# An improved numerical solution of the singular boundary integral equation of the compressible fluid flow around obstacles using modified shape functions 

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#### Abstract

In this work an improved numerical solution of the singular boundary integral equation of the 2D compressible fluid flow around obstacles is obtained by a boundary element method based on modified shape functions and cubic boundary elements. The singular boundary integral equation with sources distribution is considered in this paper, and for its discretization cubic boundary elements are used. The integrals of singular kernels are evaluated using modified shape functions which are deduced by using series expansions for the basis functions we choose for the local approximation models. A computer code is made using Mathcad programming language and, based on it, some particular cases are solved. In order to validate the proposed method, comparisons between numerical solutions and exact ones are performed for the considered test problems. The advantage of using modified shape functions for evaluating the singularities is pointed out through a comparison study between the numerical solution obtained by the method proposed in this paper and the one obtained by using a truncation method for evaluating the singularities.


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## 1 Introduction

When solving problems of real life described by partial differential equations or systems of partial differential equations with boundary conditions, seldom this can be done analytically, and so, in order to find an approximate solution, numerical techniques, such as: the finite difference method, the finite element method, the finite volume method, the boundary element method, and others, have to be applied.
Among these methods the literature highlights the boundary element method because of its advantages over the other, especially when dealing with fluid flows around obstacles, in fact with problems with infinite domains. The reduction by one of the problem's dimension, less nodal values need to be found, a reduced computational effort is needed, obtaining an exact boundary formulation of the problem, are only some of these advantages, presented in many books dedicated to this method (as, for example, [1-5]). These advantages recommend the boundary element method as a powerful and efficient numer-

[^0]ical technique, suitable for a wide class of problems arising in different domains. The complex boundary element method can also be successfully used to solve different problems, especially problems of fluid flow (see, for example, [6]).
In this paper, the boundary element method is applied in order to find an improved numerical solution for a boundary value problem with a nonlinear boundary condition, namely the two-dimensional problem of the compressible fluid flow around obstacles. Our goal is to solve, by discretization, a singular boundary integral equation associated to the problem, and to obtain the numerical solution of the problem with a computer code made in Mathcad, based on this approach.
Different methods have been applied to solve this problem and many equivalent integral formulations were deduced for it (see [7-14]). Some similar problems were solved in [1517]. We have considered in this approach the singular boundary integral equation with source distribution, for its simplicity, and because it is formulated in velocity terms, the primary variables of interest, a fact that offers many advantages.
The singular boundary integral equation we refer to in the present work is solved in [11] by using a collocation method. Different kinds of boundary elements as linear, or quadratic, are used in [18, 19]. In [14] a brief description of the problem is made, a solution that uses cubic boundary elements is obtained, and the advantages of using a boundary element method to solve the mentioned problem are also presented. The treatment of singularities represents a great source of errors when applying this method, but using suitable methods to overpass this difficulty, numerical solutions of great accuracy can be obtained. In the mentioned paper a truncation method is used to evaluate the integrals with singular kernels and very good numerical results are obtained. The present study is made in order to improve the numerical solution by applying another method to deal with the singularities. So, in the present paper the singular boundary integral equation is solved by using cubic boundary elements, and, for evaluating the singularities, modified shape functions, deduced on Taylor series expansions, are used.
For better understanding the meanings of the functions that appear in the boundary integral formulation we briefly present the problem to solve: we want to find the perturbation produced in a subsonic uniform compressible fluid flow by the presence of an obstacle and the fluid's action on it.
The mathematical model of the problem consists in a system of partial differential equations with a nonlinear boundary condition and the condition that the perturbation vanishes at great distances. In dimensionless variables it can be written as (see [11]):
\[

\left\{$$
\begin{array}{lc}
\frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}=0, & (\beta+u) n_{x}+\beta^{2} v n_{y}=0 \\
\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}=0, & \text { on } C,
\end{array}
$$ \quad \lim (u, v)=0\right.
\]

where $C$ (named 'obstacle boundary'), assumed to be smooth and closed, is the curve obtained from the real obstacle boundary with the transformation: $x=X, y=\beta Y$ ( $X, Y$ being the dimensionless spatial variables), $\frac{u}{\beta}$ and $v$ are the components of the perturbation velocity, $n_{x}, n_{y}$ denote the components, in the new system of coordinates, of the normal unit vector outward the fluid, $\beta=\sqrt{1-M^{2}}$ (for subsonic flow, $M=$ Mach number).

The singular boundary integral equation is deduced, in the same paper, by assimilating the boundary with a continuous distribution of sources, of intensity $f$, assumed to satisfy a Hölder condition on $C$. The singular boundary integral equation, in dimensionless
variables, is

$$
\begin{equation*}
\left(n_{x}^{0^{2}}+\beta^{2} n_{y}^{0^{2}}\right) f\left(\overline{\mathbf{x}}_{0}\right)+\frac{1}{\pi} \int_{C} f(\overline{\mathbf{x}}) \frac{\left(x-x_{0}\right) n_{x}^{0}+\beta^{2}\left(y-y_{0}\right) n_{y}^{0}}{\left\|\overline{\mathbf{x}}-\overline{\mathbf{x}}_{0}\right\|^{2}} d s=2 \beta n_{x}^{0} \tag{1}
\end{equation*}
$$

where the same notations as before are used, $n_{x}^{0}, n_{y}^{0}$ being the components of the normal unit vector outward the fluid in the point $\overline{\mathbf{x}}_{0} \in C$ and $f$ the intensity of sources. The symbol ' $\prime$ ' denotes the Cauchy Principal Value of the integral.

## 2 The discretization procedure

For solving the singular boundary integral equation (1), we consider $N$ one-dimensional, isoparametric cubic boundary elements, noted $L_{j}, j=\overline{1, N}$, each of them with four nodes: two extremes and two interior ones. For each pair of adjacent elements there is a common extreme node, so we need only $3 N$ nodes for the boundary discretization. Replacing $C=$ $\bigcup_{j=1}^{N} L_{j}$, and considering that (1) is satisfied in every node $\overline{\mathbf{x}}_{i}$, we get the discretized form of (1):

$$
\begin{equation*}
A_{i} f\left(\overline{\mathbf{x}}_{i}\right)+\frac{1}{\pi} \sum_{j=1}^{N} \int_{L_{j}} f(\overline{\mathbf{x}}) \frac{\left(x-x_{i}\right) n_{x}^{i}+\beta^{2}\left(y-y_{i}\right) n_{y}^{i}}{\left\|\overline{\mathbf{x}}-\overline{\mathbf{x}}_{i}\right\|^{2}} d s=2 \beta n_{x}^{i}, \quad i=\overline{1,3 N}, \tag{2}
\end{equation*}
$$

where $A_{i}=n_{x}^{i}{ }^{2}+\beta^{2} n_{y}^{i^{2}}$. In fact (2) represents the linear system (of $3 N$ equations) the problem is reduced to.

For simplifying the writing we do not use the notation referring to the Cauchy principal value of an integral, but when $\overline{\mathbf{x}}_{i} \in L_{j}$ the integrals in (2) have singular kernels, and they are understood in this way.

The same set of basic functions (see [3, 4]), noted $N_{1}, N_{2}, N_{3}, N_{4}$, is used for locally describing the geometry and the unknown function on a boundary element. The expressions of these functions, in the homogeneous variable $\xi$, are

$$
\begin{array}{ll}
N_{1}(\xi)=-9 \frac{(\xi-1)\left(\xi+\frac{1}{3}\right)\left(\xi-\frac{1}{3}\right)}{16}, & N_{2}(\xi)=27 \frac{(\xi+1)(\xi-1)\left(\xi-\frac{1}{3}\right)}{16}, \\
N_{3}(\xi)=-27 \frac{(\xi+1)(\xi-1)\left(\xi+\frac{1}{3}\right)}{16}, & N_{4}(\xi)=9 \frac{\left(\xi+\frac{1}{3}\right)\left(\xi-\frac{1}{3}\right)(\xi+1)}{16}, \quad \xi \in[-1,1] . \tag{3}
\end{array}
$$

As in [14] two systems of numbering are used: a global one, in which $f_{j}, j=\overline{1,3 N}$ represents the nodal value of the intensity at node number $j$, and a local one in which $f_{l}^{j}$, $l=\overline{1,4}, j=\overline{1, N}$ represents the nodal value of the $l$ th node of element number $j$. Denoting by $[\mathbf{N}]=\left(N_{1} N_{2} N_{3} N_{4}\right)$ a line matrix, by $\left\{\mathbf{x}^{j}\right\},\left\{\mathbf{y}^{j}\right\},\left\{\mathbf{f}^{j}\right\}$ the column matrices made with the coordinates of $L_{j}$ nodes and the nodal values of the unknown function corresponding to the same boundary element, for $L_{j}$, the following approximation models stand:

$$
\begin{equation*}
x=[\mathbf{N}]\left\{\mathbf{x}^{j}\right\}, \quad y=[\mathbf{N}]\left\{\mathbf{y}^{j}\right\}, \quad f=[\mathbf{N}]\left\{\mathbf{f}^{j}\right\} . \tag{4}
\end{equation*}
$$

Introducing (3) in (2) we obtain

$$
\begin{equation*}
A_{i} f\left(\overline{\mathbf{x}}_{i}\right)+\frac{1}{\pi} \sum_{j=1}^{N} \int_{-1}^{1} \frac{\left([\mathbf{N}]\left\{\mathbf{x}^{j}\right\}-x_{i}\right) n_{x}^{i}+\beta^{2} n_{y}^{i}\left([\mathbf{N}]\left\{\mathbf{y}^{j}\right\}-y_{i}\right)}{\left\|[\mathbf{N}]\left\{\overline{\mathbf{x}}^{j}\right\}-\overline{\mathbf{x}}_{i}\right\|^{2}}[\mathbf{N}]\left\{\mathbf{f}^{j}\right\} J^{j}(\xi) d \xi=2 \beta n_{x}^{i}, \tag{5}
\end{equation*}
$$

where $J^{j}(\xi)$ is the coordinate transformation Jacobian.

Denoting by

$$
\begin{align*}
a_{i j}^{l} & =\int_{-1}^{1} N_{l} \frac{\left([\mathbf{N}]\left\{\mathbf{x}^{j}\right\}-x_{i}\right) n_{x}^{i}+\beta^{2} n_{y}^{i}\left([\mathbf{N}]\left\{\mathbf{y}^{j}\right\}-y_{i}\right)}{\left\|[\mathbf{N}]\left\{\overline{\mathbf{x}}^{j}\right\}-\overline{\mathbf{x}}_{i}\right\|^{2}} J^{j}(\xi) d \xi, \\
\quad i & =\overline{1,3 N}, j=\overline{1, N}, l=\overline{1,4}, \tag{6}
\end{align*}
$$

we can write (5) as

$$
\begin{equation*}
A_{i} f_{i}+\frac{1}{\pi} \sum_{j=1}^{N}\left(\sum_{l=1}^{4} a_{i j}^{l} f_{l}^{j}\right)=2 \beta n_{x}^{i} \tag{7}
\end{equation*}
$$

Using only the global system of numbering, we obtain the following linear algebraic system:

$$
\begin{equation*}
\mathbf{A}\{\mathbf{f}\}=\{\mathbf{B}\}, \quad \mathbf{A} \in M_{3 N}(R),\{\mathbf{f}\},\{\mathbf{B}\} \in R^{3 N}, B_{i}=2 \pi \beta n_{x}^{i} . \tag{8}
\end{equation*}
$$

## 3 Modified shape functions for singular coefficients evaluation

In order to build the computer code necessary for obtaining the numerical solution we need to compute the coefficients of $\mathbf{A}$. The expressions of coefficients arising from nonsingular integrals are given in [14] and can be evaluated by using any mathematical software when knowing the geometry of the obstacle, in fact the nodes coordinates, because they depend only on these. The integrals of singular kernels are evaluated in the mentioned paper with the simplest method, namely the truncation method. The goal of the present paper is to use another numerical procedure to treat the singularities in order to get a more accurate numerical solution. Such a technique is to use modified shape function to evaluate the integrals of singular kernels (see [3]). It is used in [20], the paper in which quadratic boundary elements were used to solve the same singular boundary integral equation, and it had offered numerical results of high accuracy.
Referring to the boundary element noted $L_{j}, j=\overline{1, N}$, singular kernels appear when $\overline{\mathbf{x}}_{i}$ is one of its nodes, so when $i \in\{3 j-2,3 j-1,3 j, 3 j+1\}, j=\overline{1, N}$, considering that $3 N+1=1$, the boundary being closed.
Denoting by $\eta$ the value of $\xi$ corresponding to $\overline{\mathbf{x}}_{i}$, and using the properties of the set of basis function we can write

$$
\begin{equation*}
[\mathbf{N}]\left\{\mathbf{x}^{j}\right\}-x_{i}=\sum_{l=1}^{4} N_{l}(\xi) x_{l}^{j}-x_{i}=\sum_{l=1}^{4} N_{l}(\xi) x_{l}^{j}-\sum_{l=1}^{4} N_{l}(\eta) x_{l}^{j}=\sum_{l=1}^{4}\left(N_{l}(\xi)-N_{l}(\eta)\right) x_{l}^{j} . \tag{9}
\end{equation*}
$$

Based on a Taylor expansion of $N_{l}(\xi)$ at $\eta$ we have

$$
\begin{equation*}
N_{l}(\xi)=N_{l}(\eta)+\frac{1}{1!} N_{l}^{\prime}(\eta)(\xi-\eta)+\frac{1}{2!} N^{\prime \prime}(\eta)(\xi-\eta)^{2}+\frac{1}{3!} N^{\prime \prime \prime}(\eta)(\xi-\eta)^{3} . \tag{10}
\end{equation*}
$$

Denoting by

$$
\begin{equation*}
\hat{N}_{l}(\xi, \eta)=N_{l}^{\prime}(\eta)+\frac{1}{2} N_{l}^{\prime \prime}(\eta)(\xi-\eta)^{1}+\frac{1}{6} N_{l}^{\prime \prime \prime}(\eta)(\xi-\eta)^{2} \tag{11}
\end{equation*}
$$

we can write (9) as

$$
\begin{equation*}
[\mathbf{N}]\left\{\mathbf{x}^{j}\right\}-x_{i}=(\xi-\eta) \sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) x_{l}^{j} \tag{12}
\end{equation*}
$$

Similarly we get

$$
\begin{equation*}
[\mathbf{N}]\left\{\mathbf{y}^{j}\right\}-y_{i}=\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) y_{l}^{j}(\xi-\eta) \tag{13}
\end{equation*}
$$

The functions $\hat{N}_{l}(\xi, \eta), l=\overline{1,4}$, from (11) are named modified shape functions and they are used for evaluating the coefficients arising from integrals with singular kernels.

In the case of isoparametric cubic boundary elements their expressions, in the homogeneous variables, are

$$
\begin{align*}
& \hat{N}_{1}(\xi, \eta)=-\frac{9}{16}\left(\xi^{2}+\eta^{2}+\xi \eta-\xi-\eta-\frac{1}{9}\right), \\
& \hat{N}_{2}(\xi, \eta)=\frac{27}{16}\left(\xi^{2}+\eta^{2}+\xi \eta-\frac{1}{3} \xi-\frac{1}{3} \eta-1\right), \\
& \hat{N}_{3}(\xi, \eta)=-\frac{27}{16}\left(\xi^{2}+\eta^{2}+\xi \eta+\frac{1}{3} \xi+\frac{1}{3} \eta-1\right),  \tag{14}\\
& \hat{N}_{1}(\xi, \eta)=\frac{9}{16}\left(\xi^{2}+\eta^{2}+\xi \eta+\xi+\eta-\frac{1}{9}\right) .
\end{align*}
$$

Doing the same for the denominator of the integrand in (6) we obtain

$$
\left\|[\mathbf{N}]\left\{\overline{\mathbf{x}}^{j}\right\}-\overline{\mathbf{x}}_{i}\right\|^{2}=(\xi-\eta)^{2} \hat{N}_{i j}(\xi, \eta),
$$

where

$$
\begin{equation*}
\hat{N}_{i j}(\xi, \eta)=\left(\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) x_{l}^{j}\right)^{2}+\left(\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) y_{l}^{j}\right)^{2} . \tag{15}
\end{equation*}
$$

Denoting

$$
\begin{equation*}
F_{i j}(\xi, \eta)=\left(\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) x_{l}^{j}\right) n_{x}^{i}+\beta^{2}\left(\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) y_{l}^{j}\right) n_{y}^{i}, \tag{16}
\end{equation*}
$$

equation (6) becomes

$$
\begin{equation*}
a_{i j}^{l}=\int_{-1}^{1} N_{l}(\eta) \frac{F_{i j}(\xi, \eta)}{(\xi-\eta) \hat{N}_{i j}(\xi, \eta)} J^{j}(\xi) d \xi+\int_{-1}^{1} \hat{N}_{l}(\xi, \eta) \frac{F_{i j}(\xi, \eta)}{\hat{N}_{i j}(\xi, \eta)} J^{j}(\xi) d \xi . \tag{17}
\end{equation*}
$$

As one can see in the case of integrals with singular kernels, only the first integral in (17) still presents a singularity. Its evaluation is made numerically, according to the definition of the Cauchy Principal Value of an integral, by using a small parameter $\varepsilon$ to isolate the singularity.

The properties of the basis functions $N_{l}, l=\overline{1,4}$, corresponding to boundary element nodes, can be summarized as follows:

$$
\begin{align*}
& N_{l}(-1)=\left\{\begin{array}{ll}
1 & \text { if } l=1, \\
0 & \text { otherwise },
\end{array} \quad N_{l}\left(\frac{-1}{3}\right)= \begin{cases}1 & \text { if } l=2, \\
0 & \text { otherwise },\end{cases} \right.  \tag{18}\\
& N_{l}\left(\frac{1}{3}\right)=\left\{\begin{array}{ll}
1 & \text { if } l=3, \\
0 & \text { otherwise },
\end{array} \quad N_{l}(1)= \begin{cases}1 & \text { if } l=4, \\
0 & \text { otherwise } .\end{cases} \right.
\end{align*}
$$

First we consider the case when the node $\overline{\mathbf{x}}_{i}$ coincide with the first node of element $L_{j}$, so when $i=3 j-2$. For this case $\eta=-1$. Introducing relations (18) in (17) we obtain the following expressions of the coefficients:

$$
\begin{align*}
& a_{i j}^{1}=\int_{-1+\varepsilon}^{1} \frac{F_{i j}(\xi,-1)}{(\xi+1) \hat{N}_{i j}(\xi,-1)} J^{j}(\xi) d \xi+\int_{-1}^{1} \hat{N}_{1}(\xi,-1) \frac{F_{i j}(\xi,-1)}{\hat{N}_{i j}(\xi,-1)} J^{j}(\xi) d \xi,  \tag{19}\\
& a_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}(\xi,-1) \frac{F_{i j}(\xi,-1)}{\hat{N}_{i j}(\xi,-1)} J^{j}(\xi) d \xi, \quad k=2,3,4 .
\end{align*}
$$

If the node $\overline{\mathbf{x}}_{i}$ coincides with the second node of element $L_{j}$, so when $i=3 j-1$, we have $\eta=\frac{-1}{3}$, and the following expression for the coefficients:

$$
\begin{align*}
a_{i j}^{k}= & \int_{-1}^{1} \hat{N}_{k}\left(\xi, \frac{-1}{3}\right) \frac{F_{i j}\left(\xi, \frac{-1}{3}\right)}{\hat{N}_{i j}\left(\xi, \frac{-1}{3}\right)} J^{j}(\xi) d \xi, \quad k=1,3,4, \\
a_{i j}^{2}= & \int_{-1}^{-\frac{1}{3}-\varepsilon} \frac{F_{i j}\left(\xi, \frac{-1}{3}\right)}{\left(\xi+\frac{1}{3}\right) \hat{N}_{i j}\left(\xi, \frac{-1}{3}\right)} J^{j}(\xi) d \xi+\int_{-\frac{1}{3}+\varepsilon}^{1} \frac{F_{i j}\left(\xi, \frac{-1}{3}\right)}{\left(\xi+\frac{1}{3}\right) \hat{N}_{i j}\left(\xi, \frac{-1}{3}\right)} J^{j}(\xi) d \xi  \tag{20}\\
& +\int_{-1}^{1} \hat{N}_{2}\left(\xi, \frac{-1}{3}\right) \frac{F_{i j}\left(\xi, \frac{-1}{3}\right)}{\hat{N}_{i j}\left(\xi, \frac{-1}{3}\right)} J^{j}(\xi) d \xi .
\end{align*}
$$

For the third node of $L_{j}$, so when $i=3 j$, for which $\eta=\frac{1}{3}$, similar expressions are found:

$$
\begin{align*}
a_{i j}^{k}= & \int_{-1}^{1} \hat{N}_{k}\left(\xi, \frac{1}{3}\right) \frac{F_{i j}\left(\xi, \frac{1}{3}\right)}{\hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} j^{j}(\xi) d \xi, \quad k=1,2,4, \\
a_{i j}^{3}= & \int_{-1}^{\frac{1}{3}-\varepsilon} \frac{F_{i j}\left(\xi, \frac{1}{3}\right)}{\left(\xi-\frac{1}{3}\right) \hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} J^{j}(\xi) d \xi+\int_{\frac{1}{3}-\varepsilon}^{\frac{1}{3}+\varepsilon} \frac{F_{i j}\left(\xi, \frac{1}{3}\right)}{\left(\xi-\frac{1}{3}\right) \hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} J^{j}(\xi) d \xi  \tag{21}\\
& +\int_{-1}^{1} \hat{N}_{3}\left(\xi, \frac{1}{3}\right) \frac{F_{i j}\left(\xi, \frac{1}{3}\right)}{\hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} J^{j}(\xi) d \xi .
\end{align*}
$$

For $i=3 j+1, \eta=1$, and the coefficients are given by the relations

$$
\begin{align*}
& a_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}(\xi, 1) \frac{F_{i j}(\xi, 1)}{\hat{N}_{i j}(\xi, 1)} J^{j}(\xi) d \xi, \quad k=1,2,3, \\
& a_{i j}^{4}=\int_{-1}^{1-\varepsilon} \frac{F_{i j}(\xi, 1)}{(\xi-1) \hat{N}_{i j}(\xi, 1)} J^{j}(\xi) d \xi+\int_{-1}^{1} \hat{N}_{4}(\xi, 1) \frac{F_{i j}(\xi, 1)}{\hat{N}_{i j}(\xi, 1)} J^{j}(\xi) d \xi . \tag{22}
\end{align*}
$$

Finally, the expressions of all the elements of matrix $\mathbf{A}$ from (8) are evaluated. Denoting by $A A_{i k}, i, k=\overline{1,3 N}$, the elements of $\mathbf{A}$, we have

$$
\begin{align*}
& A A_{i k}= \begin{cases}A_{i k}, & i \neq k, \\
\pi A_{i}+A_{i i}, & i=k,\end{cases} \\
& \text { where } A_{i k}= \begin{cases}a_{i \frac{k+2}{3}}^{1}+a_{i \frac{k-1}{3}}^{4} & \text { if } k \equiv 1(\bmod 3), k=\overline{2,3 N}, \\
a_{i 1}^{1}+a_{i N}^{4} & \text { if } k=1, \\
a_{i \frac{k+1}{2}}^{2} & \text { if } k \equiv 2(\bmod 3), k=\overline{1,3 N}, \\
a_{1 \frac{k}{3}}^{3} & \text { if } k \equiv 0(\bmod 3), k=\overline{1,3 N} .\end{cases} \tag{23}
\end{align*}
$$

The solutions of system (8), namely the nodal values of sources intensity, $f_{1}, f_{2}, \ldots, f_{3 N}$ are used to evaluate the perturbation velocity components.

## 4 The velocity field and the local pressure coefficient

The components of the perturbation velocity on the boundary, $\frac{u}{\beta}, v$, can be evaluated in the same manner as in the case of solving the singular boundary integral equation (1), using the following relations (see [11]), $\overline{\mathbf{x}}_{0} \in C$ :

$$
\begin{align*}
& u\left(\overline{\mathbf{x}}_{0}\right)=-\frac{1}{2} f\left(\overline{\mathbf{x}}_{0}\right) n_{x}^{0}-\frac{1}{2 \pi} \oint_{C} f(\overline{\mathbf{x}}) \frac{x-x_{0}}{\left\|\overline{\mathbf{x}}-\overline{\mathbf{x}}_{0}\right\|^{2}} d s,  \tag{24}\\
& v\left(\overline{\mathbf{x}}_{0}\right)=-\frac{1}{2} f\left(\overline{\mathbf{x}}_{0}\right) n_{y}^{0}-\frac{1}{2 \pi} \oint_{C} f(\overline{\mathbf{x}}) \frac{y-y_{0}}{\left\|\overline{\mathbf{x}}-\overline{\mathbf{x}}_{0}\right\|^{2}} d s .
\end{align*}
$$

After introducing the approximation models (4) into the above relations we get the following expressions:

$$
\begin{align*}
& u\left(\overline{\mathbf{x}}_{i}\right)=-\frac{1}{2} f\left(\overline{\mathbf{x}}_{i}\right) n_{x}^{i}-\frac{1}{2 \pi} \sum_{j=1}^{N} \int_{-1}^{1} \frac{[\mathbf{N}]\left\{\mathbf{x}^{j}\right\}-x_{i}}{\left\|[\mathbf{N}]\left\{\overline{\mathbf{x}}^{j}\right\}-\overline{\mathbf{x}}_{i}\right\|^{2}}[\mathbf{N}]\left\{\mathbf{f}^{j}\right\} J^{j}(\xi) d \xi, \\
& u\left(\overline{\mathbf{x}}_{i}\right)=-\frac{1}{2} f_{i} n_{x}^{i}-\frac{1}{2} \sum_{j=1}^{N}\left(\sum_{l=1}^{4} b_{i j^{l}}^{l} f_{l}\right), \\
& v\left(\overline{\mathbf{x}}_{i}\right)=-\frac{1}{2} f\left(\overline{\mathbf{x}}_{i}\right) n_{y}^{i}-\frac{1}{2 \pi} \sum_{j=1}^{N} \int_{-1}^{1} \frac{[\mathbf{N}]\left\{\mathbf{y}^{j}\right\}-y_{i}}{\left\|[\mathbf{N}]\left\{\overline{\mathbf{x}}^{j}\right\}-\overline{\mathbf{x}}_{i}\right\|^{2}}[\mathbf{N}]\left\{\mathbf{f}^{j}\right\} J^{j}(\xi) d \xi,  \tag{25}\\
& v\left(\overline{\mathbf{x}}_{i}\right)=-\frac{1}{2} f_{i} n_{y}^{i}-\frac{1}{2} \sum_{j=1}^{N}\left(\sum_{l=1}^{4} c_{i j}^{l} f_{l}^{j}\right), \\
& b_{i j}^{l}=\int_{-1}^{1} N_{l}(\xi) \frac{[\mathbf{N}]\left\{\mathbf{x}^{j}\right\}-x_{i}}{\left\|[\mathbf{N}]\left\{\overline{\mathbf{x}}^{j}\right\}-\overline{\mathbf{x}}_{i}\right\|^{2}} j^{j}(\xi) d \xi, \\
& c_{i j}^{l}=\int_{-1}^{1} N_{l}(\xi) \frac{[\mathbf{N}]\left\{\mathbf{x}^{j}\right\}-x_{i}}{\left\|[\mathbf{N}]\left\{\overline{\mathbf{x}}^{j}\right\}-\overline{\mathbf{x}}_{i}\right\|^{2}} J^{j}(\xi) d \xi, \quad l=\overline{1,4}, i=\overline{1,3 N}, j=\overline{1, N} .
\end{align*}
$$

The coefficients resulted from nonsingular integrals have same expressions as in [14], and they can easily be evaluated with a computer code, because they depend only on the nodes coordinates. For the singular ones we deduce their expressions using modified shape functions as in the case of elements of matrix $\mathbf{A}$.

We get the following relations:

$$
\begin{align*}
& b_{i j}^{l}=\int_{-1}^{1} N_{l}(\eta) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) x_{l}^{j}}{(\xi-\eta) \hat{N}_{i j}(\xi, \eta)} j^{j}(\xi) d \xi+\int_{-1}^{1} \hat{N}_{l}(\xi, \eta) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) x_{l}^{j}}{\hat{N}_{i j}(\xi, \eta)} j^{j}(\xi) d \xi,  \tag{26}\\
& c_{i j}^{l}=\int_{-1}^{1} N_{l}(\eta) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) y_{l}^{j}}{(\xi-\eta) \hat{N}_{i j}(\xi, \eta)} j^{j}(\xi) d \xi+\int_{-1}^{1} \hat{N}_{l}(\xi, \eta) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, \eta) y_{l}^{j}}{\hat{N}_{i j}(\xi, \eta)} j^{j}(\xi) d \xi . \tag{27}
\end{align*}
$$

So, for evaluating the singular coefficients we use the following expressions: for $i=3 j-2$, $b_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}(\xi,-1) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi,-1) j_{l}^{j}}{\hat{N}_{i j}(\xi,-1)} J^{j}(\xi) d \xi, k=2,3,4$,

$$
\begin{align*}
b_{i j}^{1}= & \int_{-1+\varepsilon}^{1} \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi,-1) x_{l}^{j}}{(\xi+1) \hat{N}_{i j}(\xi,-1)} j^{j}(\xi) d \xi \\
& +\int_{-1}^{1} \hat{N}_{1}(\xi,-1) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi,-1) x_{l}^{j}}{\hat{N}_{i j}(\xi,-1)} J^{j}(\xi) d \xi \tag{28}
\end{align*}
$$

for $i=3 j-1, b_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}\left(\xi,-\frac{1}{3}\right) \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi,-\frac{1}{3}\right) x_{l}^{j}}{\hat{N}_{i j}\left(\xi,-\frac{1}{3}\right)} j^{j}(\xi) d \xi, k=1,3,4$,

$$
\begin{align*}
b_{i j}^{2}= & \int_{-1}^{-\frac{1}{3}-\varepsilon} \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi,-\frac{1}{3}\right) x_{l}^{j}}{\left(\xi+\frac{1}{3}\right) \hat{N}_{i j}\left(\xi,-\frac{1}{3}\right)} j^{j}(\xi) d \xi+\int_{-\frac{1}{3}+\varepsilon}^{1} \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi,-\frac{1}{3}\right) x_{l}^{j}}{\left(\xi+\frac{1}{3}\right) \hat{N}_{i j}\left(\xi,-\frac{1}{3}\right)} j^{j}(\xi) d \xi \\
& +\int_{-1}^{1} \hat{N}_{2}\left(\xi,-\frac{1}{3}\right) \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi,-\frac{1}{3}\right) x_{l}^{j}}{\hat{N}_{i j}\left(\xi,-\frac{1}{3}\right)} J^{j}(\xi) d \xi, \tag{29}
\end{align*}
$$

for $i=3 j, b_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}\left(\xi, \frac{1}{3}\right) \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi, \frac{1}{3}\right) x_{l}^{j}}{\hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} J^{j}(\xi) d \xi, k=1,2,4$,

$$
\begin{align*}
b_{i j}^{3}= & \int_{-1}^{\frac{1}{3}-\varepsilon} \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi, \frac{1}{3}\right) x_{l}^{j}}{\left(\xi-\frac{1}{3}\right) \hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} J^{j}(\xi) d \xi+\int_{\frac{1}{3}+\varepsilon}^{1} \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi, \frac{1}{3}\right) x_{l}^{j}}{\left(\xi-\frac{1}{3}\right) \hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} j^{j}(\xi) d \xi \\
& +\int_{-1}^{1} \hat{N}_{3}\left(\xi, \frac{1}{3}\right) \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi, \frac{1}{3}\right) x_{l}^{j}}{\hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} J^{j}(\xi) d \xi, \tag{30}
\end{align*}
$$

for $i=3 j+1, b_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}(\xi, 1) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, 1) x_{l}^{j}}{\hat{N}_{i j}(\xi, 1)} J^{j}(\xi) d \xi, k=1,2,3$,

$$
\begin{equation*}
b_{i j}^{4}=\int_{-1}^{1-\varepsilon} \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, 1) x_{l}^{j}}{(\xi-1) \hat{N}_{i j}(\xi, 1)} J^{j}(\xi) d \xi+\int_{-1}^{1} \hat{N}_{4}(\xi, 1) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, 1) x_{l}^{j}}{\hat{N}_{i j}(\xi, 1)} J^{j}(\xi) d \xi \tag{31}
\end{equation*}
$$

We find similar expressions for coefficients from (27), namely for $i=3 j-2$, $c_{i j}^{k}=$ $\int_{-1}^{1} \hat{N}_{k}(\xi,-1) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi,-1) y_{l}^{j}}{\hat{N}_{i j}(\xi,-1)} J^{j}(\xi) d \xi, k=2,3,4$,

$$
\begin{equation*}
c_{i j}^{1}=\int_{-1+\varepsilon}^{1} \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi,-1) y_{l}^{j}}{(\xi+1) \hat{N}_{i j}(\xi,-1)} J^{j}(\xi) d \xi+\int_{-1}^{1} \hat{N}_{1}(\xi,-1) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi,-1) y_{l}^{j}}{\hat{N}_{i j}(\xi,-1)} J^{j}(\xi) d \xi, \tag{32}
\end{equation*}
$$

$$
\begin{align*}
& \text { for } i=3 j-1, c_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}\left(\xi,-\frac{1}{3}\right) \frac{\left.\sum_{l=1}^{4} \hat{N}_{l}(\xi),-\frac{1}{\hat{N}_{i j}}\right) j_{l}^{j}\left(\xi,-\frac{1}{3}\right)}{j}(\xi) d \xi, k=1,3,4 \text {, } \\
& \left.\left.c_{i j}^{2}=\int_{-1}^{-\frac{1}{3}-\varepsilon} \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi,-\frac{1}{3}\right) y_{l}^{j}}{\left(\xi+\frac{1}{3}\right) \hat{N}_{i j}\left(\xi,-\frac{1}{3}\right)}\right)^{j}(\xi) d \xi+\int_{-\frac{1}{3}+\varepsilon}^{1} \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi,-\frac{1}{3}\right) y_{l}^{j}}{\left(\xi+\frac{1}{3}\right) \hat{N}_{i j}\left(\xi,-\frac{1}{3}\right)}\right)^{j}(\xi) d \xi \\
& +\int_{-1}^{1} \hat{N}_{2}\left(\xi,-\frac{1}{3}\right) \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi,-\frac{1}{3}\right) y_{l}^{j}}{\hat{N}_{i j}\left(\xi,-\frac{1}{3}\right)} J^{j}(\xi) d \xi,  \tag{33}\\
& \text { for } i=3 j, c_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}\left(\xi, \frac{1}{3}\right) \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi, \frac{1}{3}\right) j_{l}}{\hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} j(\xi) d \xi, k=1,2,4 \text {, } \\
& c_{i j}^{3}=\int_{-1}^{\frac{1}{3}-\varepsilon} \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi, \frac{1}{3} l_{l}^{j}\right.}{\left(\xi-\frac{1}{3}\right) \hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} j^{j}(\xi) d \xi+\int_{\frac{1}{3}+\varepsilon}^{1} \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi, \frac{1}{3}\right) y_{l}^{j}}{\left(\xi-\frac{1}{3}\right) \hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} j^{j}(\xi) d \xi \\
& +\int_{-1}^{1} \hat{N}_{3}\left(\xi, \frac{1}{3}\right) \frac{\sum_{l=1}^{4} \hat{N}_{l}\left(\xi, \frac{1}{3}\right) y_{l}^{j}}{\hat{N}_{i j}\left(\xi, \frac{1}{3}\right)} J^{j}(\xi) d \xi,  \tag{34}\\
& \text { for } i=3 j+1, c_{i j}^{k}=\int_{-1}^{1} \hat{N}_{k}(\xi, 1) \frac{\sum_{l=1}^{4} \hat{1}_{l}(\xi, 1) j_{l}}{\hat{N}_{i j}(\xi, 1)} J j(\xi) d \xi, k=1,2,3, \\
& c_{i j}^{4}=\int_{-1}^{1-\varepsilon} \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, 1) y_{l}^{j}}{(\xi-1) \hat{N}_{i j}(\xi, 1)} j^{j}(\xi) d \xi+\int_{-1}^{1} \hat{N}_{4}(\xi, 1) \frac{\sum_{l=1}^{4} \hat{N}_{l}(\xi, 1) y_{l}^{j}}{\hat{N}_{i j}(\xi, 1)} J^{j}(\xi) d \xi . \tag{35}
\end{align*}
$$

For $u$ and $v$ on the boundary the following relations hold:

$$
\begin{equation*}
u\left(\overline{\mathbf{x}}_{i}\right)=\sum_{k=1}^{3 N} u_{i k} f_{k}, \quad v\left(\overline{\mathbf{x}}_{i}\right)=\sum_{k=1}^{3 N} v_{i k} f_{k}, \tag{36}
\end{equation*}
$$

where $u_{i k}=-\frac{1}{2} n x^{i} \delta_{k}^{i}-\frac{1}{2 \pi} b b_{i k}, v_{i k}=-\frac{1}{2} n y^{i} \delta_{k}^{i}-\frac{1}{2 \pi} c c_{i k}$;

$$
\begin{align*}
& b b_{i k}= \begin{cases}b_{i k+2}^{1}+b_{i \frac{k-1}{3}}^{4} & \text { if } k \equiv 1(\bmod 3), k=\overline{2,3 N}, \\
b_{i 1}^{1}+b_{i N}^{4} & \text { if } k=1, \\
b_{i \frac{k+1}{2}}^{3} & \text { if } k \equiv 2(\bmod 3), \\
b_{i \frac{k}{3}}^{3} & \text { if } k \equiv 0(\bmod 3),\end{cases}  \tag{37}\\
& c c_{i k}= \begin{cases}c_{i \frac{k+2}{3}}^{1}+c_{i k-1}^{4} & \text { if } k \equiv 1(\bmod 3), k=\overline{2,3 N}, \\
c_{i 1}^{3}+c_{i N}^{4} & \text { if } k=1, \\
c_{i \frac{k+1}{3}}^{c^{k}} & \text { if } k \equiv 2(\bmod 3), \\
c_{i \frac{k}{3}} & \text { if } k \equiv 0(\bmod 3) .\end{cases}
\end{align*}
$$

The nodal values of the velocity components are used to evaluate the pressure coefficient with relation:

$$
\begin{equation*}
c p=\frac{2}{\gamma M^{2}}\left\{\left[1+\frac{M^{2}(\gamma-1)}{2}\left(1-\nu^{2}-\left(1+\frac{u}{\beta}\right)^{2}\right)\right]^{\frac{\gamma}{\gamma-1}}-1\right\}, \quad M \neq 0, \tag{38}
\end{equation*}
$$

where $\gamma$ is a fluid constant, the ratio between the specific heat at constant volume and the specific heat at constant pressure. For the incompressible case, so for $M \rightarrow 0$, we get the following relation: $c p=1-v^{2}-(1+u)^{2}$.

## 5 Numerical results and conclusions

Based on the above approach we have made a computer code in order to obtain the numerical solution of the problem. We have used Mathcad 14 programming tools to do this. Because the best way to validate the computer code is by making an analytical checking, we have considered some particular situations with exact solutions. Comparisons based on graphical representations are made between numerical and exact solutions.

For the incompressible case and a circular obstacle, the solution of the problem can be found in [21]. There we can find the analytical expressions of the components of the dimensionless velocity $(u, v)$ on the boundary, and of the local pressure coefficient, $c p$.

For this case the computer code outputs the numerical and the exact nodal values of the velocity components and of the local pressure coefficient, based on the following input data: the number of nodes used for the boundary discretization and $\varepsilon$ value.
In Figure 1 the comparison between the numerical and the exact nodal values of the velocity component along the $O x$ axis is made in case of considering 30 nodes on the boundary (a), respectively 45 nodes (b), and $\varepsilon=0.01$.
In Figures 2 and 3 the comparisons between the nodal values of the component along the $O y$ axis, and between the nodal values of the local pressure coefficient are performed, for the same values of the mentioned parameters.

Good agreement between the exact and the numerical solutions can be observed, even if we have considered $\varepsilon=0.01$, and only 10 , respectively 15 , boundary elements for the boundary discretization.


Figure 1 The nodal values of the perturbation velocity component along Ox axis - exact (vx) and numerical (Ux) solution. (a) 30 nodes; (b) 45 nodes.


Figure 2 The nodal values of the perturbation velocity component along $O y$ axis - exact (vy) and numerical (Uy) solution. (a) 30 nodes; (b) 45 nodes.


Figure 3 The nodal values of the local pressure coefficient - exact ( $c p$ ) and numerical ( $C p$ ) solution. (a) 30 nodes; (b) 45 nodes.


Figure 4 The errors between the numerical and the exact nodal values of the perturbation velocity component along Ox axis - modified shape functions (Err $\boldsymbol{X}$ ), truncation method (Ert $\boldsymbol{X}$ ). (a) 30 nodes; (b) 45 nodes.

The improvement of the numerical solutions obtained with the method developed in this paper is shown through a comparison between them and those obtained in [14], where cubic boundary elements were also used for the boundary discretization, but the coefficients arising from integrals with singular kernels were evaluated using the truncation


Figure 5 The errors between the numerical and the exact nodal values of the perturbation velocity component along Oy axis - modified shape functions (Err $\boldsymbol{Y}$ ), truncation method (Ert $\boldsymbol{Y}$ ). (a) 30 nodes; (b) 45 nodes.
method. Because the numerical values are very close to the exact one in both cases the comparison is made through the absolute errors that appear.
$\operatorname{Err} X, \operatorname{Err} Y$ denote the absolute errors between the numerical and the exact values of the velocity components along $O x$, respectively $O y$, when the numerical ones are got with the developed method, so using modified shape functions, and analogous notations, $\operatorname{Ert} X$, Ert $Y$, are used when the numerical solutions are obtained using the truncation method.

In Figure 4 comparisons between $\operatorname{Err} X$ and $\operatorname{Ert} X$ are made for the case of 30 nodes on the boundary (a), respectively for 45 nodes (b), and $\varepsilon=0.01$.

In Figure 5 similar comparisons are made for $\operatorname{Err} Y$ and $\operatorname{Ert} Y$.
From these graphics we can see that using modified shape functions for the treatment of singularities leads to better numerical results, the errors being much lower in this case.
The coefficients arising from integrals with singular kernels greatly influence the well behavior of the system the problem is reduced at, and that is why it is very important to choose a suitable technique to evaluate them with great accuracy.

The numerical solution is compared in the present paper with the exact one, in order to show the accuracy of the first one, and then, in order to prove the fact that using modified shape functions for evaluating singular coefficients we obtain a better approximation for the solution, we have compared the numerical results with those obtained when truncation method was used to evaluate the singularities. The comparisons have shown that we
get a good accuracy for the numerical solution in both situations but, when using modified shape functions, the numerical solution was improved, even for the small numbers of boundary elements 10 , respectively 15 , and for $\varepsilon=0.01$.

Implementing an efficient method to evaluate the integrals of singular kernels can lead to numerical solutions of great accuracy, and this paper recommends the techniques based on modified shape functions as useful tools to succeed in this.

## Competing interests

The author declares that she has no competing interests.

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