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Boundedness of solutions to a second-order periodic system with p-Laplacian and unbounded perturbation terms

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Abstract

The second-order periodic system with p-Laplacian and unbounded time-dependent perturbation terms is investigated. Using the principle integral method, it is shown that under certain assumptions on the unbounded and periodic terms, all solutions to the equation possess boundedness.

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1 Introduction and main result

Consider the following second-order differential equation

$$(\varphi_p(x'))' + a\varphi_p(x^+) - b\varphi_p(x^-) + z(t)f(x) = e(t), \quad (1.1)$$

where $\varphi_p(s) = |s|^{p-2}s$ with constant $p > 2$. Variable $x \in \mathbb{R}$, $t \in \mathbb{R}$, $x^+ = \max(x, 0)$, $x^- = \max(-x, 0)$. a and b are positive constants ($a \neq b$) satisfying $a^{-\frac{1}{p}} + b^{-\frac{1}{p}} = 2\omega^{-1}$, ω is an irrational number, $f(x) = o(|x|)$, $z(t)$ and $e(t)$ are $2\pi_p$ periodic functions with $\pi_p = \frac{2\pi(p-1)^{\frac{1}{p}}}{p \sin \frac{\pi}{p}}$.

When $p = 2$, Eq. (1.1) is turned into

$$x'' + ax^+ - bx^- + z(t)f(x) = e(t), \quad \pi_p = \pi. \quad (1.2)$$

Provided that $z(t)f(x) = 0$, $e(t) = 1 + \gamma h(t)$ in which $h(t)$ is a suitable function, investigating the boundedness of solutions to Eq. (1.2) is very complicated. Ortega [1] proves that every solution to Eq. (1.2) is bounded if $h \in C^4(\mathbb{S}^1)$, where $\mathbb{S}^1 = \mathbb{R}/2\pi\mathbb{Z}$, and γ is sufficiently small. Under certain conditions on the initial data, Alonso and Ortega [2] obtain that there exists a function $e(t)$ to ensure that all solutions to Eq. (1.2) are unbounded. Ambrosio [3] establishes the boundedness to solutions to fractional relativistic Schrödinger equations. A differential inclusion system involving the $p(t)$ -Laplacian is investigated in [4].

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Giacomini et al. [5] utilize the bifurcation theory to discuss the multiplicity for a strongly singular quasi-linear problem. The asymptotic properties of solutions for a second-order nonlinear discrete equation of the Emden-Fowler type are acquired in [6]. Under appropriate restrictions, Jiao et al. [7] discuss the boundedness of all solutions to Eq. (1.2) (see also [8–10]).

For $p \geq 2$, when $a^{-\frac{1}{p}} + b^{-\frac{1}{p}} = 2\omega^{-1}$, where ω^{-1} is an irrational number, Yang [11] investigates Eq. (1.1) and obtains that all the solution to Eq. (1.1) are bounded under certain assumptions. Liu [12] discusses the bounded condition for Eq. (1.1) provided that f is smooth and $\lim_{x \rightarrow \pm\infty} f(x)$ is finite. Ma [13] discusses the bounded condition for Eq. (1.1) provided that f is unbounded and $z(t) = 1$.

When $p = 2$, without the assumption that $\lim_{x \rightarrow \pm\infty} f(x)$ is finite, Zhang [14] has acquired the conditions to ensure that each solution of Eq. (1.1) is bounded. In this work, we will extend the result in [14] to the case $p > 2$ under the following assumptions:

(A₁): $z(t), e(t) \in C^6(\mathbb{S}^1)$, where $\mathbb{S}^1 = \mathbb{R}/2\pi_p\mathbb{Z}$.

(A₂): If $f(x) \in C^6(\mathbb{R} \setminus \{0\}) \cap C^0(\mathbb{R})$, then there are two positive constants C and $\frac{1}{p-1} < \gamma < 1$, such that $|x^k f^{(k)}(x)| \leq C|x|^\gamma$, provided that $x \in \mathbb{R} \setminus \{0\}$ and $0 \leq k \leq 6$.

(A₃): There exist positive constants β_1 and β_2 such that $p\beta_1 > q\beta_2 > 0$, where positive constants p and q satisfy $\frac{1}{p} + \frac{1}{q} = 1$ and

$$xf(x) \geq \beta_1|x|^{\gamma+1}, \quad x^2f'(x) \leq \beta_2|x|^{\gamma+1}, \quad x \in \mathbb{R} \setminus \{0\}.$$

Here, we mention that condition (A₁) does not require $z(t) = 1$, namely, condition (A₁) is different from $z(t) = 1$ in Ma [13]. Now, we state our main conclusion.

Theorem 1.1 *Assume that $p > 2$ and (A₁) – (A₃) hold and $\hat{z} = \frac{1}{2\pi_p} \int_0^{2\pi_p} z(t)dt \neq 0$. Then every solution of Eq. (1.1) is bounded, namely, $\sup_{t \in \mathbb{R}} (|x(t)| + |x'(t)|) < \infty$.*

We set $F(x) = \int_0^x f(s)ds$. In this work, we utilize c and C to denote any positive constants (not concerning their quantity). k, l, m and n are nonnegative integers.

The structure of this work is the following: Sect. 2 presents action-angle variables, exchanging time and angle variables, and several lemmas. Section 3 provides the proof of Theorem 1.1.

2 Preliminaries

In this part, we provide several lemmas that help prove Theorem 1.1. Throughout Sect. 2, we assume that the hypotheses of Theorem 1.1 always hold.

2.1 Action-angle coordinates

Let $x' = -\omega\varphi_q(y)$, then $y = -\omega^{1-p}\varphi_p(x')$, and the equivalent form of Eq. (1.1) is the following:

$$x' = -\omega\varphi_q(y), \quad y' = \omega[a_1\varphi_p(x^+) - b_1\varphi_p(x^-)] + \omega^{1-p}[z(t)f(x) - e(t)]$$

with the Hamiltonian function

$$H(x, y, t) = \frac{\omega}{q}|y|^q + \frac{\omega}{p}(a_1|x^+|^p + b_1|x^-|^p) + \omega^{1-p}(z(t)F(x) - e(t)x), \tag{2.1}$$

where $a_1 = \omega^{-p}a, b_1 = \omega^{-p}b, a_1$ and b_1 satisfy $a_1^{-\frac{1}{p}} + b_1^{-\frac{1}{p}} = 2$.

Let $\sin_p(t)$ satisfy the problem

$$(\varphi_p(C'(t)))' + \varphi_p(C(t)) = 0, \quad C(0) = 0, \quad C'(0) = 1.$$

From the conclusions in [15–17], we confirm that $\sin_p(t)$ is a $2\pi_p$ -periodic C^2 odd function with $\sin_p(\pi_p - t) = \sin_p(t)$ for $t \in [0, \frac{\pi_p}{2}]$ and $\sin_p(2\pi_p - t) = -\sin_p(t)$ for $t \in [\pi_p, 2\pi_p]$. Moreover, for $t \in [0, \frac{\pi_p}{2}]$ and $\sin'_p(t) > 0$, $\sin_p(t) \in (0, (p - 1)^{\frac{1}{p}})$ is implicitly given by

$$\int_0^{\sin_p(t)} \frac{ds}{(1 - \frac{s^p}{p-1})^{\frac{1}{p}}} = t.$$

Suppose that $v(t)$ satisfies the initial problem

$$(\varphi_p(x'(t)))' + a_1\varphi_p(x^+) - b_1\varphi_p(x^-) = 0, \quad x(0) = (p - 1)^{\frac{1}{p}}, \quad x'(0) = 0.$$

Letting $\varphi_p(v') = u$ and $q = p/(p - 1) > 1$ yields

$$\frac{|u|^q}{q} + \frac{a_1|v^+|^p + b_1|v^-|^p}{p} = \frac{a_1}{q}. \tag{2.2}$$

Using (2.2), we obtain that the action-angle coordinate transformation $\psi_0: x = (d_1r)^{\frac{1}{p}}v(\theta)$, $y = (d_1r)^{\frac{1}{q}}u(\theta)$ with $d_1 = pa_1^{-1}$. ψ_0 is a symplectic transformation since its value of the Jacobian determinant is 1. Under ψ_0 , Hamiltonian function (2.1) is transformed into

$$h(r, \theta, t) = \omega r + \omega^{1-p}z(t)F((d_1r)^{\frac{1}{p}}v(\theta)) - \omega^{1-p}e(t)(d_1r)^{\frac{1}{p}}v(\theta) \in C^{1,1,6}(\mathbb{R}^+ \times \mathbb{S}^1 \times \mathbb{S}^1). \tag{2.3}$$

Let $\Xi = \{\theta \in \mathbb{S}^1 : v(\theta) = 0\}$. When $\theta \in \mathbb{S}^1 \setminus \Xi$ ($t \in \mathbb{S}^1$ is a parameter), we have $h(r, t, \theta) \in \mathbb{C}^6$ with respect to r .

2.2 Lemmas

Utilizing the ideas in [13, 14, 18], from conditions (A_2) and (A_3) , we obtain the following conclusions.

Lemma 2.1 *For $r \gg 1, k \leq 6$, it holds that*

$$|\partial_r^k F((d_1r)^{\frac{1}{p}}v(\theta))| \leq Cr^{-k+\frac{\gamma+1}{p}},$$

$$|\partial_r^k f((d_1r)^{\frac{1}{p}}v(\theta))| \leq Cr^{-k+\frac{\gamma}{p}},$$

in which $\theta \in \mathbb{S}^1$ provided that $k = 1; \theta \in \mathbb{S}^1 \setminus \Xi$ if $k \geq 2$.

Lemma 2.2 *Let*

$$\bar{F}(r) = \int_0^{2\pi_p} F((d_1\omega^{-1}r)^{\frac{1}{p}}v(\theta))d\theta. \tag{2.4}$$

For $r \gg 1$, the following conclusions hold

$$|\bar{F}^{(k)}(r)| \leq Cr^{-k+\frac{\gamma+1}{p}}, \quad k \leq 6,$$

$$\bar{F}'(r) \geq cr^{-1+\frac{\gamma+1}{p}}$$

and

$$\bar{F}''(r) \leq -Cr^{-2+\frac{\gamma+1}{p}}.$$

Proof For the sake of simplicity, we write $x = (d_1\omega^{-1}r)^{\frac{1}{p}}v(\theta)$. Using (2.4) and noticing that $\Xi \cap [0, 2\pi_p]$ is a finite set, we have

$$\bar{F}'(r) = \frac{1}{pr} \int_{[0, 2\pi_p] \setminus \Xi} f(x)x d\theta.$$

Using condition (A3) yields

$$\bar{F}'(r) = \frac{1}{pr} \int_{[0, 2\pi_p] \setminus \Xi} f(x)x d\theta \geq \frac{\beta_1}{pr} \int_{[0, 2\pi_p] \setminus \Xi} |x|^{\gamma+1} d\theta = cr^{-1+\frac{\gamma+1}{p}}.$$

Differentiating (2.4) with respect to variable r , from the above analysis and condition (A3), we have

$$\begin{aligned} \bar{F}''(r) &= \frac{1}{p^2r^2} \int_{[0, 2\pi_p] \setminus \Xi} f(x)x^2 d\theta - \frac{1}{qr} \bar{F}'(r) \\ &\leq \frac{\beta_2}{p^2r^2} \int_{[0, 2\pi_p] \setminus \Xi} |x|^{\gamma+1} d\theta - \frac{1}{qr} \bar{F}'(r) \\ &\leq \frac{\beta_2}{pr\beta_1} \bar{F}'(r) - \frac{1}{qr} \bar{F}'(r) \\ &= \left(\frac{\beta_2}{p\beta_1} - \frac{1}{q} \right) \frac{\bar{F}'(r)}{r} \\ &\leq \left(\frac{\beta_2}{p\beta_1} - \frac{1}{q} \right) cr^{-2+\frac{\gamma+1}{p}}, \end{aligned}$$

which finishes the proof. □

From Lemmas 2.1 and 2.2. combined with condition (A₁), we obtain that the following conclusion holds.

Lemma 2.3 *Let $h_1(r, \theta, t) = \omega^{1-p}z(t)F((d_1r)^{\frac{1}{p}}v(\theta)) - \omega^{1-p}e(t)(d_1r)^{\frac{1}{p}}v(\theta)$. For $r \gg 1, t \in \mathbb{S}^1$ then*

$$|\partial_r^k \partial_t^l h_1(r, \theta, t)| \leq cr^{-k+\frac{\gamma+1}{p}}, \tag{2.5}$$

in which $\theta \in \mathbb{S}^1$ provided that $k = 1; \theta \in \mathbb{S}^1 \setminus \Xi$ if $k \geq 2$.

Let

$$g(r, \theta, t) = r^{-\frac{1}{p}} h_1(r, \theta, t). \tag{2.6}$$

From Lemma 2.3, for $r \gg 1$, we have

$$|\partial_r^k \partial_t^l g(r, \theta, t)| \leq cr^{-k+\frac{\gamma}{p}}, \quad k+l \leq 6. \tag{2.7}$$

Lemma 2.4 For $r \gg 1, k+l \leq 6$, then

$$\begin{cases} 0 < cr \leq h(r, t, \theta) < Cr, \\ \partial_r h(r, t, \theta) > \frac{\omega}{2}, \\ |\partial_r^k \partial_t^l h(r, t, \theta)| \leq Cr^{-k+1}, \end{cases} \tag{2.8}$$

in which $\theta \in \mathbb{S}^1$ provided that $k = 1; \theta \in \mathbb{S}^1 \setminus \Xi$ if $k \geq 2$.

Proof From (2.3) and Lemma 2.1, we obtain

$$\lim_{r \rightarrow +\infty} \frac{h}{r} = \omega > 0,$$

and for $r \gg 1$,

$$\frac{\partial h}{\partial r} = \omega + \omega^{1-p} z(t) \partial_r F((d_1 r)^{\frac{1}{p}} v(\theta)) - \frac{d_1}{p} \omega^{1-p} e(t) (d_1 r)^{\frac{1}{p}-1} v(\theta) > \frac{\omega}{2},$$

which together with (2.5)–(2.7) completes the proof of (2.8). □

Lemma 2.5 [15] Provided that function $f(x, t)$ satisfies

$$|\partial_x^k \partial_t^l f(x, t)| \leq Cx^{-k} |f(x, t)|$$

for all sufficiently large $x > 0$ and all $k, l : k+l \leq N$, where $N \in \mathbb{N}$. Suppose that

$$\partial_x f(x, t) \geq cx^{-1} f(x, t) > 0$$

for all sufficiently large $x > 0$. Then, the inverse function $g(y, t)$ of f in x satisfies

$$|\partial_y^k \partial_t^l g(y, t)| \leq Cy^{-k} g(y, t)$$

for all $K+l \leq N$ and all sufficiently large y .

Using Lemmas 2.3 and 2.4, for $h \gg 1, t \in \mathbb{S}^1$, we have

$$|\partial_h^k \partial_t^l r(h, t, \theta)| \leq Ch^{-k+1}, \quad k+l \leq 6, \quad \theta \in \mathbb{S}^1 \setminus \Xi. \tag{2.9}$$

Thus, we write (2.3) as

$$h(r, \theta, t) = \omega r + r^{\frac{1}{p}} g(r, \theta, t), \quad r = r(h, t, \theta). \tag{2.10}$$

In fact, $v(t) \in C^2(\mathbb{S}^1)$ does not belong to $C^4(\mathbb{S}^1)$. We exchange the time and angle variables to prove Theorem 1.1.

2.3 Exchange of time and angle variables

Based on the conclusions in [15], the identity $rd\theta - hdt = -(hdt - rd\theta)$ guarantees that if we can solve $r = r(h, t, \theta)$ from (2.3) as a function of h, t, θ , then

$$\frac{dh}{d\theta} = -\frac{\partial r}{\partial t}r(h, t, \theta), \quad \frac{dt}{d\theta} = \frac{\partial r}{\partial h}r(h, t, \theta), \tag{2.11}$$

i.e., Eq. (2.11) is a Hamiltonian system with a Hamiltonian function $r = r(h, t, \theta)$ in which action, angle, and time variables are h, t , and θ , respectively. The following lemma gives a more detailed description of r in (2.10) according to the magnitude of h .

Lemma 2.6 *Provided that $h \gg 1, \theta \in \mathbb{S}^1 \setminus \Xi, t \in \mathbb{S}^1$, it holds that*

$$r(h, t, \theta) = \omega^{-1}h - \omega^{-p}z(t)F((d_1\omega^{-1}h)^{\frac{1}{p}}v(\theta)) + R(h, t, \theta), \tag{2.12}$$

where

$$|\partial_h^k \partial_t^l R(h, t, \theta)| \leq Ch^{-k+\max\{\nu, \frac{1}{p}\}}, \quad k + l \leq 6. \tag{2.13}$$

Proof Using the identity (2.10) yields

$$r = \omega^{-1}h - \omega^{-1}r^{\frac{1}{p}}g(r, t, \theta). \tag{2.14}$$

Utilizing the identity (2.6) and the Taylor formula, we obtain that function $g = g(r, \theta, t)$ satisfies

$$\begin{aligned} g(r, \theta, t) &= g(\omega^{-1}h - \omega^{-1}r^{\frac{1}{p}}g, \theta, t) \\ &= g(\omega^{-1}h, \theta, t) + R_0(h, t, \theta) \\ &= (\omega^{-1}h)^{-\frac{1}{p}}\omega^{1-p}z(t)F((d_1\omega^{-1}h)^{\frac{1}{p}}v(\theta)) - d_1^{\frac{1}{p}}\omega^{1-p}e(t)v(\theta) + R_0(h, t, \theta), \end{aligned} \tag{2.15}$$

in which $R_0(h, t, \theta) = -\int_0^1 g'_r(\omega^{-1}h - s\omega^{-1}r^{\frac{1}{p}}g, \theta, t)\omega^{-1}r^{\frac{1}{p}}g ds$.

Substituting (2.14) into (2.15), we have

$$\begin{aligned} r &= \omega^{-1}h - \omega^{-1}g(r, t, \theta)(\omega^{-1}h)^{\frac{1}{p}}(1 - h^{-1}r^{\frac{1}{p}}g)^{\frac{1}{p}} \\ &= \omega^{-1}h - \omega^{-1}g(r, t, \theta)(\omega^{-1}h)^{\frac{1}{p}} \\ &\quad + \frac{1}{p}\omega^{-1}g(r, t, \theta)(\omega^{-1}h)^{\frac{1}{p}}\int_0^1 (1 - sh^{-1}r^{\frac{1}{p}}g)^{\frac{1}{p}-1}h^{-1}r^{\frac{1}{p}}g ds \\ &= \omega^{-1}h - \omega^{-p}z(t)F((d_1\omega^{-1}h)^{\frac{1}{p}}v(\theta)) + R_1(h, t, \theta) + R_2(h, t, \theta) + R_3(h, t, \theta), \end{aligned}$$

¹ C^4 is four times continuously differentiable functions in \mathbb{R} or \mathbb{S}^1 , and C^6 is six times continuously differentiable functions in \mathbb{R} or \mathbb{S}^1 .

where

$$\begin{aligned}
 R_1(h, t, \theta) &= \omega^{-(2+\frac{1}{p})} h^{\frac{1}{p}} \int_0^1 g_r(\omega^{-1}h - s\omega^{-1}r^{\frac{1}{p}}g, \theta, t) r^{\frac{1}{p}} g ds, \\
 R_2(h, t, \theta) &= \frac{1}{p} \omega^{-(1+\frac{1}{p})} h^{\frac{1}{p}-1} \int_0^1 (1 - sh^{-1}r^{\frac{1}{p}}g)^{\frac{1}{p}-1} r^{\frac{1}{p}} g^2 ds, \\
 R_3(h, t, \theta) &= d_1^{\frac{1}{p}} \omega^{-(p+\frac{1}{p})} v(\theta) e(t) h^{\frac{1}{p}}.
 \end{aligned}$$

Direct computation gives

$$\partial_h^k \partial_t^l r^{\frac{1}{p}}(h, t, \theta) = \sum r^{\frac{1}{p}-m} \partial_h^{k_1} \partial_t^{l_1} r(h, t, \theta) \partial_h^{k_2} \partial_t^{l_2} r(h, t, \theta) \cdots \partial_h^{k_m} \partial_t^{l_m} r(h, t, \theta)$$

with $1 \leq m \leq k + l$, $k_1 + k_2 \cdots + k_m = k$ and $l_1 + l_2 + \cdots + l_m = l$. Using (2.9) yields

$$|\partial_h^k \partial_t^l r^{\frac{1}{p}}(h, t, \theta)| \leq Ch^{-k+\frac{1}{p}}.$$

Similarly, we acquire

$$\begin{aligned}
 |\partial_h^k \partial_t^l g(h, t, \theta)| &\leq Ch^{-k+\frac{\gamma}{p}}, \\
 |\partial_h^k \partial_t^l g_r(\omega^{-1}h - s\omega^{-1}r^{\frac{1}{p}}g, t, \theta)| &\leq C^{-k-1+\frac{\gamma}{p}}.
 \end{aligned}$$

Using $p > 2$ and the expression of R_1 yields

$$|\partial_h^k \partial_t^l R_1(h, t, \theta)| \leq Ch^{-k-1+\frac{2+2\gamma}{p}} \leq Ch^{-k+\gamma}.$$

Analogously, we obtain

$$\begin{aligned}
 |\partial_h^k \partial_t^l R_2(h, t, \theta)| &\leq Ch^{-k+\gamma}, \\
 |\partial_h^k \partial_t^l R_3(h, t, \theta)| &\leq Ch^{-k+\frac{1}{p}}.
 \end{aligned}$$

Letting $R(h, t, \theta) = R_1(h, t, \theta) + R_2(h, t, \theta) + R_3(h, t, \theta)$, we obtain that inequality (2.13) holds. □

2.4 Canonical transformation

In this part, two lemmas are established to make sure that the Poincare map of the new system is close to a twist map.

Lemma 2.7 *There exists a canonical transformation ψ_1 of the form: $\psi_1 : (\lambda, \varphi) \rightarrow (h, t)$*

$$h = \lambda + U(\lambda, t, \theta), \quad \varphi = t + V(\lambda, t, \theta),$$

where U and V are $2\pi_p$ periodic about θ . Under ψ_1 , the Hamiltonian function (2.12) is transformed into

$$r_1(\lambda, \varphi, \theta) = \omega^{-1}\lambda - \omega^{-p} \bar{z} F((d_1 \lambda \omega^{-1})^{\frac{1}{p}} v(\theta)) + \bar{R}_1(\lambda, \varphi, \theta). \tag{2.16}$$

Moreover, for $\lambda \gg 1, \theta \in \mathbb{S}^1 \setminus \Xi, t \in \mathbb{S}^1$, it holds that

$$|\partial_\lambda^k \partial_\varphi^l \bar{R}_1(\lambda, \varphi, \theta)| \leq C \lambda^{-k + \max\{\gamma, \frac{\gamma+1}{p}\}}, \quad k + l \leq 5. \tag{2.17}$$

Proof We make a transformation $\psi_1 : (\lambda, \varphi) \rightarrow (h, t)$ implicitly given by

$$h = \lambda + \partial_t S_1(\lambda, t, \theta), \quad \varphi = t + \partial_\lambda S_1(\lambda, t, \theta) \tag{2.18}$$

with

$$S_1(\lambda, t, \theta) = \int_0^t \omega^{1-p} z_1(t) F\left((d_1 \lambda \omega^{-1})^{\frac{1}{p}} v(\theta)\right) dt.$$

Under ψ_1 , Hamiltonian (2.12) becomes

$$\begin{aligned} r_1(\lambda, \varphi, \theta) &= \omega^{-1}(\lambda + \partial_t S_1) - \omega^{-p} \hat{z} F\left((d_1 \omega^{-1}(\lambda + \partial_t S_1))^{\frac{1}{p}} v(\theta)\right) + \partial_\theta S_1 \\ &\quad - \omega^{-p} z_1(t) F\left((d_1 \omega^{-1}(\lambda + \partial_t S_1))^{\frac{1}{p}} v(\theta)\right) + R(\lambda + \partial_t S_1, t, \theta) \\ &= \omega^{-1} \lambda - \omega^{-p} \hat{z} F\left((d_1 \lambda \omega^{-1})^{\frac{1}{p}} v(\theta)\right) + R_4(\lambda, \varphi, \theta) \\ &\quad + R_5(\lambda, \varphi, \theta) + R_6(\lambda, \varphi, \theta) + R_7(\lambda, \varphi, \theta), \end{aligned}$$

where $z_1(t) = z(t) - \hat{z}$ and

$$\begin{aligned} R_4 &= -\omega^p \hat{z} \int_0^1 \partial_\lambda F\left((d_1 \omega^{-1}(\lambda + \mu \partial_t S_1))^{\frac{1}{p}} v(\theta)\right) \partial_t S_1 d\mu \\ &= -\frac{\hat{z} \omega^p}{p} \int_0^1 f\left((d_1 \omega^{-1}(\lambda + \mu \partial_t S_1))^{\frac{1}{p}} v(\theta)\right) v(\theta) d_1 \omega^{-1}(\lambda + \mu \partial_t S_1)^{-\frac{1}{q}} \partial_t S_1 d\mu, \end{aligned} \tag{2.19}$$

$$R_5 = - \int_0^1 \omega^{-p} z_1(t) \partial_{d_1 \omega^{-1} \lambda} F\left((d_1 \omega^{-1}(\lambda + \mu \partial_t S_1))^{\frac{1}{p}} v(\theta)\right) d_1 \omega^{-1} \partial_t S_1 d\mu,$$

$$R_6 = \partial_\theta S_1(\lambda, t, \theta),$$

$$R_7 = R(\lambda + \partial_t S_1, t, \theta).$$

From Lemma 2.1, for $\lambda \gg 1$ and $k + l \leq 6$, we have

$$|\partial_\lambda^k \partial_t^l S_1(\lambda, t, \theta)| \leq C \lambda^{-k + \frac{\gamma+1}{p}}, \tag{2.20}$$

which together with (2.18) yields

$$\begin{cases} \frac{1}{2} < \partial_\varphi t(\lambda, \varphi, \theta) < \frac{3}{2}, & |\partial_\lambda t(\lambda, \varphi, \theta)| < \lambda^{-2 + \frac{\gamma+1}{p}}, \\ |\partial_\lambda h(\lambda, \varphi, \theta)| \leq C, & |\partial_\varphi h(\lambda, \varphi, \theta)| \leq C \lambda^{\frac{\gamma+1}{p}}. \end{cases} \tag{2.21}$$

For $2 \leq k + l \leq 5$, utilizing direct calculations gives rise to

$$|\partial_\lambda^k \partial_\varphi^l h(\lambda, \varphi, \theta)| \leq C \lambda^{-k + \frac{\gamma+1}{p}}, \quad |\partial_\lambda^k \partial_\varphi^l t(\lambda, \varphi, \theta)| \leq C \lambda^{-k-1 + \frac{\gamma+1}{p}}. \tag{2.22}$$

First, we prove $|\partial_\lambda^k \partial_\varphi^l R_4| \leq C\lambda^{-k+\frac{\gamma+1}{p}}$. Direct computation gives

$$\partial_\lambda^k \partial_\varphi^l \partial_t S_1(\lambda, t, \theta) = \sum \partial_\lambda^m \partial_t^{n+1} S_1(\lambda, t, \theta) \partial_\lambda^{k_1} \partial_\varphi^{l_1} t \partial_\lambda^{k_2} \partial_\varphi^{l_2} t \dots \partial_\lambda^{k_n} \partial_\varphi^{l_n} t$$

with $1 \leq m + n \leq k + l$, $m + k_1 + k_2 \dots + k_m = k$ and $l_1 + l_2 + \dots + l_n = l$. Using (2.20), (2.21), and (2.22) yields

$$|\partial_\lambda^k \partial_\varphi^l \partial_t S_1| \leq C\lambda^{-k+\frac{\gamma+1}{p}}.$$

In the same way, we obtain

$$|\partial_\lambda^k \partial_\varphi^l (\lambda + \mu \partial_t S_1)^{-\frac{1}{q}}| \leq C\lambda^{-k-\frac{1}{q}}$$

and

$$\left| \partial_\lambda^k \partial_\varphi^l f\left((d_1 \omega^{-1} (\lambda + \mu \partial_t S_1))^{\frac{1}{p}} v(\theta)\right) \right| \leq C\lambda^{-k+\frac{\gamma}{p}}.$$

Noticing $0 < \frac{1}{p-1} < \gamma < 1$, from (2.19), we have $|\partial_\lambda^k \partial_\varphi^l R_4| \leq C\lambda^{-k+\frac{\gamma}{p}}$. Similarly, we obtain

$$|\partial_\lambda^k \partial_\varphi^l R_i| \leq C\lambda^{-k+\frac{\gamma+1}{p}}, \quad i = 5, 6.$$

Applying (2.13), (2.21), and (2.22) gives rise to

$$|\partial_\lambda^k \partial_\varphi^l R_7| \leq C\lambda^{-k+\max\{\gamma, \frac{1}{p}\}}.$$

Set $\bar{R}_1(\lambda, \varphi, \theta) = R_4(\lambda, \varphi, \theta) + R_5(\lambda, \varphi, \theta) + R_6(\lambda, \varphi, \theta) + R_7(\lambda, \varphi, \theta)$. Hence, inequality (2.17) holds. □

Next, we eliminate the new time variable θ at the first time by constructing the transformation.

Lemma 2.8 *There exists a canonical transformation $\psi_2 : (\lambda, \varphi) \rightarrow (\lambda, \tau)$:*

$$\psi_2 : \lambda = \lambda, \quad \varphi = \tau + \partial_\lambda S_2(\lambda, \theta).$$

Under ψ_2 , the Hamiltonian (2.16) is transformed into

$$r_2(\lambda, \tau, \theta) = \omega^{-1} \lambda - \omega^{-p} \bar{z} \bar{F}(\lambda) + \bar{R}_2(\lambda, \tau, \theta). \tag{2.23}$$

The new disturbance term \bar{R}_2 satisfies

$$|\partial_\lambda^k \partial_\tau^l \bar{R}_2(\lambda, \tau, \theta)| \leq C\lambda^{-k+\max\{\gamma, \frac{\gamma+1}{p}\}} \tag{2.24}$$

for $k + l \leq 5, \lambda \gg 1, \theta \in \mathbb{S}^1 \setminus \Xi$ and $t \in \mathbb{S}^1$.

Proof We choose generating function

$$S_2(\lambda, \theta) = \int_0^\theta \omega^{-p} \hat{z} [F((d_1 \omega^{-1} \lambda)^{\frac{1}{p}} \nu(\theta)) - \bar{F}(\lambda)] d\theta.$$

Under ψ_2 , then the Hamiltonian (2.16) is transformed into

$$r_2(\lambda, \tau, \theta) = r_1(\lambda, \varphi, \theta) + \partial_\theta S_2 = \omega^{-1} \lambda - \omega^{-p} \hat{z} \bar{F}(\lambda) + \bar{R}_2(\lambda, \tau, \theta),$$

where

$$\bar{R}_2(\lambda, \tau, \theta) = \bar{R}_1(\lambda, \tau + \partial_\lambda S_2, \theta). \tag{2.25}$$

Thus, inequality (2.24) is obtained from (2.17), (2.23), (2.25) and Lemma 2.2. The proof of Lemma 2.8 is finished. \square

3 Proof of main result

Without loss of generality, we only need to prove Theorem 1.1 for the case $\hat{e} > 0$. For $\hat{e} < 0$, the proof is similar. For given $0 < \delta < 1$, define transformation $\psi_3 : (\lambda, \tau) \rightarrow (\nu, \tau)$ by

$$\bar{F}'(\lambda) = \delta \nu \omega^p (\hat{z})^{-1}, \quad \tau = \tau, \quad 1 \leq \nu \leq 4. \tag{3.1}$$

Due to $\lambda \rightarrow +\infty, \bar{F}'(\lambda) \rightarrow 0$, thus $\lambda \rightarrow +\infty \Leftrightarrow \delta \rightarrow 0$. For $\lambda = \lambda(\delta \nu)$, the following estimates hold.

Lemma 3.1 $c \delta^{\frac{p}{\nu+1-p}} \leq \lambda(\delta \nu) \leq C \delta^{\frac{p}{\nu+1-p}}, |\partial_\nu^k \lambda(\delta \nu)| \leq C \lambda(\delta \nu) \quad k \leq 4.$

Proof From Lemma 2.2 and (3.1), we have $c \delta^{\frac{p}{\nu+1-p}} \leq \lambda(\delta \nu) \leq C \delta^{\frac{p}{\nu+1-p}}$.

Differentiating (3.1) with respect to ν , we have $\bar{F}''(\lambda) = \omega^p \delta \hat{z}^{-1}$. Using Lemma 2.2 yields

$$|\partial_\nu \lambda| = \left| \frac{\omega^p \delta \hat{z}^{-1}}{\bar{F}''(\lambda)} \right| = \left| \frac{\omega^p \delta \hat{z}^{-1} \lambda}{\bar{F}''(\lambda) \lambda} \right| \leq \left| \frac{\delta \lambda}{\lambda^{-1 + \frac{\nu+1}{p}}} \right| = \left| \frac{c \delta \lambda}{\bar{F}'(\lambda)} \right| = \frac{c \delta \lambda}{\delta \nu} \leq C \lambda.$$

Taking $k(k > 1)$ order derivative about ν on both sides of (3.1), we obtain

$$\bar{F}''(\lambda) \partial_\nu^k \lambda + \sum_{s=2}^{s=k} \bar{F}^{(s+1)} \partial_\nu^{k_1} \lambda \partial_\nu^{k_2} \dots \partial_\nu^{k_s} \lambda = 0$$

with $k_1 + k_2 + \dots + k_s = k$. Thus,

$$\partial_\nu^k \lambda = \sum_{s=2}^{s=k} \frac{\bar{F}^{(s+1)} \partial_\nu^{k_1} \lambda \partial_\nu^{k_2} \dots \partial_\nu^{k_s} \lambda}{\bar{F}''(\lambda)}.$$

From Lemma 2.2, using the induction methods yields

$$|\partial_\nu^k \lambda| \leq C \lambda, \quad k = 2, 3, 4,$$

which completes the proof of Lemma 3.1. \square

From the definition ψ_3 , we have

$$\frac{dv}{d\theta} = \delta^{-1} \omega^{-p} \hat{z} \bar{F}''(\lambda) \frac{d\lambda}{d\theta} = \delta^{-1} \omega^{-p} \hat{z} \bar{F}''(\lambda) \partial_\tau \bar{R}_2(\lambda, \tau, \theta).$$

Introducing a new time variable ϑ by $\theta = -\vartheta$ yields

$$\frac{dv}{d\vartheta} = l_1(v, \tau, \vartheta, \delta), \quad \frac{d\tau}{d\vartheta} = -\omega^{-1} + \delta v + l_2(v, \tau, \vartheta, \delta), \tag{3.2}$$

where

$$l_1(v, \tau, \vartheta, \delta) = \delta^{-1} \omega^{-p} \hat{z} \bar{F}''(\lambda) \partial_\tau \bar{R}_2(\lambda, \tau, -\vartheta),$$

$$l_2(v, \tau, \vartheta, \delta) = -\partial_\lambda \bar{R}_2(\lambda, \tau, -\vartheta).$$

Lemma 3.2 *Provided that $p > 2$, $\frac{1}{p-1} < \gamma < 1$, $0 < \delta \ll 1$, $k + l \leq 4$ and $\tau \in \mathbb{S}^1 \setminus \Xi(i = 1, 2)$, it holds that*

$$|\partial_v^k \partial_\tau^l l_i(v, \tau, \vartheta, \delta)| \leq C \delta^\sigma, \tag{3.3}$$

where $\sigma = \frac{p}{\gamma+1-p}(-1 + \gamma) > 0$.

Proof For $k = 0$, we have

$$|\partial_\tau^l l_2| = |\partial_\lambda \partial_\tau^l \bar{R}_2(\lambda, \tau, -\vartheta)| \leq C \lambda^{-1+\max\{\frac{\gamma+1}{p}, \gamma\}} \leq C \delta^{\frac{p}{\gamma+1-p}(-1+\max\{\frac{\gamma+1}{p}, \gamma\})} \leq C \delta^\sigma.$$

Using the assumption $\gamma > \frac{1}{p-1}$ derives $\frac{1+\gamma}{p} < \gamma$. We have $|\partial_\tau^l l_2| \leq C \delta^\sigma$.

For $k > 0$, we obtain

$$\begin{aligned} |\partial_v^k \partial_\tau^l l_2| &= |\partial_v^k \partial_\tau^l \partial_\lambda \bar{R}_2(\lambda, \tau, -\vartheta)| \\ &\leq C \lambda^{-1+\max\{\frac{\gamma+1}{p}, \gamma\}} \\ &\leq C \delta^{\frac{p}{\gamma+1-p}(-1+\max\{\frac{\gamma+1}{p}, \gamma\})} \\ &\leq C \delta^\sigma. \end{aligned}$$

For l_1 , we have the same estimate. The proof of Lemma 3.2 is completed. □

From Lemmas 3.1–3.2 and (3.3), we see that the solutions of (3.2) with initial value $v(0) = v_0 \in [1, 2]$, $\tau(0) = \tau_0$ do exist for $0 \leq \vartheta \leq 4\pi_p$ if $\delta \ll 1$. Integrating (3.2) from 0 to $2\pi_p$, we derive that Poincaré map P in (3.2) takes the following form

$$P: \begin{cases} \tau_{2\pi_p} = \tau_0 - \omega^{-1} 2\pi_p + \delta(v_0 + P_2(v_0, \tau_0, \delta)), \\ v_{2\pi_p} = v_0 + \delta P_1(v_0, \tau_0, \delta), \end{cases}$$

where $|\partial_{v_0}^k \partial_{\tau_0}^l P_i| \leq C \delta^{\sigma-1}$ for $k + l \leq 4$, $i = 1, 2$.

Since P is a Poincaré map in (3.2), it is an area-preserving, and thus it possesses the intersection property in the annulus $[1, 2] \times \mathbb{S}^1$. Namely, if Γ is an embedded circle in

$[1, 2] \times \mathbb{S}^1$ homotopic to a circle $v = \text{constant}$, then $P(\Gamma) \cap \Gamma \neq \emptyset$ (see [18]). Now, we have verified that the mapping P satisfies all the conditions of Moser's twist theorem. Hence, there exists an invariant curve Γ_δ of P surrounding $v_0 = 1$ if $\delta \ll 1$. The Γ_δ is located in ring domain $\{(v, \tau) | \delta < v < 2\delta\}$. Note that $\delta \rightarrow 0 \Leftrightarrow \lambda \rightarrow \infty$. The points $(\lambda, \varphi, \theta)$ satisfying $r_1(\lambda, \varphi, \theta) = r_1(\lambda, \varphi, \theta)|_{(\lambda, \varphi) \in \Gamma_\delta}$ form an invariant torus \mathbf{T}_δ^2 in the extended phase space $(\lambda, \varphi, \theta)$. Thus, $\psi^{-1}(\Gamma_\delta)$ is an invariant torus for Eq. (2.1) in $(x, y, t) \in \mathbb{R}^2 \times \mathbb{S}^1$, which is far away from $(0, 0)$, where $\psi = \psi_1 \psi_0$. The solution of Eq. (2.1) starting from inside of $\psi^{-1}(\Gamma_\delta)$ is contained inside of $\psi^{-1}(\Gamma_\delta)$. Thus, the solution of Eq. (2.1) is bounded. The proof of Theorem 1.1 is finished.

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Author contributions

The three authors contributed equally to this paper.

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Data availability

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Declarations

Competing interests

The authors declare no competing interests.

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