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Existence of solutions for nonlinear mixed type integro-differential functional evolution equations with nonlocal conditions

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Abstract

Using the Mönch fixed point theorem, this article proves the existence of mild solutions for nonlinear mixed type integro-differential functional evolution equations with nonlocal conditions in Banach spaces. Some restricted conditions on *a priori* estimation and measure of noncompactness estimation have been deleted, and compactness conditions of evolution operators or compactness conditions on a nonlinear term $f(t, X_r, X_r, X_r)$ have been weakened. Our results extend and improve many known results.

MSC: 34G20; 34K30

Keywords: integro-differential functional evolution equation; mild solution; nonlocal conditions; fixed point; Banach spaces

1 Introduction

Let $(X, \|\cdot\|)$ be a Banach space, $C[J, X] = \{x : J = [0, a] \rightarrow X, x(t) \text{ is continuous in } J\}$ with the norm $\|x\|_C = \sup_{t \in J} \|x(t)\|$. It is easy to verify that $C[J, X]$ is a Banach space. The space of X -valued Bochner integrable functions on J with the norm $\|x\|_1 = \int_0^a \|x(s)\| ds$ is denoted by $L[J, X]$. Consider the following nonlinear mixed type integro-differential functional evolution equations with nonlocal conditions in a Banach space X (IVP),

$$x'(t) = A \left[x(t) + \int_0^t F(t-s)x(s) ds \right] + f(t, x(\sigma_1(t)), (Kx_{\sigma_2})(t), (Hx_{\sigma_3})(t)), \quad t \in J, \quad (1.1)$$

$$x(0) = g(x) + x_0, \quad (1.2)$$

where

$$(Kx_{\sigma_2})(t) = \int_0^t k(t, s, x(\sigma_2(s))) ds, \quad (Hx_{\sigma_3})(t) = \int_0^a h(t, s, x(\sigma_3(s))) ds, \quad (1.3)$$

A is the generator of a strongly continuous semigroup in the Banach space X , and $F(t)$ is a bounded operator for $t \in J$, $x_0 \in X$, $f \in C[J \times X^3, X]$, $g : C[J, X] \rightarrow X$, $k \in C[\Delta \times X, X]$, $\Delta = \{(t, s) \in J \times J : s \leq t\}$, $h \in C[J \times J \times X, X]$, $\sigma_i \in C[J, J]$ and $\sigma_i(t) \leq t$ ($i = 1, 2, 3$).

For the existence of mild solutions of integro-differential functional evolution equations in abstract spaces, there are many research results, see [1–16], and references therein. In order to obtain the existence and controllability of mild solutions in these study papers,

usually, some restricted conditions on a priori estimation and compactness conditions of an evolution operator or compactness conditions on $f(t, X_r, X_r, X_r)$ are used.

Recently, using a fixed point theorem, Haribhau Laxman Tidkey and Machindra Baburao Dhakne [1] have studied the existence of mild solutions of IVP (1.1)-(1.2) when $\sigma_i(t) = t$ ($i = 1, 2, 3$), the compactness of the resolvent operator and the restricted condition

$$M_1[\|x_0\| + G_1 + Lrb + LKrb^2 + LK_1b^2 + LHrb^2 + LH_1b^2 + L_1b] \leq r$$

with $M_1[Lb + LKb^2 + LHb^2] < 1$ is used. Malar [17] and Shi [18] studied the existence of mild solutions of semilinear mixed type integrodifferential evolution equations with the equicontinuous semigroup

$$\begin{cases} x'(t) = Ax(t) + f(t, x(t), \int_0^t a(t, s)k(s, x(s)) ds, \\ \int_0^a b(t, s)h(s, x(s)) ds), \quad t \in [0, a], \\ x(0) = x_0 + g(x). \end{cases} \quad (1.4)$$

Solvability of the scalar equation

$$m(t) = K_1 + K_2 \int_0^t h(s, m(s), n(s), q(s)) ds, \quad t \in J$$

and the restricted condition on measure of noncompactness estimation

$$\int_0^t [\eta_1(s) + k_1\eta_2(s) + k_2\eta_3(s)] ds \leq K$$

are used in [17]. But estimations (3.15) and (3.21) in [18] seem to be incorrect, as they have no meaning.

In this paper, using the Mönch fixed point theorem, we investigate the existence of mild solutions of IVP (1.1)-(1.2). Some restricted conditions on a priori estimation and measure of noncompactness estimation have been deleted, and compactness conditions of a resolvent operator or compactness conditions on a nonlinear term $f(t, X_r, X_r, X_r)$ have been weakened. Our results extend and improve some corresponding results in papers [1–4, 6–21].

2 Preliminaries

We will make the following assumptions:

- (H₁) A generates a strongly continuous semigroup in the Banach space X .
- (H₂) $F(t) \in B(X)$, $0 \leq t \leq a$. $F(t) : Y \rightarrow Y$ and for $x(\cdot)$ continuous in Y , $AF(\cdot)x(\cdot) \in L^1[J, X]$. For $x \in X$, $F'(t)x$ is continuous in $t \in J$, where $B(X)$ is the space of all linear and bounded operators on X , and Y is the Banach space formed from $D(A)$, the domain of A , endowed with the graph norm.

Definition 2.1 [5] $R(t)$ is a resolvent operator of (1.1) with $f \equiv 0$ if $R(t) \in B(X)$ for $0 \leq t \leq a$ and satisfies the following conditions:

- (1) $R(0) = I$, the identity operator on X ,

- (2) for all $x \in X$, $R(t)x$ is continuous for $0 \leq t \leq a$,
 (3) $R(t) \in B(Y)$, $0 \leq t \leq a$; for $y \in Y$, $R(\cdot)y \in C^1[J, X] \cap C[J, Y]$ and

$$\begin{aligned} \frac{d}{dt}R(t)y &= A \left[R(t)y + \int_0^t F(t-s)R(s)y \, ds \right] \\ &= R(t)Ay + \int_0^t R(t-s)AF(s)y \, ds, \quad 0 \leq t \leq a. \end{aligned} \tag{2.1}$$

The resolvent operator $R(t)$ is said to be equicontinuous if $\{t \rightarrow R(t)x : x \in B\}$ is equicontinuous for the entire bounded set $B \subset X$ and $t > 0$. If $x \in C[J, X]$ satisfies the following integral equation:

$$x(t) = R(t)(x_0 + g(x)) + \int_0^t R(t-s)f(s, x(\sigma_1(s)), (Kx_{\sigma_2})(s), (Hx_{\sigma_3})(s)) \, ds, \quad t \in J,$$

then x is said to be a mild solution IVP (1.1)-(1.2).

Lemma 2.2 [14] *Let the conditions (H_1) , (H_2) be satisfied. Then (1.1) with $f \equiv 0$ has a unique resolvent operator.*

The following lemma is obvious.

Lemma 2.3 *Let the resolvent operator $R(t)$ be equicontinuous. If there is $\rho \in L[J, \mathbb{R}^+]$ such that $\|x(t)\| \leq \rho(t)$ for a.e. $t \in J$, then the set $\{\int_0^t R(t-s)x(s) \, ds\}$ is equicontinuous.*

Lemma 2.4 [22] *Let $V \in C[J, E]$ be an equicontinuous bounded subset. Then $\alpha(V(t)) \in C[J, \mathbb{R}^+]$ ($\mathbb{R}^+ = [0, \infty)$), $\alpha(V) = \max_{t \in J} \alpha(V(t))$.*

Lemma 2.5 [23] *Let $V = \{x_n\} \subset L[J, E]$ and there exists $\sigma \in L[J, \mathbb{R}^+]$ such that $\|x_n(t)\| \leq \sigma(t)$ for any $x \in V$ and a.e. $t \in J$. Then $\alpha(V(t)) \in L[J, \mathbb{R}^+]$ and*

$$\alpha \left(\left\{ \int_0^t x_n(s) \, ds : n \in \mathbb{N} \right\} \right) \leq 2 \int_0^t \alpha(V(s)) \, ds, \quad t \in J.$$

Lemma 2.6 [24] (Mönch) *Let E be a Banach space, Ω a closed convex subset in E and $y_0 \in \Omega$. Suppose that the continuous operator $F : \Omega \rightarrow \Omega$ has the following property:*

$$V \subset \Omega \text{ countable, } V \subset \overline{\text{co}}(\{y_0\} \cup F(V)) \Rightarrow V \text{ is relatively compact.}$$

Then F has a fixed point in Ω .

For $V \subset C[J, X]$, let $V(t) = \{x(t) : x \in V\}$, $V_{\sigma_i}(t) = \{x(\sigma_i(t)) : x \in V\}$ ($i = 1, 2, 3$), $(KV)(t) = \{(Kx)(t) : x \in V\}$, $(HV)(t) = \{(Hx)(t) : x \in V\}$ ($t \in J$), $X_r = \{x \in X : \|x\| \leq r\}$ and $S_r = \{x \in C[J, X] : \|x\|_C \leq r\}$ for any $r > 0$. $\alpha(\cdot)$ and $\alpha_C(\cdot)$ denote the Kuratowski measure of noncompactness in X and $C[J, X]$ respectively. For details on the properties of noncompact measure, we refer the reader to [22].

3 Existence of a mild solution

We make the following assumptions for convenience.

(H₃) There exist constants $l_g > 0$, $M > 0$ and $4l_g M < 1$ such that

$$\|g(x) - g(y)\| \leq l_g \|x - y\|_C, \quad x, y \in C[J, X],$$

and $g(0) = 0$.

(H₃') $g : C[J, X] \rightarrow E$ is continuous, compact and there exists a constant $N \geq 0$ such that $\|g(x)\| \leq N$.

(H₄) There exists $q \in C[J, \mathbb{R}^+]$ such that

$$\|f(t, x, y, z)\| \leq q(t)(\|x\| + \|y\| + \|z\|), \quad t \in J, x, y, z \in X.$$

(H₅) There exist $k_0 \in C[\Delta, \mathbb{R}^+]$, $h_0 \in C[J \times J, \mathbb{R}^+]$ such that

$$\|k(t, s, x)\| \leq k_0(t, s)\|x\|, \quad (t, s) \in \Delta, x \in X,$$

$$\|h(t, s, x)\| \leq h_0(t, s)\|x\|, \quad t, s \in J, x \in X.$$

(H₆) For any $r > 0$ and a bounded set $V_i \subset X_r$, there exist constants $l_i > 0$ ($i = 1, 2, 3$) such that

$$\alpha(f(t, V_1, V_2, V_3)) \leq l_1 \alpha(V_1) + l_2 \alpha(V_2) + l_3 \alpha(V_3), \quad t \in J.$$

(H₇) For any $r > 0$ and a bounded set $V \subset X_r$,

$$\alpha(k(t, s, V)) \leq k_0(t, s)\alpha(V), \quad (t, s) \in \Delta,$$

$$\alpha(h(t, s, V)) \leq h_0(t, s)\alpha(V), \quad t, s \in J.$$

(H₈) The resolvent operator $R(t)$ is equicontinuous and $\|R(t)\| \leq Me^{-wt}$ for $t \in J$ and some positive number

$$w = \max\{2Mq_0(1 + K_0a + H_0a), 4M(l_1 + 2l_2aK_0 + 2l_3aH_0)\},$$

where $K_0 = \max_{(t,s) \in \Delta} k_0(t, s)$, $H_0 = \max_{t,s \in J} h_0(t, s)$, $q_0 = \max_{t \in J} q(t)$.

Without loss of generality, we always suppose that $x_0 = 0$.

Theorem 3.1 *Let conditions (H₁), (H₂), (H₃)-(H₈) be satisfied. Then IVP (1.1)-(1.2) has at least one mild solution.*

Proof Let

$$\begin{aligned} (Fx)(t) &= R(t)g(x) \\ &+ \int_0^t R(t-s)f(s, x(\sigma_1(s)), (Kx_{\sigma_2})(s), (Hx_{\sigma_3})(s)) ds, \quad t \in J. \end{aligned} \tag{3.1}$$

We have by (H_3) , (H_4) and (H_5) ,

$$\begin{aligned} & \| (Fx)(t) \| \\ & \leq \| R(t)g(x) \| + \int_0^t \| R(t-s) \| \| f(s, x(\sigma_1(s)), (Kx_{\sigma_2})(s), (Hx_{\sigma_3})(s)) \| ds \\ & \leq M \| g(x) \| + M \int_0^t e^{-w(t-s)} q(s) (\| x(\sigma_1(s)) \| + \| (Kx)(\sigma_2(s)) \| + \| (Hx)(\sigma_3(s)) \|) ds \\ & \leq l_g M \| x \|_C \\ & \quad + Mq_0 \int_0^t e^{w(s-t)} \left(\| x(s) \| + \int_0^s k_0(s,r) \| x(r) \| dr + \int_0^a h_0(s,r) \| x(r) \| dr \right) ds \\ & \leq l_g M \| x \|_C + Mq_0 \int_0^t e^{w(s-t)} (1 + K_0 a + H_0 a) \| x \|_C ds \\ & \leq l_g M \| x \|_C + Mq_0 (1 + K_0 a + H_0 a) w^{-1} \| x \|_C \leq \| x \|_C. \end{aligned} \tag{3.2}$$

Let

$$B_R = \{ x \in C[J, X] : \| x \|_C \leq R \}.$$

Then B_R is a closed convex subset in $C[J, X]$, $0 \in B_R$ and $F : B_R \rightarrow B_R$. Similar to the proof of [6] and [9], it is easy to verify that F is a continuous operator from B_R into B_R . For $x \in B_R$, $s \in J$, (H_4) and (H_5) imply

$$\| f(s, x(\sigma_1(s)), (Kx_{\sigma_2})(s), (Hx_{\sigma_3})(s)) \| \leq q(s) \left(1 + \int_0^s k_0(s,r) dr + \int_0^a h_0(s,r) dr \right) R. \tag{3.3}$$

We can show from (3.3), (H_8) and Lemma 2.3 that $F(B_R)$ is an equicontinuous subset in $C[J, X]$.

Let $V \subset B_R$ be a countable set and $V \subset \overline{\text{co}}(\{0\} \cup F(V))$, then

$$V(t) \subset \overline{\text{co}}(\{0\} \cup (FV)(t)). \tag{3.4}$$

From equicontinuity of $F(B_R)$ and (3.4), we know that V is an equicontinuous subset in $C[J, X]$. By the properties of noncompact measure, the conditions (H_3) , (H_6) , (H_7) , (3.4) and Lemma 2.5, we have

$$\begin{aligned} \alpha(V(t)) & \leq \alpha((FV)(t)) \\ & \leq \| R(t) \| \alpha(g(V)) + 2 \int_0^t \| R(t-s) \| \alpha(f(s, V_{\sigma_1}(s), (KV_{\sigma_2})(s), (HV_{\sigma_3})(s))) ds \\ & \leq l_g M \alpha_C(V) + 2M \int_0^t e^{w(s-t)} \left[l_1 \alpha(V(\sigma_1(s))) + 2l_2 \int_0^s k_0(s,r) \alpha(V(\sigma_2(r))) dr \right. \\ & \quad \left. + 2l_3 \int_0^a h_0(s,r) \alpha(V(\sigma_3(r))) dr \right] ds \\ & \leq l_g M \alpha_C(V) \\ & \quad + 2M \int_0^t e^{w(s-t)} \left[l_1 \alpha(V(s)) ds + 2 \left(l_2 \int_0^s K_0 + l_3 \int_0^a H_0 \right) \alpha(V(r)) dr \right] ds \end{aligned}$$

$$\begin{aligned} &\leq l_g M \alpha_c(V) + 2M(l_1 + 2l_2 a K_0 + 2l_3 a H_0) \alpha_c(V) \int_0^t e^{w(s-t)} ds \\ &\leq l_g M \alpha_c(V) + 2M(l_1 + 2l_2 a K_0 + 2l_3 a H_0) w^{-1} \alpha_c(V) \leq \frac{3}{4} \alpha_c(V), \quad t \in J. \end{aligned} \quad (3.5)$$

(3.5) together with Lemma 2.4 imply that $\alpha_c(V) \leq \frac{3}{4} \alpha_c(V)$, and so $\alpha_c(V) = 0$. Hence V is relatively compact in $C[J, X]$. Lemma 2.6 implies that F has a fixed point in $C[J, X]$. Then IVP (1.1)-(1.2) has at least one mild solution. The proof is completed. \square

Theorem 3.2 *Let the conditions (H_1) , (H_2) and (H'_3) - (H_8) be satisfied. Then IVP (1.1)-(1.2) has at least one mild solution.*

Proof Similar to (3.2) and (3.5), it is easy to verify

$$\|(Fx)(t)\| \leq MN + Mq_0(1 + K_0 a + H_0 a) w^{-1} \|x\|_C = MN + \eta \|x\|_C,$$

where $\eta = Mq_0(1 + K_0 a + H_0 a) w^{-1} < 1$. Taking $R > MN(1 - \eta)^{-1}$, let $B_R = \{x \in C[J, X] : \|x\|_C \leq R\}$. We have $F : B_R \rightarrow B_R$ and the inequality (3.5) is transformed into $\alpha(V(t)) \leq \frac{1}{2} \alpha_c(V)$, $t \in J$.

The other proof is similar to the proof of Theorem 3.1, we omit it. \square

4 An example

Let $X = L^2[0, \pi]$. Consider the following partial functional integro-differential equation with a nonlocal condition,

$$\begin{cases} u_t(t, y) = u_y(t, y) + \int_0^t F(t-s) u_y(s, y) ds + \gamma_1 \sin u(t-r, y) \\ \quad + \int_0^t \frac{\gamma_2 u(s-r, y) ds}{(1+t)} + \int_0^a \frac{\gamma_3 u(s-r, y) ds}{(1+t)(1+s)^2}, \quad 0 \leq t \leq a, \\ u(0, y) = u_0(y) + \gamma_4 u(y), \end{cases} \quad (4.1)$$

where $r, \gamma_i \in \mathbb{R}$ ($i = 1, 2, 3, 4$), $\sigma_1(t) = \sigma_2(t) = \sigma_3(t) = t - r$, $0 \leq r \leq t \leq a$, $F(t)$ satisfies the condition (H_2) ,

$$\begin{aligned} &f(t, u(\sigma(t)), (Ku_\sigma)(t), (Su_\sigma)(t))(y) \\ &= \gamma_1 \sin u(t-r, y) + \int_0^t \frac{\gamma_2 u(s-r, y) ds}{(1+t)} + \int_0^a \frac{\gamma_3 u(s-r, y) ds}{(1+t)(1+s)^2}, \end{aligned} \quad (4.2)$$

$$k(t, s, u(\sigma(s)))(y) = \frac{u(s-r, y)}{1+t}, \quad h(t, s, u(\sigma(s)))(y) = \frac{u(s-r, y)}{(1+t)(1+s)^2}, \quad (4.3)$$

$$g(u)(y) = \gamma_4 u(y). \quad (4.4)$$

Let the operator A be defined by $Aw = w'$, $w \in D(A)$ with the domain

$$D(A) = \{w \in E : w' \in E, w' \text{ is almost everywhere bounded}\}.$$

Then A generates a translation semigroup $R(t)$ and $R(t)$ is equicontinuous. The problem (4.1) can be regarded as a form of IVP (1.1)-(1.2). We have by (4.2), (4.3) and (4.4),

$$\|f(t, u, v, z)\| \leq |\gamma| (\|u\| + \|v\| + \|z\|), \quad |\gamma| = \max\{|\gamma_1|, |\gamma_2|, |\gamma_3|\}, u, v, z \in X,$$

$$\|k(t, s, u)\| \leq \|u\|, \quad \|h(t, s, u)\| \leq \|u\|, \quad u \in X,$$

and

$$\|g(u) - g(v)\| \leq |\gamma_4| \|u - v\|_C, \quad g(0) = 0.$$

γ_4 and M can be chosen such that $4M|\gamma_4| < 1$. In addition, for any $r > 0$ and a bounded set $V_i \subset X_r$ ($i = 1, 2, 3$), we can show that by the diagonal method,

$$\alpha(f(t, V_1, V_2, V_3)) \leq |\gamma|(\alpha(V_1) + \alpha(V_2) + \alpha(V_3)), \quad t \in J,$$

$$\alpha(k(t, s, V_1)) \leq \alpha(V_1), \quad t, s \in \Delta,$$

$$\alpha(h(t, s, V_1)) \leq \alpha(V_1), \quad t, s \in [0, a].$$

Hence all the conditions of Theorem 3.1 are satisfied, the problem (4.1) has at least one mild solution in $C[J, X]$.

Competing interests

The author declares that they have no competing interests.

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