

RESEARCH

Open Access



Nonexistence results for a time-fractional biharmonic diffusion equation

Mohamed Jleli^{1*} and Bessem Samet¹

*Correspondence: jleli@ksu.edu.sa

¹Department of Mathematics, College of Science, King Saud University, Riyadh 11451, Saudi Arabia

Abstract

We consider weak solutions of the nonlinear time-fractional biharmonic diffusion equation $\partial_t^\alpha u + \partial_t^\beta u + u_{xxxx} = h(t, x)|u|^p$ in $(0, \infty) \times (0, 1)$ subject to the initial conditions $u(0, x) = u_0(x)$, $u_t(0, x) = u_1(x)$ and the Navier boundary conditions $u(t, 1) = u_{xx}(t, 1) = 0$, where $\alpha \in (0, 1)$, $\beta \in (1, 2)$, ∂_t^α (resp. ∂_t^β) is the fractional derivative of order α (resp. β) with respect to the time-variable in the Caputo sense, $p > 1$ and h is a measurable positive weight function. Using nonlinear capacity estimates specifically adapted to the fourth-order differential operator $\frac{\partial^4}{\partial x^4}$, the domain, the initial conditions and the boundary condition, a general nonexistence result is established. Next, some special cases of weight functions h are discussed.

Mathematics Subject Classification: 35A01; 35R11; 26A33

Keywords: Time-fractional biharmonic diffusion equation; Weak solution; Nonexistence; Caputo fractional derivative

1 Introduction

In this paper, we study the nonexistence of weak solutions of the nonlinear time-fractional biharmonic diffusion equation

$$\partial_t^\alpha u + \partial_t^\beta u + u_{xxxx} = h(t, x)|u|^p, \quad t > 0, 0 < x < 1, \quad (1.1)$$

where $u = u(t, x)$, $\alpha \in (0, 1)$, $\beta \in (1, 2)$, ∂_t^α (resp. ∂_t^β) is the fractional derivative of order α (resp. β) with respect to the time-variable in the Caputo sense, $p > 1$ and h is a measurable weight function with $h(t, x) > 0$ almost everywhere in $(0, \infty) \times (0, 1)$. Equation (1.1) is considered subject to the initial conditions

$$u(0, x) = u_0(x), \quad u_t(0, x) = u_1(x), \quad 0 < x < 1 \quad (1.2)$$

and the Navier boundary conditions

$$u(t, 1) = u_{xx}(t, 1) = 0, \quad t > 0, \quad (1.3)$$

where $u_0, u_1 \in L^1_{\text{loc}}((0, 1])$. Namely, our goal is to establish sufficient conditions under which the considered problem admits no weak solution.

© The Author(s) 2024. **Open Access** This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit <http://creativecommons.org/licenses/by/4.0/>.

The topic of time-fractional evolution equations has gained considerable attention in recent decades due to its widespread applications in various fields of science, such as physics, chemistry and biology, see, e.g., [4, 9, 17, 18]. We can find in the literature several studies related to time-fractional evolution equations in both theoretical and numerical directions. In the theoretical point of view, several investigations have been made regarding well-posedness, inverse problems, asymptotic analysis, decay estimates, etc., see, e.g., [1, 8, 11, 15, 20, 23]. For some numerical contributions, we refer to [2, 5, 7].

The issue of nonexistence of solutions to time-fractional evolution equations was initiated by Kirane and his collaborators, see, e.g., Fino and Kirane [6], Kirane and Tatar [16], Kirane and Laskri [13] and Kirane and Malik [14]. Since then, this topic was developed by many authors, see, e.g., [3, 10, 19, 21, 22, 24] and the references therein. In particular, Tatar [22] considered the time-fractional diffusion equation

$$\partial_t^{1+\alpha} u + \partial_t^\beta u - \Delta u = h(t, x)|u|^p, \quad t > 0, x \in \mathbb{R}^N, \tag{1.4}$$

where $\alpha, \beta \in (0, 1), p > 1$ and h satisfies

$$h(R^2 t, R^\beta x) = R^\rho h(t, x)$$

for some $\rho > 0$ and large $R > 0$. Namely, it has been proven that if $u(0, \cdot), u_t(0, \cdot) \geq 0$ and

$$1 < p \leq 1 + \frac{2\beta + \rho}{1 + \beta N - 2\beta},$$

then (1.4) admits no weak solution.

The novelty of this work with respect to the above cited contributions (in particular [22]) lies in the following facts:

- (a) Problem (1.1) is posed in a bounded domain;
- (b) Problem (1.1) is governed by a fourth-order differential operator.

In this paper, our approach is based on nonlinear capacity estimates specifically adapted to the fourth-order differential operator $\frac{\partial^4}{\partial x^4}$, the domain, the initial conditions (1.2) and the boundary condition (1.3).

The rest of the paper is organized as follows. Section 2 is devoted to some preliminaries on fractional calculus. In Sect. 3, we define weak solutions to the considered problem and state our obtained results. In Sect. 4, we establish some useful lemmas. Finally, we prove our obtained results in Sect. 5.

Throughout this paper, we shall use the following notations. By C (or C_i), we mean a positive constant that is independent of the parameters T, R and the solution u . The value of this constant is not important and is not necessarily the same from one line to another. For a positive real number ℓ , the notation $\ell \gg 1$ means that ℓ is sufficiently large.

2 Preliminaries

In this section, we briefly recall some notions and results related to fractional operators and fix some notations. For more details, we refer to [12].

Let $T > 0$. The left-sided and right-sided Riemann–Liouville fractional integrals of order $\gamma > 0$ of $f \in C([0, T])$ are defined respectively by

$$I_0^\gamma f(t) = \frac{1}{\Gamma(\gamma)} \int_0^t (t-s)^{\gamma-1} f(s) ds, \quad 0 < t \leq T$$

and

$$I_T^\gamma f(t) = \frac{1}{\Gamma(\gamma)} \int_t^T (s - t)^{\gamma-1} f(s) ds, \quad 0 \leq t < T,$$

where Γ is the Gamma function. It can be easily seen that

$$\lim_{t \rightarrow 0^+} I_0^\gamma f(t) = \lim_{t \rightarrow T^-} I_T^\gamma f(t) = 0. \tag{2.1}$$

We have the following integration by parts rule.

Lemma 2.1 *Let $\gamma > 0$ and $f, g \in C([0, T])$. We have*

$$\int_0^T g(t) I_0^\gamma f(t) dt = \int_0^T f(t) I_T^\gamma g(t) dt.$$

For $T > 0$ and $\ell \gg 1$, let

$$M(t) = T^{-\ell} (T - t)^\ell, \quad 0 \leq t \leq T. \tag{2.2}$$

For the proof of the following lemma, see [12, Property 2.1, p 71].

Lemma 2.2 *Let $0 < \kappa < 1$. For all $t \in [0, T]$, we have*

$$I_T^\kappa M(t) = \frac{\Gamma(\ell + 1)}{\Gamma(\ell + 1 + \kappa)} T^{-\ell} (T - t)^{\ell + \kappa}, \tag{2.3}$$

$$\frac{d}{dt} I_T^\kappa M(t) = -\frac{\Gamma(\ell + 1)}{\Gamma(\ell + \kappa)} T^{-\ell} (T - t)^{\ell + \kappa - 1}, \tag{2.4}$$

$$\frac{d^2}{dt^2} I_T^\kappa M(t) = \frac{\Gamma(\ell + 1)}{\Gamma(\ell + \kappa - 1)} T^{-\ell} (T - t)^{\ell + \kappa - 2}. \tag{2.5}$$

Let $\gamma \in (n - 1, n)$, where n is positive integer and $f \in C^n([0, T])$. The Caputo fractional derivative of order γ of f is defined by

$$\begin{aligned} {}^C D_0^\gamma f(t) &= I_0^{n-\gamma} \frac{d^n f}{dt^n}(t) \\ &= \frac{1}{\Gamma(n - \gamma)} \int_0^t (t - s)^{n-\gamma-1} \frac{d^n f}{ds^n}(s) ds, \quad 0 < t < T. \end{aligned}$$

Let $F = F(t, x) : [0, T] \times J \rightarrow \mathbb{R}$, where $J \subset \mathbb{R}$. The left-sided and right-sided Riemann–Liouville fractional integrals of order $\gamma > 0$ of F with respect to the time-variable t are defined respectively by

$$\begin{aligned} I_0^\gamma F(t, x) &= I_0^\gamma F(\cdot, x)(t) \\ &= \frac{1}{\Gamma(\gamma)} \int_0^t (t - s)^{\gamma-1} F(s, x) ds \end{aligned}$$

and

$$\begin{aligned}
 I_T^\gamma F(t, x) &= I_T^\gamma F(\cdot, x)(t) \\
 &= \frac{1}{\Gamma(\gamma)} \int_t^T (s - t)^{\gamma-1} F(s, x) ds.
 \end{aligned}$$

If $\gamma \in (n - 1, n)$, where n is positive integer, the Caputo fractional derivative of order γ of F with respect to the time-variable t is denoted by $\partial_t^\gamma F(t, x)$ and is defined by

$$\begin{aligned}
 \partial_t^\gamma F(t, x) &= {}^C D_0^\gamma F(\cdot, x)(t) \\
 &= I_0^{n-\gamma} \frac{\partial^n F}{\partial t^n}(t, x) \\
 &= \frac{1}{\Gamma(n - \gamma)} \int_0^t (t - s)^{n-\gamma-1} \frac{\partial^n F}{\partial s^n}(s, x) ds.
 \end{aligned}$$

3 The results

Let us first define weak solutions to (1.1)–(1.3). For all $T > 0$, let

$$Q_T = [0, T] \times (0, 1].$$

We introduce the set

$$\Phi_T = \{ \varphi \in C^4(Q_T) : \varphi \geq 0, \text{supp}(\varphi) \subset\subset Q_T, \varphi(T, \cdot) \equiv 0, \varphi(\cdot, 1) = \varphi_{xx}(\cdot, 1) \equiv 0 \}.$$

Definition 3.1 We say that $u \in L^p_{\text{loc}}([0, \infty) \times (0, 1], h(t, x) dt dx) \cap L^1_{\text{loc}}([0, \infty) \times (0, 1])$ is a weak solution to (1.1)–(1.3), if

$$\begin{aligned}
 &\int_{Q_T} |u|^p h(t, x) \varphi dx dt + \int_0^1 u_0(x) (I_T^{1-\alpha} \varphi(0, x) - (I_T^{2-\beta} \varphi)_t(0, x)) dx \\
 &\quad + \int_0^1 u_1(x) I_T^{2-\beta} \varphi(0, x) dx \\
 &= \int_{Q_T} u (- (I_T^{1-\alpha} \varphi)_t + (I_T^{2-\beta} \varphi)_{tt} + \varphi_{xxxx}) dx dt
 \end{aligned} \tag{3.1}$$

for every $T > 0$ and $\varphi \in \Phi_T$.

Notice that if u is a classical solution to (1.1)–(1.3), then multiplying (1.1) by $\varphi \in \Phi_T$, integrating by parts, using property (2.1), the integration by parts rule given by Lemma 2.1, (1.2) and (1.3), we obtain (3.1).

We are now in position to state our main results. We first consider the case

$$u_1 \equiv 0, \quad u_0 \in L^1((0, 1)), \quad \int_0^1 u_0(x)(1 - x) dx > 0. \tag{3.2}$$

Theorem 3.1 Let $0 < \alpha < 1 < \beta < 2, p > 1, h(t, x) > 0$ almost everywhere in $(0, \infty) \times (0, 1)$ and $h^{\frac{-1}{p-1}} \in L^1_{\text{loc}}([0, \infty) \times (0, 1])$. Assume that the initial data satisfy (3.2). If there exists

$\theta > 0$ such that

$$\liminf_{T \rightarrow \infty} T^{\alpha-1+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt = 0, \tag{3.3}$$

then (1.1)–(1.2)–(1.3) admits no weak solution.

We next consider the case

$$u_0 \equiv 0, \quad u_1 \in L^1((0, 1)), \quad \int_0^1 u_1(x)(1-x) \, dx > 0. \tag{3.4}$$

Theorem 3.2 *Let $0 < \alpha < 1 < \beta < 2$, $p > 1$, $h(t, x) > 0$ almost everywhere in $(0, \infty) \times (0, 1)$ and $h^{\frac{-1}{p-1}} \in L^1_{loc}([0, \infty) \times (0, 1])$. Assume that the initial data satisfy (3.4). If there exists $\theta > 0$ such that*

$$\liminf_{T \rightarrow \infty} T^{\beta-2+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt = 0, \tag{3.5}$$

then (1.1)–(1.2)–(1.3) admits no weak solution.

We finally consider the case

$$u_i \in L^1((0, 1)), \quad \int_0^1 u_i(x)(1-x) \, dx > 0, \, i = 0, 1. \tag{3.6}$$

Theorem 3.3 *Let $0 < \alpha < 1 < \beta < 2$, $p > 1$, $h(t, x) > 0$ almost everywhere in $(0, \infty) \times (0, 1)$ and $h^{\frac{-1}{p-1}} \in L^1_{loc}([0, \infty) \times (0, 1])$. Assume that the initial data satisfy (3.6). If there exists $\theta > 0$ such that*

$$\liminf_{T \rightarrow \infty} T^{-\max\{1-\alpha, 2-\beta\}+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt = 0, \tag{3.7}$$

then (1.1)–(1.2)–(1.3) admits no weak solution.

We discuss below some particular cases of weight functions h . We first consider the case when $h^{\frac{-1}{p-1}}$ is a L^1 -function.

Corollary 3.4 *Let $0 < \alpha < 1 < \beta < 2$, $p > 1$, $h(t, x) > 0$ almost everywhere in $(0, \infty) \times (0, 1)$ and $h^{\frac{-1}{p-1}} \in L^1([0, \infty) \times (0, 1])$. If the initial data satisfy (3.2) or (3.4) or (3.6), then (1.1)–(1.3) admit no weak solution.*

We now study the case when

$$h(t, x) = t^\rho x^\sigma, \quad t > 0, 0 < x < 1. \tag{3.8}$$

From Theorem 3.1, we deduce the following result.

Corollary 3.5 *Let $0 < \alpha < 1 < \beta < 2$ and h be the function defined by (3.8), where $\rho > 0$ and $\sigma \in \mathbb{R}$. Assume that the initial data satisfy (3.2). If*

$$1 + \rho < p < 1 + \frac{\rho}{\alpha}, \tag{3.9}$$

then (1.1)–(1.3) admit no weak solution.

From Theorem 3.2, we deduce the following result.

Corollary 3.6 *Let $0 < \alpha < 1 < \beta < 2$ and h be the function defined by (3.8), where $\rho > 0$ and $\sigma \in \mathbb{R}$. Assume that the initial data satisfy (3.4). If*

$$1 + \rho < p < 1 + \frac{\rho}{\beta - 1}, \tag{3.10}$$

then (1.1)–(1.3) admit no weak solution.

From Theorem 3.3, we deduce the following result.

Corollary 3.7 *Let $0 < \alpha < 1 < \beta < 2$ and h be the function defined by (3.8), where $\rho > 0$ and $\sigma \in \mathbb{R}$. Assume that the initial data satisfy (3.6). If*

$$1 + \rho < p < 1 + \frac{\rho}{1 - \max\{1 - \alpha, 2 - \beta\}}, \tag{3.11}$$

then (1.1)–(1.3) admit no weak solution.

4 Auxiliary results

Some useful estimates are established in this section. Throughout this section, we have $0 < \alpha < 1 < \beta < 2$, $p > 1$ and $h = h(t, x) > 0$ almost everywhere.

Let us consider a cut-off function $\xi \in C^\infty([0, \infty))$ satisfying

$$0 \leq \xi \leq 1, \quad \xi \equiv 0 \text{ in } \left[0, \frac{1}{2}\right], \xi \equiv 1 \text{ in } [1, \infty).$$

For $\ell, R \gg 1$, let

$$\xi_R(x) = (1 - x)\xi^\ell(Rx), \quad x \in (0, 1],$$

that is,

$$\xi_R(x) = \begin{cases} 0 & \text{if } 0 < x \leq \frac{1}{2R}, \\ (1 - x)\xi^\ell(Rx) & \text{if } \frac{1}{2R} \leq x \leq \frac{1}{R}, \\ 1 - x & \text{if } \frac{1}{R} \leq x \leq 1. \end{cases} \tag{4.1}$$

For $\ell, T, R \gg 1$, let

$$\varphi(t, x) = M(t)\xi_R(x), \quad (t, x) \in Q_T, \tag{4.2}$$

where M is the function defined by (2.2). The following lemma follows immediately from the properties of ξ , (4.1) and (4.2).

Lemma 4.1 *We have $\varphi \in \Phi_T$.*

We now introduce the nonlinear capacity terms

$$\text{Cap}_1(\varphi) = \int_{Q_T} \varphi^{\frac{-1}{p-1}} |(I_T^{1-\alpha} \varphi)_t|^{\frac{p}{p-1}} h^{\frac{-1}{p-1}} dx dt \tag{4.3}$$

$$\text{Cap}_2(\varphi) = \int_{Q_T} \varphi^{\frac{-1}{p-1}} |(I_T^{2-\beta} \varphi)_{tt}|^{\frac{p}{p-1}} h^{\frac{-1}{p-1}} dx dt, \tag{4.4}$$

$$\text{Cap}_3(\varphi) = \int_{Q_T} \varphi^{\frac{-1}{p-1}} |\varphi_{xxxx}|^{\frac{p}{p-1}} h^{\frac{-1}{p-1}} dx dt. \tag{4.5}$$

Lemma 4.2 *Let $h^{\frac{-1}{p-1}} \in L^1_{\text{loc}}([0, \infty) \times (0, 1])$. We have*

$$\text{Cap}_1(\varphi) \leq CT^{\frac{-\alpha p}{p-1}} \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt. \tag{4.6}$$

Proof By (2.2), (2.4) (with $\kappa = 1 - \alpha$) and (4.2), for all $(t, x) \in Q_T$, we have

$$\begin{aligned} \varphi^{\frac{-1}{p-1}} |(I_T^{1-\alpha} \varphi)_t|^{\frac{p}{p-1}} h^{\frac{-1}{p-1}} &= M^{\frac{-1}{p-1}}(t) \xi_R^{\frac{-1}{p-1}}(x) \xi_R^{\frac{p}{p-1}}(x) \left| \frac{dI_T^{1-\alpha} M}{dt} \right|^{\frac{p}{p-1}} h^{\frac{-1}{p-1}}(t, x) \\ &= \xi_R(x) M^{\frac{-1}{p-1}}(t) \left| \frac{dI_T^{1-\alpha} M}{dt} \right|^{\frac{p}{p-1}} h^{\frac{-1}{p-1}}(t, x) \\ &= C \xi_R(x) [T^{-\ell} (T-t)^\ell]^{\frac{-1}{p-1}} [T^{-\ell} (T-t)^{\ell-\alpha}]^{\frac{p}{p-1}} h^{\frac{-1}{p-1}}(t, x) \\ &= CT^{-\ell} \xi_R(x) (T-t)^{\ell-\frac{\alpha p}{p-1}} h^{\frac{-1}{p-1}}(t, x). \end{aligned}$$

Integrating over Q_T , we get by the properties of ξ , (4.1) and (4.3) that

$$\begin{aligned} \text{Cap}_1(\varphi) &\leq CT^{-\ell} \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 \xi_R(x) (T-t)^{\ell-\frac{\alpha p}{p-1}} h^{\frac{-1}{p-1}}(t, x) dx dt \\ &\leq CT^{-\ell} \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 (T-t)^{\ell-\frac{\alpha p}{p-1}} h^{\frac{-1}{p-1}}(t, x) dx dt \\ &\leq CT^{\frac{-\alpha p}{p-1}} \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt, \end{aligned}$$

which proves (4.6). □

Similarly, using (2.2), (2.5) (with $\kappa = 2 - \beta$), (4.2) and (4.4), we obtain the following estimate.

Lemma 4.3 *Let $h^{\frac{-1}{p-1}} \in L^1_{\text{loc}}([0, \infty) \times (0, 1])$. We have*

$$\text{Cap}_2(\varphi) \leq CT^{\frac{-\beta p}{p-1}} \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt. \tag{4.7}$$

Lemma 4.4 *Let $h^{\frac{-1}{p-1}} \in L^1_{\text{loc}}([0, \infty) \times (0, 1])$. We have*

$$\text{Cap}_3(\varphi) \leq CR^{\frac{4p}{p-1}} \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt. \tag{4.8}$$

Proof By (2.2) and (4.2), for all $(t, x) \in Q_T$, we have

$$\varphi^{\frac{-1}{p-1}} |\varphi_{xxxx}|^{\frac{p}{p-1}} h^{\frac{-1}{p-1}} = T^{-\ell} (T-t)^{\ell} \xi_R^{\frac{-1}{p-1}}(x) \left| \frac{d^4 \xi_R}{dx^4} \right|^{\frac{p}{p-1}} h^{\frac{-1}{p-1}}(t, x). \tag{4.9}$$

On the other hand, for all $x \in (0, 1)$, we have by (4.1) that

$$\begin{aligned} \frac{d^4 \xi_R}{dx^4}(x) &= \frac{d^4}{dx^4} [(1-x)\xi^{\ell}(Rx)] \\ &= \frac{d^2}{dx^2} \left(\frac{d^2}{dx^2} [(1-x)\xi^{\ell}(Rx)] \right) \\ &= \frac{d^2}{dx^2} \left((1-x) \frac{d^2}{dx^2} [\xi^{\ell}(Rx)] - 2 \frac{d}{dx} [\xi^{\ell}(Rx)] \right) \\ &= (1-x) \frac{d^4}{dx^4} [\xi^{\ell}(Rx)] - 4 \frac{d^3}{dx^3} [\xi^{\ell}(Rx)], \end{aligned}$$

which implies by (4.1) that (recall that $0 \leq \xi \leq 1$)

$$\text{supp} \left(\frac{d^4 \xi_R}{dx^4} \right) \subset \left[\frac{1}{2R}, \frac{1}{R} \right] \tag{4.10}$$

and for all $x \in \text{supp}(\frac{d^4 \xi_R}{dx^4})$,

$$\begin{aligned} \left| \frac{d^4 \xi_R}{dx^4} \right| &\leq C \left((1-x) \left| \frac{d^4}{dx^4} [\xi^{\ell}(Rx)] \right| + \left| \frac{d^3}{dx^3} [\xi^{\ell}(Rx)] \right| \right) \\ &\leq C (R^4 \xi^{\ell-4}(Rx) + R^3 \xi^{\ell-3}(Rx)) \\ &\leq CR^4 \xi^{\ell-4}(Rx). \end{aligned} \tag{4.11}$$

Then, from (4.5), (4.9), (4.10) and (4.11), we deduce that

$$\begin{aligned} \text{Cap}_3(\varphi) &\leq CR^{\frac{4p}{p-1}} T^{-\ell} \int_{t=0}^T \int_{x=\frac{1}{2R}}^{\frac{1}{R}} (T-t)^{\ell} \xi^{\ell-\frac{4p}{p-1}}(Rx) h^{\frac{-1}{p-1}}(t, x) dx dt \\ &\leq CR^{\frac{4p}{p-1}} \int_{t=0}^T \int_{x=\frac{1}{2R}}^{\frac{1}{R}} h^{\frac{-1}{p-1}}(t, x) dx dt, \end{aligned}$$

which proves (4.8). □

5 Proofs of the obtained results

This section is devoted to the proofs of Theorems 3.1, 3.2, 3.3 and Corollaries 3.4, 3.5, 3.6 and 3.7.

Proof of Theorem 3.1 Let us suppose that

$$u \in L^p_{\text{loc}}([0, \infty) \times (0, 1], h(t, x) dt dx) \cap L^1_{\text{loc}}([0, \infty) \times (0, 1])$$

is a weak solution to (1.1)–(1.3). By Lemma 4.1 and (3.1), for all $\ell, T, R \gg 1$, we have

$$\begin{aligned} & \int_{Q_T} |u|^p h(t, x) \varphi \, dx \, dt + \int_0^1 u_0(x) (I_T^{1-\alpha} \varphi(0, x) - (I_T^{2-\beta} \varphi)_t(0, x)) \, dx \\ & \quad + \int_0^1 u_1(x) I_T^{2-\beta} \varphi(0, x) \, dx \\ & \leq \int_{Q_T} |u| (|(I_T^{1-\alpha} \varphi)_t| + |(I_T^{2-\beta} \varphi)_{tt}| + |\varphi_{xxxx}|) \, dx \, dt, \end{aligned} \tag{5.1}$$

where φ is the function defined by (4.2). On the other hand, by Young’s inequality, we have

$$\begin{aligned} \int_{Q_T} |u| |(I_T^{1-\alpha} \varphi)_t| \, dx \, dt &= \int_{Q_T} (|u| h^{\frac{1}{p}} \varphi^{\frac{1}{p}}) (\varphi^{-\frac{1}{p}} |(I_T^{1-\alpha} \varphi)_t| h^{\frac{1}{p}}) \, dx \, dt \\ &\leq \frac{1}{3} \int_{Q_T} |u|^p h(t, x) \varphi \, dx \, dt + C \text{Cap}_1(\varphi), \end{aligned} \tag{5.2}$$

where $\text{Cap}_1(\varphi)$ is the integral term given by (4.3). Similarly, we have

$$\int_{Q_T} |u| |(I_T^{2-\beta} \varphi)_{tt}| \, dx \, dt \leq \frac{1}{3} \int_{Q_T} |u|^p h(t, x) \varphi \, dx \, dt + C \text{Cap}_2(\varphi) \tag{5.3}$$

and

$$\int_{Q_T} |u| |\varphi_{xxxx}| \, dx \, dt \leq \frac{1}{3} \int_{Q_T} |u|^p h(t, x) \varphi \, dx \, dt + C \text{Cap}_3(\varphi), \tag{5.4}$$

where $\text{Cap}_i(\varphi)$, $i = 2, 3$, are given by (4.4) and (4.5). In view of (5.1), (5.2), (5.3) and (5.4), we get

$$\begin{aligned} & \int_0^1 u_0(x) (I_T^{1-\alpha} \varphi(0, x) - (I_T^{2-\beta} \varphi)_t(0, x)) \, dx + \int_0^1 u_1(x) I_T^{2-\beta} \varphi(0, x) \, dx \\ & \leq C \sum_{i=1}^3 \text{Cap}_i(\varphi). \end{aligned} \tag{5.5}$$

On the other hand, by (4.2), (2.3) (with $\kappa \in \{1 - \alpha, 2 - \beta\}$) and (2.4) (with $\kappa = 2 - \beta$), for all $x \in (0, 1)$, we have

$$\begin{aligned} I_T^{1-\alpha} \varphi(0, x) &= C_1 T^{1-\alpha} (1-x) \xi^\ell(Rx), \\ (I_T^{2-\beta} \varphi)_t(0, x) &= -C_2 T^{1-\beta} (1-x) \xi^\ell(Rx), \\ I_T^{2-\beta} \varphi(0, x) &= C_3 T^{2-\beta} (1-x) \xi^\ell(Rx). \end{aligned}$$

Then, it holds that

$$\begin{aligned} & \int_0^1 u_0(x) (I_T^{1-\alpha} \varphi(0, x) - (I_T^{2-\beta} \varphi)_t(0, x)) \, dx + \int_0^1 u_1(x) I_T^{2-\beta} \varphi(0, x) \, dx \\ & = (C_1 T^{1-\alpha} + C_2 T^{1-\beta}) \int_0^1 u_0(x) (1-x) \xi^\ell(Rx) \, dx \end{aligned} \tag{5.6}$$

$$+ C_3 T^{2-\beta} \int_0^1 u_1(x)(1-x)\xi^\ell(Rx) dx.$$

Since $u_1 \equiv 0$, (5.6) reduces to

$$\begin{aligned} & \int_0^1 u_0(x)(I_T^{1-\alpha} \varphi(0,x) - (I_T^{2-\beta} \varphi)_t(0,x)) dx + \int_0^1 u_1(x)I_T^{2-\beta} \varphi(0,x) dx \\ &= (C_1 T^{1-\alpha} + C_2 T^{1-\beta}) \int_0^1 u_0(x)(1-x)\xi^\ell(Rx) dx. \end{aligned} \tag{5.7}$$

Since $u_0 \in L^1((0,1))$, the properties of ξ and the dominated convergence theorem give us that

$$\lim_{R \rightarrow \infty} \int_0^1 u_0(x)(1-x)\xi^\ell(Rx) dx = \int_0^1 u_0(x)(1-x) dx.$$

Furthermore, the positivity of $\int_0^1 u_0(x)(1-x) dx$ (by (3.2)) and the definition of the limit imply that for $R \gg 1$,

$$\int_0^1 u_0(x)(1-x)\xi^\ell(Rx) dx \geq \frac{1}{2} \int_0^1 u_0(x)(1-x) dx,$$

which yields (for $T \gg 1$)

$$(C_1 T^{1-\alpha} + C_2 T^{1-\beta}) \int_0^1 u_0(x)(1-x)\xi^\ell(Rx) dx \geq CT^{1-\alpha} \int_0^1 u_0(x)(1-x) dx. \tag{5.8}$$

Now, it follows from (5.5), (5.7), (5.8), Lemmas 4.2, 4.3 and 4.4 that

$$\begin{aligned} T^{1-\alpha} \int_0^1 u_0(x)(1-x) dx &\leq C(T^{\frac{-\alpha p}{p-1}} + T^{\frac{-\beta p}{p-1}} + R^{\frac{4p}{p-1}}) \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t,x) dx dt \\ &\leq C(T^{\frac{-\alpha p}{p-1}} + R^{\frac{4p}{p-1}}) \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t,x) dx dt, \end{aligned}$$

that is,

$$\int_0^1 u_0(x)(1-x) dx \leq C(T^{-(\frac{\alpha}{p-1}+1)} + T^{\alpha-1}R^{\frac{4p}{p-1}}) \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t,x) dx dt. \tag{5.9}$$

We now take $2R = T^\theta$, where $\theta > 0$, and (5.9) reduces to

$$\begin{aligned} \int_0^1 u_0(x)(1-x) dx &\leq C(T^{-(\frac{\alpha}{p-1}+1)} + T^{\alpha-1+\frac{4\theta p}{p-1}}) \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t,x) dx dt \\ &= C(T^{-(\frac{\alpha}{p-1}+\alpha+\frac{4\theta p}{p-1})} + 1) T^{\alpha-1+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t,x) dx dt, \end{aligned}$$

which implies that

$$\int_0^1 u_0(x)(1-x) dx \leq CT^{\alpha-1+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t,x) dx dt. \tag{5.10}$$

Hence, if (3.3) is satisfied for some $\theta > 0$, then passing to the infimum limit as $T \rightarrow \infty$ in (5.10), we obtain $\int_0^1 u_0(x)(1-x) dx \leq 0$, which contradicts (3.2). This completes the proof of Theorem 3.1. \square

Proof of Theorem 3.2 We also use the contradiction argument supposing that u is a weak solution to (1.1)–(1.3). Following exactly the first steps of the proof of Theorem 3.1, we obtain (5.5) and (5.6). Since $u_0 \equiv 0$, (5.6) reduces to

$$\begin{aligned} & \int_0^1 u_0(x)(I_T^{1-\alpha} \varphi(0, x) - (I_T^{2-\beta} \varphi)_t(0, x)) dx + \int_0^1 u_1(x) I_T^{2-\beta} \varphi(0, x) dx \\ &= C_3 T^{2-\beta} \int_0^1 u_1(x)(1-x) \xi^\ell(Rx) dx. \end{aligned} \tag{5.11}$$

As in the proof of Theorem 3.1, by (3.4), the properties of ξ and the dominated convergence theorem, we have

$$\lim_{R \rightarrow \infty} \int_0^1 u_1(x)(1-x) \xi^\ell(Rx) dx = \int_0^1 u_1(x)(1-x) dx > 0,$$

which implies that for $R \gg 1$,

$$\int_0^1 u_1(x)(1-x) \xi^\ell(Rx) dx \geq \frac{1}{2} \int_0^1 u_1(x)(1-x) dx. \tag{5.12}$$

Now, using (5.5), (5.11), (5.12), Lemmas 4.2, 4.3 and 4.4, we get

$$T^{2-\beta} \int_0^1 u_1(x)(1-x) dx \leq C(T^{\frac{-\alpha p}{p-1}} + R^{\frac{4p}{p-1}}) \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt,$$

that is,

$$\int_0^1 u_1(x)(1-x) dx \leq C(T^{\beta-2-\frac{\alpha p}{p-1}} + T^{\beta-2} R^{\frac{4p}{p-1}}) \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt. \tag{5.13}$$

We now take $2R = T^\theta$, where $\theta > 0$, and (5.13) reduces to

$$\begin{aligned} \int_0^1 u_1(x)(1-x) dx &\leq C(T^{\beta-2-\frac{\alpha p}{p-1}} + T^{\beta-2+\frac{4\theta p}{p-1}}) \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt \\ &= C(T^{-(\frac{\alpha p}{p-1} + \frac{4\theta p}{p-1})} + 1) T^{\beta-2+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt, \end{aligned}$$

which implies that

$$\int_0^1 u_1(x)(1-x) dx \leq C T^{\beta-2+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt. \tag{5.14}$$

Hence, if (3.5) is satisfied for some $\theta > 0$, then passing to the infimum limit as $T \rightarrow \infty$ in (5.14), we obtain $\int_0^1 u_1(x)(1-x) dx \leq 0$, which contradicts (3.4). This completes the proof of Theorem 3.2. \square

Proof of Theorem 3.3 Assuming that u is a weak solution to (1.1)–(1.3) and following exactly the first steps of the proof of Theorem 3.1, we obtain (5.5) and (5.6). On the other hand, by (3.6), the properties of ξ and the dominated convergence theorem, for all $i = 0, 1$, we get

$$\lim_{R \rightarrow \infty} \int_0^1 u_i(x)(1-x)\xi^\ell(Rx) dx = \int_0^1 u_i(x)(1-x) dx > 0,$$

which yields (for $T, R \gg 1$)

$$\begin{aligned} & (C_1 T^{1-\alpha} + C_2 T^{1-\beta}) \int_0^1 u_0(x)(1-x)\xi^\ell(Rx) dx + C_3 T^{2-\beta} \int_0^1 u_1(x)(1-x)\xi^\ell(Rx) dx \\ & \geq C \left(T^{1-\beta} \int_0^1 u_0(x)(1-x) dx + T^{2-\beta} \int_0^1 u_1(x)(1-x) dx \right) \\ & \geq CT^{\max\{1-\alpha, 2-\beta\}} \int_0^1 (u_0(x) + u_1(x))(1-x) dx. \end{aligned} \tag{5.15}$$

Then, by (5.5), (5.6), (5.15), Lemmas 4.2, 4.3 and 4.4, we obtain

$$\begin{aligned} & T^{\max\{1-\alpha, 2-\beta\}} \int_0^1 (u_0(x) + u_1(x))(1-x) dx \\ & \leq C \left(T^{\frac{-\alpha p}{p-1}} + T^{\frac{-\beta p}{p-1}} + R^{\frac{4p}{p-1}} \right) \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt \\ & \leq C \left(T^{\frac{-\alpha p}{p-1}} + R^{\frac{4p}{p-1}} \right) \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt, \end{aligned}$$

that is,

$$\begin{aligned} & \int_0^1 (u_0(x) + u_1(x))(1-x) dx \\ & \leq C \left(T^{-\max\{1-\alpha, 2-\beta\} - \frac{\alpha p}{p-1}} + T^{-\max\{1-\alpha, 2-\beta\}} R^{\frac{4p}{p-1}} \right) \int_{t=0}^T \int_{x=\frac{1}{2R}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt. \end{aligned} \tag{5.16}$$

Taking $2R = T^\theta$, where $\theta > 0$, (5.16) reduces to

$$\begin{aligned} & \int_0^1 (u_0(x) + u_1(x))(1-x) dx \\ & \leq C \left(T^{-\max\{1-\alpha, 2-\beta\} - \frac{\alpha p}{p-1}} + T^{-\max\{1-\alpha, 2-\beta\} + \frac{4\theta p}{p-1}} \right) \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt \\ & = C \left(T^{-\left(\frac{\alpha p}{p-1} + \frac{4\theta p}{p-1}\right)} + 1 \right) T^{-\max\{1-\alpha, 2-\beta\} + \frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt, \end{aligned}$$

which yields

$$\int_0^1 (u_0(x) + u_1(x))(1-x) dx \leq CT^{-\max\{1-\alpha, 2-\beta\} + \frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T^{-\theta}}^1 h^{\frac{-1}{p-1}}(t, x) dx dt. \tag{5.17}$$

Hence, if (3.7) is satisfied for some $\theta > 0$, then passing to the infimum limit as $T \rightarrow \infty$ in (5.17), we obtain $\int_0^1 (u_0(x) + u_1(x))(1 - x) dx \leq 0$, which contradicts (3.6). This completes the proof of Theorem 3.3. \square

Proof of Corollary 3.4 If $h^{\frac{-1}{p-1}} \in L^1([0, \infty) \times (0, 1))$, then for all $\theta > 0$, we have

$$\lim_{T \rightarrow \infty} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) dx dt = \int_{t=0}^{\infty} \int_{x=0}^1 h^{\frac{-1}{p-1}}(t, x) dx dt \in (0, \infty).$$

Then, for $T \gg 1$,

$$0 < \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) dx dt \leq C. \tag{5.18}$$

(i) If the initial data satisfy (3.2), then for all $\theta > 0$, we have by (5.18) that

$$T^{\alpha-1+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) dx dt \leq CT^{\alpha-1+\frac{4\theta p}{p-1}}. \tag{5.19}$$

In particular, for

$$0 < \theta < \frac{(p-1)(1-\alpha)}{4p},$$

we have $\alpha - 1 + \frac{4\theta p}{p-1} < 0$, which implies by (5.19) that

$$\lim_{T \rightarrow \infty} T^{\alpha-1+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) dx dt = 0.$$

Then Theorem 3.1 applies.

(ii) If the initial data satisfy (3.4), then for all $\theta > 0$, we have by (5.18) that

$$T^{\beta-2+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) dx dt \leq CT^{\beta-2+\frac{4\theta p}{p-1}}. \tag{5.20}$$

In particular, for

$$0 < \theta < \frac{(p-1)(2-\beta)}{4p},$$

we have $\beta - 2 + \frac{4\theta p}{p-1} < 0$, which implies by (5.20) that

$$\lim_{T \rightarrow \infty} T^{\beta-2+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) dx dt = 0.$$

Then Theorem 3.2 applies.

(iii) If the initial data satisfy (3.6), then for all $\theta > 0$, we have by (5.18) that

$$T^{-\max\{1-\alpha, 2-\beta\}+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) dx dt \leq CT^{-\max\{1-\alpha, 2-\beta\}+\frac{4\theta p}{p-1}}. \tag{5.21}$$

In particular, for

$$0 < \theta < \frac{(p-1) \max\{1-\alpha, 2-\beta\}}{4p},$$

we have $-\max\{1-\alpha, 2-\beta\} + \frac{4\theta p}{p-1} < 0$, which implies by (5.21) that

$$\lim_{T \rightarrow \infty} T^{-\max\{1-\alpha, 2-\beta\} + \frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt = 0.$$

Then Theorem 3.3 applies. This completes the proof of Corollary 3.4. □

Proof of Corollary 3.5 For all $\theta > 0$, we have (since $p > 1 + \rho$ by (3.9))

$$\begin{aligned} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt &= \int_{t=0}^T \int_{x=T-\theta}^1 t^{\frac{-\rho}{p-1}} x^{\frac{-\sigma}{p-1}} \, dx \, dt \\ &= CT^{1-\frac{\rho}{p-1}} \int_{T-\theta}^1 x^{\frac{-\sigma}{p-1}} \, dx. \end{aligned} \tag{5.22}$$

On the other hand, we have

$$\int_{T-\theta}^1 x^{\frac{-\sigma}{p-1}} \, dx \leq \begin{cases} C & \text{if } 1 - \frac{\sigma}{p-1} > 0, \\ C \ln T & \text{if } 1 - \frac{\sigma}{p-1} = 0, \\ CT^{-\theta(1-\frac{\sigma}{p-1})} & \text{if } 1 - \frac{\sigma}{p-1} < 0, \end{cases}$$

which implies that

$$\int_{T-\theta}^1 x^{\frac{-\sigma}{p-1}} \, dx \leq C(\ln T + T^{-\theta(1-\frac{\sigma}{p-1})}). \tag{5.23}$$

Then, (5.22) and (5.23) yield

$$T^{\alpha-1 + \frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt \leq C(T^{\gamma_1(\theta)} \ln T + T^{\gamma_2(\theta)}), \tag{5.24}$$

where

$$\begin{aligned} \gamma_1(\theta) &= \frac{\alpha(p-1) - \rho + 4\theta p}{p-1}, \\ \gamma_2(\theta) &= \frac{\alpha(p-1) - \rho + \theta(3p + \sigma + 1)}{p-1}. \end{aligned}$$

We now take θ so that

$$\begin{cases} 0 < \theta < \frac{\rho - \alpha(p-1)}{4p}, \\ (3p + \sigma + 1)\theta < \rho - \alpha(p-1). \end{cases} \tag{5.25}$$

Notice that due to (3.9), the set of θ satisfying (5.25) is nonempty. Namely, we know from (3.9) that $\rho - \alpha(p - 1) > 0$. So, if $3p + \sigma + 1 \leq 0$, then for all

$$0 < \theta < \frac{\rho - \alpha(p - 1)}{4p},$$

(5.25) is satisfied. If $3p + \sigma + 1 > 0$, then for all

$$0 < \theta < \min \left\{ \frac{\rho - \alpha(p - 1)}{4p}, \frac{\rho - \alpha(p - 1)}{3p + \sigma + 1} \right\},$$

(5.25) is satisfied. Remark also that by (5.25), we have $\gamma_i(\theta) < 0$ for all $i = 1, 2$. Then, passing to the limit as $T \rightarrow \infty$ in (5.24), we get

$$\lim_{T \rightarrow \infty} T^{\alpha-1+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt = 0,$$

so Theorem 3.1 applies. This completes the proof of Corollary 3.5. □

Proof of Corollary 3.6 Using (5.22) and (5.23), for all $\theta > 0$, we get

$$T^{\beta-2+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt \leq C(T^{\mu_1(\theta)} \ln T + T^{\mu_2(\theta)}), \tag{5.26}$$

where

$$\begin{aligned} \mu_1(\theta) &= \frac{(\beta - 1)(p - 1) - \rho + 4\theta p}{p - 1}, \\ \mu_2(\theta) &= \frac{(\beta - 1)(p - 1) - \rho + \theta(3p + \sigma + 1)}{p - 1}. \end{aligned}$$

We now take θ so that

$$\begin{cases} 0 < \theta < \frac{\rho - (\beta - 1)(p - 1)}{4p}, \\ (3p + \sigma + 1)\theta < \rho - (\beta - 1)(p - 1). \end{cases} \tag{5.27}$$

Due to (3.10), the set of θ satisfying (5.27) is nonempty. Furthermore, we have $\mu_i(\theta) < 0$ for all $i = 1, 2$. Then, passing to the limit as $T \rightarrow \infty$ in (5.26), we get

$$\lim_{T \rightarrow \infty} T^{\beta-2+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt = 0,$$

so Theorem 3.2 applies. This completes the proof of Corollary 3.6. □

Proof of Corollary 3.7 Using (5.22) and (5.23), for all $\theta > 0$, we get

$$T^{-\max\{1-\alpha, 2-\beta\}+\frac{4\theta p}{p-1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt \leq C(T^{\lambda_1(\theta)} \ln T + T^{\lambda_2(\theta)}), \tag{5.28}$$

where

$$\lambda_1(\theta) = \frac{(1 - \max\{1 - \alpha, 2 - \beta\})(p - 1) - \rho + 4\theta p}{p - 1},$$

$$\lambda_2(\theta) = \frac{(1 - \max\{1 - \alpha, 2 - \beta\})(p - 1) - \rho + \theta(3p + \sigma + 1)}{p - 1}.$$

We now take θ so that

$$\begin{cases} 0 < \theta < \frac{\rho - (1 - \max\{1 - \alpha, 2 - \beta\})(p - 1)}{4p}, \\ (3p + \sigma + 1)\theta < \rho - (1 - \max\{1 - \alpha, 2 - \beta\})(p - 1). \end{cases} \tag{5.29}$$

Due to (3.11), the set of θ satisfying (5.29) is nonempty. We also have by (5.29) that $\lambda_i(\theta) < 0$ for all $i = 1, 2$. Then, passing to the limit as $T \rightarrow \infty$ in (5.28), we get

$$\lim_{T \rightarrow \infty} T^{-\max\{1 - \alpha, 2 - \beta\} + \frac{4\theta p}{p - 1}} \int_{t=0}^T \int_{x=T-\theta}^1 h^{\frac{-1}{p-1}}(t, x) \, dx \, dt = 0,$$

so Theorem 3.3 applies. The proof of Corollary 3.7 is then completed. □

Author contributions

All authors contributed equally in this work.

Funding

The first author is supported by Researchers Supporting Project number (RSP2024R57), King Saud University, Riyadh, Saudi Arabia.

Data Availability

No datasets were generated or analysed during the current study.

Declarations

Ethics approval and consent to participate

Not applicable.

Competing interests

The authors declare no competing interests.

Received: 22 April 2024 Accepted: 6 May 2024 Published online: 23 May 2024

References

1. Affili, E., Valdinoci, E.: Decay estimates for evolution equations with classical and fractional time derivatives. *J. Differ. Equ.* **266**(7), 4027–4060 (2019)
2. Alikhanov, A.A.: A new difference scheme for the time fractional diffusion equation. *J. Comput. Phys.* **280**, 424–438 (2015)
3. Alotaibi, M., Jleli, M., Ragusa, M.A., Samet, B.: On the absence of global weak solutions for a nonlinear time-fractional Schrödinger equation. *Appl. Anal.* **103**(1), 1–15 (2024)
4. Barbero, G., Evangelista, L.R., Lenzi, E.K.: Time-fractional approach to the electrochemical impedance: the displacement current. *J. Electroanal. Chem.* **920**, 116588 (2022)
5. Chen, F., Xu, Q., Hesthaven, J.S.: A multi-domain spectral method for time-fractional differential equations. *J. Comput. Phys.* **293**, 157–172 (2015)
6. Fino, A.Z., Kirane, M.: Qualitative properties of solutions to a time-space fractional evolution equation. *Q. Appl. Math.* **70**, 133–157 (2012)
7. Ford, N.J., Yan, Y.: An approach to construct higher order time discretisation schemes for time fractional partial differential equations with nonsmooth data. *Fract. Calc. Appl. Anal.* **20**(5), 1076–1105 (2017)
8. Górká, P., Prado, H., Pons, D.J.: The asymptotic behavior of the time fractional Schrödinger equation on Hilbert space. *J. Math. Phys.* **61**(3), 031501 (2020)
9. Hapca, S., Crawford, J.W., MacMillan, K., Wilson, M.J., Young, I.M.: Modelling nematode movement using time-fractional dynamics. *J. Theor. Biol.* **248**, 212–224 (2007)
10. Kassymov, A., Tokmagambetov, N., Torebek, B.T.: Multi-term time-fractional diffusion equation and system: mild solutions and critical exponents. *Publ. Math. (Debr.)* **100**, 295–321 (2022)
11. Kian, Y., Yamamoto, M.: On existence and uniqueness of solutions for semilinear fractional wave equations. *Fract. Calc. Appl. Anal.* **20**(1), 117–138 (2017)
12. Kilbas, A.A., Srivastava, H.M., Trujillo, J.J.: Theory and applications of fractional differential equations. In: Mill, J.V. (ed.) *North-Holland Mathematics Studies*, vol. 204. Elsevier, Amsterdam (2006)
13. Kirane, M., Laskri, Y.: Nonexistence of global solutions to a hyperbolic equation with a space-time fractional damping. *Appl. Math. Comput.* **167**, 1304–1310 (2005)

14. Kirane, M., Malik, S.A.: The profile of blowing-up solutions to a nonlinear system of fractional differential equations. *Nonlinear Anal.* **73**, 3723–3736 (2010)
15. Kirane, M., Sadybekov, M.A., Sarsenbi, A.A.: On an inverse problem of reconstructing a subdiffusion process from nonlocal data. *Math. Methods Appl. Sci.* **42**, 2043–2052 (2019)
16. Kirane, M., Tatar, N.E.: Exponential growth for a fractionally damped wave equation. *Z. Anal. Anwend.* **22**, 167–177 (2003)
17. Laskin, N.: Time fractional quantum mechanics. *Chaos Solitons Fractals* **102**, 16–28 (2017)
18. Naber, M.: Time fractional Schrödinger equation. *J. Math. Phys.* **45**, 3339–3352 (2004)
19. Samet, B.: Blow-up phenomena for a nonlinear time fractional heat equation in an exterior domain. *Comput. Math. Appl.* **78**, 1380–1385 (2019)
20. Smadiyeva, A.G., Torebek, B.T.: Decay estimates for the time-fractional evolution equations with time-dependent coefficients. *Proc. R. Soc. A* **479**(2276), 20230103 (2023)
21. Tatar, N.E.: A blow up result for a fractionally damped wave equation. *NoDEA Nonlinear Differ. Equ. Appl.* **12**(2), 215–226 (2005)
22. Tatar, N.E.: Nonexistence results for a fractional problem arising in thermal diffusion in fractal media. *Chaos Solitons Fractals* **36**, 1205–1214 (2008)
23. Tuan, N.H., Kirane, M., Luu, V.C.H., Bin-Mohsin, B.: A regularization method for time-fractional linear inverse diffusion problems. *Electron. J. Differ. Equ.* **2016**, 290 (2016)
24. Zhang, Q.G., Sun, H.R.: The blow-up and global existence of solutions of Cauchy problems for a time fractional diffusion equation. *Topol. Methods Nonlinear Anal.* **46**, 69–92 (2015)

Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Submit your manuscript to a SpringerOpen[®] journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► [springeropen.com](https://www.springeropen.com)
