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Finite-time blowup for the 3-D viscous primitive equations of oceanic and atmospheric dynamics



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Abstract

In this paper, we prove that for certain class of initial data, the corresponding solutions to the 3-D viscous primitive equations blow up in finite time. Specifically, we find a special solution to simplify the 3-D systems, assuming that the pressure function p(x, y, t) is a concave function. We also consider the equations on the line x = 0, y = 0.

Keywords: Blow-up; Primitive equations; Viscous; Special solution

1 Introduction

To the best of our knowledge, many researchers devote their studies to some nonlinear partial differential equations using mathematical physics methods [1-10]. Many works have investigated the primitive equations of ocean and atmospheric dynamics since the 1990s. In [7-13], the authors have shown the global well-posedness of strong solutions to primitive systems. In [14], it was shown that for certain class of smooth initial data, the solutions of the 2-D inviscid primitive equations are blown up in finite time by looking for a self-similar solution. In [15], the blow-up for the 2-D Prandtl equation in the maximum norm of u_x or u_{xy} was introduced.

It is worth mentioning that it has been proved that for certain class of initial data, the corresponding solutions of the 3-D primitive equations without viscosity blow up in finite time by looking for a self-similar solution in [16]. However, we cannot find the self-similar solution to the viscous system.

In 2023, the corresponding solutions of the 2-D viscous primitive equations were proven in [17]; the main problem was to solve the viscosity term. In this paper, we study the corresponding solutions to the 3-D primitive equations with viscosity. We need not only to solve the viscosity similarly to the method described in [17] but also to consider the effect of dimensional changes.

The three-dimensional primitive equations for large-scale oceanic and atmospheric dynamics are given by the system of partial differential equations:

$$u_t + uu_x + vu_y + wu_z + p_x - Rv = v_H \Delta_H u + v_3 u_{zz},$$
(1.1)

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$$v_t + uv_x + vv_y + wv_z + p_y + Ru = v_H \Delta_H v + v_3 v_{zz},$$
(1.2)

$$p_z + T = 0, \tag{1.3}$$

$$T_t + uT_x + vT_y + wT_z = Q + \kappa_H \Delta_H T + \kappa_3 T_{zz}, \qquad (1.4)$$

$$u_x + v_y + w_z = 0, (1.5)$$

with the initial value (u_0, v_0, T_0) and the relevant geophysical boundary conditions. Here, the horizontal velocity (u, v), the vertical velocity w, the temperature T, and the pressure pare the unknowns. R is the rotation parameter, v_H is the horizontal viscosity parameter, v_3 is the vertical viscosity parameter, κ_H is the horizontal diffusion parameter, and κ_3 is the vertical diffusion parameter. Here, $\Delta_H = \partial_{xx} + \partial_{yy}$ denotes the horizontal Laplacian operator.

2 Derivation of the reduced equations

In this section, we try to construct a special solution to the 3-D primitive equations and get the expression of the term of pressure to simplify the system. Then, we restrict the reduced equation on the surface x = 0, y = 0.

For simplicity, we take T(x, y, z, t) = 0 and consider the simplified primitive equations without the Coriolis force

$$u_t + uu_x + vu_y + wu_z + p_x = u_{zz}, (2.1)$$

$$v_t + uv_x + vv_y + wv_z + p_y = v_{zz},$$
(2.2)

$$p_z = 0, \tag{2.3}$$

$$u_x + v_y + w_z = 0, (2.4)$$

in the horizontal channel $\Omega = \{(x, y, z) : 0 \le z \le H, (x, y) \in D \subset \mathbb{R}^2\}$ and $t \in [0, T)$, with initial and boundary conditions:

$$(u,v)|_{t=0} = (u_0,v_0)(x,y,z), \tag{2.5}$$

$$(u, v, w)|_{z=0} = (u, v, w)|_{z=H} = 0,$$
(2.6)

$$(u, v)|_{\partial D} = (u_1, v_1).$$
 (2.7)

Specifically, we assume that p(x, y, t) is a concave function, with respect to the variable x. Then, we have

$$p_{xx} \ge 0. \tag{2.8}$$

We construct the solution to the system (2.1)-(2.4) with the structure

$$(u(x, y, z, t), k(x, y, t)u(x, y, z, t), w(x, y, z, t)),$$
(2.9)

with u(x, y, z, t) being strictly increasing in $0 \le z \le H$,

$$u_z > 0.$$
 (2.10)

After the above assumptions, we have

$$v_0 = ku_0, \qquad v_1 = ku_1. \tag{2.11}$$

Plugging the form (2.9) into (2.2) and using (2.1), we get

$$uk_t + u^2 k_x + ku^2 k_y - kp_x + p_y = 0. (2.12)$$

By differentiating (2.12) with respect to *z* and using (2.10), we have

$$k_t + 2u(k_x + kk_y) = 0. (2.13)$$

By differentiating (2.13) with respect to *z*, we get

$$(k_x + kk_y) = 0. (2.14)$$

Combing (2.13) and (2.14), we get $k_t = 0$. Plugging these equations into (2.12) gives the following

$$p_y - kp_x = 0. (2.15)$$

The systems to be studied in this paper can be formulated as follows

$$u_t + uu_x + vu_y + wu_z + p_x = u_{zz}, (2.16)$$

$$v_t + uv_x + vv_y + wv_z + p_y = v_{zz}, (2.17)$$

$$u_x + v_y + w_z = 0, (2.18)$$

with initial and boundary conditions:

$$(u,v)|_{t=0} = (u_0, ku_0)(x, y, z), \tag{2.19}$$

$$(u, v, w)|_{z=0} = (u, v, w)|_{z=H} = 0,$$
(2.20)

$$(u,v)|_{\partial D} = (u_1, ku_1), \tag{2.21}$$

there $u_z(x, y)$, k(x, y) and p(x, y, t) satisfy (2.10), (2.14), and (2.15).

Lemma 2.1 If (u, v, w)(x, y, z, t) is the classical solution to (2.16)–(2.21), then v(x, y, z, t) = k(x, y)u(x, y, z, t). See Lemma 2.1 in [16].

Therefore, studying the problem (2.16)–(2.21) is equivalent to studying the following reduced problem for only two unknown functions *u* and *w*

$$u_t + uu_x + ku \cdot u_y + wu_z + p_x = u_{zz}, \tag{2.22}$$

$$u_x + (ku)_y + w_z = 0, (2.23)$$

with initial and boundary condition

$$(u,w)|_{z=0} = (u,w)|_{z=H} = 0, \tag{2.24}$$

$$u|_{\partial D} = u_1, \tag{2.25}$$

$$u|_{t=0} = u_0(x, y, z). \tag{2.26}$$

In addition, we impose the following condition

$$u(x, y, z, t) = -u(-x, y, z, t); \qquad w(x, y, z, t) = w(-x, y, z, t);$$

$$p(x, y, t) = p(-x, y, z, t).$$
(2.27)

By differentiating equation (2.22) with respect to *x*, we obtain

$$u_{tx} + u_x^2 + uu_{xx} + (ku)_x u_y + ku \cdot u_{xy} + w_x u_z + wu_{xz} + p_{xx} = u_{zzx}.$$
(2.28)

By averaging (2.28) with respect to the *z* variable over [0, H] and multiplying $\frac{1}{H}$, we obtain

$$\frac{1}{H} \int_{0}^{H} \left[u_{tx} + 2u_{x}^{2} + 2uu_{xx} + (ku \cdot u)_{xy} - u_{zzx} \right] dz + p_{xx} = 0.$$
(2.29)

Thus,

$$\frac{1}{H} \int_{0}^{H} \left[u_{t} + 2uu_{x} + (ku \cdot u)_{y} - u_{zz} \right] dz + p_{x} = C(y, t)$$
(2.30)

for some function C(y, t). Due to (2.28), we know that p_x and u are odd functions, with respect to the variable x, then

$$C(y,t) = 0,$$
 (2.31)

and consequently

$$p_x = -\frac{1}{H} \int_0^H \left[u_t + 2uu_x + (ku \cdot u)_y - u_{zz} \right] dz.$$
(2.32)

Substituting (2.32) into system (2.22), we obtain the closed system

$$u_t + uu_x + ku \cdot u_y + wu_z - u_{zz} = -\frac{1}{H} \int_0^H \left[u_t + 2uu_x + (ku \cdot u)_y - u_{zz} \right] dz.$$
(2.33)

By differentiating with respect to *x*, we have

$$u_{tx} + u_x^2 + uu_x + (ku)_x u_y + ku \cdot u_{xy} + w_x u_z + wu_{xz} - u_{zzx}$$

= $\frac{1}{H} \int_0^H \left[u_{tx} + 2u_x^2 + 2uu_{xx} + (ku \cdot u)_{yx} - u_{xzz} \right] dz.$ (2.34)

Let us consider the restriction of the evolution of equation (2.34) on the surface x = 0, y = 0. Since *u* is an odd function, and *w* is an even function, with respect to the variable *x*, we have

$$u(0,0,z,t) = 0;$$
 $w_x(0,0,z,t) = 0.$ (2.35)

This, together with (2.34), implies

$$u_{tx}(0,0,z,t) + (u_x(0,0,z,t))^2 - \int_0^z u_x \, dz \cdot u_{xz}(0,0,z,t)$$

= $\frac{1}{H} \int_0^H [u_{tx}(0,0,z,t) + 2(u_x(0,0,z,t))^2 - u_{xzz}] \, dz.$ (2.36)

Denoting by

$$a(z,t) = -u_x(0,0,z,t), \tag{2.37}$$

we obtain

$$a_{t} = a^{2} + a_{zz} - \int_{0}^{z} a \, dz \cdot a_{z} - \frac{1}{H} \int_{0}^{H} \left(-a_{t} + 2a^{2} + a_{zz} \right) dz, \qquad (2.38)$$

with the initial and boundary conditions

$$a(z,0) = a_0(z), \qquad a(0,t) = 0, \qquad a(H,t) = 0.$$
 (2.39)

In particular, due to equations (2.8) and (2.32), we have

$$f(t) = \frac{1}{H} \int_0^H \left(-a_t + 2a^2 + a_{zz} \right) dz \le 0.$$
(2.40)

3 Main result and the proof

In this section, we will give Lemma 3.1 and the main result.

Lemma 3.1 Define

$$F(a) = \int_0^H a^2 dz, \qquad E(a) = \int_0^H \left(\frac{1}{2}a_z^2 - \frac{1}{4}a^3\right) dz, \qquad G = -\frac{E}{F^{\beta}},$$
(3.1)

where $\beta \in (1, \frac{5}{4})$. Let a_0 be nonnegative, compactly supported initial data such that $E(a_0) < 0$, $a_{zz}(0, t) = 0$ and $a_{zz}(H, t) = 0$. Then, there exists a finite time T such that either

$$\lim_{t \to T} \max_{z} a = +\infty, \tag{3.2}$$

or at least one of the following results

$$\lim_{t \to T} a_z(0,t) = +\infty, \tag{3.3}$$

$$\lim_{t \to T} a_z(H, t) = +\infty.$$
(3.4)

Remark 3.1 Using Lemma 2.1, we reduce the system (2.1)-(2.7) to the system (2.22)-(2.26) with two unknown functions and three variables. Then, we consider the problem on the surface x = 0 and y = 0. So, the proof of Lemma 3.1 takes the same method as in [17].

Theorem 3.1 Assuming that $p_{xx} \ge 0$ and the conditions (2.10) and (2.27) are satisfied, we can get Lemma 3.1. Then, smooth solutions to (2.16)–(2.21) do not exist globally in time.

Remark 3.2 In the Lemma 3.1, $a(z, t) = -u_x(0, 0, z, t)$, so the blowup is in the norm of u_x or u_{xy} .

4 Conclusions

This study has shown that the 3-D primitive equations with viscosity blow up on the surface x = 0 and y = 0. In this paper, we consider the simplified equations. We plan to solve unreduced systems in the future.

Author contributions

Lin Zheng wrote the whole manuscript and reviewed it.

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Declarations

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Competing interests

The authors declare no competing interests.

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