# Sign-changing solutions for coupled Schrödinger system 

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## Abstract

In this paper we study the following nonlinear Schrödinger system:

$$
\begin{cases}-\Delta u+\alpha u=|u|^{p-1} u+\frac{2}{q+1} \lambda|u|^{\frac{p-3}{2}} u|v|^{\frac{q+1}{2}}, & x \in \mathbb{R}^{3}, \\ -\Delta v+\beta v=|v|^{q-1} v+\frac{2}{p+1} \lambda|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} v, & x \in \mathbb{R}^{3}, \\ u(x) \rightarrow 0, \quad v(x) \rightarrow 0, \quad \text { as }|x| \rightarrow \infty, & \end{cases}
$$

where $3 \leq p, q<5, \alpha, \beta$ are positive parameters. We show that there exists $\lambda_{k}>0$ such that the equation has at least $k$ radially symmetric sign-changing solutions and at least $k$ seminodal solutions for each $k \in \mathbb{N}$ and $\lambda \in\left(0, \lambda_{k}\right)$. Moreover, we show the existence of a least energy radially symmetric sign-changing solution for each $\lambda \in\left(0, \lambda_{0}\right)$ where $\lambda_{0} \in\left(0, \lambda_{1}\right]$.

## 1 Background and main results

Consider the following nonlinear coupled Schrödinger system:

$$
\left\{\begin{array}{l}
-\Delta u+\alpha u=|u|^{p-1} u+\frac{2}{q+1} \lambda|u|^{\frac{p-3}{2}} u|v|^{\frac{q+1}{2}}, \quad x \in \Omega,  \tag{1.1}\\
-\Delta v+\beta v=|v|^{q-1} v+\frac{2}{p+1} \lambda|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} v, \quad x \in \Omega \\
u=v=0 \quad \text { on } \partial \Omega .
\end{array}\right.
$$

Here $\Omega=\mathbb{R}^{N}$ or $\Omega$ is a smooth bounded domain in $\mathbb{R}^{N}, \alpha, \beta$ are positive parameters and $\lambda \neq 0$ is a coupling constant.

In the case $p=q=3$, system (1.1) becomes the cubic system:

$$
\left\{\begin{array}{l}
-\Delta u+\alpha u=u^{3}+\lambda u v^{2}, \quad x \in \Omega  \tag{1.2}\\
-\Delta v+\beta v=v^{3}+\lambda u^{2} v, \quad x \in \Omega \\
u=v=0 \quad \text { on } \partial \Omega
\end{array}\right.
$$

which arises in the study of many physical phenomena like nonlinear optics and BoseEinstein condensation (cf. [15, 17]). Therefore, in the last decades, system (1.2) has received great interest from mathematicians. When $\Omega$ is the entire space $\mathbb{R}^{N}$, the existence of
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least energy and other finite energy solutions of (1.2) was studied in [2, 11, 12, 18, 21, 22, 27] and the references therein. In particular, when $\lambda>0$ is sufficiently large, infinitely many radially symmetric sign-changing solutions of (1.2) were obtained in [23]. Liu and Wang [20] studied a general $m$-coupled system $(m \geq 2)$ and proved that system (1.2) has infinitely many nontrivial solutions, but whether solutions obtained in [20] are positive or sign-changing cannot be determined there (see also [21]). When $\Omega \subset \mathbb{R}^{N}(N=2,3)$ is a smooth bounded domain, there are also many papers studying (1.2). Lin and Wei [18] proved that a least energy solution of (1.2) exists within an appropriate range of $\lambda$. Dancer, Wei, and Weth [14] and Noris and Ramos [24] proved the existence of infinitely many positive solutions of (1.2). When $\Omega$ is a ball, a multiplicity result on positive radially symmetric solutions was given in [29]. Later, by using a global bifurcation approach, the result of [29] was reproved by [4] without requiring the symmetric condition. Under some more general assumptions, Sato and Wang [26] proved that system (1.2) has infinitely many semipositive solutions (i.e., at least one component is positive). In [14], the authors proved the existence of unbounded sequence solutions for $N \leq 3$ and $\lambda \leq-1$. As pointed out above, for $\lambda \leq-1$, Wei and Weth [29] proved that (1.2) has a radially symmetric solution, which turns out to be a positive solution.
We remark that the existence of infinitely many sign-changing solutions or seminodal solutions to (1.2) was solved by Chen, Lin, and Zou [10] and Liu, Liu, and Wang [19] independently, where $N \leq 3$ and $\lambda<0$.
To the best of our knowledge, the existence of sign-changing solutions to (1.1) has not ever been studied in the literature when $\Omega=\mathbb{R}^{3}$ and $3 \leq p, q<5$. The main goal of this paper is to study the existence of sign-changing solutions, seminodal solutions, and least energy sign-changing solutions to problem (1.1) when $\lambda>0$ is small. This will complement the study made in [14, 19, 21, 22, 29].

Definition 1.1 A solution $(u, v)$ is called nontrivial if $u \not \equiv 0$ and $v \not \equiv 0$, a solution $(u, v)$ is semitrivial if $(u, v)$ is type of $(u, 0)$ or $(0, v)$. We call a solution $(u, v)$ positive if $u>0$ and $v>0$ in $\mathbb{R}^{N}$, a solution $(u, v)$ sign-changing if both $u$ and $v$ change sign, a solution $(u, v)$ seminodal if one changes sign and the other one is positive.

The first main result of the current paper is as follows.

Theorem 1.1 Assume $\alpha, \beta>0$. Then for any $k \in \mathbb{N}$ there exists $\lambda_{k}>0$ such that system (1.1) possesses at least $k$ radially symmetric sign-changing solutions for each fixed $\lambda \in\left(0, \lambda_{k}\right)$.

We can also study some further properties of the sign-changing solutions obtained in Theorem 1.1. It is well known that a nontrivial solution $(u, v) \in H^{1}\left(\mathbb{R}^{N}\right) \times H^{1}\left(\mathbb{R}^{N}\right)$ is called a least energy solution if its energy is minimal among the energy of all nontrivial solutions. A sign-changing solution is called a least energy sign-changing solution if it has the least energy among all sign-changing solutions. Precisely, we have the following theorem.

Theorem 1.2 Assume $\alpha, \beta>0$. Then there exists $\lambda_{0} \in\left(0, \lambda_{1}\right]$ such that system (1.1) possesses a least energy radially symmetric sign-changing solution for each fixed $\lambda \in\left(0, \lambda_{0}\right)$.

Theorem 1.3 Assume $\alpha, \beta>0$. Then for any $k \in \mathbb{N}$ there exists $\lambda_{k}>0$ such that system (1.1) possesses at least $k$ seminodal solutions for each fixed $\lambda \in\left(0, \lambda_{k}\right)$.

Remark 1.1 We can prove that system (1.1) possesses at least $k$ seminodal solutions with the first component positive and the second component radially symmetric sign-changing or the first component radially symmetric sign-changing and the second component positive.

The structure of this paper is as follows. In Sect. 2 we prove the existence of at least $k$ radially symmetric sign-changing solutions. The main tool will be the use of a new notion of vector genus by [28] and a new constrained problem by [10], which will be used to construct minimax values. Remark that the ideas in [10,28] cannot be used directly, and here we will give some new ideas. The crucial idea in this paper is turning to study a new problem with two constraints to obtain sign-changing solutions of (1.1). This idea has never been used for (1.1) in the literature up to our knowledge. We will give all the necessary details of the proof. Section 3 is then dedicated to the proof of Theorem 1.2 by using a minimizing argument. Finally in Sect. 4 we will present the proof of Theorem 1.3 applying the arguments in Sect. 2 and Sect. 3.

We give some notations here. Throughout this paper, we denote the norm of $L^{p}\left(\mathbb{R}^{N}\right)$ by $|u|_{p}=\left(\int_{\mathbb{R}^{N}}|u|^{p} d x\right)^{\frac{1}{p}}$, the norm of $H^{1}\left(\mathbb{R}^{N}\right)$ by $\|u\|^{2}=\int_{\mathbb{R}^{N}}\left(|\nabla u|^{2}+|u|^{2}\right) d x$, and positive constants (possibly different in different places) by C. Define $H_{r}:=H_{r}^{1}\left(\mathbb{R}^{N}\right) \times H_{r}^{1}\left(\mathbb{R}^{N}\right)$ as a subspace of $H:=H^{1}\left(\mathbb{R}^{N}\right) \times H^{1}\left(\mathbb{R}^{N}\right)$ with norm $\|(u, v)\|_{H_{r}}^{2}:=\|u\|_{\alpha}^{2}+\|v\|_{\beta}^{2}$ where

$$
\begin{aligned}
& H_{r}^{1}\left(\mathbb{R}^{N}\right):=\left\{u \in H^{1}\left(\mathbb{R}^{N}\right): u \text { is radially symmetric }\right\}, \\
& \|u\|_{\alpha}^{2}:=\int_{\mathbb{R}^{N}}\left(|\nabla u|^{2}+\alpha|u|^{2}\right) d x .
\end{aligned}
$$

## 2 Proof of Theorem 1.1

In this section, we assume that $N=3,3 \leq p, q<2^{*}-1=5$ and $\alpha, \beta>0$. Without loss of generality, we assume $p \leq q$. Let $\lambda \in(0,1)$. For any $k \in \mathbb{N}$, let $X_{k+1} \subset H_{r}^{1}\left(\mathbb{R}^{3}\right), \operatorname{dim} X_{k+1}=$ $k+1$, and there exists $u_{0} \in X_{k+1}$ and $u_{0}>0$. Then there exists $m>0$ such that for any $(u, v) \in X_{k+1} \times X_{k+1}$ satisfying $|u|_{p+1}^{p+1},|v|_{q+1}^{q+1}<2$, we have

$$
\begin{equation*}
\|u\|_{\alpha}^{2}<m, \quad\|v\|_{\beta}^{2}<m . \tag{2.1}
\end{equation*}
$$

Without loss of generality, we can assume $m>1$. Obviously, the sign-changing solutions of system (1.1) are the critical points of the $C^{2}$ functional $\Phi_{\lambda}: H_{r} \rightarrow \mathbb{R}$ given by

$$
\begin{align*}
\Phi_{\lambda}(u, v):= & \frac{1}{2}\left(\|u\|_{\alpha}^{2}+\|v\|_{\beta}^{2}\right)-\frac{1}{p+1}|u|_{p+1}^{p+1}-\frac{1}{q+1}|v|_{q+1}^{q+1} \\
& -\frac{4 \lambda}{(p+1)(q+1)} \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q+1}{2}} d x . \tag{2.2}
\end{align*}
$$

We will look for solutions of Eq. (1.1) as critical points of the functional $\Phi_{\lambda}$ restricted to the sphere

$$
\mathcal{A}:=\left\{(u, v) \in H_{r}:|u|_{p+1}=1,|v|_{q+1}=1\right\} .
$$

To obtain at least $k$ sign-changing critical points, we need to define several minimax energy levels using a new definition of vector genus introduced by [28]. As in [28], we recall
vector genus and take the transformations

$$
\sigma_{i}: \mathcal{A} \rightarrow \mathcal{A}, \quad \sigma_{1}(u, v)=(-u, v), \quad \sigma_{2}(u, v)=(u,-v), \quad i=1,2 .
$$

Consider the class of sets

$$
\mathcal{F}=\left\{A \subset \mathcal{A}: A \text { is a closed set and } \sigma_{i}(u, v) \in A, \forall(u, v) \in A, i=1,2\right\}
$$

and for each $A \in \mathcal{F}$ and $k_{1}, k_{2} \in \mathbb{N}$, the class of functions

$$
\begin{aligned}
F_{\left(k_{1}, k_{2}\right)}(A)= & \left\{f=\left(f_{1}, f_{2}\right): A \rightarrow \prod_{i=1}^{2} \mathbb{R}^{k_{i}-1}: f_{i}: A \rightarrow \mathbb{R}^{k_{i}-1}\right. \text { continuous, } \\
& \left.f_{i}\left(\sigma_{i}(u, v)\right)=-f_{i}(u, v) \text { for each } i, f_{i}\left(\sigma_{j}(u, v)\right)=f_{i}(u, v) \text { for } i \neq j\right\} .
\end{aligned}
$$

where $\mathbb{R}^{0}:=\{0\}$.
Definition 2.1 (Vector genus, see [28]) For every nonempty and closed set $A \subset H_{0}^{1}(\Omega)$ such that $-A=A$, we define

$$
\gamma(A):=\inf \left\{k: \text { there exists } h: A \rightarrow \mathbb{R}^{k} \backslash\{0\} \text { continuous and odd }\right\}
$$

and $\gamma(A):=\infty$ if no such $k$ exists.
Let $A \in \mathcal{F}$ and take any $k_{1}, k_{2} \in \mathbb{N}$. We say that $\gamma(A) \geq\left(k_{1}, k_{2}\right)$ if for every $f \in F_{\left(k_{1}, k_{2}\right)}(A)$ there exists $(u, v) \in A$ such that $f(u, v)=\left(f_{1}(u, v), f_{2}(u, v)\right)=(0,0)$. We denote

$$
\Gamma^{\left(k_{1}, k_{2}\right)}:=\left\{A \in \mathcal{F}: \gamma(A) \geq\left(k_{1}, k_{2}\right)\right\} .
$$

Remark 2.1 Note that Definition 2.1 does not actually define the quantity $\gamma(A)$ but gives the meaning of $\gamma(A) \geq\left(k_{1}, k_{2}\right)$ only. A different notation of genus was introduced by Chang, Wang, and Zhang in [8].

Lemma 2.1 (see [28]) Let $f=\left(f_{1}, f_{2}\right): \prod_{i=1}^{2} S^{k_{i}} \rightarrow \prod_{i=1}^{2} \mathbb{R}^{k_{i}}$ be a continuous function such that $f_{i}\left(\sigma_{i}(u, v)\right)=-f_{i}(u, v), f_{i}\left(\sigma_{j}(u, v)\right)=f_{i}(u, v)$ for any $i, j=1,2, i \neq j$, then there exists $\left(u_{0}, v_{0}\right) \in \prod_{i=1}^{2} S^{k_{i}}$ such that $f\left(u_{0}, v_{0}\right)=(0, \ldots, 0)$.

Lemma 2.2 (see [28]) The following properties hold.
(1) Take $A_{1} \times A_{2} \subset \mathcal{A}$ and let $\eta_{i}: S^{k_{i}-1} \rightarrow A_{i}$ be a homeomorphism such that $\eta_{i}(-x)=-\eta_{i}(x)$ for every $x \in S^{k_{i}-1}, i=1,2$. Then $A_{1} \times A_{2} \in \Gamma^{\left(k_{1}, k_{2}\right)}$, where $S^{k_{i}-1}=\left\{x \in \mathbb{R}^{k_{i}}:|x|=1\right\}$.
(2) We have $\overline{\eta(A)} \in \Gamma^{\left(k_{1}, k_{2}\right)}$ whenever $A \in \Gamma^{\left(k_{1}, k_{2}\right)}$ and a continuous map $\eta: A \rightarrow \mathcal{A}$ is such that $\eta \circ \sigma_{i}=\sigma_{i} \circ \eta, \forall i=1,2$.

Together with the notation of vector genus, to obtain sign-changing solutions, we will use cones of positive or negative functions based on the works such as [5, 13, 30]. We define the cone

$$
\mathcal{P}_{1}:=\left\{(u, v) \in H_{r}: u \geq 0\right\}, \quad \mathcal{P}_{2}:=\left\{(u, v) \in H_{r}: v \geq 0\right\},
$$

and take $\mathcal{P}:=\bigcup_{i=1}^{2}\left(\mathcal{P}_{i} \cup-\mathcal{P}_{i}\right)$. Moreover, for any $\delta>0$, we define

$$
\mathcal{P}_{\delta}:=\left\{(u, v) \in H_{r}: \operatorname{dist}((u, v), \mathcal{P})<\delta\right\},
$$

where

$$
\begin{aligned}
\operatorname{dist}((u, v), \mathcal{P}):= & \min \left\{\operatorname{dist}_{p+1}\left(u, \mathcal{P}_{1}\right), \operatorname{dist}_{p+1}\left(u,-\mathcal{P}_{1}\right),\right. \\
& \left.\operatorname{dist}_{q+1}\left(v, \mathcal{P}_{2}\right), \operatorname{dist}_{q+1}\left(v,-\mathcal{P}_{2}\right)\right\} \\
\operatorname{dist}_{p+1}\left(u, \pm \mathcal{P}_{1}\right):= & \inf _{\omega \in \pm \mathcal{P}_{1}}|u-\omega|_{p+1}=\left|u^{\mp}\right|_{p+1} \\
\operatorname{dist}_{q+1}\left(v, \pm \mathcal{P}_{2}\right):= & \inf _{\omega \in \pm \mathcal{P}_{2}}|v-\omega|_{q+1}=\left|v^{\mp}\right|_{q+1}
\end{aligned}
$$

where $u^{ \pm}:=\max \{0, \pm u\}$.
Lemma 2.3 For any $0<\delta<2^{-\frac{1}{p+1}}$, there holds $A \backslash \mathcal{P}_{\delta} \neq \emptyset$ whenever $A \in \Gamma^{\left(k_{1}, k_{2}\right)}$ with $k_{1}, k_{2} \geq 2$.

Proof For any $A \in \Gamma^{\left(k_{1}, k_{2}\right)}$, define $f=\left(f_{1}, f_{2}\right)$ by

$$
\begin{aligned}
& f_{1}(u, v)=\left(\int_{\mathbb{R}^{3}}|u|^{p} u d x, 0, \ldots, 0\right), \\
& f_{2}(u, v)=\left(\int_{\mathbb{R}^{3}}|v|^{q} v d x, 0, \ldots, 0\right),
\end{aligned}
$$

then $f \in F_{\left(k_{1}, k_{2}\right)}(A)$, so by Definition 2.1, there exists $\left(u_{0}, v_{0}\right) \in A$ such that $f\left(u_{0}, v_{0}\right)=$ $(0, \ldots, 0)$. By $A \in \mathcal{A}$, we deduce that

$$
\begin{aligned}
& \int_{\mathbb{R}^{3}}\left(u_{0}^{+}\right)^{p+1} d x=\int_{\mathbb{R}^{3}}\left(u_{0}^{-}\right)^{p+1} d x=\frac{1}{2}, \\
& \int_{\mathbb{R}^{3}}\left(v_{0}^{+}\right)^{q+1} d x=\int_{\mathbb{R}^{3}}\left(v_{0}^{-}\right)^{q+1} d x=\frac{1}{2},
\end{aligned}
$$

therefore, $\operatorname{dist}\left(\left(u_{0}, v_{0}\right), \mathcal{P}\right)=2^{-\frac{1}{p+1}}$, and so $\left(u_{0}, v_{0}\right) \in A \backslash \mathcal{P}_{\delta}$ for any $0<\delta<2^{-\frac{1}{p+1}}$.

For technical reasons, we will work on the neighborhood of $\mathcal{A}$ in $H_{r}^{1}\left(\mathbb{R}^{3}\right)$,

$$
\begin{equation*}
\mathcal{A}^{*}:=\left\{(u, v) \in H_{r}: \frac{1}{2}<|u|_{p+1}^{p+1}<2, \frac{1}{2}<|v|_{q+1}^{q+1}<2\right\}, \tag{2.3}
\end{equation*}
$$

when $u \in \mathcal{A}^{*},(u, v) \not \equiv(0,0)$. Define

$$
\begin{align*}
\mathcal{B}_{m}^{*} & :=\left\{(u, v) \in \mathcal{A}^{*}:\|u\|_{\alpha}^{2}<m,\|v\|_{\beta}^{2}<m\right\},  \tag{2.4}\\
\mathcal{B}_{m} & :=\left\{(u, v) \in \mathcal{A}:\|u\|_{\alpha}^{2}<m,\|v\|_{\beta}^{2}<m\right\},  \tag{2.5}\\
\mathcal{C}_{m} & :=\left\{(u, v) \in \mathcal{A}:\|u\|_{\alpha}^{2}=m,\|v\|_{\beta}^{2}=m\right\} . \tag{2.6}
\end{align*}
$$

Let $S_{p}$ and $S_{q}$ be the sharp constants of the Sobolev embedding $H_{r}^{1}\left(\mathbb{R}^{3}\right) \hookrightarrow L^{p+1}\left(\mathbb{R}^{3}\right)$ and $H_{r}^{1}\left(\mathbb{R}^{3}\right) \hookrightarrow L^{q+1}\left(\mathbb{R}^{3}\right)$, respectively,

$$
\begin{equation*}
\|u\|_{\alpha}^{2} \geq S_{p}|u|_{p+1}^{2}, \quad\|v\|_{\beta}^{2} \geq S_{q}|v|_{q+1}^{2}, \quad \forall u, v \in H_{r}^{1}\left(\mathbb{R}^{3}\right) \tag{2.7}
\end{equation*}
$$

For any $(u, v) \in H_{r} \backslash\{(0,0)\}$, we have

$$
\begin{equation*}
\sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)=\Phi_{\lambda}\left(t_{u, v, \lambda} u, s_{u, v, \lambda} v\right)=: \Psi_{\lambda}(u, v) \tag{2.8}
\end{equation*}
$$

where $t_{u, v, \lambda}, s_{u, v, \lambda} \geq 0$ satisfy

$$
\left.\frac{\partial}{\partial t} \Phi_{\lambda}(t u, s v)\right|_{\left(t_{u, v, \lambda}, s_{u}, v, \lambda\right)}=\left.\frac{\partial}{\partial s} \Phi_{\lambda}(t u, s v)\right|_{\left(t_{u, v, \lambda}, s_{u v, \lambda}\right)}=0
$$

Note that for $t, s \geq 0$,

$$
\begin{align*}
\Phi_{\lambda}(t u, s v):= & \frac{1}{2}\left(t^{2}\|u\|_{\alpha}^{2}+s^{2}\|v\|_{\beta}^{2}\right)-\frac{t^{p+1}}{p+1}|u|_{p+1}^{p+1}-\frac{s^{q+1}}{q+1}|v|_{q+1}^{q+1} \\
& -\frac{4 \lambda}{(p+1)(q+1)} t^{\frac{p+1}{2}} s^{\frac{q+1}{2}} \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q+1}{2}} d x . \tag{2.9}
\end{align*}
$$

Define

$$
\begin{aligned}
F(u, v, \lambda ; t, s) & :=t\|u\|_{\alpha}^{2}-t^{p}|u|_{p+1}^{p+1}-\frac{2}{q+1} t^{\frac{p-1}{2}} s^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q+1}{2}} d x \\
& :=t F_{1}(u, v, \lambda ; t, s)
\end{aligned}
$$

and

$$
\begin{aligned}
G(u, v, \lambda ; t, s) & :=s\|v\|_{\beta}^{2}-s^{q}|v|_{q+1}^{q+1}-\frac{2}{p+1} t^{\frac{p+1}{2}} s^{\frac{q-1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q+1}{2}} d x \\
& :=s G_{1}(u, v, \lambda ; t, s)
\end{aligned}
$$

which implies

$$
\begin{equation*}
F_{1}\left(u, v, \lambda ; t_{u, v, \lambda}, s_{u, v, \lambda}\right)=G_{1}\left(u, v, \lambda ; t_{u, v, \lambda}, s_{u, v, \lambda}\right)=0 \tag{2.10}
\end{equation*}
$$

Since $F_{1}(u, v, \lambda ; t, s)$ and $G_{1}(u, v, \lambda ; t, s)$ are decreasing with respect to $t>0$ and $s>0$, respectively, $F_{1}(u, v, \lambda ; 0,0)>0, G_{1}(u, v, \lambda ; 0,0)>0$, so $t_{u, v, \lambda}, s_{u, v, \lambda}$ are unique. Note that for $t, s \geq 0$, $3 \leq p, q<5$, by (2.9), we can choose some positive constant $T$ such that $\Phi_{\lambda}(t u, s v)<0$ for any $t, s>T$, therefore, $t_{u, v, \lambda}, s_{u, v, \lambda} \in[0, T]$.
Define

$$
\begin{equation*}
\tilde{m}>\left[(q+1) S_{p}\left(\frac{1}{2}\right)^{\frac{2}{p+1}}\right]^{\frac{2}{p+q-2}}+\frac{4(p+1)(q+1)}{(p-1)\left(\frac{S_{p}}{8}\right)^{\frac{2}{p-1}}} m^{\frac{p+1}{p-1}}+m . \tag{2.11}
\end{equation*}
$$

Then $B_{m} \subset B_{\widetilde{m}}, B_{m}^{*} \subset B_{\widetilde{m}}^{*}$.

Lemma 2.4 For any $k \in \mathbb{N}$, there exist $\tilde{\lambda} \in(0,1)$ and $T_{1}>T_{2}>0$ such that for any $\lambda \in(0, \tilde{\lambda})$ and $(u, v) \in B_{\widetilde{m}}^{*}$, we have

$$
\begin{equation*}
T_{2} \leq t_{u, v, \lambda}, s_{u, v, \lambda} \leq T_{1} . \tag{2.12}
\end{equation*}
$$

Furthermore, there exist $\lambda_{k} \in(0, \tilde{\lambda}]$ and $c_{k}>0$ such that for any $\lambda \in\left(0, \lambda_{k}\right)$, we have

$$
\begin{equation*}
\sup _{(u, v) \in \mathcal{B}_{m}} \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)<c_{k} \leq \inf _{(u, v) \in \mathcal{C}_{\tilde{m}}} \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v) . \tag{2.13}
\end{equation*}
$$

Proof We see from (2.9) and (2.10) that

$$
\begin{align*}
\sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)= & \Phi_{\lambda}\left(t_{u, v, \lambda} u, s_{u, v, \lambda} v\right) \\
= & \left(\frac{1}{2}-\frac{1}{p+1}\right) t_{u, v, \lambda}^{2}\|u\|_{\alpha}^{2}+\left(\frac{1}{2}-\frac{1}{q+1}\right) s_{u, v, \lambda}^{q+1}|v|_{q+1}^{q+1}  \tag{2.14}\\
& +\frac{(q-1)}{(p+1)(q+1)} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q+1}{2}} d x .
\end{align*}
$$

Firstly, we claim that there exist $\tilde{\lambda} \in(0,1)$ and $T_{1}>T_{2}>0$ such that for any $\lambda \in(0, \tilde{\lambda})$ and $(u, v) \in B_{\widetilde{m}}^{*}$, we have

$$
T_{2} \leq t_{u, v, \lambda}, s_{u, v, \lambda} \leq T_{1}
$$

By (2.10),

$$
\begin{aligned}
& t_{u, v, \lambda} \leq\left(\frac{\|u\|_{\alpha}^{2}}{|u|_{p+1}^{p+1}}\right)^{\frac{1}{p-1}}<(2 \widetilde{m})^{\frac{1}{p-1}}<2 \widetilde{m} \\
& s_{u, v, \lambda} \leq\left(\frac{\|v\|_{\beta}^{2}}{|v|_{q+1}^{q+1}}\right)^{\frac{1}{q-1}}<(2 \widetilde{m})^{\frac{1}{q-1}}<2 \widetilde{m}
\end{aligned}
$$

Thus, we obtain that

$$
t_{u, v, \lambda}, s_{u, v, \lambda}<2 \widetilde{m}=: T_{1} .
$$

Define

$$
\tilde{\lambda}=\frac{(q+1) S_{p}\left(\frac{1}{2}\right)^{\frac{2}{p+1}}}{8(2 \widetilde{m})^{\frac{p+q-2}{2}}}
$$

We see from (2.11) that $\tilde{\lambda} \in(0,1)$. Moreover, by (2.7) and (2.10), for any $\lambda \in(0, \tilde{\lambda})$, we have

$$
\begin{aligned}
t_{u, v, \lambda}^{p-1}|u|_{p+1}^{p+1} & =\|u\|_{\alpha}^{2}-\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q+1}{2}} d x \\
& >S_{p}\left(\frac{1}{2}\right)^{\frac{2}{p+1}}-\frac{2}{q+1}(2 \widetilde{m})^{\frac{p+q-2}{2}} \lambda|u|_{p+1}^{\frac{p+1}{2}}|v|_{q+1}^{\frac{q+1}{2}}
\end{aligned}
$$

$$
\begin{aligned}
& >S_{p}\left(\frac{1}{2}\right)^{\frac{2}{p+1}}-\frac{4}{q+1}(2 \tilde{m})^{\frac{p+q-2}{2}} \lambda \\
& >\frac{1}{2} S_{p}\left(\frac{1}{2}\right)^{\frac{2}{p+1}}>\frac{S_{p}}{4}
\end{aligned}
$$

Then we get $t_{u, v, \lambda}>\left(\frac{S_{p}}{8}\right)^{\frac{1}{p-1}}$. Similarly, we have $s_{u, v, \lambda}>\left(\frac{S_{q}}{8}\right)^{\frac{1}{q-1}}$. Thus, we get

$$
t_{u, v, \lambda}, s_{u, v, \lambda}>\min \left\{\left(\frac{S_{p}}{8}\right)^{\frac{1}{p-1}},\left(\frac{S_{q}}{8}\right)^{\frac{1}{q-1}}\right\}=: T_{2}
$$

This completes $T_{2} \leq t_{u, v, \lambda} \leq T_{1}$.
Now we prove the existence of $\lambda_{k}$ and $c_{k}$. For any $(u, v) \in \bar{B}_{\widetilde{m}}$ and $\lambda \in(0, \widetilde{\lambda}]$, by (2.14), there holds

$$
\begin{aligned}
& \left.\left.\left|\sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)-\left(\frac{1}{2}-\frac{1}{p+1}\right) t_{u, v, \lambda}^{2}\|u\|_{\alpha}^{2}-\left(\frac{1}{2}-\frac{1}{q+1}\right) s_{u, v, \lambda}^{q+1}\right| v\right|_{q+1} ^{q+1} \right\rvert\, \\
& \left.\quad=\left.\left|\frac{(q-1)}{(p+1)(q+1)} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}\right| u\right|^{\frac{p+1}{2}}|v|^{\frac{q+1}{2}} d x \right\rvert\, \leq C \lambda .
\end{aligned}
$$

Hence,

$$
\begin{aligned}
& \sup _{(u, v) \in B_{m}} \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v) \\
& \leq \sup _{(u, v) \in B_{m}}\left[\left(\frac{1}{2}-\frac{1}{p+1}\right) t_{u, v, \lambda}^{2}\|u\|_{\alpha}^{2}+\left(\frac{1}{2}-\frac{1}{q+1}\right) s_{u, v, \lambda}^{q+1}|v|_{q+1}^{q+1}\right]+C \lambda \\
& \leq \sup _{(u, v) \in B_{m}}\left[\left(\frac{1}{2}-\frac{1}{p+1}\right)\left(\frac{\|u\|_{\alpha}^{2}}{|u|_{p+1}^{p+1}}\right)^{\frac{2}{p-1}}\|u\|_{\alpha}^{2}+\left(\frac{1}{2}-\frac{1}{q+1}\right)\left(\frac{\|v\|_{\beta}^{2}}{|v|_{q+1}^{q+1}}\right)^{\frac{q+1}{q-1}}\right]+C \lambda \\
& \leq\left(\frac{1}{2}-\frac{1}{p+1}\right) m^{\frac{p+1}{p-1}}+\left(\frac{1}{2}-\frac{1}{q+1}\right) m^{\frac{q+1}{q-1}}+C \lambda \\
& \leq 2\left(\frac{1}{2}-\frac{1}{q+1}\right) m^{\frac{p+1}{p-1}}+C \lambda<(q+1) m^{\frac{p+1}{p-1}}+C \lambda,
\end{aligned}
$$

and

$$
\begin{aligned}
& \inf _{(u, v) \in \mathcal{C}_{\widetilde{m}}} \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v) \\
& \quad \geq \inf _{(u, v) \in \mathcal{C}_{\tilde{m}}}\left[\left(\frac{1}{2}-\frac{1}{p+1}\right) t_{u, v, \lambda}^{2}\|u\|_{\alpha}^{2}+\left(\frac{1}{2}-\frac{1}{q+1}\right) s_{u, v, \lambda}^{q+1}|v|_{q+1}^{q+1}\right]-C \lambda \\
& \quad>\inf _{(u, v) \in \mathcal{C}_{\widetilde{m}}}\left(\frac{1}{2}-\frac{1}{p+1}\right) t_{u, v, \lambda}^{2}\|u\|_{\alpha}^{2}-C \lambda \\
& \quad \geq\left(\frac{1}{2}-\frac{1}{p+1}\right)\left(\frac{S_{p}}{8}\right)^{\frac{2}{p-1}} \widetilde{m}-C \lambda,
\end{aligned}
$$

then by (2.11), we can choose

$$
\lambda_{k}=\min \left\{\frac{q+1}{2 C} m^{\frac{p+1}{p-1}}, \tilde{\lambda}\right\}
$$

$$
c_{k}=\left(\frac{1}{2}-\frac{1}{p+1}\right)\left(\frac{S_{p}}{8}\right)^{\frac{2}{p-1}} \tilde{m}-C \lambda_{k}
$$

such that $c_{k}>0$ for any $0<\lambda<\lambda_{k}$ the conclusion holds.

For any $(u, v) \in B_{\widetilde{m}}^{*}$, the following linear problem

$$
\left\{\begin{array}{l}
-\Delta \varphi+\alpha \varphi-\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda|u|^{\frac{p-3}{2}} \varphi|v|^{\frac{q+1}{2}}=t_{u, v, \lambda}^{p-1}|u|^{p-1} u  \tag{2.15}\\
-\Delta \psi+\beta \psi-\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q-3}{2}} \lambda|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} \psi=s_{u, v, \lambda}^{q-1}|v|^{q-1} v, \\
\varphi(x) \rightarrow 0, \quad \psi(x) \rightarrow 0, \quad \text { as }|x| \rightarrow \infty
\end{array}\right.
$$

has a unique solution $(\varphi, \psi) \in H_{r} \backslash\{(0,0)\}$. Then we can choose $\lambda_{k}$ small enough such that for any $\varphi, \psi \in H_{r}^{1}\left(\mathbb{R}^{3}\right)$,

$$
\begin{aligned}
\int_{\mathbb{R}^{3}}|u|^{p-1} u \varphi d x & =\frac{\|\varphi\|_{\alpha}^{2}-\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} \int_{u, v, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p-3}{2}} \varphi^{2}|v|^{\frac{q+1}{2}} d x}{t_{u, v, \lambda}^{p-1}} \\
& \geq \frac{\frac{1}{2}\|\varphi\|_{\alpha}^{2}}{t_{u, v, \lambda}^{p-1}}>0
\end{aligned}
$$

and

$$
\begin{aligned}
\int_{\mathbb{R}^{3}}|v|^{q-1} v \psi d x & =\frac{\|\psi\|_{\beta}^{2}-\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} \lambda_{u, v, \lambda}^{\frac{q-3}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} \psi^{2} d x}{s_{u, v, \lambda}^{q-1}} \\
& \geq \frac{\frac{1}{2}\|\psi\|_{\beta}^{2}}{s_{u, v, \lambda}^{q-1}}>0 .
\end{aligned}
$$

Define

$$
\mu:=\frac{1}{\int_{\mathbb{R}^{3}}|u|^{p-1} u \varphi d x}, \quad v:=\frac{1}{\int_{\mathbb{R}^{3}}|v|^{q-1} v \psi d x}
$$

then $\mu>0, \nu>0$ and $(\widetilde{\varphi}, \widetilde{\psi}):=(\mu \varphi, \nu \psi)$ is the unique solution of

$$
\left\{\begin{array}{l}
-\Delta \widetilde{\varphi}+\alpha \widetilde{\varphi}-\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} \lambda_{u, v, \lambda}^{\frac{q+1}{2}} \lambda|u|^{\frac{p-3}{2}} \widetilde{\varphi}|v|^{\frac{q+1}{2}}=\mu t_{u, v, \lambda}^{p-1}|u|^{p-1} u  \tag{2.16}\\
-\Delta \widetilde{\psi}+\beta \widetilde{\psi}-\frac{2}{p+1} t_{u, v, \lambda}^{2} s_{u, v, \lambda}^{\frac{q-3}{2}} \lambda|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} \widetilde{\psi}=v s_{u, v, \lambda}^{q-1}|v|^{q-1} v, \\
\int_{\mathbb{R}^{3}}|u|^{p-1} u \widetilde{\varphi} d x=\int_{\mathbb{R}^{3}}|v|^{q-1} v \tilde{\psi} d x=1 \\
\widetilde{\varphi}(x) \rightarrow 0, \quad \widetilde{\psi}(x) \rightarrow 0, \quad \text { as }|x| \rightarrow \infty
\end{array}\right.
$$

Fixed any $k \in \mathbb{N}$, we define

$$
A_{1}:=\left\{u \in X_{k+1}:|u|_{p+1}=1\right\}, \quad A_{2}:=\left\{v \in X_{k+1}:|v|_{q+1}=1\right\} .
$$

There is an odd homeomorphism from $S^{k}$ to $A_{1}$ and $A_{2}$. By Lemma 2.2(1), $A:=A_{1} \times A_{2} \in$ $\Gamma^{(k+1, k+1)}$. Observe that from (2.1) we deduce that $A \subset B_{m}$, and so by (2.13),

```
sup}\mp@subsup{\operatorname{sup}}{|}{}\mp@subsup{\Phi}{\lambda}{}(tu,sv)<\mp@subsup{c}{k}{
(u,v)\inAt,s\geq0
```

Define

$$
\Gamma_{\lambda}^{\left(k_{1}, k_{2}\right)}:=\left\{A \in \Gamma^{\left(k_{1}, k_{2}\right)}: A \subset B_{\widetilde{m}}, \sup _{(u, v) \in A} \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)<c_{k}\right\}
$$

Observe that $\Gamma_{\lambda}^{\left(k_{1}, k_{2}\right)} \neq \emptyset, \Gamma_{\lambda}^{\left(k_{1}, k_{2}\right)} \subset \Gamma_{\lambda}^{\left(k_{1}^{\prime}, k_{2}^{\prime}\right)}$ when $k_{1} \geq k_{1}^{\prime}$ and $k_{2} \geq k_{2}^{\prime}$. We are now ready to define a sequence of minimax energy levels which will turn out to be critical levels for $\Phi_{\lambda}$ over $\mathcal{A}$. For every $k_{1}, k_{2} \in[2, k+1]$ and $0<\delta<2^{-\frac{1}{p+1}}$, define

$$
\begin{equation*}
d_{\lambda, \delta}^{k_{1}, k_{2}}:=\inf _{A \in \Gamma_{\lambda}^{\left(k_{1}, k_{2}\right)}} \sup _{A \backslash \mathcal{P}_{\delta}} \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v) . \tag{2.17}
\end{equation*}
$$

It is easy to see that

$$
\begin{equation*}
d_{\lambda, \delta}^{k_{1}, k_{2}}<c_{k} \quad \text { for any } 0<\delta<2^{-\frac{1}{p+1}}, 2 \leq k_{1}, k_{2} \leq k+1 \tag{2.18}
\end{equation*}
$$

As a step towards to the proof of Theorem 1.1, we will prove that $d_{\lambda, \delta}^{k_{1}, k_{2}}$ is indeed a critical level of $\Phi_{\lambda}$ for $\delta$ sufficiently small. To prove Theorem 1.1, it is necessary to find a pseudogradient for $\Phi_{\lambda}$ over $\mathcal{A}$ for which $\mathcal{P}_{\delta}$ is positively invariant for the associated flow. We can now define the operator

$$
K: B_{\widetilde{m}}^{*} \rightarrow H_{r} ; \quad(u, v) \mapsto(\widetilde{\varphi}, \widetilde{\psi})
$$

that is, for any $(u, v) \in B_{\widetilde{m}}^{*}, K(u, v)=(\widetilde{\varphi}, \widetilde{\psi})$ is the unique solution of (2.16). It is easy to prove that $K\left(\sigma_{i}(u, v)\right)=\sigma_{i}(K(u, v)), i=1,2$.

Now, we give some property of the operator $K$. We can now prove that $K$ is a compact $C^{1}$ operator.

Lemma 2.5 The operator $K$ is of class $C^{1}$.
Proof Define $C^{1}$ maps $J_{i}: B_{\widetilde{m}}^{*} \times H_{r}^{1}\left(\mathbb{R}^{3}\right) \times \mathbb{R} \rightarrow H_{r}^{1}\left(\mathbb{R}^{3}\right) \times \mathbb{R}, i=1,2$, by

$$
\begin{aligned}
& J_{1}((u, v), \omega, \gamma) \\
& =\left(\omega-(-\Delta+\alpha)^{-1}\left(\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda|u|^{\frac{p-3}{2}} \omega|v|^{\frac{q+1}{2}}+\gamma t_{u, v, \lambda}^{p-1}|u|^{p-1} u\right),\right. \\
& \left.\quad \int_{\mathbb{R}^{3}}|u|^{p-1} u \omega d x-1\right)
\end{aligned}
$$

and

$$
\begin{aligned}
J_{2}( & (u, v), \omega, \gamma) \\
= & \left(\omega-(-\Delta+\beta)^{-1}\left(\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q-3}{2}} \lambda|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} \omega+\gamma s_{u, v, \lambda}^{q-1}|v|^{q-1} v\right)\right. \\
& \left.\int_{\mathbb{R}^{3}}|v|^{q-1} v \omega d x-1\right)
\end{aligned}
$$

then by $(2.16), J_{1}((u, v), \widetilde{\varphi}, \mu)=J_{2}((u, v), \widetilde{\psi}, v)=0$. Moreover, the derivatives of $J_{1}$ and $J_{2}$ with respect to $(\omega, \gamma)$ at the point $((u, v), \widetilde{\varphi}, \mu)$ and $((u, v), \widetilde{\psi}, v)$ in the direction $\left(\omega_{0}, \gamma_{0}\right)$,
respectively, are

$$
\begin{aligned}
D_{\omega, \gamma} & J_{1}((u, v), \tilde{\varphi}, \mu)\left(\omega_{0}, \gamma_{0}\right) \\
= & \left(\omega_{0}-(-\Delta+\alpha)^{-1}\left(\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda|u|^{\frac{p-3}{2}} \omega_{0}|v|^{\frac{q+1}{2}}+\gamma_{0} t_{u, v, \lambda}^{p-1}|u|^{p-1} u\right),\right. \\
& \left.\int_{\mathbb{R}^{3}}|u|^{p-1} u \omega_{0} d x\right)
\end{aligned}
$$

and

$$
\begin{aligned}
D_{\omega, \gamma} & J_{2}((u, v), \tilde{\psi}, v)\left(\omega_{0}, \gamma_{0}\right) \\
= & \left(\omega_{0}-(-\Delta+\beta)^{-1}\left(\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} \lambda_{u, v, \lambda}^{\frac{q-3}{2}} \lambda|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} \omega_{0}+\gamma_{0} s_{u, v, \lambda}^{q-1}|v|^{q-1} v\right),\right. \\
& \left.\int_{\mathbb{R}^{3}}|v|^{q-1} v \omega_{0} d x\right) .
\end{aligned}
$$

We claim that $D_{\omega, \gamma} J_{1}((u, v), \tilde{\varphi}, \mu)$ and $D_{\omega, \gamma} J_{2}((u, v), \tilde{\psi}, v)$ are bijective maps. In fact, for any $(\omega, \gamma) \in H_{r}^{1}\left(\mathbb{R}^{3}\right) \times \mathbb{R}$, the following linear problems

$$
\begin{aligned}
& -\Delta \omega_{1}+\alpha \omega_{1}-\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda|u|^{\frac{p-3}{2}} \omega_{1}|v|^{\frac{q+1}{2}}=-\Delta \omega+\alpha \omega, \\
& -\Delta \omega_{2}+\alpha \omega_{2}-\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda|u|^{\frac{p-3}{2}} \omega_{2}|v|^{\frac{q+1}{2}}=t_{u, v, \lambda}^{p-1}|u|^{p-1} u,
\end{aligned}
$$

have unique solutions $\omega_{1}, \omega_{2} \in H_{r}^{1}\left(\mathbb{R}^{3}\right), \omega_{2} \neq 0$ by $u \in B_{\widetilde{m}}^{*}$ and (2.12), then we define

$$
\gamma_{0}=\frac{\gamma-\int_{\mathbb{R}^{3}}|u|^{p-1} u \omega_{1} d x}{\int_{\mathbb{R}^{3}}|u|^{p-1} u \omega_{2} d x}
$$

we have

$$
D_{\omega, \gamma} J_{1}((u, v), \widetilde{\varphi}, \mu)\left(\omega_{1}+\gamma_{0} \omega_{2}, \gamma_{0}\right)=(\omega, \gamma),
$$

that is, $D_{\omega, \gamma} J_{1}((u, v), \widetilde{\varphi}, \mu)$ is surjective. Similarly, $D_{\omega, \gamma} J_{2}((u, v), \tilde{\psi}, v)$ is surjective.
If $D_{\omega, \gamma} J_{1}((u, v), \widetilde{\varphi}, \mu)\left(\omega_{0}, \gamma_{0}\right)=(0,0)$, then

$$
\left\{\begin{array}{l}
-\Delta \omega_{0}+\alpha \omega_{0}=\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda|u|^{\frac{p-3}{2}} \omega_{0}|v|^{\frac{q+1}{2}}+\gamma_{0} t_{u, v, \lambda}^{p-1}|u|^{p-1} u, \\
\int_{\mathbb{R}^{3}}|u|^{p-1} u \omega_{0} d x=0
\end{array}\right.
$$

so $\omega_{0} \equiv 0, \gamma_{0} t_{u, v, \lambda}^{p-1}|u|^{p-1} u \equiv 0$, by $t_{u, v, \lambda}>0, u \in B_{\widetilde{m}}^{*}$, we have $\gamma_{0}=0$, this implies $D_{\omega, \gamma} J_{1}((u, v)$, $\widetilde{\varphi}, \mu)$ is injective. Therefore, $D_{\omega, \gamma} J_{1}((u, v), \widetilde{\varphi}, \mu)$ is bijective. Similarly, $D_{\omega, \gamma} J_{2}((u, v), \widetilde{\psi}, v)$ is a bijective map. Then we can apply the implicit theorem to the $C^{1} \operatorname{maps} D_{\omega, \gamma} J_{1}((u, v), \widetilde{\varphi}, \mu)$ and $D_{\omega, \gamma} J_{2}((u, v), \tilde{\psi}, v)$, we have the conclusions.

Lemma 2.6 Let $\left\{\left(u_{n}, v_{n}\right)\right\}_{n \geq 1} \subset B_{\widetilde{m}}$. For any $0<\lambda<\lambda_{k}$, there exists $\left(\widetilde{\varphi}_{0}, \widetilde{\psi}_{0}\right) \in H_{r}$ such that, up to a subsequence,

$$
K\left(u_{n}, v_{n}\right) \rightarrow\left(\widetilde{\varphi}_{0}, \widetilde{\psi}_{0}\right), \quad \text { strongly in } H_{r} .
$$

Proof Since $\left\{\left(u_{n}, v_{n}\right)\right\}_{n \geq 1} \subset B_{\widetilde{m}}$, we have

$$
\begin{aligned}
& \left(u_{n}, v_{n}\right) \rightharpoonup\left(u_{0}, v_{0}\right) \quad \text { weakly in } H_{r}, \\
& u_{n} \rightarrow u_{0}, \quad \text { strongly in } L^{p+1}\left(\mathbb{R}^{3}\right), \\
& v_{n} \rightarrow v_{0}, \quad \text { strongly in } L^{q+1}\left(\mathbb{R}^{3}\right),
\end{aligned}
$$

and $\left|u_{0}\right|_{p+1}=\left|v_{0}\right|_{q+1}=1$. By (2.12), we also have

$$
t_{u_{n}, v_{n}, \lambda} \rightarrow t_{u_{0}, v_{0}, \lambda}>0, \quad s_{u_{n}, v_{n}, \lambda} \rightarrow s_{u_{0}, v_{0}, \lambda}>0
$$

Then by (2.3), (2.7), (2.12), and (2.15),

$$
\begin{aligned}
\frac{1}{2}\left\|\varphi_{n}\right\|_{\alpha}^{2} & \leq\left\|\varphi_{n}\right\|_{\alpha}^{2}-\frac{2}{q+1} t_{u_{n}, v_{n}, \lambda}^{\frac{p-3}{2}} s_{u_{n}, v_{n}, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{\frac{p-3}{2}} \varphi_{n}^{2}\left|v_{n}\right|^{\frac{q+1}{2}} d x \\
& =t_{u_{n}, v_{n}, \lambda}^{p-1} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{p-1} u_{n} \varphi_{n} d x \\
& \leq C \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{p}\left|\varphi_{n}\right| d x \\
& \leq C\left|u_{n}\right|_{p+1}^{p}\left|\varphi_{n}\right|_{p+1} \leq C\left\|\varphi_{n}\right\|_{\alpha} .
\end{aligned}
$$

Similar estimates hold for $\psi_{n}$, we get $\left\|\psi_{n}\right\|_{\beta}^{2} \leq C\left\|\psi_{n}\right\|_{\beta}$, so $\left\{\left(\varphi_{n}, \psi_{n}\right)\right\}_{n \geq 1} \subset H_{r}$ are bounded. Thus

$$
\begin{aligned}
& \left(\varphi_{n}, \psi_{n}\right) \rightharpoonup\left(\varphi_{0}, \psi_{0}\right) \quad \text { weakly in } H_{r}, \\
& \varphi_{n} \rightarrow \varphi_{0}, \quad \text { strongly in } L^{p+1}\left(\mathbb{R}^{3}\right) \\
& \psi_{n} \rightarrow \psi_{0}, \quad \text { strongly in } L^{q+1}\left(\mathbb{R}^{3}\right) .
\end{aligned}
$$

Then by (2.15) and Hölder's inequality,

$$
\begin{aligned}
& \int_{\mathbb{R}^{3}}\left(\nabla \varphi_{n} \nabla\left(\varphi_{n}-\varphi_{0}\right)+\alpha \varphi_{n}\left(\varphi_{n}-\varphi_{0}\right)\right) d x \\
&= \frac{2}{q+1} t_{u_{n}, v_{n}, \lambda}^{\frac{p-3}{2}} s_{u_{n}, v_{n}, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{\frac{p-3}{2}} \varphi_{n}\left(\varphi_{n}-\varphi_{0}\right)\left|v_{n}\right|^{\frac{q+1}{2}} d x \\
&+t_{u_{n}, v_{n}, \lambda}^{p-1} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{p-1} u_{n}\left(\varphi_{n}-\varphi_{0}\right) d x \\
& \quad \rightarrow 0, \quad \text { as } n \rightarrow \infty .
\end{aligned}
$$

Hence,

$$
\left\|\varphi_{n}\right\|_{\alpha}^{2}=\int_{\mathbb{R}^{3}}\left(\nabla \varphi_{n} \nabla \varphi_{0}+\alpha \varphi_{n} \varphi_{0}\right) d x+o(1)=\left\|\varphi_{0}\right\|_{\alpha}^{2}+o(1) .
$$

Similarly, we have $\left\|\psi_{n}\right\|_{\beta}^{2}=\left\|\psi_{0}\right\|_{\beta}^{2}+o(1)$. Therefore, we have $\left(\varphi_{n}, \psi_{n}\right) \rightarrow\left(\varphi_{0}, \psi_{0}\right)$ strongly in $H_{r}$ and $\left(\varphi_{0}, \psi_{0}\right)$ satisfies
since $\left|u_{0}\right|_{p+1}=\left|v_{0}\right|_{q+1}=1$, so $\varphi_{0} \neq 0, \psi_{0} \neq 0$ and

$$
\begin{aligned}
& \mu_{n}:=\frac{1}{\int_{\mathbb{R}^{3}}\left|u_{n}\right|^{p-1} u_{n} \varphi_{n} d x} \rightarrow \frac{1}{\int_{\mathbb{R}^{3}}\left|u_{0}\right|^{p-1} u_{0} \varphi_{0} d x}=: \mu_{0}, \\
& v_{n}:=\frac{1}{\int_{\mathbb{R}^{3}}\left|v_{n}\right|^{q-1} v_{n} \psi_{n} d x} \rightarrow \frac{1}{\int_{\mathbb{R}^{3}}\left|v_{0}\right|^{q-1} v_{0} \psi_{0} d x}=: v_{0} .
\end{aligned}
$$

We see that

$$
\left(\widetilde{\varphi}_{n}, \widetilde{\psi}_{n}\right)=\left(\mu_{n} \varphi_{n}, v_{n} \psi_{n}\right) \rightarrow\left(\mu_{0} \varphi_{0}, v_{0} \psi_{0}\right)=:\left(\widetilde{\varphi}_{0}, \widetilde{\psi}_{0}\right), \quad \text { strongly in } H_{r} .
$$

This completes the proof.

Define

$$
B_{\widetilde{m}, \lambda}:=\left\{(u, v) \in B_{\widetilde{m}}: \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)<c_{k}\right\},
$$

then by (2.13) we obtain $B_{m} \subset B_{\widetilde{m}, \lambda}$.
Lemma 2.7 For any $0<\delta<2^{-\frac{1}{p+1}}$ sufficiently small, we have that

$$
\operatorname{dist}(K(u, v), \mathcal{P})<\frac{\delta}{2}, \quad \forall(u, v) \in B_{\widetilde{m}, \lambda}, \quad \operatorname{dist}((u, v), \mathcal{P})<\delta .
$$

Proof Suppose by contradiction that there exist $\delta_{n} \rightarrow 0$ and $\left(u_{n}, v_{n}\right) \in B_{\widetilde{m}, \lambda}$ satisfying $\operatorname{dist}\left(\left(u_{n}, v_{n}\right), \mathcal{P}\right)<\delta_{n}$ and $\operatorname{dist}\left(K\left(u_{n}, v_{n}\right), \mathcal{P}\right) \geq \frac{\delta_{n}}{2}$. We suppose that $\operatorname{dist}\left(\left(u_{n}, v_{n}\right), \mathcal{P}\right)=\left|u_{n}^{-}\right|_{p+1}$ without loss of generality. Let $\left(\widetilde{\varphi}_{n}, \widetilde{\psi}_{n}\right)=K\left(u_{n}, v_{n}\right)$ and $\widetilde{\varphi}_{n}=\mu_{n} \varphi_{n}, \widetilde{\psi}_{n}=v_{n} \psi_{n}$. By a similar proof as in Lemma 2.6, we have that $\mu_{n}$ and $v_{n}$ are uniformly bounded. By (2.12), we can take $\lambda_{k}$ smaller if necessary such that for any $\lambda \in\left(0, \lambda_{k}\right)$ and $(u, v) \in B_{\widetilde{m}}^{*}$, we get

$$
\frac{1}{2}\left\|\widetilde{\varphi}_{n}^{-}\right\|_{\alpha}^{2} \leq\left\|\widetilde{\varphi}_{n}^{-}\right\|_{\alpha}^{2}-\frac{2}{q+1} t_{u_{n}, v_{n}, \lambda}^{\frac{p-3}{2}} s_{u_{n}, v_{n}, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{\frac{p-3}{2}}\left(\widetilde{\varphi}_{n}^{-}\right)^{2}\left|v_{n}\right|^{\frac{q+1}{2}} d x .
$$

This together with (2.7) and (2.16) allows us to get

$$
\begin{aligned}
& \left|\widetilde{\varphi}_{n}^{-}\right|_{p+1}^{2} \leq \frac{1}{S_{p}}\left\|\widetilde{\varphi}_{n}^{-}\right\|_{\alpha}^{2} \\
& \quad \leq C\left(\left\|\widetilde{\varphi}_{n}^{-}\right\|_{\alpha}^{2}-\frac{2}{q+1} t_{u_{n}, v_{n}, \lambda}^{\frac{p-3}{2}} s_{u_{n}, v_{n}, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{\frac{p-3}{2}}\left(\widetilde{\varphi}_{n}^{-}\right)^{2}\left|v_{n}\right|^{\frac{q+1}{2}} d x\right)
\end{aligned}
$$

$$
\begin{aligned}
& =-C u_{n} t_{u_{n}, v_{n}, \lambda}^{p-1} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{p-1} u_{n} \widetilde{\varphi}_{n}^{-} d x \\
& \leq C \int_{\mathbb{R}^{3}}\left(u_{n}^{-}\right)^{p} \widetilde{\varphi}_{n}^{-} d x \leq C\left|u_{n}^{-}\right|_{p+1}^{p}\left|\widetilde{\varphi}_{n}^{-}\right|_{p+1} \leq C \delta_{n}^{p}\left|\widetilde{\varphi}_{n}^{-}\right|_{p+1}
\end{aligned}
$$

and hence $\operatorname{dist}\left(K\left(u_{n}, v_{n}\right), \mathcal{P}\right) \leq\left|\widetilde{\varphi}_{n}^{-}\right|_{p+1} \leq C \delta_{n}^{p}<\frac{\delta_{n}}{2}$ for $n$ sufficiently large, which is a contradiction. This completes the proof.

Now define a map

$$
V: B_{\widetilde{m}}^{*} \rightarrow H_{r} ; \quad(u, v) \mapsto(u, v)-K(u, v)
$$

It is easy to prove that $V\left(\sigma_{i}(u, v)\right)=\sigma_{i}(V(u, v)), i=1,2$. We will prove that if $(u, v) \in B_{\widetilde{m}} \backslash \mathcal{P}$, $V(u, v)=0$, then $\left(t_{u, v, \lambda} u, s_{u, v, \lambda} v\right)$ is a sign-changing solution of Eq. (1.1). Firstly, we prove that $V$ satisfies the Palais-Smale type condition and $V$ is a pseudogradient for $\sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)$ over $B_{\tilde{m}}$. Denote $\Psi_{\lambda}(u, v):=\sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)$.

Lemma 2.8 (Palais-Smale type condition) Let $\left(u_{n}, v_{n}\right) \in B_{\widetilde{m}}$ be such that

$$
\Psi_{\lambda}\left(u_{n}, v_{n}\right) \rightarrow c<c_{k} \quad \text { and } \quad V\left(u_{n}, v_{n}\right) \rightarrow 0 \quad \text { strongly in } H_{r} .
$$

Then there exists $\left(u_{0}, v_{0}\right) \in B_{\widetilde{m}}$ such that $\left(u_{n}, v_{n}\right) \rightarrow\left(u_{0}, v_{0}\right)$ strongly in $H_{r}, u p$ to a subsequence, and $V\left(u_{0}, v_{0}\right)=0$. We also have

$$
\text { For any }(u, v) \in B_{\widetilde{m}}, \quad\left\langle\nabla \Psi_{\lambda}(u, v), V(u, v)\right\rangle_{H_{r}} \geq \frac{T_{2}^{2}}{2}\|V(u, v)\|_{H_{r}}^{2}
$$

Proof Similar as Lemma 2.6, we have, up to a subsequence,

$$
\begin{aligned}
& \left(u_{n}, v_{n}\right) \rightharpoonup\left(u_{0}, v_{0}\right) \quad \text { weakly in } H_{r}, \\
& K\left(u_{n}, v_{n}\right) \rightarrow\left(\widetilde{\varphi}_{0}, \widetilde{\psi}_{0}\right) \quad \text { strongly in } H_{r} .
\end{aligned}
$$

Then we have, as $n \rightarrow \infty$,

$$
\begin{aligned}
o(1) & =\left\langle V\left(u_{n}, v_{n}\right),\left(u_{n}-u_{0}, v_{n}-v_{0}\right)\right\rangle_{H_{r}} \\
& =\left\langle u_{n}-\widetilde{\varphi}_{n}, u_{n}-u_{0}\right\rangle_{H_{r}}+\left\langle v_{n}-\widetilde{\psi}_{n}, v_{n}-v_{0}\right\rangle_{H_{r}} \\
& =\left\langle u_{n}, u_{n}-u_{0}\right\rangle_{H_{r}}-\left\langle\widetilde{\varphi}_{n}, u_{n}-u_{0}\right\rangle_{H_{r}}+\left\langle v_{n}, v_{n}-v_{0}\right\rangle_{H_{r}}-\left\langle\widetilde{\psi}_{n}, v_{n}-v_{0}\right\rangle_{H_{r}}
\end{aligned}
$$

whence

$$
\left\langle u_{n}, u_{n}-u_{0}\right\rangle_{H_{r}}+\left\langle v_{n}, v_{n}-v_{0}\right\rangle_{H_{r}}=o(1)
$$

Then $\left(u_{n}, v_{n}\right) \rightarrow\left(u_{0}, v_{0}\right)$ strongly in $H_{r}$ and $\left(u_{0}, v_{0}\right) \in \bar{B}_{\widetilde{m}}$,

$$
\Phi_{\lambda}\left(t_{u_{0}, v_{0}, \lambda} u_{0}, s_{u_{0}, v_{0}, \lambda} v_{0}\right)=\lim _{n \rightarrow \infty} \Phi_{\lambda}\left(t_{u_{n}, v_{n}, \lambda} u_{n}, s_{u_{n}, v_{n}, \lambda} v_{n}\right)=c<c_{k},
$$

then by (2.13), we have $\left(u_{0}, v_{0}\right) \in B_{\widetilde{m}}, V\left(u_{0}, v_{0}\right)=\lim _{n \rightarrow \infty} V\left(u_{n}, v_{n}\right)=0$.

Finally, we prove that $V$ is a pseudogradient for $\Psi_{\lambda}(u, v)$ over $B_{\widetilde{m}}$. By (2.9) and (2.10) we can prove that

$$
\begin{align*}
\left\langle\nabla \Psi_{\lambda}(u, v),(\omega, 0)\right\rangle_{H_{r}}= & t_{u, v, \lambda}^{2} \int_{\mathbb{R}^{3}}(\nabla u \nabla \omega+\alpha u \omega) d x \\
& -\frac{2 \lambda}{q+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \int_{\mathbb{R}^{3}}|u|^{\frac{p-3}{2}} u \omega|v|^{\frac{q+1}{2}} d x,  \tag{2.19}\\
\left\langle\nabla \Psi_{\lambda}(u, v),(0, \omega)\right\rangle_{H_{r}}= & s_{u, v, \lambda}^{2} \int_{\mathbb{R}^{3}}(\nabla v \nabla \omega+\beta v \omega) d x \\
& -\frac{2 \lambda}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} v \omega d x \tag{2.20}
\end{align*}
$$

hold for any $(u, v) \in \mathcal{B}_{\widetilde{m}}$ and $\omega \in H_{r}^{1}\left(\mathbb{R}^{3}\right)$. We can take $\lambda_{k}$ smaller if necessary such that for any $\lambda \in\left(0, \lambda_{k}\right)$ by (2.19), (2.20), (2.12), and (2.16)

$$
\begin{aligned}
& \left\langle\nabla \Psi_{\lambda}(u, v), V(u, v)\right\rangle_{H_{r}} \\
& =t_{u, v, \lambda}^{2} \int_{\mathbb{R}^{3}}(\nabla u \nabla(u-\widetilde{\varphi})+\alpha u(u-\widetilde{\varphi})) d x \\
& +s_{u, v, \lambda}^{2} \int_{\mathbb{R}^{3}}(\nabla v \nabla(v-\tilde{\psi})+\beta v(v-\widetilde{\psi})) d x \\
& -\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p+1}{2}} \frac{q}{u, v, \lambda}_{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p-3}{2}} u(u-\widetilde{\varphi})|v|^{\frac{q+1}{2}} d x \\
& -\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} v(v-\widetilde{\psi}) d x \\
& =t_{u, v, \lambda}^{2}\|u-\widetilde{\varphi}\|_{\alpha}^{2}+s_{u, v, \lambda}^{2}\|v-\widetilde{\psi}\|_{\beta}^{2} \\
& +t_{u, v, \lambda}^{2} \int_{\mathbb{R}^{3}}(\nabla \widetilde{\varphi} \nabla(u-\widetilde{\varphi})+\alpha \widetilde{\varphi}(u-\widetilde{\varphi})) d x \\
& +s_{u, v, \lambda}^{2} \int_{\mathbb{R}^{3}}(\nabla \tilde{\psi} \nabla(u-\tilde{\psi})+\alpha \tilde{\psi}(v-\widetilde{\psi})) d x \\
& -\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p+1}{2}}{ }^{\frac{q+1}{2}} u_{u, \lambda, \lambda} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p-3}{2}} u(u-\widetilde{\varphi})|v|^{\frac{q+1}{2}} d x \\
& -\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} v(v-\widetilde{\psi}) d x \\
& =t_{u, v, \lambda}^{2}\|u-\widetilde{\varphi}\|_{\alpha}^{2}+s_{u, v, \lambda}^{2}\|v-\widetilde{\psi}\|_{\beta}^{2} \\
& -\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p-3}{2}}(u-\widetilde{\varphi})^{2}|v|^{\frac{q+1}{2}} d x \\
& -\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}}(v-\widetilde{\psi})^{2} d x \\
& \geq \frac{t_{u, v, \lambda}^{2}}{2}\|u-\widetilde{\varphi}\|_{\alpha}^{2}+\frac{s_{u, v, \lambda}^{2}}{2}\|v-\widetilde{\psi}\|_{\beta}^{2} \\
& \geq \frac{T_{2}^{2}}{2}\left(\|u-\widetilde{\varphi}\|_{\alpha}^{2}+\|v-\widetilde{\psi}\|_{\beta}^{2}\right)=\frac{T_{2}^{2}}{2}\|V(u, v)\|_{H_{r}}^{2} .
\end{aligned}
$$

This completes the proof.

Lemma 2.9 There exists a unique global solution $\eta=\left(\eta_{1}, \eta_{2}\right): \mathbb{R}^{+} \times B_{\widetilde{m}, \lambda} \rightarrow H_{r}$ for the initial value problem

$$
\left\{\begin{array}{l}
\frac{d}{d t} \eta(t,(u, v))=-V(\eta(t,(u, v)))  \tag{2.21}\\
\eta(0,(u, v))=(u, v) \in B_{\widetilde{m}, \lambda}
\end{array}\right.
$$

## Moreover,

(1) For any $t>0$ and $(u, v) \in B_{\widetilde{m}, \lambda}$, there holds $\eta(t,(u, v)) \in B_{\widetilde{m}, \lambda}$;
(2) For any $t>0,(u, v) \in B_{\widetilde{m}, \lambda}$, there holds $\eta\left(t, \sigma_{i}(u, v)\right)=\sigma_{i}(\eta(t,(u, v))), i=1,2$;
(3) For any $(u, v) \in B_{\widetilde{m}, \lambda}, \Psi_{\lambda}(\eta(t,(u, v)))$ is nonincreasing in $t$;
(4) There exists $\delta_{0} \in\left(0,2^{-\frac{1}{p+1}}\right)$ such that, for any $0<\delta<\delta_{0},(u, v) \in B_{\widetilde{m}, \lambda} \cap \mathcal{P}_{\delta}$ and $t>0$, there holds $\eta(t,(u, v)) \in \mathcal{P}_{\delta}$.

Proof It follows from Lemma 2.5 that $V \in C^{1}\left(B_{\widetilde{m}}^{*}, H_{r}\right)$. As $B_{\widetilde{m}, \lambda} \subset B_{\widetilde{m}} \subset B_{\widetilde{m}}^{*}$, we get that $V \in C^{1}\left(B_{\widetilde{m}, \lambda}, H_{r}\right)$. Then there exists a solution $\eta:\left[0, T_{\max }\right) \times B_{\widetilde{m}, \lambda} \rightarrow H_{r}$, where $T_{\max }$ is the maximal time such that (2.21) has a solution $\eta \in B_{\widetilde{m}}^{*}$.
For any $(u, v) \in B_{\widetilde{m}, \lambda}$ and $t \in\left(0, T_{\max }\right)$, there holds

$$
\begin{aligned}
& \frac{d}{d t} \\
& \quad \int_{\mathbb{R}^{3}}\left|\eta_{1}(t,(u, v))\right|^{p+1} d x \\
& \quad=-(p+1) \int_{\mathbb{R}^{3}}\left|\eta_{1}(t,(u, v))\right|^{p-1} \eta_{1}(t,(u, v)) V_{1}(\eta(t,(u, v))) d x \\
& \quad=-(p+1) \int_{\mathbb{R}^{3}}\left|\eta_{1}(t,(u, v))\right|^{p-1} \eta_{1}(t,(u, v))\left[\eta_{1}(t,(u, v))-K_{1}(\eta(t,(u, v)))\right] d x \\
& \quad=(p+1)-(p+1) \int_{\mathbb{R}^{3}}\left|\eta_{1}(t,(u, v))\right|^{p+1} d x,
\end{aligned}
$$

so we have

$$
\frac{d}{d t}\left[e^{(p+1) t}\left(\int_{\mathbb{R}^{3}}\left|\eta_{1}(t,(u, v))\right|^{p+1} d x-1\right)\right]=0
$$

Then

$$
\begin{aligned}
e^{(p+1) t}\left(\int_{\mathbb{R}^{3}}\left|\eta_{1}(t,(u, v))\right|^{p+1} d x-1\right) & =\int_{\mathbb{R}^{3}}\left|\eta_{1}(0,(u, v))\right|^{p+1} d x-1 \\
& =\int_{\mathbb{R}^{3}}|u|^{p+1} d x-1 \equiv 0 .
\end{aligned}
$$

Similarly, there holds

$$
\begin{aligned}
e^{(q+1) t}\left(\int_{\mathbb{R}^{3}}\left|\eta_{2}(t,(u, v))\right|^{q+1} d x-1\right) & =\int_{\mathbb{R}^{3}}\left|\eta_{2}(0,(u, v))\right|^{q+1} d x-1 \\
& =\int_{\mathbb{R}^{3}}|v|^{q+1} d x-1 \equiv 0,
\end{aligned}
$$

we deduce that for any $(u, v) \in B_{\widetilde{m}, \lambda}$ and $t \in\left[0, T_{\max }\right)$,

$$
\int_{\mathbb{R}^{3}}\left|\eta_{1}(t,(u, v))\right|^{p+1} d x \equiv \int_{\mathbb{R}^{3}}\left|\eta_{2}(t,(u, v))\right|^{q+1} d x \equiv 1 .
$$

Thus, for any $t \in\left[0, T_{\max }\right),(u, v) \in B_{\widetilde{m}}$, we have $\eta(t,(u, v)) \in B_{\widetilde{m}}^{*} \cap \mathcal{A}=B_{\widetilde{m}}$. If $T_{\max }<+\infty$, then $\eta\left(T_{\max },(u, v)\right) \in \mathcal{C}_{\widetilde{m}}$. There holds $\Psi_{\lambda}\left(\eta\left(T_{\max },(u, v)\right)\right) \geq c_{k}$ by (2.13). Moreover,

$$
\begin{align*}
\frac{d}{d t} \Psi_{\lambda}(\eta(t,(u, v))) & =\left\langle\nabla \Psi_{\lambda}(\eta(t,(u, v))), \frac{d}{d t} \eta(t,(u, v))\right\rangle_{H_{r}} \\
& =-\left\langle\nabla \Psi_{\lambda}(\eta(t,(u, v))), V(\eta(t,(u, v)))\right\rangle_{H_{r}}  \tag{2.22}\\
& \leq-\frac{T_{2}^{2}}{2}\|V(\eta(t,(u, v)))\|_{H_{r}}^{2} \leq 0 .
\end{align*}
$$

On the other hand, we see from $(u, v) \in B_{\widetilde{m}, \lambda}$ and (2.22),

$$
\Psi_{\lambda}\left(\eta\left(T_{\max },(u, v)\right)\right) \leq \Psi_{\lambda}(\eta(0,(u, v)))=\Psi_{\lambda}(u, v)<c_{k}
$$

it yields a contradiction, so $T_{\max }=+\infty, \eta(t,(u, v)) \in B_{\widetilde{m}, \lambda}$ and (1)(3) hold.
Since $V\left(\sigma_{i}(u, v)\right)=\sigma_{i}(V(u, v)), i=1,2$, then (2) holds.
Take $\delta_{0}>0$ as in Lemma 2.7, note that as $t \rightarrow 0$,

$$
\begin{aligned}
\eta(t,(u, v)) & =(u, v)+\left.t \frac{d}{d t} \eta(t,(u, v))\right|_{t=0}+o(t) \\
& =(u, v)-t V(u, v)+o(t)=(1-t)(u, v)+t K(u, v)+o(t)
\end{aligned}
$$

hence for any $0<\delta<\delta_{0},(u, v) \in B_{\widetilde{m}, \lambda} \cap \mathcal{P}_{\delta}$, we have

$$
\begin{aligned}
\operatorname{dist}(\eta(t,(u, v)), \mathcal{P}) & =\operatorname{dist}((1-t)(u, v)+t K(u, v)+o(t), \mathcal{P}) \\
& \leq(1-t) \operatorname{dist}((u, v), \mathcal{P})+t \operatorname{dist}(K(u, v), \mathcal{P})+o(t) \\
& <(1-t) \delta+\frac{t \delta}{2}+o(t)<\delta
\end{aligned}
$$

for sufficiently small $t>0$, and (4) holds. This completes the proof.
To prove Theorem 1.1, we will give that $d_{\lambda, \delta}^{k_{1}, k_{2}}$ is indeed critical energy level for $\delta>0$ sufficiently small.

Lemma 2.10 For any $k \in \mathbb{N}, k_{1}, k_{2} \in[2, k+1], 0<\delta<\delta_{0}$, and $0<\lambda<\lambda_{k}$, there exists $\left(\widetilde{u}_{0}, \widetilde{v}_{0}\right) \in H_{r}$ such that $\left(\widetilde{u}_{0}, \widetilde{v}_{0}\right)$ is a sign-changing solution of $E q$. (1.1) and $\Phi_{\lambda}\left(\widetilde{u}_{0}, \widetilde{v}_{0}\right)=d_{\lambda, \delta}^{k_{1}, k_{2}}$.

Proof By (2.18) we see that $d_{\lambda, \delta}^{k_{1}, k_{2}}<c_{k}$. Assume that there is small $0<\varepsilon<1$ such that for any $(u, v) \in B_{\widetilde{m}, \lambda},\left|\Psi_{\lambda}(u, v)-d_{\lambda, \delta}^{k_{1}, k_{2}}\right| \leq 2 \varepsilon$, $\operatorname{dist}((u, v), \mathcal{P}) \geq \delta$, there holds $\|V(u, v)\|_{H_{r}}^{2} \geq \varepsilon$. By (2.17), there exists $A \in \Gamma_{\lambda}^{\left(k_{1}, k_{2}\right)}$ such that

$$
\begin{equation*}
\sup _{A \backslash \mathcal{P}_{\delta}} \Psi_{\lambda}(u, v)<d_{\lambda, \delta}^{k_{1}, k_{2}}+\varepsilon, \tag{2.23}
\end{equation*}
$$

then $\sup _{A} \Psi_{\lambda}(u, v)<c_{k}, A \subset B_{\widetilde{m}, \lambda}$. Thus we consider the set $A_{0}=\eta\left(\frac{4}{T_{2}^{2}}, A\right), A_{0} \in B_{\widetilde{m}, \lambda}$ by Lemma 2.9(1). From Lemma 2.2(2), Lemma 2.3, and Lemma 2.9(3), we get

$$
\sup _{A_{0}} \Psi_{\lambda}(u, v) \leq \sup _{A} \Psi_{\lambda}(u, v)<c_{k}
$$

so $A_{0} \in \Gamma_{\lambda}^{\left(k_{1}, k_{2}\right)}$ and $A_{0} \backslash \mathcal{P}_{\delta} \neq \emptyset$. Then, by (2.15), (2.19), and Lemma 2.9(3), for the $\varepsilon>0$, $t \in\left[0, \frac{4}{T_{2}^{2}}\right]$, there exists $(u, v) \in A$ such that $\eta\left(\frac{4}{T_{2}^{2}},(u, v)\right) \in A_{0} \backslash \mathcal{P}_{\delta}$ satisfying

$$
\begin{align*}
d_{\lambda, \delta}^{k_{1}, k_{2}} & \leq \sup _{A_{0} \backslash \mathcal{P}_{\delta}} \Psi_{\lambda}(u, v)<\Psi_{\lambda}\left(\eta\left(\frac{4}{T_{2}^{2}},(u, v)\right)\right)+\varepsilon  \tag{2.24}\\
& \leq \Psi_{\lambda}(\eta(t,(u, v)))+\varepsilon \leq \Psi_{\lambda}(u, v)+\varepsilon<d_{\lambda, \delta}^{k_{1}, k_{2}}+2 \varepsilon .
\end{align*}
$$

We conclude that $\|V(\eta(t,(u, v)))\|_{H_{r}}^{2} \geq \varepsilon$ for any $t \in\left[0, \frac{4}{T_{2}^{2}}\right]$ and

$$
\begin{aligned}
\frac{d}{d t} \Psi_{\lambda}(\eta(t,(u, v))) & =-\left\langle\nabla \Psi_{\lambda}(\eta(t,(u, v))), V(\eta(t,(u, v)))\right\rangle_{H_{r}} \\
& \leq-\frac{T_{2}^{2}}{2}\|V(\eta(t,(u, v)))\|_{H_{r}}^{2} \leq-\frac{T_{2}^{2}}{2} \varepsilon .
\end{aligned}
$$

Therefore, by integrating over 0 to $\frac{4}{T_{2}^{2}}$ and (2.24), we have

$$
\begin{aligned}
\left(d_{\lambda, \delta}^{k_{1}, k_{2}}-\varepsilon\right)-\left(d_{\lambda, \delta}^{k_{1}, k_{2}}+\varepsilon\right) & <\Psi_{\lambda}\left(\eta\left(\frac{4}{T_{2}^{2}},(u, v)\right)\right)-\Psi_{\lambda}(u, v) \\
& \leq-\frac{T_{2}^{2}}{2} \varepsilon \int_{0}^{\frac{4}{T_{2}^{2}}} d t=-2 \varepsilon,
\end{aligned}
$$

it yields a contradiction, and therefore, for any $\varepsilon=\frac{1}{n}>0$, there exists $\left(u_{n}, v_{n}\right) \in B_{\widetilde{m}, \lambda}$ such that

$$
\left|\Psi_{\lambda}\left(u_{n}, v_{n}\right)-d_{\lambda, \delta}^{k_{1}, k_{2}}\right| \leq 2 \varepsilon, \quad\left\|V\left(u_{n}, v_{n}\right)\right\|_{H_{r}}^{2} \leq \varepsilon \quad \text { and } \quad \operatorname{dist}\left(\left(u_{n}, v_{n}\right), \mathcal{P}\right) \geq \delta .
$$

By Lemma 2.8, there exists $\left(u_{0}, v_{0}\right) \in B_{\widetilde{m}, \lambda}$ such that $\left(u_{n}, v_{n}\right) \rightarrow\left(u_{0}, v_{0}\right)$ strongly in $H_{r}$, up to a subsequence. Hence, we have

$$
\Psi_{\lambda}\left(u_{0}, v_{0}\right)=d_{\lambda, \delta}^{k_{1}, k_{2}}, \quad V\left(u_{0}, v_{0}\right)=0 \quad \text { and } \quad \operatorname{dist}\left(\left(u_{0}, v_{0}\right), \mathcal{P}\right) \geq \delta .
$$

We conclude that $\left(u_{0}, v_{0}\right)$ is sign-changing and $\left(u_{0}, v_{0}\right)=K\left(u_{0}, v_{0}\right)=\left(\widetilde{\varphi}_{0}, \widetilde{\psi}_{0}\right)$. It follows from (2.16) that ( $u_{0}, v_{0}$ ) satisfies

$$
\left\{\begin{array}{l}
-\Delta u_{0}+\alpha u_{0}=\mu t_{u_{0}, v_{0}, \lambda}^{p-1}\left|u_{0}\right|^{p-1} u_{0}+\frac{2}{q+1} t_{u_{0}, v_{0}, \lambda}^{\frac{p-3}{2}} s_{u_{u_{0}}}^{\frac{q+1}{2}} \lambda\left|u_{0}\right|^{\frac{p-3}{2}} u_{0}\left|v_{0}\right|^{\frac{q+1}{2}},  \tag{2.25}\\
-\Delta v_{0}+\beta v_{0}=v s_{u_{0}, v_{0}, \lambda}^{q-1}\left|v_{0}\right|^{q-1} v_{0}+\frac{2}{p+1} t_{u_{0}, v_{0}, \lambda}^{\frac{p+1}{2}} s_{u_{0}, v_{0}, \lambda}^{2} \\
\left.u_{0}\right|^{\frac{p+1}{2}}\left|v_{0}\right|^{\frac{q-3}{2}} v_{0}, \\
u_{0}(x) \rightarrow 0, \quad v_{0}(x) \rightarrow 0, \quad \text { as }|x| \rightarrow \infty
\end{array}\right.
$$

On the other hand, $t_{u_{0}, v_{0}, \lambda}$ and $s_{u_{0}, v_{0}, \lambda}$ satisfy

$$
\begin{aligned}
& \left\|u_{0}\right\|_{\alpha}^{2}=t_{u_{0}, v_{0}, \lambda}^{p-1}\left|u_{0}\right|_{p+1}^{p+1}+\frac{2}{q+1} t_{u_{0}, v_{0}, \lambda}^{\frac{p-3}{2}} s_{u_{0}, v_{0}, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}\left|u_{0}\right|^{\frac{p+1}{2}}\left|v_{0}\right|^{\frac{q+1}{2}} d x, \\
& \left\|v_{0}\right\|_{\beta}^{2}=s_{u_{0}, v_{0}, \lambda}^{q-1}\left|v_{0}\right|_{q+1}^{q+1}+\frac{2}{p+1} t_{u_{0}, v_{0}, \lambda}^{\frac{p+1}{2}} s_{u_{0}, v_{0}, \lambda}^{\frac{q-3}{2}} \lambda \int_{\mathbb{R}^{3}}\left|u_{0}\right|^{\frac{p+1}{2}}\left|v_{0}\right|^{\frac{q+1}{2}} d x,
\end{aligned}
$$

then we have $\mu=v=1$. Hence, we have that $\left(t_{u_{0}, v_{0}, \lambda} u_{0}, s_{u_{0}, v_{0}, \lambda} v_{0}\right)$ is a sign-changing solution of Eq. (1.1) by problem (2.25) and

$$
\Phi_{\lambda}\left(\widetilde{u}_{0}, \widetilde{v}_{0}\right):=\Phi_{\lambda}\left(t_{u_{0}, v_{0}, \lambda} u_{0}, s_{u_{0}, v_{0}, \lambda} v_{0}\right)=\Psi_{\lambda}\left(u_{0}, v_{0}\right)=d_{\lambda, \delta}^{k_{1}, k_{2}}
$$

This completes the proof.

Proof of Theorem 1.1 Observe that from Lemma 2.10 we know that for any $k \in \mathbb{N}, k_{1}, k_{2} \in$ [ $2, k+1], 0<\delta<\delta_{0}$, and $0<\lambda<\lambda_{k}$, there exists a sign-changing solution ( $\widetilde{u}_{0}, \widetilde{v}_{0}$ ) with $\Phi_{\lambda}\left(\widetilde{u}_{0}, \widetilde{v}_{0}\right)=d_{\lambda, \delta}^{k_{1}, k_{2}}$. For any fixed $k_{1} \in[2, k+1]$, we have

$$
d_{\lambda, \delta}^{k_{1}, 2} \leq d_{\lambda, \delta}^{k_{1}, 3} \leq \cdots \leq d_{\lambda, \delta}^{k_{1}, k} \leq d_{\lambda, \delta}^{k_{1}, k+1}<c_{k}
$$

Suppose that problem (1.1) has at most $k-1$ sign-changing solutions by contradiction, then there exists $k_{2} \in[2, k]$ satisfying

$$
d:=d_{\lambda, \delta}^{k_{1}, k_{2}}=d_{\lambda, \delta}^{k_{1}, k_{2}+1}<c_{k} .
$$

Now define

$$
\mathcal{M}:=\left\{(u, v) \in B_{\widetilde{m}}:(u, v) \text { sign-changing, } \Psi_{\lambda}(u, v)=d, V(u, v)=0\right\},
$$

then $\mathcal{M} \subset \mathcal{F}$ is finite. So there exist $N \in[1, k-1]$ and $\left\{\left(u_{n}, v_{n}\right)\right\}_{1 \leq n \leq N} \subset \mathcal{M}$ such that

$$
\mathcal{M}=\left\{\left\{\left(u_{n}, v_{n}\right)\right\} \cup\left\{\left(-u_{n}, v_{n}\right)\right\} \cup\left\{\left(u_{n},-v_{n}\right)\right\} \cup\left\{\left(-u_{n},-v_{n}\right)\right\}\right\}_{1 \leq n \leq N} .
$$

For any $1 \leq n \leq N$, there exist open neighborhoods $\Omega_{n}^{1}, \Omega_{n}^{2}, \Omega_{n}^{3}, \Omega_{n}^{4}$ of $\left\{\left(u_{n}, v_{n}\right)\right\},\left\{\left(-u_{n}, v_{n}\right)\right\}$, $\left\{\left(u_{n},-v_{n}\right)\right\},\left\{\left(-u_{n},-v_{n}\right)\right\}$, respectively, such that

$$
\begin{aligned}
& \Omega_{n}^{1} \cap \Omega_{n}^{2} \cap \Omega_{n}^{3} \cap \Omega_{n}^{4}=\emptyset, \\
& \mathcal{M} \subset \bigcup_{n=1}^{3}\left(\Omega_{n}^{1} \cup \Omega_{n}^{2} \cup \Omega_{n}^{3} \cup \Omega_{n}^{4}\right)=: \Omega
\end{aligned}
$$

Define

$$
\mathcal{M}_{\rho}:=\left\{(u, v) \in B_{\widetilde{m}}: \operatorname{dist}_{H_{r}}((u, v), \mathcal{M})<\rho\right\},
$$

we can choose $\rho>0$ small enough such that $\mathcal{M}_{2 \rho} \subset \Omega$. Since $\mathcal{M}$ is finite, then there is $\varepsilon_{0} \in\left(0, \frac{c_{k}-d}{2}\right)$ such that for any $(u, v) \in B_{\widetilde{m}} \backslash\left(\mathcal{P}_{\delta} \cup \mathcal{M}_{\rho}\right),\left|\Psi_{\lambda}(u, v)-d\right| \leq 2 \varepsilon_{0}$, we have

$$
\begin{equation*}
\|V(u, v)\|_{H_{r}}^{2} \geq \varepsilon_{0} \tag{2.26}
\end{equation*}
$$

In fact, if for any $\varepsilon=\frac{1}{n}>0$ there exists $\left(u_{n}, v_{n}\right) \in B_{\widetilde{m}} \backslash\left(\mathcal{P}_{\delta} \cup \mathcal{M}_{\rho}\right)$ satisfying $\left|\Psi_{\lambda}\left(u_{n}, v_{n}\right)-d\right| \leq$ $2 \varepsilon$, then there holds $\left\|V\left(u_{n}, v_{n}\right)\right\|_{H_{r}}^{2} \leq \varepsilon$. Then, by Lemma 2.8, there exists $\left(u_{0}, v_{0}\right) \in$ $B_{\widetilde{m}} \backslash\left(\mathcal{P}_{\delta} \cup \mathcal{M}_{\rho}\right)$ such that $\left(u_{n}, v_{n}\right) \rightarrow\left(u_{0}, v_{0}\right)$ strongly in $H_{r}$, up to a subsequence, $\Psi_{\lambda}\left(u_{0}, v_{0}\right)=$ $d$ and $V\left(u_{0}, v_{0}\right)=0$. Therefore, $\left(u_{0}, v_{0}\right) \in \mathcal{M}_{\rho}$. It yields a contradiction.

Moreover, for $(u, v) \in \mathcal{M}, V(u, v)=0$, then for $\rho>0$ small enough, there exists $T_{0}>0$ such that for any $(u, v) \in \overline{\mathcal{M}}_{2 \rho}$,

$$
\begin{equation*}
\|V(u, v)\|_{H_{r}} \leq T_{0} \tag{2.27}
\end{equation*}
$$

Let

$$
\begin{equation*}
T:=\frac{1}{2} \min \left\{1, \frac{\rho T_{2}^{2}}{4 T_{0}}\right\} \tag{2.28}
\end{equation*}
$$

By (2.17), for $\varepsilon_{0}>0$, there exists $A \in \Gamma_{\lambda}^{\left(k_{1}, k_{2}+1\right)}$ such that

$$
\begin{equation*}
\sup _{A \backslash \mathcal{P}_{\delta}} \Psi_{\lambda}(u, v)<d_{\lambda, \delta}^{k_{1}, k_{2}+1}+\frac{T \varepsilon_{0}}{2}=d+\frac{T \varepsilon_{0}}{2} \tag{2.29}
\end{equation*}
$$

Let $B:=A \backslash \mathcal{M}_{2 \rho}$, then $B \subset \mathcal{F}$.
We claim that $\gamma(B) \geq\left(k_{1}, k_{2}\right)$. In view of a contradiction, suppose that $\gamma(B)<\left(k_{1}, k_{2}\right)$. From Definition 2.1, we know that there exists $f \in F_{\left(k_{1}, k_{2}\right)}(B)$ such that $f(u, v)=\left(f_{1}(u, v)\right.$, $\left.f_{2}(u, v)\right) \neq(0,0)$ for any $(u, v) \in B$. Take $\widetilde{f}=\left(\widetilde{f}_{1}, \widetilde{f}_{2}\right) \in C\left(H_{r}, \mathbb{R}^{k_{1}-1} \times \mathbb{R}^{k_{2}-1}\right)$ such that $\left.\widetilde{f}\right|_{B}=f$ by Tietze's extension theorem. Define

$$
\begin{aligned}
& F_{1}(u, v):=\tilde{f}_{1}(u, v)+\tilde{f}_{1}\left(\sigma_{2}(u, v)\right)-\tilde{f}_{1}\left(\sigma_{1}(u, v)\right)-\tilde{f}_{1}(-u,-v), \\
& F_{2}(u, v):=\widetilde{f}_{2}(u, v)+\tilde{f}_{2}\left(\sigma_{1}(u, v)\right)-\tilde{f}_{2}\left(\sigma_{2}(u, v)\right)-\tilde{f}_{2}(-u,-v),
\end{aligned}
$$

then $F:=\left(F_{1}, F_{2}\right) \in C\left(H_{r}, \mathbb{R}^{k_{1}-1} \times \mathbb{R}^{k_{2}-1}\right),\left.F\right|_{B}=4 \widetilde{f}, F_{i}\left(\sigma_{i}(u, v)\right)=-4 \widetilde{f}_{i}(u, v)=-F_{i}(u, v)$ and $F_{i}\left(\sigma_{j}(u, v)\right)=4 \widetilde{f}_{i}(u, v)=F_{i}(u, v), i \neq j, i, j=1,2$.

Define the continuous function

$$
g(u, v):= \begin{cases}1, & (u, v) \in \bigcup_{n=1}^{3}\left(\overline{\Omega_{n}^{1}} \cup \overline{\Omega_{n}^{2}}\right), \\ -1, & (u, v) \in \bigcup_{n=1}^{3}\left(\overline{\Omega_{n}^{3}} \cup \overline{\Omega_{n}^{4}}\right)\end{cases}
$$

and $g\left(\sigma_{1}(u, v)\right)=g(u, v), g\left(\sigma_{2}(u, v)\right)=-g(u, v)$. Take $\tilde{g} \in C\left(H_{r}, \mathbb{R}\right)$ such that $\left.\tilde{g}\right|_{\Omega}=g$ by Tietze's extension theorem. Define

$$
G(u, v):=\widetilde{g}(u, v)+\widetilde{g}\left(\sigma_{1}(u, v)\right)-\widetilde{g}\left(\sigma_{2}(u, v)\right)-\widetilde{g}(-u,-v),
$$

then $G \in C\left(H_{r}, \mathbb{R}\right),\left.G\right|_{\Omega}=4 \widetilde{g}, G\left(\sigma_{1}(u, v)\right)=G(u, v)$, and $G\left(\sigma_{2}(u, v)\right)=-G(u, v)$. Therefore, we can define

$$
\begin{aligned}
& H_{1}(u, v):=F_{1}(u, v) \in \mathbb{R}^{k_{1}-1} \\
& H_{2}(u, v):=\left(F_{2}(u, v), G(u, v)\right) \in \mathbb{R}^{k_{2}}
\end{aligned}
$$

then $H:=\left(H_{1}, H_{2}\right) \in C\left(A, \mathbb{R}^{k_{1}-1} \times \mathbb{R}^{k_{2}}\right)$ and $H \in F_{\left(k_{1}, k_{2}+1\right)}(A)$. Since $A \in \Gamma_{\lambda}^{\left(k_{1}, k_{2}+1\right)}, \gamma(A) \geq$ $\left(k_{1}, k_{2}+1\right)$, so there exists $(u, v) \in A$ such that $H(u, v)=(0,0)$. If $(u, v) \in B=A \backslash \mathcal{M}_{2 \rho}$, then

$$
F(u, v)=4 \widetilde{f}(u, v)=4 f(u, v) \neq(0,0)
$$

a contradiction. Thus $(u, v) \in \mathcal{M}_{2 \rho}$, then

$$
G(u, v)=4 \widetilde{g}(u, v)=4 g(u, v) \neq(0,0)
$$

a contradiction. Therefore, $\gamma(B) \geq\left(k_{1}, k_{2}\right)$.
Since $B \subset A \subset B_{\widetilde{m}}, \sup _{B} \Psi_{\lambda}(u, v) \leq \sup _{A} \Psi_{\lambda}(u, v)<c_{k}$, then we have $B \subset B_{\widetilde{m}, \lambda}$ and $B \in$ $\Gamma_{\lambda}^{\left(k_{1}, k_{2}\right)}$. Define $B_{0}:=\eta\left(\frac{\rho}{2 T_{0}}, B\right)$, then $B_{0} \subset B_{\widetilde{m}, \lambda}, B_{0} \in \Gamma^{\left(k_{1}, k_{2}\right)}, B_{0} \backslash P_{\delta} \neq \emptyset$, and $\sup _{B_{0}} \Psi_{\lambda}(u, v) \leq$ $\sup _{B} \Psi_{\lambda}(u, v)<c_{k}$ by Lemma 2.2(2) and Lemma 2.3, so $B_{0} \in \Gamma_{\lambda}^{\left(k_{1}, k_{2}\right)}$. Thus $\sup _{B_{0} \backslash \mathcal{P}_{\delta}} \Psi_{\lambda}(u$, $v) \geq d_{\lambda, \delta}^{k_{1}, k_{2}}$ by (2.17).
We claim that $\eta(t,(u, v)) \notin \mathcal{M}_{\rho}$ for any $t \in\left(0, \frac{\rho}{2 T_{0}}\right),(u, v) \in B$. In view of a contradiction, if there exists $t_{0} \in\left(0, \frac{\rho}{2 T_{0}}\right)$ such that $\eta\left(t_{0},(u, v)\right) \in \mathcal{M}_{\rho}$, for $(u, v) \in B=A \backslash \mathcal{M}_{2 \rho}$, by the continuity of $\eta$, there exists $0 \leq t_{1}<t_{2} \leq t_{0}$ satisfying $\eta\left(t_{1},(u, v)\right) \in \partial \mathcal{M}_{2 \rho}, \eta\left(t_{2},(u, v)\right) \in \partial \mathcal{M}_{\rho}$, and $\eta(t,(u, v)) \in \mathcal{M}_{2 \rho} \backslash \mathcal{M}_{\rho}$ for any $t \in\left(t_{1}, t_{2}\right)$. Then by (2.27) we have

$$
\rho \leq\left\|\eta\left(t_{1},(u, v)\right)-\eta\left(t_{2},(u, v)\right)\right\|_{H_{r}}=\left\|\int_{t_{1}}^{t_{2}} V(\eta(t,(u, v)))\right\|_{H_{r}} \leq 2 T_{0}\left(t_{2}-t_{1}\right)
$$

so $\frac{\rho}{2 T_{0}} \leq t_{2}-t_{1} \leq t_{0}-0<\frac{\rho}{2 T_{0}}$, this yields a contradiction.
For $\varepsilon_{0}>0$, there exists $(u, v) \in B$ such that $\eta\left(\frac{\rho}{2 T_{0}},(u, v)\right) \in B_{0} \backslash \mathcal{P}_{\delta}$ satisfies

$$
d_{\lambda, \delta}^{k_{1}, k_{2}} \leq \sup _{B_{0} \backslash \mathcal{P}_{\delta}} \Psi_{\lambda}(u, v)<\Psi_{\lambda}\left(\eta\left(\frac{\rho}{2 T_{0}},(u, v)\right)\right)+\frac{T \varepsilon_{0}}{2} .
$$

Moreover, $\eta(t,(u, v)) \in B_{\widetilde{m}, \lambda}$ for any $t \geq 0$, then by Lemma 2.9(4), $\eta(t,(u, v)) \notin \mathcal{P}_{\delta}$ for any $t \in\left[0, \frac{\rho}{2 T_{0}}\right]$. Therefore,

$$
\begin{equation*}
\eta(t,(u, v)) \in B_{\widetilde{m}} \backslash\left(\mathcal{P}_{\delta} \cup \mathcal{M}_{\rho}\right) \tag{2.30}
\end{equation*}
$$

In particular, $(u, v) \notin P_{\delta}$. Moreover, by (2.29) and Lemma 2.9 (3), we get

$$
\begin{align*}
d_{\lambda, \delta}^{k_{1}, k_{2}} & \leq \sup _{B_{0} \backslash \mathcal{P}_{\delta}} \Psi_{\lambda}(u, v)<\Psi_{\lambda}\left(\eta\left(\frac{\rho}{2 T_{0}},(u, v)\right)\right)+\frac{T \varepsilon_{0}}{2} \\
& \leq \Psi_{\lambda}(\eta(t,(u, v)))+\frac{T \varepsilon_{0}}{2}  \tag{2.31}\\
& \leq \Psi_{\lambda}(u, v)+\frac{T \varepsilon_{0}}{2}<d_{\lambda, \delta}^{k_{1}, k_{2}+1}+\frac{T \varepsilon_{0}}{2}+\frac{T \varepsilon_{0}}{2}
\end{align*}
$$

that is,

$$
\left|\Psi_{\lambda}(u, v)-d\right| \leq \frac{T \varepsilon_{0}}{2}<2 \varepsilon_{0}
$$

So we see from (2.26) and Lemma 2.8 that

$$
\begin{align*}
\frac{d}{d t} \Psi_{\lambda}(\eta(t,(u, v))) & =-\left\langle\nabla \Psi_{\lambda}(\eta(t,(u, v))), V(\eta(t,(u, v)))\right\rangle_{H_{r}} \\
& \leq-\frac{T_{2}^{2}}{2}\|V(\eta(t,(u, v)))\|_{H_{r}}^{2} \leq-\frac{T_{2}^{2}}{2} \varepsilon_{0} . \tag{2.32}
\end{align*}
$$

Finally, we deduce from (2.28), (2.31), and (2.32) that

$$
\begin{aligned}
d_{\lambda, \delta}^{k_{1}, k_{2}} & <\Psi_{\lambda}\left(\eta\left(\frac{\rho}{2 T_{0}},(u, v)\right)\right)+\frac{T \varepsilon_{0}}{2} \\
& \leq \Psi_{\lambda}(u, v)+\frac{T \varepsilon_{0}}{2}-\int_{0}^{\frac{\rho}{2 T_{0}}} \frac{T_{2}^{2}}{2} \varepsilon_{0} d t \\
& <d_{\lambda, \delta}^{k_{1}, k_{2}}+\frac{T \varepsilon_{0}}{2}+\frac{T \varepsilon_{0}}{2}-\frac{T_{2}^{2}}{2} \varepsilon_{0} \frac{\rho}{2 T_{0}} \\
& =d_{\lambda, \delta}^{k_{1}, k_{2}}+\frac{\varepsilon_{0}}{2}\left(2 T-\frac{T_{2}^{2} \rho}{2 T_{0}}\right) \leq d_{\lambda, \delta}^{k_{1}, k_{2}},
\end{aligned}
$$

this yields a contradiction. This completes the proof.

## 3 Proof of Theorem 1.2

Using Theorem 1.1, for $k=1$, there exists $\lambda_{1}>0$ such that system (1.1) has a radially symmetric sign-changing solution $\left(u_{1}, v_{1}\right)$ for any $\lambda \in\left(0, \lambda_{1}\right)$ and for $k_{1}=k_{2}=2$,

$$
\Phi_{\lambda}\left(u_{1}, v_{1}\right)=d_{\lambda, \delta}^{2,2}<c_{1} .
$$

Let

$$
U_{\lambda}:=\left\{(u, v) \in H_{r}:(u, v) \text { is a sign-changing solution of }(1.1)\right\},
$$

then $U_{\lambda} \neq \emptyset$ by Theorem 1.1, we can define

$$
d_{\lambda}:=\inf _{(u, v) \in U_{\lambda}} \Phi_{\lambda}(u, v)
$$

and $d_{\lambda}<c_{1}$. Let $\left(u_{n}, v_{n}\right) \in U_{\lambda}$ be a minimizing sequence of $d_{\lambda}$ with $\Phi_{\lambda}\left(u_{n}, v_{n}\right) \rightarrow d_{\lambda}$, $\Phi_{\lambda}\left(u_{n}, v_{n}\right)<c_{1}$ and $\Phi_{\lambda}^{\prime}\left(u_{n}, v_{n}\right)=0$. Then

$$
\begin{align*}
\left(\frac{1}{2}\right. & \left.-\frac{1}{p+1}\right)\left(\left\|u_{n}\right\|_{\alpha}^{2}+\left\|v_{n}\right\|_{\beta}^{2}\right) \\
\leq & \left(\frac{1}{2}-\frac{1}{p+1}\right)\left(\left\|u_{n}\right\|_{\alpha}^{2}+\left\|v_{n}\right\|_{\beta}^{2}\right)+\left(\frac{1}{p+1}-\frac{1}{q+1}\right)\left|v_{n}\right|_{q+1}^{q+1}  \tag{3.1}\\
& +\frac{2}{p+1}\left(\frac{1}{p+1}-\frac{1}{q+1}\right) \lambda \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{\frac{p+1}{2}}\left|v_{n}\right|^{\frac{q+1}{2}} d x \\
= & \Phi_{\lambda}\left(u_{n}, v_{n}\right)-\frac{1}{p+1} \Phi_{\lambda}^{\prime}\left(u_{n}, v_{n}\right)\left(u_{n}, v_{n}\right)<c_{1} .
\end{align*}
$$

Observe that $\left\{\left(u_{n}, v_{n}\right)\right\}_{n \geq 1}$ is bounded in $H_{r}$, we may assume that, up to a subsequence,

$$
\begin{aligned}
& \left(u_{n}, v_{n}\right) \rightharpoonup\left(u_{0}, v_{0}\right) \quad \text { weakly in } H_{r}, \\
& u_{n} \rightarrow u_{0}, \quad \text { strongly in } L^{p+1}\left(\mathbb{R}^{3}\right), \\
& v_{n} \rightarrow v_{0}, \quad \text { strongly in } L^{q+1}\left(\mathbb{R}^{3}\right) .
\end{aligned}
$$

Since $\Phi_{\lambda}^{\prime}\left(u_{n}, v_{n}\right)=0$, it is standard to prove that

$$
\left(u_{n}, v_{n}\right) \rightarrow\left(u_{0}, v_{0}\right) \quad \text { strongly in } H_{r},
$$

and $\Phi_{\lambda}^{\prime}\left(u_{0}, v_{0}\right)=0, \Phi_{\lambda}\left(u_{0}, v_{0}\right)=d_{\lambda}$.
Moreover, $\Phi_{\lambda}^{\prime}\left(u_{n}, v_{n}\right)\left(u_{n}^{ \pm}, 0\right)=0$ and $\Phi_{\lambda}^{\prime}\left(u_{n}, v_{n}\right)\left(0, v_{n}^{ \pm}\right)=0$, we deduce from (2.7) and (3.1) that

$$
\begin{aligned}
S_{p}\left|u_{n}^{ \pm}\right|_{p+1}^{2} & \leq\left\|u_{n}^{ \pm}\right\|_{\alpha}^{2}=\left|u_{n}^{ \pm}\right|_{p+1}^{p+1}+\frac{2}{q+1} \lambda \int_{\mathbb{R}^{3}}\left|u_{n}^{ \pm}\right|^{\frac{p+1}{2}}\left|v_{n}\right|^{\frac{q+1}{2}} d x \\
& \leq\left|u_{n}^{ \pm}\right|_{p+1}^{p+1}+\frac{2}{q+1} \lambda\left|u_{n}^{ \pm}\right|_{p+1}^{\frac{p+1}{2}}\left|v_{n}\right|_{q+1}^{\frac{q+1}{2}} \\
& <\left|u_{n}^{ \pm}\right|_{p+1}^{p+1}+\frac{2}{q+1}\left[\frac{c_{1}}{\left(\frac{1}{2}-\frac{1}{p+1}\right) S_{q}}\right]^{\frac{q+1}{4}} \lambda\left|u_{n}^{ \pm}\right|_{p+1}^{\frac{p+1}{2}} .
\end{aligned}
$$

We can choose $0<\lambda_{0}<\lambda_{1}$ small enough such that for any $\lambda \in\left(0, \lambda_{0}\right)$ we have

$$
S_{p}\left|u_{n}^{ \pm}\right|_{p+1}^{2}<2\left|u_{n}^{ \pm}\right|_{p+1}^{p+1},
$$

which implies $\left|u_{n}^{ \pm}\right|_{p+1} \geq \xi_{1}>0$ for any $n \geq 1$. Similarly, $\left|v_{n}^{ \pm}\right|_{q+1} \geq \xi_{2}>0$ for any $n \geq 1$. Therefore, $\left|u_{0}^{ \pm}\right|_{p+1} \geq \xi_{1}>0,\left|v_{0}^{ \pm}\right|_{q+1} \geq \xi_{2}>0$, and so Eq. (1.1) has a least energy signchanging solution $\left(u_{0}, v_{0}\right)$. This completes the proof.

## 4 The proof of Theorem 1.3

In this section, we obtain seminodal solutions $(u, v)$ such that $u$ is positive, $v$ is signchanging and use the same notations as in Sect. 2 for convenience. Define the $C^{1}$ functional

$$
\begin{aligned}
\Phi_{\lambda}(u, v): & =\frac{1}{2}\left(\|u\|_{\alpha}^{2}+\|v\|_{\beta}^{2}\right)-\frac{1}{p+1}\left|u^{+}\right|_{p+1}^{p+1}-\frac{1}{q+1}|v|_{q+1}^{q+1} \\
& -\frac{4 \lambda}{(p+1)(q+1)} \int_{\mathbb{R}^{3}}|u|^{\frac{p+1}{2}}|v|^{\frac{q+1}{2}} d x,
\end{aligned}
$$

where $(u, v) \in \widetilde{H}_{r}:=\left\{(u, v) \in H_{r}: u^{+} \neq 0, v \neq 0\right\}$,

$$
\begin{aligned}
& \mathcal{A}:=\left\{(u, v) \in H_{r}:\left|u^{+}\right|_{p+1}=1,|v|_{q+1}=1\right\}, \\
& \mathcal{A}^{*}:=\left\{(u, v) \in H_{r}: \frac{1}{2}<\left|u^{+}\right|_{p+1}^{p+1}<2, \frac{1}{2}<|v|_{q+1}^{q+1}<2\right\}, \\
& \mathcal{B}_{m}^{*}:=\left\{(u, v) \in \mathcal{A}^{*}:\|u\|_{\alpha}^{2}<m,\|v\|_{\beta}^{2}<m\right\}, \quad \mathcal{B}_{m}:=\mathcal{B}_{m}^{*} \cap \mathcal{A} .
\end{aligned}
$$

As in Sect. 2, for any $(u, v) \in \mathcal{A}$, we define

$$
\begin{equation*}
\sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)=\Phi_{\lambda}\left(t_{u, v, \lambda} u, s_{u, v, \lambda} v\right)=: \Psi_{\lambda}(u, v) \tag{4.1}
\end{equation*}
$$

It is easy to prove that Lemma 2.4 also holds in this section by trivial modifications. Then define

$$
B_{\widetilde{m}, \lambda}:=\left\{(u, v) \in B_{\widetilde{m}}: \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)<c_{k}\right\} .
$$

For any $(u, v) \in \mathcal{B}_{\widetilde{m}}^{*}, \lambda \in\left(0, \lambda_{k}\right)$, we consider the following linear problem:

$$
\left\{\begin{array}{l}
-\Delta \varphi+\alpha \varphi-\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} s_{u, v, \lambda}^{\frac{q+1}{2}} \lambda|u|^{\frac{p-3}{2}} \varphi|v|^{\frac{q+1}{2}}=t_{u, v, \lambda}^{p-1}\left(u^{+}\right)^{p},  \tag{4.2}\\
-\Delta \psi+\beta \psi-\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q-3}{2}} \lambda|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} \psi=s_{u, v, \lambda}^{q-1}|v|^{q-1} v, \\
\varphi(x) \rightarrow 0, \quad \psi(x) \rightarrow 0, \quad \text { as }|x| \rightarrow \infty
\end{array}\right.
$$

then (4.2) has a unique solution $(\varphi, \psi) \in H_{r} \backslash\{(0,0)\}$. Define

$$
\mu:=\frac{1}{\int_{\mathbb{R}^{3}}\left(u^{+}\right)^{p} \varphi d x}>0, \quad v:=\frac{1}{\int_{\mathbb{R}^{3}}|v|^{q-1} v \psi d x}>0
$$

Then $(\widetilde{\varphi}, \widetilde{\psi}):=(\mu \varphi, \nu \psi)$ is the unique solution of the following problem:

$$
\left\{\begin{array}{l}
-\Delta \widetilde{\varphi}+\alpha \widetilde{\varphi}-\frac{2}{q+1} t_{u, v, \lambda}^{\frac{p-3}{2}} \frac{q+1}{\frac{q+1}{2}} u_{u, v, \lambda} \lambda|u|^{\frac{p-3}{2}} \widetilde{\varphi}|v|^{\frac{q+1}{2}}=u t_{u, v, \lambda}^{p-1}\left(u^{+}\right)^{p}  \tag{4.3}\\
-\Delta \widetilde{\psi}+\beta \widetilde{\psi}-\frac{2}{p+1} t_{u, v, \lambda}^{\frac{p+1}{2}} s_{u, v, \lambda}^{\frac{q-3}{2}} \lambda|u|^{\frac{p+1}{2}}|v|^{\frac{q-3}{2}} \widetilde{\psi}=v s_{u, v, \lambda}^{q-1}|v|^{q-1} v, \\
\int_{\mathbb{R}^{3}}\left(u^{+}\right)^{p} \widetilde{\varphi} d x=\int_{\mathbb{R}^{3}}|v|^{q-1} v \widetilde{\psi} d x=1, \\
\widetilde{\varphi}(x) \rightarrow 0, \quad \widetilde{\psi}(x) \rightarrow 0, \quad \text { as }|x| \rightarrow \infty
\end{array}\right.
$$

We can now also define the operator

$$
\begin{align*}
& K: B_{\widetilde{m}}^{*} \rightarrow H_{r} ; \quad(u, v) \mapsto(\widetilde{\varphi}, \widetilde{\psi}), \\
& K\left(\sigma_{2}(u, v)\right)=\sigma_{2}(K(u, v)) . \tag{4.4}
\end{align*}
$$

Then, by similar proofs as in Lemma 2.5 and Lemma 2.6, we have that $K \in C^{1}\left(B_{\widetilde{m}}^{*}, H_{r}\right)$ and $K$ satisfies the Palais-Smale type condition. Define the map

$$
V: B_{\widetilde{m}}^{*} \rightarrow H_{r} ; \quad(u, v) \mapsto(u, v)-K(u, v) .
$$

Consider the class of sets

$$
\begin{equation*}
\mathcal{F}=\left\{A \in \mathcal{A}: A \text { is a closed set and } \sigma_{2}(u, v) \in A, \forall(u, v) \in A\right\} \tag{4.5}
\end{equation*}
$$

for each $A \in \mathcal{F}$ and $k_{2} \geq 2$, the class of functions

$$
\begin{equation*}
F_{\left(1, k_{2}\right)}(A)=\left\{f: A \rightarrow \mathbb{R}^{k_{2}-1}: f \text { continuous and } f\left(\sigma_{2}(u, v)\right)=-f(u, v)\right\} . \tag{4.6}
\end{equation*}
$$

To obtain seminodal solutions, we should also define a cone of positive functions, that is,

$$
\begin{align*}
& \mathcal{P}_{2}:=\left\{(u, v) \in H_{r}: v \geq 0\right\}, \quad \mathcal{P}=\mathcal{P}_{2} \cup-\mathcal{P}_{2}, \\
& \operatorname{dist}_{q+1}((u, v), \mathcal{P}):=\min \left\{\operatorname{dist}_{q+1}\left(v, \mathcal{P}_{2}\right), \operatorname{dist}_{q+1}\left(v,-\mathcal{P}_{2}\right)\right\}, \tag{4.7}
\end{align*}
$$

thus, $v$ is sign-changing if $\operatorname{dist}_{q+1}((u, v), \mathcal{P})>0$.
Under the new definitions (4.4)-(4.6), we define vector genus, slightly different from Definition 2.1.

Definition 4.1 Let $A \in \mathcal{F}$ and take any $k_{2} \in \mathbb{N}$ with $k_{2} \geq 2$. We say that $\gamma(A) \geq\left(1, k_{2}\right)$ if for every $f \in F_{\left(1, k_{2}\right)}(A)$ there exists $(u, v) \in A$ such that $f(u, v)=0$. We denote

$$
\Gamma^{\left(1, k_{2}\right)}:=\left\{A \in \mathcal{F}: \gamma(A) \geq\left(1, k_{2}\right)\right\} .
$$

## Lemma 4.1

(1) Take $A:=A_{1} \times A_{2} \subset \mathcal{A}$ and let $\eta: S^{k_{2}-1} \rightarrow A_{2}$ be a homeomorphism such that $\eta(-x)=-\eta(x)$ for every $x \in S^{k_{2}-1}$. Then $A \in \Gamma^{\left(1, k_{2}\right) ; ~}$
(2) We have $\overline{\eta(A)} \in \Gamma^{\left(1, k_{2}\right)}$ whenever $A \in \Gamma^{\left(1, k_{2}\right)}$ and a continuous map $\eta: A \rightarrow \mathcal{A}$ is such that $\eta \circ \sigma_{2}=\sigma_{2} \circ \eta$.

Proof (1) For every $f \in F_{\left(1, k_{2}\right)}(A)$ and $u \in A_{1}$, we define a map

$$
h: S^{k_{2}-1} \rightarrow \mathbb{R}^{k_{2}-1} ; \quad h(x):=f(u, \eta(x))
$$

then by (4.6) it is easy to see that $h$ is continuous and

$$
h(-x)=f(u, \eta(-x))=f(u,-\eta(x))=-f(u, \eta(x))=-h(x) .
$$

Then Borsuk-Ulam theorem yields $x_{0} \in S^{k_{2}-1}$ such that $h\left(x_{0}\right)=f\left(u, \eta\left(x_{0}\right)\right)=0$. By Definition 4.1, we have $A \in \Gamma^{\left(1, k_{2}\right)}$.
(2) Fix any $f \in F_{\left(1, k_{2}\right)}(\overline{\eta(A)})$, then by (4.6) we have $f \circ \eta \in F_{\left(1, k_{2}\right)}(A)$. Since $A \in \Gamma^{\left(1, k_{2}\right)}$, there exists $\left(u_{0}, v_{0}\right) \in A$ such that $f \circ \eta\left(u_{0}, v_{0}\right)=0$. Then by $\eta\left(u_{0}, v_{0}\right) \in \overline{\eta(A)}$ we have $\gamma(\overline{\eta(A)}) \geq$ $\left(1, k_{2}\right)$, that is, $\overline{\eta(A)} \in \Gamma^{\left(1, k_{2}\right)}$. This completes the proof.

Lemma 4.2 Assume $k_{2} \geq 2$. Then, for any $0<\delta<2^{-\frac{1}{q+1}}$ and $A \in \Gamma^{\left(1, k_{2}\right)}$, we have $A \backslash \mathcal{P}_{\delta} \neq \emptyset$.
Proof For any $A \in \Gamma^{\left(1, k_{2}\right)}$, define $f$ by

$$
f(u, v)=\left(\int_{\mathbb{R}^{3}}|v|^{q} v d x, 0, \ldots, 0\right)
$$

then $f \in F_{\left(1, k_{2}\right)}(A)$, so by Definition 4.1, there exists $\left(u_{0}, v_{0}\right) \in A$ such that $f\left(u_{0}, v_{0}\right)=0$. We deduce from $A \in \mathcal{A}$ that

$$
\int_{\mathbb{R}^{3}}\left(v_{0}^{+}\right)^{q+1} d x=\int_{\mathbb{R}^{3}}\left(v_{0}^{-}\right)^{q+1} d x=\frac{1}{2} .
$$

Therefore, $\operatorname{dist}_{q+1}\left(\left(u_{0}, v_{0}\right), \mathcal{P}\right)=2^{-\frac{1}{q+1}}$, and so $\left(u_{0}, v_{0}\right) \in A \backslash \mathcal{P}_{\delta}$ for any $0<\delta<2^{-\frac{1}{q+1}}$. This completes the proof.

Fixed any $k \in \mathbb{N}$, we define

$$
A_{1}:=\left\{c u_{0}: c=\frac{1}{\left|u_{0}\right|_{p+1}}, u_{0}>0\right\}, \quad A_{2}:=\left\{v \in X_{k+1}:|v|_{q+1}=1\right\} .
$$

By Lemma 4.1(1), $A:=A_{1} \times A_{2} \in \Gamma^{(1, k+1)}, A \subset B_{\tilde{m}}$, and $\sup _{A} \Psi_{\lambda}(u, v)<c_{k}$. Then we can define

$$
\Gamma_{\lambda}^{\left(1, k_{2}\right)}:=\left\{A \in \Gamma^{\left(1, k_{2}\right)}: A \subset B_{\tilde{m}}, \sup _{A} \Psi_{\lambda}(u, v)<c_{k}\right\} .
$$

For any $k_{2} \in[2, k+1]$ and $0<\delta<2^{-\frac{1}{q+1}}$, we define a sequence of minimax energy level:

$$
d_{\lambda, \delta}^{1, k_{2}}:=\inf _{A \in \Gamma_{\lambda}^{\left(1, k_{2}\right)}} \sup _{A \backslash \mathcal{P}_{\delta}} \sup _{t, s \geq 0} \Phi_{\lambda}(t u, s v)
$$

It is easy to see that

$$
d_{\lambda, \delta}^{1, k_{2}}<c_{k} \quad \text { for any } 0<\delta<2^{-\frac{1}{q+1}} \text { and } 2 \leq k_{2} \leq k+1
$$

Lemma 2.7 and Lemma 2.8 also hold in Sect. 4.

Lemma 4.3 There exists a unique global solution $\eta: \mathbb{R}^{+} \times B_{\widetilde{m}, \lambda} \rightarrow H_{r}$ for the initial value problem

$$
\left\{\begin{array}{l}
\frac{d}{d t} \eta(t,(u, v))=-V(\eta(t,(u, v)))  \tag{4.8}\\
\eta(0,(u, v))=(u, v) \in B_{\widetilde{m}, \lambda}
\end{array}\right.
$$

Moreover, (1), (3), (4) of Lemma 2.9 hold and
(2) For any $t>0,(u, v) \in B_{\widetilde{m}, \lambda}, \eta\left(t, \sigma_{2}(u, v)\right)=\sigma_{2}(\eta(t,(u, v)))$.

Proof From the above discussion, we see that $V \in C^{1}\left(B_{\widetilde{m}}^{*}, H_{r}\right)$. As $B_{\widetilde{m}, \lambda} \subset B_{\widetilde{m}} \subset B_{\widetilde{m}}^{*}$, we get that $V \in C^{1}\left(B_{\widetilde{m}, \lambda}, H_{r}\right)$, then there exists a solution $\eta:\left[0, T_{\max }\right) \times B_{\widetilde{m}, \lambda} \rightarrow H_{r}$, where $T_{\max }$ is the maximal time such that (4.8) has s solution $\eta \in B_{\widetilde{m}}^{*}$.

For any $(u, v) \in B_{\widetilde{m}, \lambda}$ and $t \in\left(0, T_{\max }\right)$, there holds

$$
\begin{aligned}
\frac{d}{d t} & \int_{\mathbb{R}^{3}}\left(\eta_{1}^{+}(t,(u, v))\right)^{p+1} d x \\
& =-(p+1) \int_{\mathbb{R}^{3}}\left(\eta_{1}^{+}(t,(u, v))\right)^{p} V\left(\eta_{1}^{+}(t,(u, v))\right) d x \\
& =-(p+1) \int_{\mathbb{R}^{3}}\left(\eta_{1}^{+}(t,(u, v))\right)^{p}\left[\eta_{1}^{+}(t,(u, v))-K_{1}\left(\eta^{+}(t,(u, v))\right)\right] d x \\
& =(p+1)-(p+1) \int_{\mathbb{R}^{3}}\left(\eta_{1}^{+}(t,(u, v))\right)^{p+1} d x,
\end{aligned}
$$

so we have

$$
\frac{d}{d t}\left[e^{(p+1) t}\left(\int_{\mathbb{R}^{3}}\left(\eta_{1}^{+}(t,(u, v))\right)^{p+1} d x-1\right)\right]=0
$$

Since $\int_{\mathbb{R}^{3}}\left(\eta_{1}^{+}(0,(u, v))\right)^{p+1} d x=\int_{\mathbb{R}^{3}}\left(u^{+}\right)^{p+1} d x=1$, then for any $t \in\left[0, T_{\max }\right)$,

$$
\int_{\mathbb{R}^{3}}\left(\eta_{1}^{+}(t,(u, v))\right)^{p+1} d x \equiv 1 .
$$

The rest of the proof is the same as Lemma 2.9. This completes the proof.

Proof of Theorem 1.2 Observe that from Lemma 2.10, for any $k_{2} \in[2, k+1], 0<\delta<\delta_{0}$ small, there exists $\left(u_{0}, v_{0}\right) \in B_{\widetilde{m}}$ such that

$$
\Psi_{\lambda}\left(u_{0}, v_{0}\right)=d_{\lambda, \delta}^{1, k_{2}}, \quad V\left(u_{0}, v_{0}\right)=0 \quad \text { and } \quad \operatorname{dist}_{q+1}\left(\left(u_{0}, v_{0}\right), \mathcal{P}\right) \geq \delta
$$

We conclude that $v_{0}$ is sign-changing and $\left(u_{0}, v_{0}\right)=K\left(u_{0}, v_{0}\right)=\left(\widetilde{\varphi}_{0}, \widetilde{\psi}_{0}\right)$. It follows from (4.3) that ( $u_{0}, v_{0}$ ) satisfies

$$
\left\{\begin{array}{l}
-\Delta u_{0}+\alpha u_{0}=\mu t_{u, v, \lambda}^{p-1}\left(u_{0}^{+}\right)^{p}+\frac{2}{q+1} t_{u_{0}, v_{0}, \lambda}^{\frac{p-3}{2}} s_{u_{0}, v_{0}, \lambda}^{\frac{q+1}{2}} \lambda\left|u_{0}\right|^{\frac{p-3}{2}} u_{0}\left|v_{0}\right|^{\frac{q+1}{2}}  \tag{4.9}\\
-\Delta v_{0}+\beta v_{0}=v s_{u_{0}, v_{0}, \lambda}^{q-1}\left|v_{0}\right|^{q-1} v_{0}+\frac{2}{p+1} t_{u_{0}, v_{0}, \lambda}^{\frac{q+3}{2}} s_{u_{0}, v_{0}, \lambda}^{2} \lambda\left|u_{0}\right|^{\frac{p+1}{2}}\left|v_{0}\right|^{\frac{q-3}{2}} v_{0} \\
u_{0}(x) \rightarrow 0, \quad v_{0}(x) \rightarrow 0, \quad \text { as }|x| \rightarrow \infty
\end{array}\right.
$$

and $\left|u_{0}^{+}\right|_{p+1}=\left|v_{0}\right|_{q+1}=1$, then by (4.1) we have $\mu=v=1$. Moreover, (4.9) yields

$$
\left\|u_{0}^{-}\right\|_{\alpha}^{2}=\frac{2}{q+1} t_{u_{0}, v_{0}, \lambda}^{\frac{p-3}{2}} \lambda_{u_{0}, v_{0}, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}\left|u_{0}\right|^{\frac{p-3}{2}}\left(u_{0}^{-}\right)^{2}\left|v_{0}\right|^{\frac{q+1}{2}} .
$$

We can take $\lambda_{k}$ small enough if necessary such that for any $\lambda \in\left(0, \lambda_{k}\right)$ and $\left(u_{0}, v_{0}\right) \in \mathcal{B}_{\tilde{m}}^{*}$,

$$
\left\|u_{0}^{-}\right\|_{\alpha}^{2}-\frac{2}{q+1} t_{u_{0}, v_{0}, \lambda}^{\frac{p-3}{2}} s_{u_{0}, v_{0}, \lambda}^{\frac{q+1}{2}} \lambda \int_{\mathbb{R}^{3}}\left|u_{0}\right|^{\frac{p-3}{2}}\left(u_{0}^{-}\right)^{2}\left|v_{0}\right|^{\frac{q+1}{2}} \geq \frac{1}{2}\left\|u_{0}^{-}\right\|_{\alpha^{\prime}}^{2}
$$

then $\left\|u_{0}^{-}\right\|_{\alpha}^{2}=0$, so $u_{0} \geq 0$. By the strong maximum principle, $u_{0}>0$. Hence we have that ( $t_{u_{0}, v_{0}, \lambda} u_{0}, s_{u_{0}, v_{0}, \lambda} v_{0}$ ) is a seminodal solution of (1.1) with $t_{u_{0}, v_{0}, \lambda} u_{0}$ positive and $s_{u_{0}, v_{0}, \lambda} v_{0}$ sign-changing,

$$
\Phi_{\lambda}\left(t_{u_{0}, v_{0}, \lambda} u_{0}, s_{u_{0}, v_{0}, \lambda} v_{0}\right)=\Psi_{\lambda}\left(u_{0}, v_{0}\right)=d_{\lambda, \delta}^{1, k_{2}} .
$$

By similar proof as Theorem 1.1, we complete the proof.

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## Author contributions

Jing Zhang wrote the main manuscript text

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## Data Availability

No datasets were generated or analysed during the current study.

## Declarations

## Ethics approval and consent to participate

Not applicable.

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The authors declare no competing interests.
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