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Multiple monotone positive solutions for higher order differential equations with integral boundary conditions

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Abstract

This paper investigates the higher order differential equations with nonlocal boundary conditions

$$\begin{cases} u^{(n)}(t) + f(t, u(t), u'(t), \dots, u^{(n-2)}(t)) = 0, & t \in (0, 1), \\ u(0) = u'(0) = \dots = u^{(n-3)}(0) = 0, \\ u^{(n-2)}(0) = \int_0^1 u^{(n-2)}(s) \, dA(s), & u^{(n-2)}(1) = \int_0^1 u^{(n-2)}(s) \, dB(s). \end{cases}$$

The existence results of multiple monotone positive solutions are obtained by means of fixed point index theory for operators in a cone. **MSC:** 34B10; 34B18

Keywords: monotone positive solutions; multiplicity; higher order differential equations; nonlocal boundary conditions

1 Introduction

In this paper, we are concerned with the existence of multiple monotone positive solutions for the higher order differential equation

$$u^{(n)}(t) + f(t, u(t), u'(t), \dots, u^{(n-2)}(t)) = 0, \quad t \in (0, 1),$$
(1.1)

subject to the following integral boundary conditions:

$$\begin{cases} u(0) = u'(0) = \dots = u^{(n-3)}(0) = 0, \\ u^{(n-2)}(0) = \int_0^1 u^{(n-2)}(s) \, dA(s), \qquad u^{(n-2)}(1) = \int_0^1 u^{(n-2)}(s) \, dB(s), \end{cases}$$
(1.2)

where $n \ge 3$, $f : [0,1] \times (\mathbf{R}^+)^{n-1} \to \mathbf{R}^+$ is continuous in which $\mathbf{R}^+ = [0, +\infty)$, A and B are right continuous on [0,1), left continuous at t = 1, and nondecreasing on [0,1], with A(0) = B(0) = 0; $\int_0^1 v(s) \, dA(s)$ and $\int_0^1 v(s) \, dB(s)$ denote the Riemann-Stieltjes integrals of v with respect to A and B, respectively.

Boundary value problems (BVPs for short) for nonlinear differential equations arise in many areas of applied mathematics and physics. Many authors have discussed the existence of positive solutions for second order or higher order differential equations with



©2014 Hao and Liu; licensee Springer. This is an Open Access article distributed under the terms of the Creative Commons Attribution License (http://creativecommons.org/licenses/by/2.0), which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited. boundary conditions defined at a finite number of points, for instance, [1-12]. In [2], Graef and Yang considered the following *n*th-order multi-point BVP:

$$\begin{cases} u^{(n)}(t) + \lambda g(t)f(u(t)) = 0, & t \in (0,1), \\ u(0) = u'(0) = \cdots = u^{(n-2)}(0) = \sum_{i=1}^{m} a_i u^{(n-2)}(\xi_i) - u^{(n-2)}(1) = 0, \end{cases}$$

where $n \ge 3$, $\lambda > 0$ is a parameter, g and f are continuous functions, $\frac{1}{2} \le \xi_1 < \xi_2 < \cdots < \xi_m < 1$, $a_i > 0$ for $1 \le i \le m$ and $\sum_{i=1}^m a_i = 1$. The authors obtained the existence and nonexistence results of positive solutions by using Krasnosel'skii's fixed point theorem in cones. In [5], we studied the following second order m-point nonhomogeneous BVP:

$$\begin{cases} u''(t) + a(t)f(t, u) = 0, \quad t \in (0, 1), \\ u(0) = 0, u(1) - \sum_{i=1}^{m-2} k_i u(\xi_i) = b, \end{cases}$$

where b > 0, $k_i > 0$ (i = 1, 2, ..., m - 2), $0 < \xi_1 < \xi_2 < \cdots < \xi_{m-2} < 1$, $\sum_{i=1}^{m-2} k_i \xi_i < 1$. The authors obtained the existence, nonexistence and multiplicity of positive solutions by using the Krasnosel'skii-Guo fixed point theorem, the upper-lower solutions method and topological degree theory.

Boundary value problems with integral boundary conditions for ordinary differential equations represent a very interesting and important class of problems and arise in the study of various physical, biological and chemical processes [13–15], such as heat conduction, chemical engineering, underground water flow, thermo-elasticity, and plasma physics. They include two, three, multi-point and nonlocal BVPs as special cases. The existence and multiplicity of positive solutions for such problems have received a great deal of attention, see [16–32] and the references therein. In [17], Feng, Ji and Ge considered the existence and multiplicity of positive solutions for a class of nonlinear boundary value problems of second order differential equations with integral boundary conditions in ordered Banach spaces

$$\begin{cases} x''(t) + f(t, x(t)) = \theta, & t \in (0, 1), \\ x(0) = \int_0^1 g(t) x(t) \, dt, & x(1) = \theta, & \text{or} \\ x(0) = \theta, & x(1) = \int_0^1 g(t) x(t) \, dt. \end{cases}$$

The arguments are based upon a specially constructed cone and fixed point theory in a cone for strict set contraction operators.

Motivated by the works mentioned above, in this paper, we consider the existence of multiple monotone positive solutions for BVP (1.1) and (1.2). In comparison with previous works, our paper has several new features. Firstly, we consider higher order boundary value problems, and we allow the nonlinearity f to contain derivatives of the unknown function u(t) up to n - 2 order. Secondly, we discuss the boundary value problem with integral boundary conditions, *i.e.*, BVP (1.1) and (1.2), which includes two-point, three-point, multi-point and nonlocal boundary value problems as special cases. Thirdly, we consider the existence of multiple monotone positive solutions. To our knowledge, few papers have considered the monotone positive solutions for a higher order differential equation with integral boundary conditions. We shall emphasize here that with these new

features our work improves and generalizes the results of [2] and some other known results to some degree. In this work we shall also utilize the following fixed point theorem in cones.

Lemma 1.1 ([33, 34]) Let K be a cone in a Banach space E. Let D be an open bounded subset of E with $D_K = D \cap K \neq \emptyset$ and $\overline{D}_K \neq K$. Assume that $A : \overline{D}_K \to K$ is a compact operator such that $u \neq Au$ for $u \in \partial D_K$. Then the following results hold.

- (1) If $||Au|| \le ||u||, u \in \partial D_K$, then $i_K(A, D_K) = 1$.
- (2) If there exists $e \in K \setminus \{0\}$ such that $u \neq Au + \lambda e$ for all $u \in \partial D_K$ and $\lambda > 0$, then $i_K(A, D_K) = 0$.
- (3) Let U be open in E such that $\overline{U} \subset D_K$. If $i_K(A, D_K) = 1$ and $i_K(A, U_K) = 0$, then A has a fixed point in $D_K \setminus \overline{U}_K$. The same result holds if $i_K(A, D_K) = 0$ and $i_K(A, U_K) = 1$.

2 Preliminary lemmas

Let $E = \{u \in C^{n-2}[0,1] : u^{(i)}(0) = 0, 0 \le i \le n-3\}$, then *E* is a Banach space with the norm $||u|| = \sup_{t \in [0,1]} |u^{(n-2)}(t)|$ for each $u \in E$.

We make the following assumptions:

 $\begin{array}{ll} (H_1) \ f: [0,1]\times ({\bf R}^+)^{n-1} \to {\bf R}^+ \mbox{ is continuous.} \\ (H_2) \ k_1 > 0, \, k_4 > 0, \, k > 0, \mbox{ where } k = k_1k_4 - k_2k_3, \end{array}$

$$k_1 = 1 - \int_0^1 (1 - s) \, dA(s), \qquad k_2 = \int_0^1 s \, dA(s),$$

$$k_3 = \int_0^1 (1 - s) \, dB(s), \qquad k_4 = 1 - \int_0^1 s \, dB(s).$$

Lemma 2.1 Assume that (H_2) holds. Then, for any $y \in C[0,1]$, the BVP

$$\begin{cases} -u''(t) = y(t), & t \in (0,1), \\ u(0) = \int_0^1 u(t) \, dA(t), & u(1) = \int_0^1 u(t) \, dB(t) \end{cases}$$
(2.1)

has a unique solution u that can be expressed in the form

$$u(t) = \int_0^1 H(t,s)y(s) \, ds, \quad t \in [0,1], \tag{2.2}$$

where

$$H(t,s) = G(t,s) + \frac{tk_3 + (1-t)k_4}{k} \mathcal{G}_A(s) + \frac{tk_1 + (1-t)k_2}{k} \mathcal{G}_B(s),$$

$$\mathcal{G}_A(s) = \int_0^1 G(\tau,s) \, dA(\tau), \qquad \mathcal{G}_B(s) = \int_0^1 G(\tau,s) \, dB(\tau),$$

$$G(t,s) = \begin{cases} t(1-s), & 0 \le t \le s \le 1, \\ s(1-t), & 0 \le s \le t \le 1. \end{cases}$$
(2.3)

Proof Firstly, we prove that if u is a solution of BVP (2.1), then it will take the form of (2.2). Now, integrating differential equation (2.1) from 0 to t twice, we have

$$u(t) = u(0) + u'(0)t - \int_0^t (t - s)y(s) \, ds.$$
(2.4)

Letting t = 1 in (2.4), we get

$$u'(0) = u(1) - u(0) + \int_0^1 (1 - s)y(s) \, ds.$$
(2.5)

Substituting the boundary conditions of (2.1) and (2.5) into (2.4) yields

$$u(t) = u(0) + \left[u(1) - u(0) + \int_0^1 (1 - s)y(s) \, ds\right] t - \int_0^t (t - s)y(s) \, ds$$
$$= (1 - t) \int_0^1 u(t) \, dA(t) + t \int_0^1 u(t) \, dB(t) + \int_0^1 G(t, s)y(s) \, ds,$$
(2.6)

and, consequently,

$$\int_{0}^{1} u(t) \, dA(t) = \int_{0}^{1} (1-t) \, dA(t) \int_{0}^{1} u(t) \, dA(t) + \int_{0}^{1} t \, dA(t) \int_{0}^{1} u(t) \, dB(t)$$
$$+ \int_{0}^{1} \int_{0}^{1} G(t,s)y(s) \, ds \, dA(t),$$
$$\int_{0}^{1} u(t) \, dB(t) = \int_{0}^{1} (1-t) \, dB(t) \int_{0}^{1} u(t) \, dA(t) + \int_{0}^{1} t \, dB(t) \int_{0}^{1} u(t) \, dB(t)$$
$$+ \int_{0}^{1} \int_{0}^{1} G(t,s)y(s) \, ds \, dB(t).$$

Solving the above two equations for $\int_0^1 u(t) \, dA(t)$ and $\int_0^1 u(t) \, dB(t)$, we have

$$\begin{pmatrix} k_1 & -k_2 \\ -k_3 & k_4 \end{pmatrix} \begin{pmatrix} \int_0^1 u(t) \, dA(t) \\ \int_0^1 u(t) \, dB(t) \end{pmatrix} = \begin{pmatrix} \int_0^1 \int_0^1 G(t,s)y(s) \, ds \, dA(t) \\ \int_0^1 \int_0^1 G(t,s)y(s) \, ds \, dB(t) \end{pmatrix},$$

and so

$$\begin{pmatrix} \int_0^1 u(t) \, dA(t) \\ \int_0^1 u(t) \, dB(t) \end{pmatrix} = k^{-1} \begin{pmatrix} k_4 & k_2 \\ k_3 & k_1 \end{pmatrix} \begin{pmatrix} \int_0^1 \int_0^1 G(t,s)y(s) \, ds \, dA(t) \\ \int_0^1 \int_0^1 G(t,s)y(s) \, ds \, dB(t) \end{pmatrix}.$$
(2.7)

Hence, (2.2) follows from (2.6) and (2.7).

Next we prove that the u given by (2.2) satisfies the differential equation and boundary conditions of (2.1). From (2.2), we have

$$u(t) = \int_{0}^{t} s(1-t)y(s) \, ds + \int_{t}^{1} t(1-s)y(s) \, ds$$

+ $\frac{tk_3 + (1-t)k_4}{k} \int_{0}^{1} \left[\int_{0}^{1} G(\tau, s) \, dA(\tau) \right] y(s) \, ds$
+ $\frac{tk_1 + (1-t)k_2}{k} \int_{0}^{1} \left[\int_{0}^{1} G(\tau, s) \, dB(\tau) \right] y(s) \, ds.$ (2.8)

Direct differentiation of (2.8) gives u''(t) = -y(t). Also, from (2.2) we have

$$\begin{split} \int_0^1 u(t) \, dA(t) &= \int_0^1 \int_0^1 G(t,s) y(s) \, ds \, dA(t) \\ &+ k^{-1} \big[k_3 k_2 + k_4 (1-k_1) \big] \int_0^1 \bigg[\int_0^1 G(\tau,s) \, dA(\tau) \bigg] y(s) \, ds \\ &+ k^{-1} \big[k_1 k_2 + k_2 (1-k_1) \big] \int_0^1 \bigg[\int_0^1 G(\tau,s) \, dB(\tau) \bigg] y(s) \, ds \\ &= k^{-1} k_4 \int_0^1 \int_0^1 G(\tau,s) y(s) \, dA(\tau) \, ds \\ &+ k^{-1} k_2 \int_0^1 \int_0^1 G(\tau,s) y(s) \, dB(\tau) \, ds, \end{split}$$

and, similarly,

$$\int_0^1 u(t) \, dB(t) = k^{-1} k_3 \int_0^1 \int_0^1 G(\tau, s) y(s) \, dA(\tau) \, ds + k^{-1} k_1 \int_0^1 \int_0^1 G(\tau, s) y(s) \, dB(\tau) \, ds.$$

Therefore, by solving the above two equations with the double integrals as unknowns, we have

$$\int_{0}^{1} \int_{0}^{1} G(\tau, s) y(s) \, dA(\tau) \, ds = k_1 \int_{0}^{1} u(t) \, dA(t) - k_2 \int_{0}^{1} u(t) \, dB(t) \tag{2.9}$$

and

$$\int_0^1 \int_0^1 G(\tau, s) y(s) \, dB(\tau) \, ds = -k_3 \int_0^1 u(t) \, dA(t) + k_4 \int_0^1 u(t) \, dB(t). \tag{2.10}$$

Hence (2.6) follows from (2.2), (2.9) and (2.10), and thus $u(0) = \int_0^1 u(t) dA(t)$, $u(1) = \int_0^1 u(t) dB(t)$. This completes the proof.

Defining

$$G_3(t,s) = \int_0^t H(v,s) \, dv, \qquad G_i(t,s) = \int_0^t G_{i-1}(v,s) \, dv, \quad i \ge 4,$$

then $G_n(t,s)$ is the Green function of BVP (1.1) and (1.2). Moreover, solving BVP (1.1) and (1.2) is equivalent to finding a solution of the following integral equation:

$$u(t) = \int_0^1 G_n(t,s) f(s,u(s),u'(s),\ldots,u^{(n-2)}(s)) ds, \quad t \in [0,1].$$

Remark 2.1 If (H_2) holds, then for any $t, s \in [0, 1]$, it is easy to testify that

$$G(t,s) \ge 0,$$
 $H(t,s) \ge 0,$ $G_n(t,s) \ge 0,$ $n \ge 3.$ (2.11)

Lemma 2.2 Let $\delta \in (0, \frac{1}{2})$, then for any $t \in [\delta, 1 - \delta]$, $\eta, s \in [0, 1]$, we have

$$H(t,s) \ge \delta H(\eta,s).$$

Proof It is easy to show that $G(t,s) \ge \delta G(\eta,s)$, $\forall t \in [\delta, 1-\delta]$, $\eta, s \in [0,1]$. For $t \in [\delta, 1-\delta]$, $\eta, s \in [0,1]$, we have

$$\begin{split} H(t,s) &= G(t,s) + \frac{tk_3 + (1-t)k_4}{k} \int_0^1 G(\tau,s) \, dA(\tau) + \frac{tk_1 + (1-t)k_2}{k} \int_0^1 G(\tau,s) \, dB(\tau) \\ &\geq \delta G(\eta,s) + \frac{\delta(k_3 + k_4)}{k} \int_0^1 G(\tau,s) \, dA(\tau) + \frac{\delta(k_1 + k_2)}{k} \int_0^1 G(\tau,s) \, dB(\tau) \\ &\geq \delta \left[G(\eta,s) + \frac{\eta k_3 + (1-\eta)k_4}{k} \int_0^1 G(\tau,s) \, dA(\tau) + \frac{\eta k_1 + (1-\eta)k_2}{k} \int_0^1 G(\tau,s) \, dB(\tau) \right] \\ &= \delta H(\eta,s). \end{split}$$

For any $s \in [0,1]$, we define $\mathcal{H}(s) = \max_{t \in [0,1]} H(t,s)$. From Lemma 2.2, we know that

$$\delta \mathcal{H}(s) \le H(t,s) \le \mathcal{H}(s), \quad t \in [\delta, 1-\delta], s \in [0,1].$$

$$(2.12)$$

Lemma 2.3 Assume that (H_2) holds. If $u \in C^n[0,1]$ satisfies the boundary conditions (1.2) and

$$u^{(n)}(t) \le 0, \quad t \in [0,1],$$

then

$$u(t) \ge 0 \quad and \quad u'(t) \ge 0 \quad for \ t \in [0,1].$$
 (2.13)

Proof Let $m(t) = u^{(n-2)}(t), t \in [0,1]$, then we have

$$\begin{cases} m''(t) \le 0, \quad t \in [0,1], \\ m(0) = \int_0^1 m(t) \, dA(t), \qquad m(1) = \int_0^1 m(t) \, dB(t). \end{cases}$$

For $t \in [0,1]$, $m''(t) \le 0$ implies that

$$m(t) = m[(1-t) \cdot 0 + t \cdot 1] \ge (1-t)m(0) + tm(1).$$

Thus

$$m(0) = \int_0^1 m(t) \, dA(t) \ge m(0) \int_0^1 (1-t) \, dA(t) + m(1) \int_0^1 t \, dA(t)$$
$$= (1-k_1)m(0) + k_2m(1),$$

i.e.,

$$m(0) \ge \frac{k_2}{k_1}m(1).$$

On the other hand,

$$m(1) = \int_0^1 m(t) \, dB(t) \ge m(0) \int_0^1 (1-t) \, dB(t) + m(1) \int_0^1 t \, dB(t)$$
$$= k_3 m(0) + (1-k_4) m(1),$$

and so

$$m(1) \ge \frac{k_3}{k_4} m(0) \ge \frac{k_2 k_3}{k_1 k_4} m(1),$$

i.e., $km(1) \ge 0$, therefore $m(1) \ge 0$, and so $m(0) \ge 0$.

Now, $m(0) \ge 0$, $m(1) \ge 0$ and m(t) is concave downward, so we have

$$m(t) = u^{(n-2)}(t) \ge 0, \quad t \in [0,1].$$
 (2.14)

From (2.14) and $u(0) = u'(0) = \cdots = u^{(n-3)}(0) = 0$, we obtain (2.13). This completes the proof of Lemma 2.3.

Remark 2.2 From Lemma 2.3, if *u* is a positive solution of BVP (1.1) and (1.2), then *u* is nondecreasing on [0,1], *i.e.*, *u* is a monotone positive solution of BVP (1.1) and (1.2). Let

$$K = \left\{ u \in E : u^{(n-2)}(t) \ge 0, t \in [0,1], u^{(n-2)}(t) \ge \delta \|u\|, t \in [\delta, 1-\delta] \right\}.$$

Obviously, *K* is a cone in *E*. For any $\rho > 0$, let $K_{\rho} = \{u \in K : ||u|| < \rho\}$, $\partial K_{\rho} = \{u \in K : ||u|| = \rho\}$ and $\overline{K}_{\rho} = \{u \in K : ||u|| \le \rho\}$. Define an operator $T : K \to E$ as follows:

$$(Tu)(t) = \int_0^1 G_n(t,s) f\left(s, u(s), u'(s), \dots, u^{(n-2)}(s)\right) ds, \quad t \in [0,1].$$
(2.15)

Then *u* is a solution of BVP (1.1) and (1.2) if and only if *u* solves the operator equation u = Tu.

Lemma 2.4 Suppose that (H_1) and (H_2) hold, then $T: K \to K$ is completely continuous.

Proof For all $u \in K$, $t \in [0, 1]$, by (*H*₁), (2.11), (2.12) and (2.15), we have

$$(Tu)^{(n-2)}(t) = \int_0^1 H(t,s) f(s,u(s),u'(s),\dots,u^{(n-2)}(s)) ds \ge 0,$$

$$(Tu)^{(n-2)}(t) = \int_0^1 H(t,s) f(s,u(s),u'(s),\dots,u^{(n-2)}(s)) ds$$

$$\le \int_0^1 \mathcal{H}(s) f(s,u(s),u'(s),\dots,u^{(n-2)}(s)) ds,$$

and

$$||Tu|| \leq \int_0^1 \mathcal{H}(s) f\left(s, u(s), u'(s), \ldots, u^{(n-2)}(s)\right) ds.$$

Thus, further from the first inequality of (2.12), we have

$$(Tu)^{(n-2)}(t) = \int_0^1 H(t,s) f(s, u(s), u'(s), \dots, u^{(n-2)}(s)) ds$$

$$\geq \delta \int_0^1 \mathcal{H}(s) f(s, u(s), u'(s), \dots, u^{(n-2)}(s)) ds$$

$$\geq \delta ||Tu||, \quad t \in [\delta, 1-\delta].$$

Hence, $Tu \in K$ and $T(K) \subset K$.

Next by standard methods and the Ascoli-Arzela theorem, one can prove that $T: K \to K$ is completely continuous. So this is omitted.

Let

$$\Omega_{\rho} = \left\{ u \in K : \min_{\delta \le t \le 1-\delta} u^{(n-2)}(t) < \delta\rho \right\}$$

= $\left\{ u \in E : u^{(n-2)}(t) \ge 0, t \in [0,1], \delta ||u|| \le \min_{\delta \le t \le 1-\delta} u^{(n-2)}(t) < \delta\rho \right\}.$

Proceeding as for the proof of Lemma 2.5 in [33], we have the following.

Lemma 2.5 Ω_{ρ} has the following properties:

- (a) Ω_ρ is open relative to K;
 (b) K_{δρ} ⊂ Ω_ρ ⊂ K_ρ;
 (c) u ∈ ∂Ω_ρ if and only if min_{δ≤t≤1-δ} u⁽ⁿ⁻²⁾(t) = δρ;
- (d) if $u \in \partial \Omega_{\rho}$, then $\delta \rho \leq u^{(n-2)}(t) \leq \rho$ for $\delta \leq t \leq 1 \delta$.

Now for convenience we introduce the following notations:

$$\begin{split} f_{\delta\rho,\rho} &= \min\left\{\min_{\delta \le t \le 1-\delta} \frac{f(t, u_0, \dots, u_{n-2})}{\rho} : u_0, u_1, \dots, u_{n-3} \in [0, \rho], u_{n-2} \in [\delta\rho, \rho]\right\},\\ f^{0,\rho} &= \max\left\{\max_{0 \le t \le 1} \frac{f(t, u_0, u_1, \dots, u_{n-2})}{\rho} : (u_0, u_1, \dots, u_{n-2}) \in [0, \rho]^{n-1}\right\},\\ f^0 &= \lim_{u_0, u_1, \dots, u_{n-2} \to 0} \max_{0 \le t \le 1} \frac{f(t, u_0, u_1, \dots, u_{n-2})}{u_{n-2}},\\ f^\infty &= \lim_{u_0, u_1, \dots, u_{n-2} \to 0} \max_{0 \le t \le 1} \frac{f(t, u_0, u_1, \dots, u_{n-2})}{u_0 + u_1 + \dots + u_{n-2}},\\ f_0 &= \lim_{u_0, u_1, \dots, u_{n-2} \to 0} \min_{0 \le t \le 1-\delta} \frac{f(t, u_0, u_1, \dots, u_{n-2})}{u_{n-2}},\\ f_\infty &= \lim_{u_0+u_1+\dots+u_{n-2} \to +\infty} \min_{\delta \le t \le 1-\delta} \frac{f(t, u_0, u_1, \dots, u_{n-2})}{u_{n-2}},\\ m &= \left(\max_{0 \le t \le 1} \int_0^1 H(t, s) \, ds\right)^{-1}, \qquad M = \left(\min_{\delta \le t \le 1-\delta} \int_{\delta}^{1-\delta} H(t, s) \, ds\right)^{-1}. \end{split}$$

To prove our main results, we need the following lemmas.

Lemma 2.6 Assume that (H_1) , (H_2) hold and f satisfies

$$f^{0,\rho} \le m \quad and \quad u \ne Tu \quad for \ u \in \partial K_{\rho},$$
(2.16)

then $i_K(T, K_\rho) = 1$.

Proof For $u \in \partial K_{\rho}$, we have $0 \leq u^{(n-2)}(t) \leq \rho$ and $0 \leq u^{(i)}(t) = \int_{0}^{t} u^{(i+1)}(s) ds \leq \max_{0 \leq t \leq 1} u^{(i+1)}(t) \leq ||u|| = \rho, t \in [0,1], i = 0, 1, ..., n-3$. Then by (2.16) we have, for $t \in [0,1]$,

$$(Tu)^{(n-2)}(t) = \int_0^1 H(t,s) f(s,u(s),u'(s),\ldots,u^{(n-2)}(s)) ds$$
$$\leq m\rho \int_0^1 H(t,s) ds \leq \rho = ||u||.$$

This implies that $||Tu|| \le ||u||$ for $u \in \partial K_{\rho}$. By the point (1) in Lemma 1.1, we have $i_{K}(T, K_{\rho}) = 1$.

Lemma 2.7 Assume that (H_1) , (H_2) hold and f satisfies

$$f_{\delta\rho,\rho} \ge \delta M$$
 and $u \ne Tu$ for $u \in \partial \Omega_{\rho}$, (2.17)

then $i_K(T, K_\rho) = 0$.

Proof Let $e(t) = \frac{t^{n-2}}{(n-2)!}$, $t \in [0,1]$, then $e \in K$ with ||e|| = 1. Next we prove that

 $u \neq Tu + \lambda e$, $u \in \partial \Omega_{\rho}$, $\lambda > 0$.

In fact, if not, then there exist $u_0 \in \partial \Omega_\rho$ and $\lambda_0 > 0$ such that $u_0 = Tu_0 + \lambda_0 e$. By (2.17) and the point (d) in Lemma 2.5, we have, for $t \in [\delta, 1 - \delta]$,

$$\begin{split} u_0^{(n-2)}(t) &= (Tu_0)^{(n-2)}(t) + \lambda_0 e^{(n-2)}(t) \\ &= \int_0^1 H(t,s) f\left(s, u_0(s), u_0'(s), \dots, u_0^{(n-2)}(s)\right) ds + \lambda_0 \\ &\geq \int_{\delta}^{1-\delta} H(t,s) f\left(s, u_0(s), u_0'(s), \dots, u_0^{(n-2)}(s)\right) ds + \lambda_0 \\ &\geq \delta M \rho \int_{\delta}^{1-\delta} H(t,s) ds + \lambda_0 \geq \delta \rho + \lambda_0 > \delta \rho. \end{split}$$

This implies that $\min_{t \in [\delta, 1-\delta]} u_0^{(n-2)}(t) > \delta\rho$, and so by the point (c) in Lemma 2.5, this is a contradiction. It follows from the point (2) of Lemma 1.1 that $i_K(T, K_\rho) = 0$.

3 Main results

In the following, we shall give the main results on the existence of multiple positive solutions of BVP (1.1) and (1.2).

Theorem 3.1 Suppose that (H_1) and (H_2) are satisfied. In addition, assume that one of the following conditions holds.

(*H*₃) There exist $\rho_1, \rho_2, \rho_3 \in (0, +\infty)$ with $\rho_1 < \delta \rho_2$ and $\rho_2 < \rho_3$ such that

$$f^{0,\rho_1} \leq m$$
, $f_{\delta\rho_2,\rho_2} \geq \delta M$, $u \neq Tu$ for $u \in \partial \Omega_{\rho_2}$ and $f^{0,\rho_3} \leq m$.

(*H*₄) *There exist* $\rho_1, \rho_2, \rho_3 \in (0, +\infty)$ *with* $\rho_1 < \rho_2 < \delta \rho_3$ *such that*

$$f_{\delta\rho_1,\rho_1} \ge \delta M$$
, $f^{0,\rho_2} \le m$, $u \ne Tu$ for $u \in \partial K_{\rho_2}$ and $f_{\delta\rho_3,\rho_3} \ge \delta M$.

Then BVP (1.1) and (1.2) has two nondecreasing positive solutions u_1 , u_2 in K. Moreover, if in $(H_3) f^{0,\rho_1} \le m$ is replaced by $f^{0,\rho_1} < m$, then BVP (1.1) and (1.2) has a third nondecreasing positive solution $u_3 \in K_{\rho_1}$.

Proof Assume that (H_3) holds. We show that either T has a fixed point $u_1 \in \partial K_{\rho_1}$ or in $\Omega_{\rho_2} \setminus \overline{K}_{\rho_1}$. If $u \neq Tu$ for $u \in \partial K_{\rho_1} \cup \partial K_{\rho_3}$, by Lemmas 2.6 and 2.7, we have $i_K(T, K_{\rho_1}) = 1$, $i_K(T, \Omega_{\rho_2}) = 0$, and $i_K(T, K_{\rho_3}) = 1$. By Lemma 2.5(b), we have $\overline{K}_{\rho_1} \subset K_{\delta\rho_2} \subset \Omega_{\rho_2}$ since $\rho_1 < \delta\rho_2$. It follows from Lemma 1.1(3) that T has a fixed point $u_1 \in \Omega_{\rho_2} \setminus \overline{K}_{\rho_1}$. Similarly, T has a fixed point $u_2 \in K_{\rho_3} \setminus \overline{\Omega}_{\rho_2}$. The proof is similar when (H_4) holds.

Corollary 3.1 If there exists $\rho > 0$ such that one of the following conditions holds:

 $\begin{array}{ll} (H_5) & 0 \leq f^0 < m, f_{\delta\rho,\rho} \geq \delta M, \, u \neq Tu \ for \ u \in \partial \Omega_\rho, \, 0 \leq f^\infty < \frac{m}{n-1}, \\ (H_6) & M < f_0 \leq \infty, f^{0,\rho} \leq m, \, u \neq Tu \ for \ u \in \partial K_\rho, \, M < f_\infty \leq \infty, \end{array}$

then BVP(1.1) and (1.2) has at least two nondecreasing positive solutions in K.

Proof We show that (H_5) implies (H_3). It is easy to verify that $0 \le f^0 < m$ implies that there exists $\rho_1 \in (0, \delta\rho)$ such that $f^{0,\rho_1} < m$. Let $k \in (f^{\infty}, \frac{m}{n-1})$, by $f^{\infty} < \frac{m}{n-1}$, there exists $r > \rho$ such that $f(t, u_0, u_1, \dots, u_{n-2}) \le k(u_0 + u_1 + \dots + u_{n-2})$ for $t \in [0, 1]$, $u_0 + u_1 + \dots + u_{n-2} \in [r, +\infty)$. Let

$$M' = \max\left\{\max_{t \in [0,1]} f(t, u_0, u_1, \dots, u_{n-2}) : u_0 + u_1 + \dots + u_{n-2} \in [0,r]\right\},\$$

$$\rho_3 > \max\left\{\frac{M'}{m - (n-1)k}, r\right\},\$$

then for $(u_0, u_1, \dots, u_{n-2}) \in [0, \rho_3]^{n-1}$, we have

$$\max_{t \in [0,1]} f(t, u_0, u_1, \dots, u_{n-2}) \le M' + k(u_0 + u_1 + \dots + u_{n-2}) \le M' + k(n-1)\rho_3 < m\rho_3.$$

This implies that $f^{0,\rho_3} \leq m$ and (H_3) holds. Similarly, (H_6) implies (H_4) . This completes the proof.

Remark 3.1 We establish the multiplicity of monotone positive solutions for a higher order differential equation with integral boundary conditions, and we allow the nonlinearity f to contain derivatives of the unknown function u(t) up to n - 2 order, so our work improves and generalizes the results of [2] to some degree.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

XH wrote the first manuscript and LL corrected and improved the final version. Both authors read and approved the final manuscript.

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