, \nabla u_n)(\nabla T_k(u_n) - \nabla \omega_{\mu,j})\rho_m(u_n) dx dt \\ &= \int_{u_n \leq k} a(\cdot, u_n, \nabla u_n)(\nabla T_k(u_n) - \nabla \omega_{\mu,j})\rho_m(u_n) dx dt + \int_{u_n > k} a(\cdot, u_n, \nabla u_n)(\nabla T_k(u_n) - \nabla \omega_{\mu,j})\rho_m(u_n) dx dt \\ &= \int_Q a(\cdot, T_k(u_n), \nabla T_k(u_n))(\nabla T_k(u_n) - \nabla \omega_{\mu,j}) dx dt + \int_{u_n > k} a(\cdot, u_n, \nabla u_n)(\nabla T_k(u_n) - \nabla \omega_{\mu,j})\rho_m(u_n) dx dt \end{aligned}$$

recall that $\rho_m(u_n) = 1$ on $\{|u_n| \leq k\}$.

Let $s > 0$, $Q_s = \{(x, t) \in Q : |\nabla T_k(u)| \leq s\}$, $Q_j^s = \{(x, t) \in Q : |\nabla T_k(v_j)| \leq s\}$.

$$\begin{aligned} &\int_Q a(\cdot, u_n, \nabla u_n)(\nabla T_k(u_n) - \nabla \omega_{\mu,j})\rho_m(u_n) dx dt \\ &= \int_Q \left(a(\cdot, T_k(u_n), \nabla T_k(u_n)) - a(\cdot, T_k(u_n), \nabla T_k(v_j)\mathcal{X}_j^s) \right) (\nabla T_k(u_n) - \nabla T_k(v_j)\mathcal{X}_j^s) dx dt \\ &\quad + \int_Q a(\cdot, T_k(u_n), \nabla T_k(v_j)\mathcal{X}_j^s) (\nabla T_k(u_n) - \nabla T_k(v_j)\mathcal{X}_j^s) dx dt \\ &\quad + \int_Q a(\cdot, T_k(u_n), \nabla T_k(u_n)) \nabla T_k(v_j)\mathcal{X}_j^s dx dt \\ &\quad - \int_Q a(\cdot, u_n, \nabla u_n) \nabla \omega_{\mu,j} \rho_m(u_n) dx dt \\ &=: I_1 + I_2 + I_3 + I_4. \end{aligned}$$

By using the inequality (1.3), we can deduce the existence of some measurable function h_k such that

$$a(\cdot, T_k(u_n), \nabla T_k(u_n)) \rightharpoonup h_k \text{ in } (L_{\overline{M}}(Q))^N \text{ for } \sigma \left(\prod L_M, \prod E_{\overline{M}} \right),$$

$$J_2 = \int_Q a(\cdot, T_k(u), \nabla T_k(v_j) \mathcal{X}_j^s) (\nabla T_k(u) - \nabla T_k(v_j) \mathcal{X}_j^s) dx dt + \varepsilon(n),$$

since

$$a(\cdot, T_k(u_n), \nabla T_k(v_j) \mathcal{X}_j^s) \rightarrow a(\cdot, T_k(u), \nabla T_k(v_j) \mathcal{X}_j^s) \text{ strongly in } (E_{\overline{M}}(Q))^N,$$

$$a(\cdot, T_k(u), \nabla T_k(v_j) \mathcal{X}_j^s) \rightarrow a(\cdot, T_k(u), \nabla T_k(u) \mathcal{X}_j^s) \text{ strongly in } (E_{\overline{M}}(Q))^N,$$

and $\nabla T_k(v_j) \mathcal{X}_j^s \rightarrow \nabla T_k(u) \mathcal{X}_j^s$ strongly in $(L_{\overline{M}}(Q))^N$.

Then,

$$J_2 = \varepsilon(n, j).$$

Following the same way as in J_2 , one has

$$J_3 = \int_Q h_k \nabla T_k(u) dx dt + \varepsilon(n, j, \mu, s).$$

Concerning the terms J_4 :

$$J_4 = - \int_Q a(\cdot, T_{m+1}(u_n), \nabla T_{m+1}(u_n)) \nabla \omega_{\mu, j}^i \rho_m(u_n) dx dt$$

$$= - \int_{|u_n| \leq k} a(\cdot, T_{m+1}(u_n), \nabla T_{m+1}(u_n)) \nabla \omega_{\mu, j} \rho_m(u_n) dx dt$$

$$- \int_{k < |u_n| \leq m+1} a(\cdot, T_{m+1}(u_n), \nabla T_{m+1}(u_n)) \nabla \omega_{\mu, j} \rho_m(u_n) dx dt.$$

Letting $n \rightarrow \infty$, then

$$J_4 = - \int_{k < |u| \leq m+1} h_{m+1} \nabla \omega_{\mu, j} \rho_m(u) dx dt - \int_{|u| \leq k} h_k \nabla \omega_{\mu, j} \rho_m(u) dx dt + \varepsilon(n).$$

Taking now the limits $j \rightarrow \infty$ and after $\mu \rightarrow \infty$ in the last equality, we obtain

$$J_4 = - \int_Q h_k \nabla T_k(u) dx dt + \varepsilon(n, j, \mu).$$

Then,

$$(1) = \int_Q \left(a(\cdot, T_k(u_n), \nabla T_k(u_n)) - a(\cdot, T_k(u_n), \nabla T_k(v_j) \mathcal{X}_j^s) \right) (\nabla T_k(u_n) - \nabla T_k(v_j) \mathcal{X}_j^s) + \varepsilon(n, j, \mu, s).$$

About (2):

$$\left| \int_Q a(\cdot, u_n, \nabla u_n) \nabla u_n (T_k(u_n) - \omega_{\mu, j}) \rho'_m(u_n) dx dt \right| \leq C(k) \int_{m < |u_n| \leq m+1} a(\cdot, u_n, \nabla u_n) \nabla u_n dx dt.$$

Since (u_n) is bounded in $W_0^{1, \infty} L_D(Q)$ and using (iii), we have $(a(\cdot, u_n, \nabla u_n))$ is bounded in $L_H(Q)$, then

$$\left| \int_{m < |u_n| \leq m+1} a(\cdot, u_n, \nabla u_n) \nabla u_n dx dt \right| \leq \|a(\cdot, u_n, \nabla u_n)\|_{H, Q} \|\nabla u_n\|_{D, m < |u_n| \leq m+1} \leq \varepsilon(n, m),$$

so,

$$(2) \leq \varepsilon(n, m).$$

About (4):

Since $u \geq \psi$, then $T_k(u) \geq T_k(\psi)$ and there exist a smooth function $v_j \geq T_k(\psi)$ such that $v_j \rightarrow T_k(u)$ for the modular convergence in $W_0^{1,x} L_M(Q)$.

$$(4) = n \int_Q T_n((u_n - \psi)^-)(T_k(u_n) - T_k(v_j))_\mu \rho_m(u_n) dx dt \leq \varepsilon(n, j, \mu).$$

Taking into account now the estimation of (1), (2), (4) and (5), we obtain

$$\int_Q (a(., T_k(u_n), \nabla T_k(u_n)) - a(., T_k(u_n), \nabla T_k(v_j) \mathcal{X}_j^s)) (\nabla T_k(u_n) - \nabla T_k(v_j) \mathcal{X}_j^s) dx dt \leq \varepsilon(n, j, \mu, s, m). \quad (3.8)$$

On the other hand,

$$\begin{aligned} & \int_Q (a(., T_k(u_n), \nabla T_k(u_n)) - a(., T_k(u_n), \nabla T_k(u) \mathcal{X}^s)) (\nabla T_k(u_n) - \nabla T_k(u) \mathcal{X}^s) dx dt \\ & - \int_Q (a(., T_k(u_n), \nabla T_k(u_n)) - a(., T_k(u_n), \nabla T_k(v_j) \mathcal{X}_j^s)) (\nabla T_k(u_n) - \nabla T_k(v_j) \mathcal{X}_j^s) dx dt \\ & = \int_Q a(., T_k(u_n), \nabla T_k(u_n)) (\nabla T_k(v_j) \mathcal{X}_j^s - \nabla T_k(u) \mathcal{X}^s) dx dt \\ & - \int_Q a(., T_k(u_n), \nabla T_k(u) \mathcal{X}^s) (\nabla T_k(v_j) \mathcal{X}_j^s - \nabla T_k(u) \mathcal{X}^s) dx dt \\ & + \int_Q a(., T_k(u_n), \nabla T_k(v_j) \mathcal{X}_j^s) (\nabla T_k(u_n) - \nabla T_k(v_j) \mathcal{X}_j^s) dx dt, \end{aligned}$$

each term of the last right hand side is of the form $\varepsilon(n, j, s)$, which gives

$$\begin{aligned} & \int_Q (a(., T_k(u_n), \nabla T_k(u_n)) - a(., T_k(u_n), \nabla T_k(u) \mathcal{X}^s)) (\nabla T_k(u_n) - \nabla T_k(u) \mathcal{X}^s) dx dt \\ & = \int_Q (a(., T_k(u_n), \nabla T_k(u_n)) - a(., T_k(u_n), \nabla T_k(v_j) \mathcal{X}_j^s)) (\nabla T_k(u_n) - \nabla T_k(v_j) \mathcal{X}_j^s) dx dt \\ & + \varepsilon(n, j, s). \end{aligned}$$

Following the same technique used by Porretta [2], we have for all $r < s$:

$$\int_Q (a(., T_k(u_n), \nabla T_k(u_n)) - a(., T_k(u_n), \nabla T_k(u))) (\nabla T_k(u_n) - \nabla T_k(u)) dx dt \rightarrow 0.$$

Thus, as in the elliptic case (see [7]), there exists a subsequence also denoted by u_n such that

$$\nabla u_n \rightarrow \nabla u \text{ a.e. in } Q.$$

We deduce then that,

$$a(., T_k(u_n), \nabla T_k(u_n)) \rightharpoonup a(., T_k(u), \nabla T_k(u)) \text{ in } (L_{\overline{M}}(Q))^N \text{ for } \sigma(\prod L_M, \prod E_{\overline{M}}).$$

Lemma 3.7 For all $k > 0$,

$$\nabla T_k(u_n) \rightarrow \nabla T_k(u) \text{ for the modular convergence in } (L_M(Q))^N.$$

Proof:

We have proved that

$$\int_Q \left(a(\cdot, T_k(u_n), \nabla T_k(u_n)) - a(\cdot, T_k(u_n), \nabla T_k(v_j) \mathcal{X}_j^s) \right) (\nabla T_k(u_n) - \nabla T_k(v_j) \mathcal{X}_j^s) dx dt$$

$$\leq \epsilon(n, j, \mu, s, m) \text{ (see (3.8)).}$$

We can also deduce that

$$\int_Q (a(\cdot, T_k(u_n), \nabla T_k(u_n)) - a(\cdot, T_k(u_n), \nabla T_k(u) \mathcal{X}^s)) (\nabla T_k(u_n) - \nabla T_k(u) \mathcal{X}^s) dx dt$$

$$= \int_Q \left(a(\cdot, T_k(u_n), \nabla T_k(u_n)) - a(\cdot, T_k(u_n), \nabla T_k(v_j) \mathcal{X}_j^s) \right) (\nabla T_k(u_n) - \nabla T_k(v_j) \mathcal{X}_j^s) dx dt$$

$$+ \epsilon(n, j, s).$$

Then

$$\int_Q a(\cdot, T_k(u_n), \nabla T_k(u_n)) \nabla T_k(u_n) dx dt$$

$$\leq \int_Q a(\cdot, T_k(u_n), \nabla T_k(u_n)) \nabla T_k(u) \mathcal{X}^s dx dt$$

$$+ \int_Q a(\cdot, T_k(u_n), \nabla T_k(u) \mathcal{X}^s) (\nabla T_k(u_n) - \nabla T_k(u) \mathcal{X}^s) dx dt + \epsilon(n, j, \mu, s, m).$$

$$\overline{\lim}_n \int_Q a(\cdot, T_k(u_n), \nabla T_k(u_n)) \nabla T_k(u_n) dx dt \leq \int_Q a(\cdot, T_k(u), \nabla T_k(u)) \nabla T_k(u) \mathcal{X}^s dx dt + \lim_n \epsilon(n, j, \mu, s, m)$$

then,

$$\overline{\lim}_n \int_Q a(\cdot, T_k(u_n), \nabla T_k(u_n)) \nabla T_k(u_n) dx dt \leq \int_Q a(\cdot, T_k(u), \nabla T_k(u)) \nabla T_k(u) dx dt \leq \lim_n \int_Q a(\cdot, T_k(u_n), \nabla T_k(u_n)) \nabla T_k(u_n) dx dt.$$

Letting $n \rightarrow \infty$, we deduce

$$a(\cdot, T_k(u_n), \nabla T_k(u_n)) \nabla T_k(u_n) \rightarrow a(\cdot, T_k(u), \nabla T_k(u)) \nabla T_k(u) \mathcal{X}^s \text{ in } L^1(Q).$$

Using the same argument as above, we obtain

$$a(\cdot, T_k(u_n), \nabla T_k(u_n)) \nabla T_k(u_n) \rightarrow a(\cdot, T_k(u), \nabla T_k(u)) \nabla T_k(u) \text{ in } L^1(Q),$$

and Vitali's theorem and (1.1) gives

$$\nabla T_k(u_n) \rightarrow \nabla T_k(u) \text{ for the modular convergence in } (L_M(Q))^N.$$

3.3.1 The convergence of the problems (P_n) and the completion of the proof of Theorem 3.1

The passage to the limit is an easy task by using the last steps, then

$$a(\cdot, u_n, \nabla u_n) \rightarrow a(\cdot, u, \nabla u) \text{ weakly in } L_H(Q) \text{ and a.e. in } Q,$$

then,

$$-\int_Q u \frac{\partial \varphi}{\partial t} + \int_Q a(\cdot, u, \nabla u) \nabla \varphi dx dt - \int_\Omega \varphi du_0 = \int_Q \varphi d\mu,$$

for all $\phi \in D(\mathbb{R}^{N+1})$ which are zero in a neighborhood of $(0, T) \times \partial\Omega$ and $\{T\} \times \Omega$.

4 Conclusion

In this article, we have proved the existence of solutions of some class of unilateral problems in the Orlicz-Sobolev spaces when the right-hand side is a Radon measure.

Competing interests

The authors declare that they have no competing interests.

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