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# Solvability of some boundary value problems involving $p$ -Laplacian and non-autonomous differential operators

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## Abstract

The paper deals with the existence and non-existence of solutions of the following nonlinear non-autonomous boundary value problem governed by the  $p$ -Laplacian operator:

$$(P) \quad \begin{cases} (h(t, x(t))|x'(t)|^{p-2}x'(t))' = g(t, x(t), x'(t)) & \text{a.e. } t \in \mathbb{R}, \\ x(-\infty) = a, & x(+\infty) = b \end{cases}$$

with  $a < b$ , where  $a$  is a positive, continuous function and  $g$  is a Carathéodory nonlinear function.

We prove an existence result, underlying the relationship between the behavior of  $g(t, x, \cdot)$  as  $y \rightarrow 0$  related to that of  $g(\cdot, x, y)$  and  $h(\cdot, x)$  as  $|t| \rightarrow +\infty$ .

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## 1 Introduction

Differential equations involving the  $p$ -Laplacian operator and its generalization, the so-called  $\Phi$ -Laplacian, have been widely studied due to several applications in various sciences. Indeed, many models in non-Newtonian fluid theory, diffusion of flows in porous media, nonlinear elasticity, and theory of capillary surfaces can be expressed in terms of such differential operators.

The simplest form of a differential equation involving the  $\Phi$ -Laplacian operator is

$$(\Phi(x'))' = g(t, x, x'), \tag{1.1}$$

and it has been studied in many papers [1, 2, 7, 8, 12, 14–16, 23]. We also quote [19] for systems of differential equations, [13] for differential inclusions, [17, 18, 24] for systems of differential inclusions.

More recently, other types of differential operators, governed by an increasing function  $\Phi$ , possibly singular and not necessarily surjective, have been considered. The theory on

this subject can be found in [2] for operators having a bounded domain and in [1] for non-surjective operators.

A different type of generalization consists in dealing with mixed-type operators, that is, equations of type

$$(h(t, x)\Phi(x'))' = g(t, x, x') \quad \text{or} \quad h(t, x)(\Phi(x'))' = g(t, x, x')$$

(see, e.g., [3–6, 9–11, 22]).

In recent papers (see [20, 21]), some existence and non-existence results were proved for the boundary value problem

$$\begin{cases} (h(t, x(t))\Phi(x'(t)))' = g(t, x(t), x'(t)) & \text{a.e. } t \in \mathbb{R}, \\ x(-\infty) = a, \quad x(+\infty) = b, \end{cases}$$

where  $\Phi$  is a general increasing homeomorphism in  $\mathbb{R}$ . The generality of the differential operator  $\Phi$  required a rather strong growth assumption on the right-hand side  $g(t, x, x')$  with respect to  $x'$  (see conditions 3.3 and 3.4 in [20, Theorem 3.1]). For instance, when  $g(t, x, y) = a(t)b(x)c(y)$  and  $\Phi$  has a superlinear growth at infinity, then the condition  $c(x')/|\Phi(x')| \rightarrow 0$  as  $|x'| \rightarrow \infty$  is needed (among others) in order to obtain the existence of solutions (see [20, Corollary 4.13]). So, in the special case of the  $p$ -Laplacian operator, the function  $g(t, x, x')$  has to grow less than  $p - 1$  as  $|x'| \rightarrow +\infty$ .

The aim of the present paper is to show that when dealing with the  $p$ -Laplacian operator, that is, when one has the following equation:

$$(P) \quad \begin{cases} (h(t, x(t))|x'(t)|^{p-2}x'(t))' = g(t, x(t), x'(t)) & \text{a.e. } t \in \mathbb{R}, \\ x(-\infty) = a, \quad x(+\infty) = b \end{cases}$$

the growth assumption on the right-hand side  $g$  considered in [20] can be improved and the class of solvable problems can be widened. More in detail, when  $g(t, x, y) = a(t)b(x)c(y)$ , the assumption  $c(x')/|\Phi(x')| \rightarrow 0$  as  $|x'| \rightarrow \infty$  can be replaced by  $c(y) = O(|y|^p)$  (see condition (3.26)). To our knowledge, the existence result here presented is new also for the classical case  $p = 2$ . For instance, as an application of our results, we have that the differential equation

$$(|t|^n \beta(x)x'(t))' = -t^m g(x)(x'(t))^2,$$

where  $\beta(x), g(x)$  are generic positive continuous functions, admits solutions satisfying  $x(-\infty) = a, x(+\infty) = b$  for every  $a, b$  with  $a < b$ , provided that  $m$  is odd and  $m > 2n + 1$  (see Example 3.7). We underline that the previous equation can not be treated by means of the results in [20], since in this case  $p = 2$  and the growth of  $f$  with respect to  $x'$  is greater than  $p - 1$ .

### 2 Existence and non-existence theorem

In the whole paper we will consider a positive continuous function  $h : \mathbb{R} \times [a, b] \rightarrow \mathbb{R}$  and a Carathéodory function  $g : \mathbb{R}^3 \rightarrow \mathbb{R}$ .

We deal with the following nonlinear differential equation:

$$(h(t, x(t))|x'(t)|^{p-2}x'(t))' = g(t, x(t), x'(t)) \quad \text{a.e. } t \tag{2.1}$$

and we use the following notations:

$$\begin{aligned} m(t) &:= \min_{x \in [a,b]} h(t, x), & M(t) &:= \max_{x \in [a,b]} h(t, x), \\ m^*(t) &:= \min_{(s,x) \in [-t,t] \times [a,b]} h(s, x), & M^*(t) &:= \max_{(s,x) \in [-t,t] \times [a,b]} h(s, x). \end{aligned} \tag{2.2}$$

Of course,  $M^*(t) \geq M(t) \geq m(t) \geq m^*(t) > 0$  for every  $t \in \mathbb{R}$ , with  $\inf_{t \in \mathbb{R}} m(t)$  possibly zero. Our main results are the following general existence and non-existence theorems.

**Theorem 2.1** *Suppose that*

$$g(t, a, 0) \leq 0 \leq g(t, b, 0) \quad \text{for a.e. } t \in \mathbb{R} \tag{2.3}$$

and that there exist constants  $C_1, C_2 > 0$ , a continuous function  $\mu : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ , and a function  $\lambda \in L^q([-C_1, C_1])$  with  $1 \leq q \leq \infty$  such that

$$|g(t, x, y)| \leq \lambda(t)\mu(h(t, x)|y|^{p-1}) \quad \text{for a.e. } |t| \leq C_1, \text{ every } x \in [a, b], |y| \geq C_2, \tag{2.4}$$

$$\int^{+\infty} \frac{\tau^{\frac{q-1}{q(p-1)}}}{\mu(\tau)} d\tau = +\infty \tag{2.5}$$

(with  $\frac{q-1}{q(p-1)} = \frac{1}{p-1}$  if  $q = +\infty$ ).

At last, suppose that there exists a constant  $\gamma > 1$  such that, for every  $C > 0$ , there exists a function  $\Lambda_C \in L^1_{loc}([0, +\infty))$ , null in  $[0, C_1]$  and positive in  $(C_1, +\infty)$ , such that:

$$m(t)^{1-\gamma} \cdot \left( \int_0^t \frac{\Lambda_C(|s|)}{M(s)^\gamma} ds \right)^{-1} \in L^{\frac{1}{(p-1)(\gamma-1)}}(\mathbb{R}) \tag{2.6}$$

and there exists a function  $\eta_C \in L^1(\mathbb{R})$  such that putting

$$N_C(t) := m(t)^{-\frac{1}{p-1}} \left\{ (M^*(C_1)C^{p-1})^{1-\gamma} + (\gamma - 1) \int_0^t \frac{\Lambda_C(|s|)}{M(s)^\gamma} ds \right\}^{-\frac{1}{\gamma-1} \frac{1}{p-1}} \tag{2.7}$$

for every  $x \in [a, b]$  and every  $|y| \leq N_C(t)$ , we have

$$\begin{cases} g(t, x, y) \leq -\Lambda_C(t)|y|^{\gamma(p-1)} \\ g(-t, x, y) \geq \Lambda_C(t)|y|^{\gamma(p-1)} \end{cases} \quad \text{for a.e. } t \geq C_1, \tag{2.8}$$

$$|g(t, x, y)| \leq \eta_C(t) \quad \text{for a.e. } t \in \mathbb{R}. \tag{2.9}$$

Then there exists a function  $x \in C^1(\mathbb{R})$  such that  $t \mapsto h(t, x(t))|x'(t)|^{p-1}x'(t)$  belongs to  $W^{1,1}(\mathbb{R})$  and

$$\begin{cases} (h(t, x(t))|x'(t)|^{p-1}x'(t))' = g(t, x(t), x'(t)), & \text{for a.e. } t \in \mathbb{R}, \\ a \leq x(t) \leq b, & \text{for every } t \in \mathbb{R}, \\ x(-\infty) = a, \quad x(+\infty) = b. \end{cases} \tag{2.10}$$

*Proof* With no restriction we may assume  $C_2 > \frac{1}{2C_1}(b - a)$ . By (2.5) there exists a constant  $C$  such that

$$C > \left(\frac{M^*(C_1)}{m^*(C_1)}\right)^{\frac{1}{p-1}} C_2 \geq C_2 \tag{2.11}$$

and

$$\int_{M^*(C_1)C_2^{p-1}}^{m^*(C_1)C^{p-1}} \frac{\tau^{\frac{q-1}{q(p-1)}}}{\mu(\tau)} d\tau > \|\lambda\|_q [M^*(C_1)^{\frac{1}{p-1}}(b - a)]^{1-\frac{1}{q}}. \tag{2.12}$$

Fix  $n \in \mathbb{N}$ ,  $n > C_1$ , and put  $I_n := [-n, n]$ . Consider the truncation operator  $U : W^{1,1}(I_n) \rightarrow W^{1,1}(I_n)$  defined by

$$U(x) := U_x, \quad \text{where } U_x(t) := \max\{a, \min\{b, x(t)\}\},$$

and for every  $x \in W^{1,1}_{\text{loc}}(\mathbb{R})$ , put

$$V_x(t) := \max\{-N_C(t), \min\{U'_x(t), N_C(t)\}\}.$$

Moreover, for every  $x \in \mathbb{R}$ , put  $w(x) := \max\{x - b, 0\} + \min\{x - a, 0\}$ .

Let us consider the following auxiliary boundary value problem on the compact interval  $I_n$ :

$$(P_n^*) \quad \begin{cases} (h(t, U_x(t))|x'(t)|^{p-2}x'(t))' = g(t, U_x(t), V_x(t)) + \frac{w(x(t))}{|w(x(t))|+1}, & \text{a.e. in } I_n, \\ x(-n) = a, \quad x(n) = b. \end{cases} \tag{2.13}$$

By the same argument developed in the proof of [20, Theorem 3.1], it is possible to prove that problem (2.13) admits a solution  $u_n$  for every  $n > C_1$  such that  $a \leq u_n(t) \leq b$  for all  $t \in I_n$ , so that  $U_{u_n}(t) = u_n(t)$  for every  $t \in I_n$ . Moreover,  $u_n$  is increasing in  $[-n, -C_1]$  and in  $[C_1, n]$  and if  $u'_n(t_0) = 0$  for some  $C_1 < |t_0| < n$ , then  $u'_n(t) = 0$  whenever  $|t| > |t_0|$  (see Steps 1–2 in the proof of [20, Theorem 3.1]).

Now our goal is to prove that  $|u'_n(t)| \leq N_C(t)$  for every  $t \in I_n$ , so that also  $V_{u_n}(t) = u'_n(t)$  in  $I_n$  and consequently  $u_n$  is a solution of equation (2.1) too.

To this aim, put

$$f(t) := h(t, u_n(t))u'_n(t)|u'_n(t)|^{p-2} \quad \text{in } I_n,$$

we claim that

$$|f(t)| \leq m^*(C_1)C^{p-1} \quad \text{for every } t \in [-C_1, C_1] \tag{2.14}$$

implying that  $|u'_n(t)| \leq C$  for every  $t \in [-C_1, C_1]$ .

Indeed, notice that by the Lagrange theorem there exists a point  $\tau_0 \in I_n$  such that

$$|u'_n(\tau_0)| = \frac{1}{2C_1} |u_n(C_1) - u_n(-C_1)| \leq \frac{b-a}{2C_1} < C_2 < C,$$

so, by (2.11), we have

$$|f(\tau_0)| \leq M^*(C_1)C_2^{p-1} < m^*(C_1)C^{p-1}.$$

Assume, by contradiction, the existence of an interval  $(\tau_1, \tau_2) \subset (-C_1, C_1)$  such that  $|f(t)| < m^*(C_1)C^{p-1}$  in  $(\tau_1, \tau_2)$  and  $|f(\tau_1)| = M^*(C_1)C_2^{p-1}$ ,  $|f(\tau_2)| = m^*(C_1)C^{p-1}$  or vice versa.

Then we have  $C_2 \leq u'_n(t) \leq C$  in  $(\tau_1, \tau_2)$  and since  $N_C(t) = C(\frac{M^*(C_1)}{m(t)})^{\frac{1}{p-1}} \geq C$  for every  $t \in (-C_1, C_1)$ , we have  $|u'_n(t)| < N_C(t)$  for every  $t \in (\tau_1, \tau_2)$ . Then, by Step 1, the definition of  $(P_n^*)$ , and assumption (2.4), for a.e.  $t \in (\tau_1, \tau_2)$ , we have

$$|f'(t)| = |g(t, U_{u_n}(t), V_{u_n}(t))| \leq \lambda(t)\mu(|f(t)|).$$

Therefore, by the Hölder inequality we get

$$\begin{aligned} \int_{M^*(C_1)C_2^{p-1}}^{m^*(C_1)C^{p-1}} \frac{\tau^{\frac{q-1}{q(p-1)}}}{\mu(\tau)} d\tau &\leq \int_{\tau_1}^{\tau_2} \frac{|f(t)|^{\frac{q-1}{q(p-1)}}}{\mu(|f(t)|)} |f'(t)| dt \\ &\leq \int_{\tau_1}^{\tau_2} \lambda(t)h(t, u_n(t))^{\frac{q-1}{q(p-1)}} |u_n(t)|^{1-\frac{1}{q}} dt \\ &\leq \|\lambda\|_q M^*(C_1)^{\frac{q-1}{q(p-1)}} \left( \int_{\tau_1}^{\tau_2} |u'_n(t)| dt \right)^{1-\frac{1}{q}} \\ &\leq \|\lambda\|_q \left( M^*(C_1)^{\frac{1}{p-1}} \int_{\tau_1}^{\tau_2} |u'_n(t)| dt \right)^{1-\frac{1}{q}} \\ &\leq \|\lambda\|_q [M^*(C_1)^{\frac{1}{p-1}}(b-a)]^{1-\frac{1}{q}} \end{aligned}$$

in contradiction with (2.12). Thus, claim (2.14) is proved, and consequently we have  $|u'_n(t)| < C \leq N_C(t)$  for every  $t \in [-C_1, C_1]$ .

We now prove that  $u'_n(t) \leq N_C(t)$  for every  $t \in I_n \setminus [-C_1, C_1]$ .

To this aim, let  $\hat{t} := \sup\{t > C_1 : u'_n(\tau) < N_C(\tau) \text{ in } [C_1, t]\}$ . Assume, by contradiction,  $\hat{t} < n$ .

By the definition of  $V_{u_n}$ , we have

$$(h(t, u_n(t))u'_n(t)^{p-1})' = g(t, U_{u_n}(t), V_{u_n}(t)) = g(t, u_n(t), u'_n(t)) \quad \text{a.e. in } [C_1, \hat{t}].$$

Recalling that  $u'_n(t) \geq 0$  in  $[C_1, n]$ , by (2.8) we have

$$(h(t, u_n(t))u'_n(t)^{p-1})' \leq -\Lambda_C(t)u_n(t)^{\gamma(p-1)} \leq -\frac{\Lambda_C(t)}{M(t)^\gamma} [h(t, u_n(t))u'_n(t)^{p-1}]^\gamma$$

for a.e.  $t \in [C_1, \hat{t}]$ . Then

$$\begin{aligned} & \frac{1}{1-\gamma} \{ [h(t, u_n(t))u'_n(t)^{p-1}]^{1-\gamma} - [h(C_1, u_n(C_1))u'_n(C_1)^{p-1}]^{1-\gamma} \} \\ &= \int_{C_1}^t \frac{(h(u_n(s))u'_n(s)^{p-1})^\gamma}{(h(u_n(s))u'_n(s)^{p-1})^\gamma} ds \leq - \int_{C_1}^t \frac{\Lambda_C(s)}{M(s)^\gamma} ds = - \int_0^t \frac{\Lambda_C(s)}{M(s)^\gamma} ds \end{aligned}$$

for every  $t \in [C_1, \bar{t}]$ . Therefore,

$$\begin{aligned} (h(t, u_n(t))u'_n(t)^{p-1})^{1-\gamma} &\geq (h(C_1, u_n(C_1))u'_n(C_1)^{p-1})^{1-\gamma} + (\gamma - 1) \int_0^t \frac{\Lambda_C(s)}{M(s)^\gamma} ds \\ &> (M^*(C_1)C^{p-1})^{1-\gamma} + (\gamma - 1) \int_0^t \frac{\Lambda_C(s)}{M(s)^\gamma} ds \end{aligned}$$

implying that

$$u'_n(t) < \left( \frac{1}{m(t)} \left\{ (M^*(C_1)C^{p-1})^{1-\gamma} + (\gamma - 1) \int_0^t \frac{\Lambda_C(s)}{M(s)^\gamma} ds \right\}^{\frac{1}{1-\gamma}} \right)^{\frac{1}{p-1}} = N_C(t)$$

for every  $t \in [C_1, \hat{t}]$ , a contradiction when  $\hat{t} < n$ . So,  $\hat{t} = n$  and the claim is proved. The same argument works in the interval  $[-n, -C_1]$  too.

Therefore, we have  $|u'_n(t)| \leq N_C(t)$  for every  $t \in [-n, n]$  implying that

$$h(t, u_n(t))|u'_n(t)|^{p-2}u'_n(t) = g(t, u_n(t), u'_n(t)) \quad \text{a.e. in } I_n.$$

Now, following the same argument as in [20, Theorem 3.1], one can show that the sequence  $(\tilde{u}_n)_n$  of the functions  $u_n$  continued in a constant way in the whole  $\mathbb{R}$  converges to a solution  $x$  of problem (2.10), satisfying all the properties stated in the assertion.  $\square$

The main tool in the previous existence theorem is the summability of function  $N_C(t)$  (condition (2.6)) combined with assumption (2.8). Such conditions are not improvable in the sense that if (2.8) is satisfied with the reversed inequality and  $N_C$  is not summable, then problem (P) does not admit solutions, as stated in the following result.

**Theorem 2.2** *Suppose that there exist three constants  $C_1 \geq 0, \rho > 0, \gamma > 1$  and a positive function  $\Lambda \in L^1_{loc}([C_1, +\infty))$  such that one of the following pairs of conditions holds:*

$$g(t, x, y) \geq -\Lambda(t)y^{\gamma(p-1)} \quad \text{for a.e. } t \geq C_1, \text{ every } x \in [a, b], y \in (0, \rho) \tag{2.15}$$

or

$$g(t, x, y) \leq \Lambda(-t)y^{\gamma(p-1)} \quad \text{for a.e. } t \leq -C_1, \text{ every } x \in [a, b], y \in (0, \rho) \tag{2.16}$$

and for every constant  $C$ , the function

$$N_C(t) := \left( \frac{1}{M(t)} \left\{ C + (\gamma - 1) \int_{C_1}^t \frac{\Lambda(s)}{m(s)^\gamma} ds \right\}^{\frac{1}{1-\gamma}} \right)^{\frac{1}{p-1}} \tag{2.17}$$

does not belong to  $L^1([1, +\infty))$ .

Moreover, assume that

$$tg(t, x, y) \leq 0 \quad \text{for a.e. } |t| \geq C_1, \text{ every } (x, y) \in [a, b] \times \mathbb{R}, \tag{2.18}$$

and there exist two constants  $k, C_2 > 0$  such that

$$h(t, x_1) \leq C_2 h(t + \delta, x_2) \quad \text{for every } t > C_1, x_1, x_2 \in [a, b] \text{ and } \delta < k, \tag{2.19}$$

$$h(t + \delta, x_1) \leq C_2 h(t, x_2) \quad \text{for every } t < -C_1, x_1, x_2 \in [a, b] \text{ and } \delta < k. \tag{2.20}$$

Then each possible solution  $x$  of problem (P) is constant in  $[C_1, +\infty)$  (when (2.15) holds) or constant in  $(-\infty, -C_1]$  (when (2.16) holds).

Therefore, if both (2.15) and (2.16) hold and  $C_1 = 0$ , then problem (P) does not admit solutions, that is, there exists no function  $x \in C^1(\mathbb{R})$  such that  $t \mapsto h(t, x(t))|x'(t)|^{p-2}x'(t)$  is almost everywhere differentiable, satisfying the conditions of problem (P).

*Remark 2.1* Of course, (2.19), (2.20) are satisfied (for  $C_1 = 0$ ) when  $h(t, x) = h_1(t)h_2(x)$ , provided that  $h_1(t)$  is decreasing in  $(-\infty, 0)$  and increasing in  $(0, +\infty)$ , or  $h_1$  is uniformly continuous in  $\mathbb{R}$  and  $\inf_{t \in \mathbb{R}} h_1(t) > 0$ , or  $h_1(t) \sim |t|^{-k}$  as  $|t| \rightarrow +\infty$  for some  $k > 0$ , since  $h_2(x) > 0$  on  $[a, b]$ .

### 3 Asymptotic criteria

We now provide some applications for operators and right-hand side having the product structure

$$h(t, x) = h_1(t)h_2(x) \quad \text{and} \quad g(t, x, y) = g_1(t, x)g_2(x, y).$$

We emphasize the link between the local behavior of  $g_2(x, \cdot)$  at  $y = 0$  and of  $g_1(\cdot, x), h_1(\cdot)$  at infinity, which is crucial for the existence or non-existence of solutions.

In what follows we assume that  $h_1, h_2$  are continuous positive functions,  $g_1$  is a Carathéodory function, and  $g_2$  is a continuous function satisfying

$$g_2(x, y) > 0 \quad \text{for every } y \neq 0 \text{ and } x \in [a, b]; \quad g_2(a, 0) = g_2(b, 0) = 0.$$

Put  $\tilde{m} := \min_{x \in [a, b]} h_2(x)$  and  $\tilde{M} := \max_{x \in [a, b]} h_2(x)$ , we have

$$m(t) = \tilde{m}h_1(t) \quad \text{and} \quad M(t) = \tilde{M}h_1(t) \quad \text{for every } t \in \mathbb{R},$$

where recall that  $m(t) := \min_{x \in [a, b]} h(t, x)$  and  $M(t) := \max_{x \in [a, b]} h(t, x)$ .

Moreover, from now on we put

$$m_\infty := \inf_{t \in \mathbb{R}} h_1(t) \geq 0. \tag{3.1}$$

The following existence theorems are application of Theorem 2.1.

**Proposition 3.1** *Suppose that, for some  $C_1 > 0$ , we have*

$$t \cdot g_1(t, x) < 0 \quad \text{for a.e. } t \text{ such that } |t| \geq C_1, \text{ every } x \in [a, b], \tag{3.2}$$

and there exists a function  $\lambda \in L^q_{loc}(\mathbb{R})$ ,  $1 \leq q \leq +\infty$ , such that

$$|g_1(t, x)| \leq \lambda(t) \quad \text{for a.e. } t \in \mathbb{R}, \text{ every } x \in [a, b]. \tag{3.3}$$

Moreover, assume that there exist real constants  $\sigma, \delta$ , and  $\gamma > 1$  satisfying one of the following pairs of conditions:

$$\delta + 1 > \sigma\gamma, \quad (p - 1)(\gamma - 1) < \delta + 1 - \sigma, \tag{3.4}$$

$$\delta + 1 < \sigma\gamma, \quad \sigma > p - 1, \tag{3.5}$$

such that, for every  $x \in [a, b]$ , we have

$$h_1|t|^\sigma \leq h_1(t) \leq h_2|t|^\sigma, \quad \text{a.e. } |t| > C_1, \tag{3.6}$$

$$h_1|t|^\delta \leq |g_1(t, x)| \leq h_2|t|^\delta, \quad \text{a.e. } |t| > C_1, \tag{3.7}$$

$$g_2(x, y) \leq k_2|y|^{\gamma(p-1)} \quad \text{whenever } |y| < \rho, \tag{3.8}$$

$$g_2(x, y) \leq k_2|y|^{p-\frac{1}{q}} \quad \text{whenever } |y| > C_2, \tag{3.9}$$

$$g_2(x, y) \geq k_1|y|^{\gamma(p-1)} \quad \text{for every } y \in \mathbb{R}. \tag{3.10}$$

for certain positive constants  $h_1, h_2, k_1, k_2, \rho, C_2$ .

Then problem (P) admits solutions.

*Proof* It is not restrictive to assume  $C_2 > \max\{C_1, \frac{b-a}{2C_1}\}$ . Put  $\mu(r) := k_2(\frac{r}{m^*(C_1)})^{\frac{qp-1}{q(p-1)}}$  for  $r > 0$  (see (2.2)), from (3.3) and (3.9) the validity of conditions (2.4) and (2.5) follows.

Put  $\Lambda(t) := 0$  for  $0 \leq t \leq C_1$ , and

$$\Lambda(t) := k_1 \min \left\{ \min_{x \in [a, b]} g_1(-t, x), \min_{x \in [a, b]} -g_1(t, x) \right\} \quad \text{for } t \geq C_1.$$

By condition (3.3) we have  $\Lambda \in L^1_{loc}([0, +\infty))$ , and by (3.2) we have that  $\Lambda$  is positive. Observe that by (3.10) it follows that

$$g(t, x, y) = g_1(t, x)g_2(x, y) \leq k_1 g_1(t, x)|y|^{\gamma(p-1)} \leq -\Lambda(t)|y|^{\gamma(p-1)}$$

and

$$g(-t, x, y) = g_1(-t, x)g_2(x, y) \geq k_1 g_1(-t, x)|y|^{\gamma(p-1)} \geq \Lambda(t)|y|^{\gamma(p-1)}$$

for a.e.  $t \geq C_1$ , every  $x \in [a, b]$ , and every  $y \in \mathbb{R}$ . Then condition (2.8) of Theorem 2.1 holds, with  $\Lambda_C(\cdot) := \Lambda(\cdot)$  for every  $C > 0$ .

Now, from (3.7) it follows that  $h_1 k_1 t^\delta \leq \Lambda(t)$  for a.e.  $t \geq C_1$  and by (3.6) we deduce that, for some positive constant  $c_1$ , we have

$$\int_0^t \frac{\Lambda(|s|)}{h_1(s)^\gamma} ds = \int_{C_1}^t \frac{\Lambda(|s|)}{h_1(s)^\gamma} ds \geq c_1 |t|^{\delta-\gamma\sigma+1} \quad \text{for every } t \text{ large enough.} \tag{3.11}$$



Hence, by condition (3.6) we obtain

$$m(t)^{1-\gamma} \left( \int_0^t \frac{\Lambda(|s|)}{h_1(s)^\gamma} ds \right)^{-1} \leq c_2 |t|^{-(\delta+1-\sigma)}$$

for some positive constant  $c_2$ , implying by the second inequality in (3.4) the validity of assumption (2.6). Moreover, the function  $N_C(t)$  defined in (2.7) satisfies

$$N_C(t)^{p-1} \leq c_3 |t|^{\frac{\delta+1-\sigma\gamma}{1-\gamma}-\sigma} = c_3 |t|^{\frac{\delta+1-\sigma}{1-\gamma}} \quad \text{for } t \text{ large enough} \tag{3.12}$$

for some constant  $c_3$ . So, by the first inequality in (3.4) we have  $\lim_{|t| \rightarrow +\infty} N_C(t) = 0$ , and then a constant  $L_C^* > C_1$  exists such that  $N_C(t) \leq \rho$  for every  $|t| \geq L_C^*$ . Let us define  $\hat{C} := \max_{|t| \leq L_C^*} N_C(t)$  and

$$\eta_C(t) := \begin{cases} \max_{x \in [a,b]} |g_1(t, x)| \cdot \max_{(x,y) \in [a,b] \times [-\hat{C}, \hat{C}]} g_2(x, y) & \text{if } |t| \leq L_C^*, \\ h_2 k_2 |t|^\delta N_C(t)^{\gamma(p-1)} & \text{if } |t| > L_C^*. \end{cases}$$

By (3.7) and (3.8), for a.e.  $t \in \mathbb{R}$ , for every  $x \in [a, b]$  and every  $y \in \mathbb{R}$  such that  $|y| \leq N_C(t)$ , we have

$$|g(t, x, y)| = |g_1(t, x)| g_2(x, y) \leq \eta_C(t),$$

so it remains to prove that  $\eta_C \in L^1(\mathbb{R})$ .

By (3.3) and the continuity of the function  $g_2(\cdot, \cdot)$ , we have  $\eta_C \in L^1([-L_C^*, L_C^*])$ . Moreover, when  $|t| > L_C^*$ , by (3.12) we have

$$\eta_C(t) \leq \text{Const. } |t|^{\delta+\gamma \frac{\delta+1-\sigma}{1-\gamma}} = \text{Const. } |t|^{\frac{\delta+\gamma-\sigma\gamma}{1-\gamma}}$$

implying that  $\eta_C(t) \in L^1(\mathbb{R} \setminus [-L_C^*, L_C^*])$  by the first condition in (3.4).

Therefore, we can apply Theorem 2.1 and obtain the assertion of the present result.

The case of (3.5) is similar.

If  $\Lambda$  is the function defined above, by the first inequality in (3.5) we get that the integral function  $t \mapsto \int_0^t \frac{\Lambda(|s|)}{M(s)^\gamma} ds$  is bounded. So, the second condition in (3.5) implies the validity of assumption (2.6). Moreover, if  $\eta_C$  is defined as above, then

$$\eta_C(t) \sim \text{Const. } |t|^\delta \frac{1}{h_1(t)^\gamma} \leq \text{Const. } t^{\delta-\sigma\gamma} \quad \text{as } t \rightarrow +\infty$$

so  $\eta_C$  is summable by condition (3.5) and the proof proceeds as in the first part. □

*Remark 3.1* We underline that conditions (3.9) and (3.10) are compatible with each other for large  $|y|$  only if  $q > 1$  and  $\gamma \leq \frac{p-\frac{1}{q}}{p-1}$ . However, if  $m_\infty > 0$  (see (3.1)), condition (3.10) can be improved requiring that it holds only for  $|y|$  small enough, as the following result states.

**Proposition 3.2** *Let all the assumption of Proposition 3.1 be satisfied, with the exception of (3.10), replaced by*

$$g_2(x, y) \geq k_1 |y|^{\gamma(p-1)} \quad \text{for every } x \in [a, b], |y| < \rho. \tag{3.13}$$

*Moreover, assume that  $m_\infty > 0$ . Then problem (P) admits solutions.*

*Proof* For every fixed  $C > 0$ , let

$$\Gamma_C := \max \left\{ \rho, C \left( \frac{M^*(C_1)}{m_\infty} \right)^{\frac{1}{p-1}} \right\}, \quad \hat{m}_C := \min_{(x,y) \in [a,b] \times [\rho, \Gamma_C]} g_2(x,y),$$

and finally

$$h_C := \min \left\{ k_1, \frac{\hat{m}_C}{\Gamma_C^{\gamma(p-1)}} \right\}.$$

Let us define the function  $\Lambda(t)$  as in the proof of Proposition (3.1), with  $k_1$  replaced by  $h_C$ .

Notice that  $N_C(t) \leq \Gamma_C$  for every  $t \geq C_1$ ; moreover  $g_2(x,y) \geq h_C |y|^{\gamma(p-1)}$  whenever  $|y| \leq \Gamma_C$ . So, condition (2.8) holds whenever  $|y| < \Gamma_C$  and the proof proceeds as that of Proposition 3.1, replacing everywhere  $k_1$  with  $h_C$ . □

We state now two non-existence results, obtained applying Theorem 2.2.

**Proposition 3.3** *Suppose that*

$$t \cdot g_1(t,x) \leq 0 \quad \text{for a.e. } t \in \mathbb{R} \text{ and every } x \in [a,b], \tag{3.14}$$

*and let there exist real constants  $\delta, \gamma > 1, \Lambda > 0$  and a positive function  $\ell(t) \in L^1([0, \Lambda])$  such that*

$$|g_1(t,x)| \leq \lambda_1 |t|^\delta \quad \text{for every } x \in [a,b], \text{ a.e. } |t| > \Lambda, \tag{3.15}$$

$$|g_1(t,x)| \leq \ell(|t|) \quad \text{for a.e. } |t| \leq \Lambda, x \in [a,b], \tag{3.16}$$

$$g_2(x,y) \leq \lambda_2 y^{\gamma(p-1)} \quad \text{for every } x \in [a,b], 0 < y < \rho \tag{3.17}$$

*for some positive constants  $\lambda_1, \lambda_2, \rho$ . Moreover, assume that (3.6) holds for some constants  $h_1, h_2, \sigma$  such that one of the following pairs of conditions is satisfied:*

$$\delta + 1 > \sigma \gamma, \quad (p-1)(\gamma-1) \geq \delta + 1 - \sigma, \tag{3.18}$$

$$\delta + 1 \leq \sigma \gamma, \quad \sigma \leq p-1. \tag{3.19}$$

*At last, suppose that there exist two constants  $\epsilon, C_2 > 0$  such that*

$$h_1(t) \leq C_2 h_1(t+r) \quad \text{for every } t > 0 \text{ and } r < \epsilon \tag{3.20}$$

$$h_1(t+r) \leq C_2 h_1(t) \quad \text{for every } t < 0 \text{ and } r < \epsilon. \tag{3.21}$$

*Then problem (P) does not admit solutions.*

*Proof* Put

$$\Lambda(t) := \begin{cases} \lambda_2 \ell(t) & \text{for } t \in [0, \Lambda], \\ \lambda_1 \lambda_2 t^\delta & \text{for } t > \Lambda \end{cases}$$

we have that  $\Lambda$  is a positive function belonging to  $L^1_{\text{loc}}([0, +\infty))$  and one can easily verify that conditions (3.15), (3.16), and (3.17) ensure the validity of (2.15) and (2.16) with  $C_1 = 0$ . Moreover, by (3.6) and the very definition of  $\Lambda$ , one has

$$\begin{aligned} \rho(t) &:= \int_0^t \frac{\Lambda(\tau)}{m(\tau)^\gamma} \, d\tau \geq \int_\Lambda \frac{\Lambda(\tau)}{m(\tau)^\gamma} \, d\tau = \frac{\lambda_1 \lambda_2}{\tilde{m}^\gamma} \int_\Lambda \frac{\tau^\delta}{h_1(\tau)^\gamma} \, d\tau \\ &\geq \frac{\lambda_1 \lambda_2}{\tilde{m}^\gamma h_1^\gamma} \int_\Lambda \tau^{\delta-\gamma\delta} \, d\tau = \text{Const. } t^{\delta-\sigma\gamma+1} \quad (\text{provided } t \text{ is sufficiently large}). \end{aligned}$$

As a consequence, for every constant  $C$ , we have

$$\begin{aligned} N_C(t) &= \left( \frac{1}{M(t)[C + (\gamma - 1)\rho(t)]^{\frac{1}{\gamma-1}}} \right)^{\frac{1}{p-1}} \\ &\geq \text{Const.} \left( \frac{1}{t^{\sigma + \frac{\delta-\sigma\gamma+1}{\gamma-1}}} \right)^{\frac{1}{p-1}} = \text{Const. } t^{-\frac{\delta+1-\sigma}{(p-1)(\gamma-1)}}, \end{aligned}$$

provided  $t \in (0, +\infty)$  is sufficiently large. At last, the second assumption in (3.18) implies that  $N_C(t)$  is not summable in  $[1, +\infty)$  and the assertion follows as an application of Theorem 2.2 in the case  $C_1 = 0$ .

The case of (3.19) is similar.

By using the same notations, notice that under the first condition in (3.19) the integral function  $\rho(t) = \int_0^t \frac{\Lambda(\tau)}{m(\tau)^\gamma} \, d\tau$  is bounded, hence  $N_C(t)^{p-1} \geq \text{Const. } t^{-\sigma}$ , implying that  $N_C(t) \geq \text{Const. } t^{-\sigma/(p-1)}$ . Therefore  $N_C$  is not summable at infinity owing to the second condition in assumption (3.19), and the assertion follows from Theorem 2.2, applied for  $C_1 = 0$ .  $\square$

As an immediate application of the previous theorems, the following criteria hold.

**Corollary 3.4** *Let  $g(t, x, y) = g_1(t)g_2(x)g_3(y)$ , where  $g_1 \in L^q_{\text{loc}}(\mathbb{R})$  for some  $1 \leq q \leq +\infty$ ,  $g_3$  is continuous in  $\mathbb{R}$ , and  $g_2$  is continuous and positive in  $[a, b]$ .*

*Assume that  $g_3(y) > 0$  for  $y \neq 0$ ;  $t \cdot g_1(t) \leq 0$  for every  $t$  and suppose that there exist constants  $c_1, \dots, c_3 > 0$  such that*

$$h_1(t) \sim c_1 |t|^\sigma \text{ as } |t| \rightarrow +\infty \quad \text{for some } \sigma \in \mathbb{R}, \tag{3.22}$$

$$|g_1(t)| \sim c_2 |t|^\delta \text{ as } |t| \rightarrow +\infty \quad \text{for some } \delta \in \mathbb{R}, \tag{3.23}$$

$$g_3(y) \sim c_3 |y|^\beta \text{ as } y \rightarrow 0 \quad \text{for some } \beta > 0, \tag{3.24}$$

with

$$\delta + 1 > \frac{\sigma\beta}{p-1} \quad \text{and} \quad \beta > p - 1. \tag{3.25}$$

Then, if conditions (3.20), (3.21) hold and  $p \leq \beta + \sigma - \delta$ , (P) has no solution.

Vice versa, if  $p > \beta + \sigma - \delta$  and

$$\limsup_{|y| \rightarrow +\infty} g_3(y) / |y|^{p-\frac{1}{q}} \in [0, +\infty) \tag{3.26}$$

$$g_3(y) \geq k_1|y|^\beta \quad \forall y \in \mathbb{R}, \tag{3.27}$$

then (P) admits solutions.

*Proof* The assertion is an immediate consequence of Propositions 3.1 and 3.3 taking  $\gamma = \beta/(p - 1)$ . □

Taking into account what we have observed in Remark 3.1, the following result holds in the particular case  $m_\infty > 0$ .

**Corollary 3.5** *Let all the assumption of Corollary 3.4 hold, with the exception of (3.27). Then, if  $m_\infty > 0$ , problem (P) admits solutions.*

When assumption (3.25) is not satisfied, we can use the following result, the consequence of Propositions 3.1 and 3.3.

**Corollary 3.6** *Let all the assumptions of Corollary 3.4 be satisfied, with the exception of (3.25), that is, assume that*

$$\delta + 1 < \frac{\sigma\beta}{p - 1}. \tag{3.28}$$

*Then, if conditions (3.20), (3.21) hold and  $\sigma + 1 \leq p < \beta + 1$ , (P) has no solution.*

*Vice versa, if  $p < \sigma + 1$ ,  $p < \beta + 1$ , and we further assume (3.26) and (3.27), then (P) admits solutions.*

At last, a result analogous to Corollary 3.6 holds when condition (3.27) is removed, provided that  $m_\infty > 0$ , as in Corollary 3.5.

*Example 3.7* Let us consider the following differential equation:

$$\left( (1 + |t|^n)\beta(x)|x'(t)|^{p-2}x'(t) \right)' = -t^m g(x)(x'(t))^2,$$

where  $\beta, g$  are generic positive continuous functions. By virtue of Corollary 3.4 taking  $q = \infty, \sigma = n, \delta = m, s = 2$ , with  $m > 2n - 1$ , we deduce that the differential equations admit solutions satisfying  $x(-\infty) = a, x(+\infty) = b$ , for any pair of ordered data  $a, b$ .

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