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Starting solutions for the motion of a generalized Burgers' fluid between coaxial cylinders

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Abstract

The unsteady flow of a generalized Burgers' fluid, between two infinite coaxial circular cylinders, is studied by means of the Laplace and finite Hankel transforms. The motion of the fluid is produced by the inner cylinder that, after the initial moment, applies a longitudinal time dependent shear to the fluid. The solutions that have been obtained, presented in series form in terms of usual Bessel functions, satisfy all imposed initial and boundary conditions. Moreover, the corresponding solutions for Burgers' fluids appear as special cases of present results. For large values of t , these solutions are going to the steady solutions that are the same for both kinds of fluids. Finally, the influence of the material parameters on the fluid motion, as well as a comparison between models, is shown by graphical illustrations.

Mathematics Subject Classification (2010). 76A05; 76A10.

Keywords: Generalized Burgers' fluid, coaxial cylinders, velocity field, time-dependent shear stress, Laplace and Hankel transforms

1 Introduction

Recently, considerable attention has been focused to study the behavior of non-Newtonian fluids. Many substances of multi-phase nature and/or of high molecular weight are frequently encountered in disciplinary fields such as chemical engineering, food stuff, bio-medicine and so forth, and are also closely related to industrial processes. Typical non-Newtonian characteristics include shear-thinning, shear-thickening, viscoelasticity, viscoplasticity (i.e., the exhibition of an apparent yield stress) and so on. In particular, polymer melts and solutions, liquid crystals or biological fluids exhibit such properties which lead to non-linear viscoelastic behavior that cannot be simply described by the classical Navier-Stokes theory. Non-Newtonian fluids form a broad class of fluids in which the relation connecting the shear stress and shear rate is non-linear and hence there is no universal constitutive model available which exhibits the characteristics of all non-Newtonian fluids. Moreover, due to the flow behavior of these fluids, the governing equations become more complex to handle as additional non-linear terms appear in the equations of motion. Numerous models have been proposed to describe the response corresponding to non-Newtonian fluids. They are usually classified as fluids of differential, rate and integral type. Amongst the non-Newtonian fluids, the rate type fluids are those which take into account the elastic and memory effects. The simplest subclasses of rate type fluids are those of Maxwell and

Oldroyd-B fluids. But these fluid models do not exhibit rheological properties of many real fluids such as asphalt in geomechanics and cheese in food products.

Recently, a thermodynamic framework has been put into place to develop the 1D rate type model known as Burgers' model [1] to the frame-indifferent 3D form by Krishnan and Rajagopal [2]. This model has been successfully used to describe the motion of the earth's mantle. The Burgers' model is the preferred model to describe the response of asphalt and asphalt concrete [3]. This model is mostly used to model other geological structures, such as Olivine rocks [4] and the propagation of seismic waves in the interior of the earth [5]. In the literature, the vast majority of the flows of the rate type models has been discussed using Maxwell and Oldroyd-B models. However, the Burgers' model has not received much attention in spite of its diverse applications. We here mention some of the studies [6-12] made by using Burgers' model. The most of the above mentioned studies dealt with problems in which the velocity is given on the boundary. The motion of a fluid due to translating or rotating cylinder is of great interest to both theoretical and practical domains. The first exact solutions for motions of non-Newtonian fluids due to a circular cylinder that applies a longitudinal or rotational shear stress to the fluid are those of Bandelli and Rajagopal [13, Sects. 4 and 5]. These solutions, for rotational shear stresses, have been recently extended to generalized Burgers fluids [11,12].

The aim of this note is to extend the results of Bandelli and Rajagopal [13, Sect. 4] to Burgers and generalized Burgers fluids. More exactly, we study the motion of a generalized Burgers' fluid between two infinite coaxial circular cylinders. The motion of the fluid is induced by the inner cylinder that applies a longitudinal time dependent shear to the fluid. The solutions that have been obtained satisfy both the governing equations and all imposed initial and boundary conditions. They can immediately be reduced to the similar solutions for Burgers' fluids. As a check of the results, the equivalence of general solutions (for small values of the material parameters λ_2 and λ_4) with the known solutions for Oldroyd-B fluids is shown by graphical illustrations. Furthermore, in order to reveal some relevant physical aspects of these results, the diagrams of the velocity and shear stress are depicted against r for different values of pertinent parameters.

2 Basic governing equations

The equations governing the flow of an incompressible fluid include the continuity equation and the momentum equation. In the absence of body forces, they are

$$\nabla \cdot \mathbf{V} = 0, \quad \frac{\partial \mathbf{V}}{\partial t} + (\mathbf{V} \cdot \nabla) \mathbf{V} = \frac{1}{\rho} (\nabla \cdot \mathbf{T}), \quad (1)$$

where ρ and \mathbf{V} are, respectively, the fluid density and velocity vector and ∇ represents the gradient operator.

The Cauchy stress tensor \mathbf{T} for an incompressible generalized Burgers' fluid is characterized by the following constitutive equations [10-12]

$$\mathbf{T} = -p\mathbf{I} + \mathbf{S}, \quad \mathbf{S} + \lambda_1 \frac{\delta \mathbf{S}}{\delta t} + \lambda_2 \frac{\delta^2 \mathbf{S}}{\delta t^2} = \mu \left[\mathbf{A} + \lambda_3 \frac{\delta \mathbf{A}}{\delta t} + \lambda_4 \frac{\delta^2 \mathbf{A}}{\delta t^2} \right], \quad (2)$$

where $-p\mathbf{I}$ denotes the indeterminate spherical stress, \mathbf{S} is the extra-stress tensor, $\mathbf{A} = \mathbf{L} + \mathbf{L}^T$ is the first Rivlin-Ericksen tensor (\mathbf{L} being the velocity gradient), μ is the dynamic viscosity, λ_1 and $\lambda_3 (< \lambda_1)$ are relaxation and retardation times, λ_2 and λ_4 are new material parameters of the generalized Burgers' fluid (having the dimension of t^2), and $\delta/\delta t$ denotes the upper convected derivative defined by [10]

$$\frac{\delta \mathbf{S}}{\delta t} = \frac{d\mathbf{S}}{dt} - \mathbf{L}\mathbf{S} - \mathbf{S}\mathbf{L}^T, \quad \frac{\delta^2 \mathbf{S}}{\delta t^2} = \frac{\delta}{\delta t} \left(\frac{\delta \mathbf{S}}{\delta t} \right).$$

Into above relation, d/dt is the usual material time derivative.

This model includes as special cases the Burgers' model (for $\lambda_4 = 0$), Oldroyd-B model (for $\lambda_2 = \lambda_4 = 0$), Maxwell model (for $\lambda_2 = \lambda_3 = \lambda_4 = 0$) and the linearly viscous fluid model when $\lambda_1 = \lambda_2 = \lambda_3 = \lambda_4 = 0$. In some special flows, like that to be here considered, the governing equations corresponding to generalized Burgers' fluids also resemble those for second grade fluids. However, closed form expressions for the similar solutions corresponding to Oldroyd-B, Maxwell, second grade and Newtonian fluids cannot be obtained as limiting cases of general solutions.

For the problem under consideration we assume a velocity field \mathbf{V} and an extra-stress tensor \mathbf{S} of the form

$$\mathbf{V} = \mathbf{V}(r, t) = v(r, t)\mathbf{e}_z, \quad \mathbf{S} = \mathbf{S}(r, t), \tag{3}$$

where \mathbf{e}_z is the unit vector in the z -direction of a cylindrical coordinate system r, θ, z . For these flows the constraint of incompressibility is automatically satisfied.

Substituting Eq. (3) into Eq. (2), and assuming that the fluid is at rest up to the moment $t = 0$, i.e.:

$$\mathbf{V}(r, 0) = \frac{\partial \mathbf{V}(r, 0)}{\partial t} = \frac{\partial^2 \mathbf{V}(r, 0)}{\partial t^2} = \mathbf{0}, \quad \mathbf{S}(r, 0) = \frac{\partial \mathbf{S}(r, 0)}{\partial t} = \mathbf{0}, \tag{4}$$

it results that $S_{rr} = S_{r\theta} = S_{\theta\theta} = S_{\theta z} = 0$ for all time and [10]

$$\left(1 + \lambda_1 \frac{\partial}{\partial t} + \lambda_2 \frac{\partial^2}{\partial t^2} \right) \tau(r, t) = \mu \left(1 + \lambda_3 \frac{\partial}{\partial t} + \lambda_4 \frac{\partial^2}{\partial t^2} \right) \frac{\partial v(r, t)}{\partial r}, \tag{5}$$

where $\tau(r, t) = S_{rz}(r, t)$ is the non-trivial tangential stress. The equations of motion, in the absence of body forces, reduce to [14]

$$\frac{\partial p}{\partial r} = \frac{\partial p}{\partial \theta} = 0 \quad \text{and} \quad -\frac{\partial p}{\partial z} + \frac{\partial \tau(r, t)}{\partial r} + \frac{\tau(r, t)}{r} = \rho \frac{\partial v(r, t)}{\partial t}. \tag{6}$$

Assuming that there is no applied pressure gradient along the axial direction, Eqs. (5) and (6) lead to the following governing equation for velocity

$$\left(1 + \lambda_1 \frac{\partial}{\partial t} + \lambda_2 \frac{\partial^2}{\partial t^2} \right) \frac{\partial v(r, t)}{\partial t} = \nu \left(1 + \lambda_3 \frac{\partial}{\partial t} + \lambda_4 \frac{\partial^2}{\partial t^2} \right) \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} \right) v(r, t), \tag{7}$$

where $\nu = \mu/\rho$ is the kinematic viscosity of the fluid and ρ is its constant density.

3 Starting flow due to a time dependent shear stress

Let us consider an incompressible generalized Burgers' fluid at rest in an annular pipe between two coaxial circular cylinders of radii R_1 and $R_2 (> R_1)$. At time $t = 0^+$, a time dependent longitudinal shear stress

$$\tau(R_1, t) = f \left[1 - \frac{p_2 e^{p_1 t} - p_1 e^{p_2 t}}{p_2 - p_1} \right], \quad p_1, p_2 = \frac{-\lambda_1 \pm \sqrt{\lambda_1^2 - 4\lambda_2}}{2\lambda_2}, \quad (8)$$

and f is a constant, is applied to the inner cylinder. Due to the shear, the fluid is gradually moved. Its velocity is of the form (3) while the governing equations are given by Eqs. (5) and (7). The appropriate initial and boundary conditions are

$$v(r, 0) = \frac{\partial v(r, 0)}{\partial t} = \frac{\partial^2 v(r, 0)}{\partial t^2} = 0; \quad \tau(r, 0) = \frac{\partial \tau(r, 0)}{\partial t} = 0; \quad r \in (R_1, R_2], \quad (9)$$

$$\left(1 + \lambda_1 \frac{\partial}{\partial t} + \lambda_2 \frac{\partial^2}{\partial t^2} \right) \tau(r, t) \Big|_{r=R_1} = \mu \left(1 + \lambda_3 \frac{\partial}{\partial t} + \lambda_4 \frac{\partial^2}{\partial t^2} \right) \frac{\partial v(r, t)}{\partial r} \Big|_{r=R_1} = f; \quad t > 0, \quad (10a)$$

and

$$v(R_2, t) = 0; \quad t > 0. \quad (10b)$$

It is easy to see that $\tau(R_1, t)$ given by Eq. (8) is just the solution of Eq. (10a)₁. Furthermore, making λ_1, λ_2 and $\lambda_4 \rightarrow 0$, Eq. (10a) reduces to the boundary condition (4.3) used by Bandelli and Rajagopal [13]. It corresponds to a problem with a constant shear stress on a part of the boundary, namely

$$\tau(R_1, t) = \mu \left(1 + \lambda_3 \frac{\partial}{\partial t} \right) \frac{\partial v(r, t)}{\partial r} \Big|_{r=R_1} = f, \quad v(R_2, t) = 0; \quad t > 0. \quad (11)$$

In order to solve the partial differential equations (7) and (5), with the initial and boundary conditions (9) and (10), we shall use the Laplace and finite Hankel transforms.

3.1 Calculation of the velocity field

Applying the Laplace transform to Eq. (7) and having in mind the initial and boundary conditions (9) and (10), we find that

$$(q + \lambda_1 q^2 + \lambda_2 q^3) \bar{v}(r, q) = v(1 + \lambda_3 q + \lambda_4 q^2) \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} \right) \bar{v}(r, q); \quad r \in (R_1, R_2), \quad (12)$$

where the image function $\bar{v}(r, q) = \mathcal{L}\{v(r, t)\}$ has to satisfy the conditions

$$\frac{\partial \bar{v}(R_1, q)}{\partial r} = \frac{f}{\mu q(1 + \lambda_3 q + \lambda_4 q^2)}, \quad \bar{v}(R_2, q) = 0. \quad (13)$$

In the following, we denote by [15,16]

$$\bar{v}_H(r_n, q) = \int_{R_1}^{R_2} r \bar{v}(r, q) B(r, r_n) dr; \quad n = 1, 2, 3, \dots \quad (14)$$

the Hankel transform of $\bar{v}(r, q)$, where

$$B(r, r_n) = J_0(rr_n)Y_1(R_1 r_n) - J_1(R_1 r_n)Y_0(rr_n), \quad (15)$$

r_n are the positive roots of the transcendental equation $B(R_2, r) = 0$ and $J_p(\bullet)$ and $Y_p(\bullet)$ are Bessel functions of the first and second kind of order p . Multiplying both sides of Eq. (12) by $rB(r, r_n)$, integrating with respect to r from R_1 to R_2 and taking into

account the conditions (13) and the identity [17, Eq. (19)]

$$\int_{R_1}^{R_2} r \left[\frac{\partial^2 \bar{v}(r, q)}{\partial r^2} + \frac{1}{r} \frac{\partial \bar{v}(r, q)}{\partial r} \right] B(r, r_n) dr = \frac{2}{\pi r_n} \frac{\partial \bar{v}(R_1, q)}{\partial r} - r_n^2 \bar{v}_H(r_n, q), \quad (16)$$

we find that

$$\bar{v}_H(r_n, q) = \frac{2f}{\rho \pi r_n^3 q} \frac{1}{\lambda_2 q^3 + (\lambda_1 + \lambda_4 v r_n^2) q^2 + (1 + \lambda_3 v r_n^2) q + v r_n^2}. \quad (17)$$

For a suitable presentation of the final results, we rewrite Eq. (17) in the following equivalent form

$$\bar{v}_H(r_n, q) = \frac{2f}{\pi \mu r_n^3} \frac{1}{q} - \frac{2f}{\pi \mu r_n^3} \frac{\lambda_2 q^2 + (\lambda_1 + \lambda_4 v r_n^2) q + 1 + \lambda_3 v r_n^2}{\lambda_2 q^3 + (\lambda_1 + \lambda_4 v r_n^2) q^2 + (1 + \lambda_3 v r_n^2) q + v r_n^2}, \quad (18)$$

and use the known results (see for instance [15-17])

$$\bar{v}(r, q) = \frac{\pi^2}{2} \sum_{n=1}^{\infty} \frac{r_n^2 J_0^2(R_2 r_n) B(r, r_n)}{J_1^2(R_1 r_n) - J_0^2(R_2 r_n)} \bar{v}_H(r_n, q), \quad \int_{R_1}^{R_2} r \ln \left(\frac{r}{R_2} \right) B(r, r_n) dr = \frac{2}{\pi R_1 r_n^3}, \quad (19)$$

In order to obtain the velocity field $v(r, t) = \mathcal{L}^{-1}\{\bar{v}(r, q)\}$, we apply the inverse Laplace transform to Eq. (18) and use the identities (19) and Eq. (A1) from the Appendix. As a result, we find for the velocity field, the simple expression

$$v(r, t) = \frac{f}{\mu} R_1 \ln \left(\frac{r}{R_2} \right) + \frac{\pi f}{\rho \lambda_2} \sum_{n=1}^{\infty} \frac{r_n J_0^2(R_2 r_n) B(r, r_n)}{J_1^2(R_1 r_n) - J_0^2(R_2 r_n)} \times \left[\frac{e^{q_{1n} t}}{q_{1n}(q_{1n} - q_{2n})(q_{1n} - q_{3n})} + \frac{e^{q_{2n} t}}{q_{2n}(q_{2n} - q_{1n})(q_{2n} - q_{3n})} + \frac{e^{q_{3n} t}}{q_{3n}(q_{3n} - q_{1n})(q_{3n} - q_{2n})} \right], \quad (20)$$

where

$$q_{in} = s_{in} - \frac{\lambda_1 + \lambda_4 v r_n^2}{3\lambda_2}, \quad i = 1, 2, 3.$$

In above relations (see the Cardano's formulae [18])

$$s_{1n} = \sqrt[3]{-\frac{\beta_{1n}}{2} + \sqrt{\frac{\beta_{1n}^2}{4} + \frac{\alpha_{1n}^3}{27}}} + \sqrt[3]{-\frac{\beta_{1n}}{2} - \sqrt{\frac{\beta_{1n}^2}{4} + \frac{\alpha_{1n}^3}{27}}},$$

$$s_{2n} = \omega \sqrt[3]{-\frac{\beta_{1n}}{2} + \sqrt{\frac{\beta_{1n}^2}{4} + \frac{\alpha_{1n}^3}{27}}} + \omega^2 \sqrt[3]{-\frac{\beta_{1n}}{2} - \sqrt{\frac{\beta_{1n}^2}{4} + \frac{\alpha_{1n}^3}{27}}},$$

$$s_{3n} = \omega^2 \sqrt[3]{-\frac{\beta_{1n}}{2} + \sqrt{\frac{\beta_{1n}^2}{4} + \frac{\alpha_{1n}^3}{27}}} + \omega \sqrt[3]{-\frac{\beta_{1n}}{2} - \sqrt{\frac{\beta_{1n}^2}{4} + \frac{\alpha_{1n}^3}{27}}},$$

are the roots of the algebraic equations $X^3 + \alpha_{1n} X + \beta_{1n} = 0$, where

$$\alpha_{1n} = -\frac{(\lambda_1 + \lambda_4 v r_n^2)^2}{3\lambda_2^2} + \frac{1 + \lambda_3 v r_n^2}{\lambda_2},$$

$$\beta_{1n} = \frac{v r_n^2}{\lambda_2} + \frac{2(\lambda_1 + \lambda_4 v r_n^2)^3}{27\lambda_2^3} - \frac{(\lambda_1 + \lambda_4 v r_n^2)(1 + \lambda_3 v r_n^2)}{3\lambda_2^2},$$

and

$$\omega = \frac{-1 + i\sqrt{3}}{2}.$$

From the Routh-Hurwitz's principle [19], we get $Re(q_{in}) < 0$, if $\lambda_1\lambda_3 - \lambda_2 + \lambda_4 > -2\sqrt{\lambda_1\lambda_3\lambda_4}$, provided $\lambda_1, \lambda_2, \lambda_3, \lambda_4 > 0$.

3.2 Calculation of the shear stress

Applying the Laplace transform to Eq. (5), we find that

$$\bar{\tau}(r, q) = \mu \frac{1 + \lambda_3q + \lambda_4q^2}{1 + \lambda_1q + \lambda_2q^2} \frac{\partial \bar{v}(r, q)}{\partial r}, \tag{21}$$

where

$$\begin{aligned} \frac{\partial \bar{v}(r, q)}{\partial r} &= \frac{R_1 f}{\mu r} \frac{1}{q(1 + \lambda_3q + \lambda_4q^2)} + \frac{\pi f}{\mu} \sum_{n=1}^{\infty} \frac{J_0^2(R_2 r_n) \tilde{B}(r, r_n)}{[J_1^2(R_1 r_n) - J_0^2(R_2 r_n)]} \\ &\times \frac{1 + \lambda_1q + \lambda_2q^2}{(1 + \lambda_3q + \lambda_4q^2)\{\lambda_2q^3 + (\lambda_1 + \lambda_4\nu r_n^2)q^2 + (1 + \lambda_3\nu r_n^2)q + \nu r_n^2\}}, \end{aligned} \tag{22}$$

has been obtained from Eq. (18) applying the inverse Hankel transform and using Eqs. (19)₂ and (A2). Into above relation

$$\tilde{B}(r, r_n) = J_1(r r_n) Y_1(R_1 r_n) - J_1(R_1 r_n) Y_1(r r_n). \tag{23}$$

Finally, following the same way as in [11,12], we find that

$$\begin{aligned} \tau(r, t) &= f \left(\frac{R_1}{r} \right) \left[1 - \frac{p_2 e^{p_1 t} - p_1 e^{p_2 t}}{p_2 - p_1} \right] + \frac{\pi f}{\lambda_2} \sum_{n=1}^{\infty} \frac{J_0^2(R_2 r_n) \tilde{B}(r, r_n)}{J_1^2(R_1 r_n) - J_0^2(R_2 r_n)} \\ &\times \left[\frac{e^{q_{1n} t}}{(q_{1n} - q_{2n})(q_{1n} - q_{3n})} + \frac{e^{q_{2n} t}}{(q_{2n} - q_{1n})(q_{2n} - q_{3n})} + \frac{e^{q_{3n} t}}{(q_{3n} - q_{1n})(q_{3n} - q_{2n})} \right]. \end{aligned} \tag{24}$$

By making $\lambda_4 \rightarrow 0$ into Eqs. (20) and (24) the similar solutions for a Burgers' fluid performing the same motion are obtained. As a check of our results, let us remember the solutions [20, Eqs. (15) and (18)]

$$v_{OB}(r, t) = \frac{f}{\mu} R_1 \ln \left(\frac{r}{R_2} \right) - \frac{\pi f}{\mu} \sum_{n=1}^{\infty} \frac{J_0^2(R_2 r_n) B(r, r_n)}{r_n [J_1^2(R_1 r_n) - J_0^2(R_2 r_n)]} \frac{q_{5n} e^{q_{4n} t} - q_{4n} e^{q_{5n} t}}{q_{5n} - q_{4n}}, \tag{25}$$

and the shear stress

$$\tau_{OB}(r, t) = f \left(\frac{R_1}{r} \right) [1 - e^{-t/\lambda_1}] + \frac{\pi f}{\lambda_1} \sum_{n=1}^{\infty} \frac{J_0^2(R_2 r_n) \tilde{B}(r, r_n)}{J_1^2(R_1 r_n) - J_0^2(R_2 r_n)} \frac{e^{q_{5n} t} - e^{q_{4n} t}}{q_{5n} - q_{4n}}, \tag{26}$$

corresponding to an Oldroyd-B fluid performing the same motion. These solutions correspond to the boundary condition

$$\tau(R_1, t) = f \left(1 - e^{-\frac{t}{\lambda_1}} \right), \tag{27}$$

obtained from Eq. (8) for $\lambda_2 \rightarrow 0$, and

$$q_{4n}, q_{5n} = \frac{-(1 + \lambda_3 \nu r_n^2) \pm \sqrt{(1 + \lambda_3 \nu r_n^2)^2 - 4\nu\lambda_1 r_n^2}}{2\lambda_1}$$

By now letting λ_1 and $\lambda_3 \rightarrow 0$ into Eqs. (25) and (26), the similar solutions (see [13, Eq. (4.35)]) with $\alpha = 0$ for velocity only)

$$v_N(r, t) = \frac{f}{\mu} R_1 \ln\left(\frac{r}{R_2}\right) - \frac{\pi f}{\mu} \sum_{n=1}^{\infty} \frac{J_0^2(R_2 r_n) B(r, r_n)}{r_n [J_1^2(R_1 r_n) - J_0^2(R_2 r_n)]} e^{-\nu r_n^2 t}, \quad (28)$$

$$\tau_N(r, t) = f\left(\frac{R_1}{r}\right) + \pi f \sum_{n=1}^{\infty} \frac{J_0^2(R_2 r_n) \tilde{B}(r, r_n)}{J_1^2(R_1 r_n) - J_0^2(R_2 r_n)} e^{-\nu r_n^2 t}, \quad (29)$$

corresponding to Newtonian fluids are recovered. They correspond to a constant shear stress $\tau(R_1, t) = f$ on the inner cylinder.

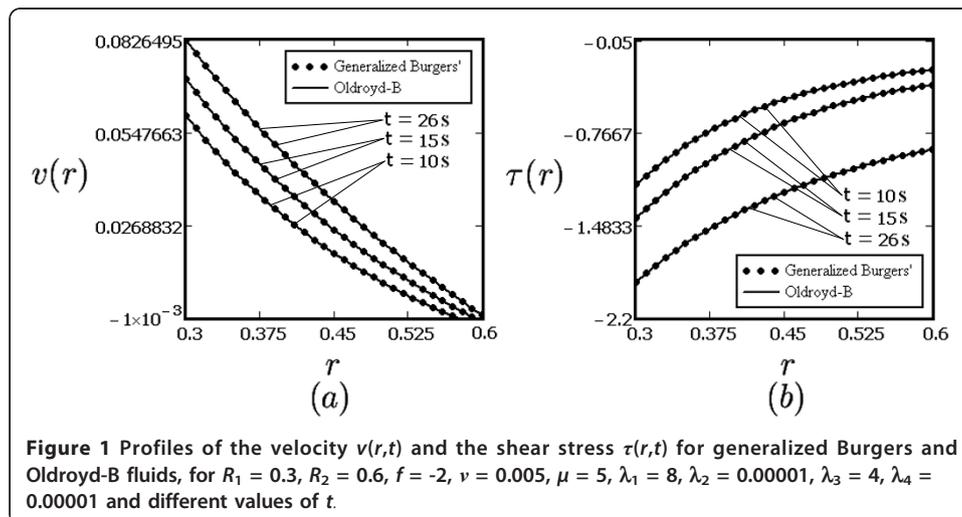
Figures 1 and 2 clearly show that the diagram of $v(r, t)$ and $\tau(r, t)$ given by Eqs. (20) and (24), as it was to be expected, are almost identical to those corresponding to Oldroyd-B and Newtonian fluids for small values of λ_2 and λ_4 , respectively $\lambda_1, \lambda_2, \lambda_3$, and λ_4 . This is a veritable check on the corrections of general solutions presented in the simple forms (20) and (24).

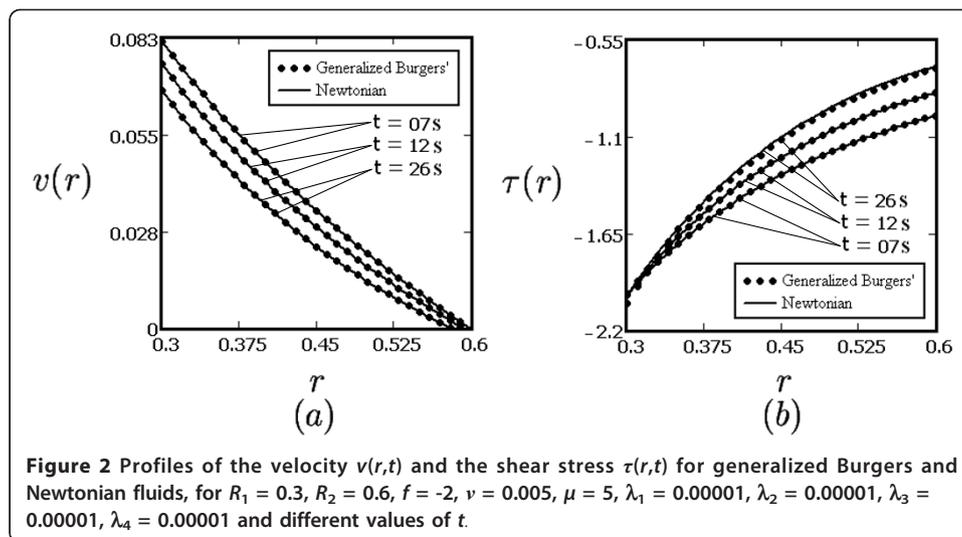
4 Steady and transient solutions

The solutions (28) and (29), as well as those for second grade fluids resulting from Eqs. (25) and (26) for $\lambda_1 \rightarrow 0$, correspond to a constant shear stress on the boundary. For large values of time t these solutions tend to the steady solutions

$$v_S(r) = \frac{f}{\mu} R_1 \ln\left(\frac{r}{R_2}\right), \quad \tau_S(r) = f\left(\frac{R_1}{r}\right), \quad (30)$$

which are the same for all types of fluids. Indeed, making $t \rightarrow \infty$ into Eqs. (20), (24), (25), and (26) we attain to Eqs. (30). This is not a surprise, because for large values of t the boundary condition (8) is identical to that corresponding to second grade and



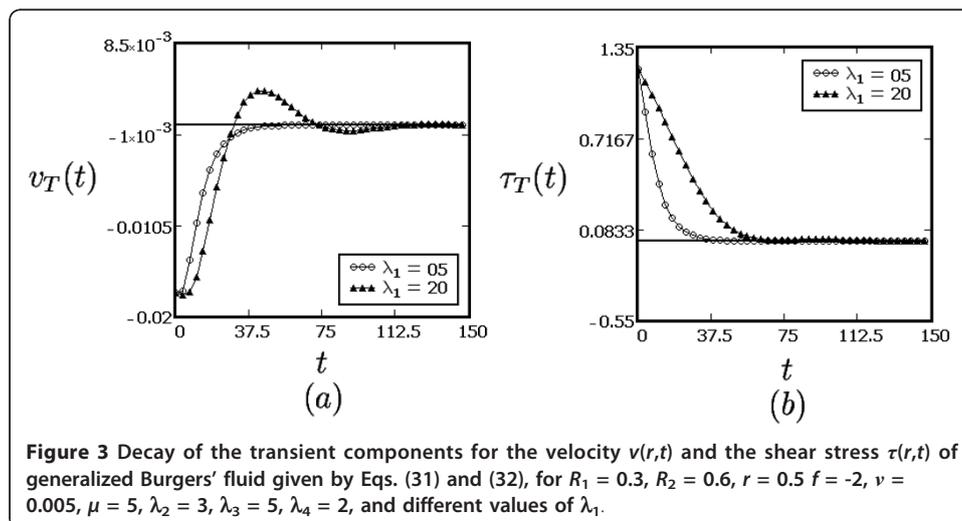


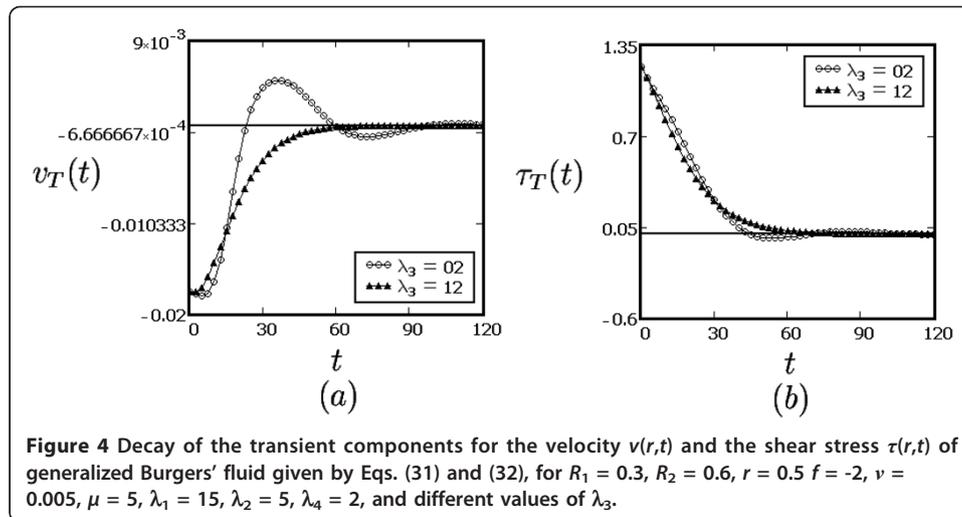
Newtonian fluids. In conclusion, after some time, the behavior of a non-Newtonian fluid can be well enough described by that of a Newtonian fluid. This time, depending of the material parameters and the constant f , can easily be determined by graphical illustrations. In order to show this, the decay of the transient solutions

$$v_T(r, t) = \frac{\pi f}{\rho \lambda_2} \sum_{n=1}^{\infty} \frac{r_n J_0^2(R_2 r_n) B_v(r, r_n)}{J_1^2(R_1 r_n) - J_0^2(R_2 r_n)} \times \left[\frac{e^{q_{1n}t}}{q_{1n}(q_{1n} - q_{2n})(q_{1n} - q_{3n})} + \frac{e^{q_{2n}t}}{q_{2n}(q_{2n} - q_{1n})(q_{2n} - q_{3n})} + \frac{e^{q_{3n}t}}{q_{3n}(q_{3n} - q_{1n})(q_{3n} - q_{2n})} \right], \quad (31)$$

$$\tau_T(r, t) = f \left(\frac{R_1}{r} \right) \left[\frac{p_1 e^{p_2 t} - p_2 e^{p_1 t}}{p_2 - p_1} \right] + \frac{\pi f}{\lambda_2} \sum_{n=1}^{\infty} \frac{J_0^2(R_2 r_n) \tilde{B}_v(r, r_n)}{J_1^2(R_1 r_n) - J_0^2(R_2 r_n)} \times \left[\frac{e^{q_{1n}t}}{(q_{1n} - q_{2n})(q_{1n} - q_{3n})} + \frac{e^{q_{2n}t}}{(q_{2n} - q_{1n})(q_{2n} - q_{3n})} + \frac{e^{q_{3n}t}}{(q_{3n} - q_{1n})(q_{3n} - q_{2n})} \right], \quad (32)$$

in time, is depicted in Figures 3, 4, and 5 for different values of λ_1 , λ_3 and ν . These figures clearly show that the required time to reach the steady state is an increasing



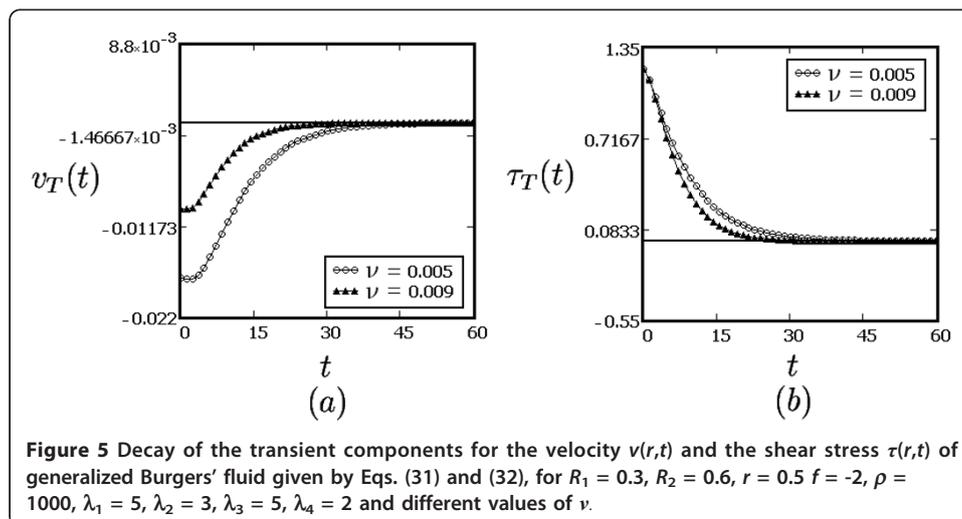


function with respect to λ_1 and a decreasing one with regard to λ_3 and ν . A simple analysis shows that the required time to reach the steady state for Maxwell fluids, for instance, is higher in comparison with Newtonian fluids. According to Figure 4, it also results that the required time to reach the steady state is lower for second grade fluids in comparison with Newtonian fluids.

5 Numerical results and discussion

In the previous sections, we have presented exact analytical solutions for a flow problem of a generalized Burgers' fluid. In order to verify and capture relevant physical effects of the obtained results, several graphs are depicted in this section. The numerical results illustrate the velocity as well as shear stress profiles for the axial flow induced by the inner cylinder. We interpret these results with respect to the variations of emerging parameters of interest.

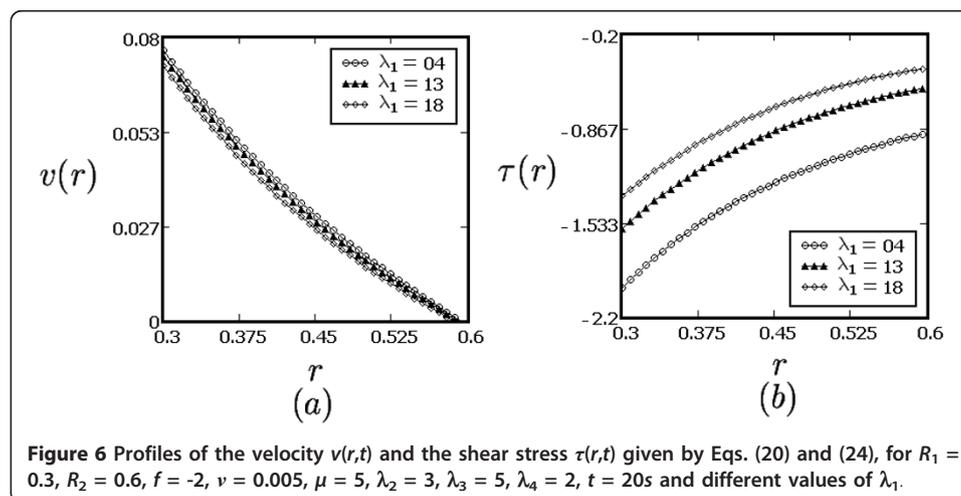
For large values of t , all solutions tend to the steady solutions $v_S(r,t)$ and $\tau_S(r,t)$ which are the same for all kinds of fluids although the motion of rate type fluids (generalized Burgers, Burgers, Oldroyd-B, and Maxwell) is due to a time dependent shear stress on

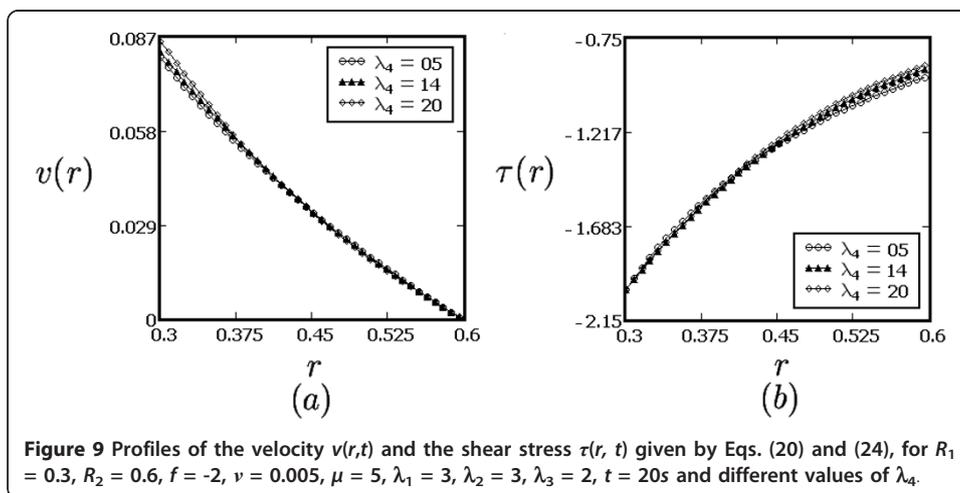
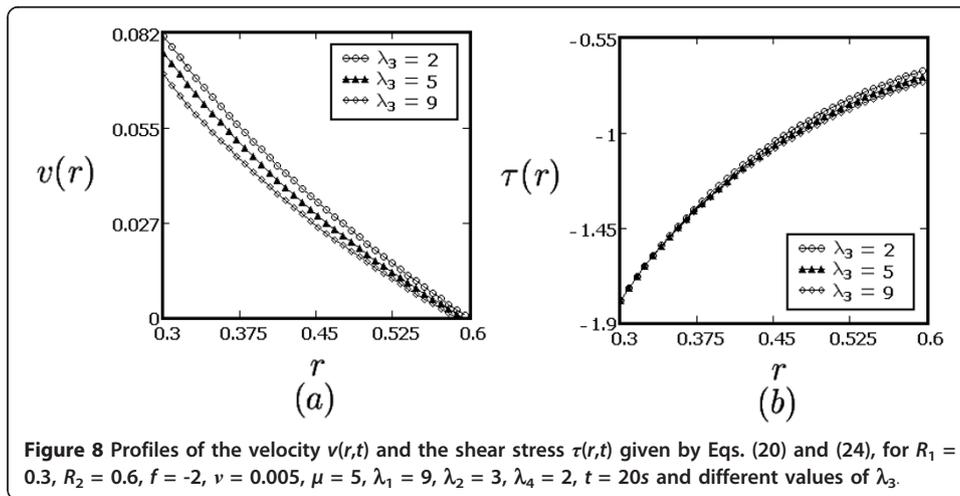
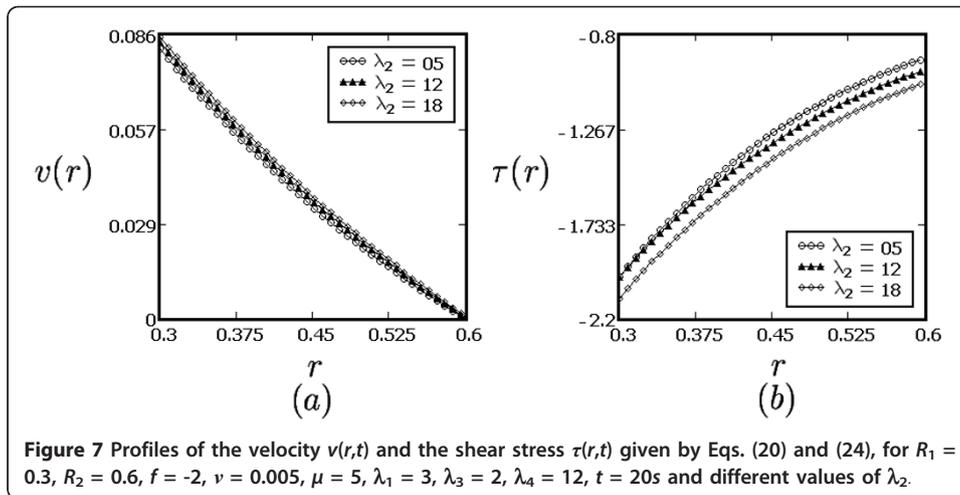


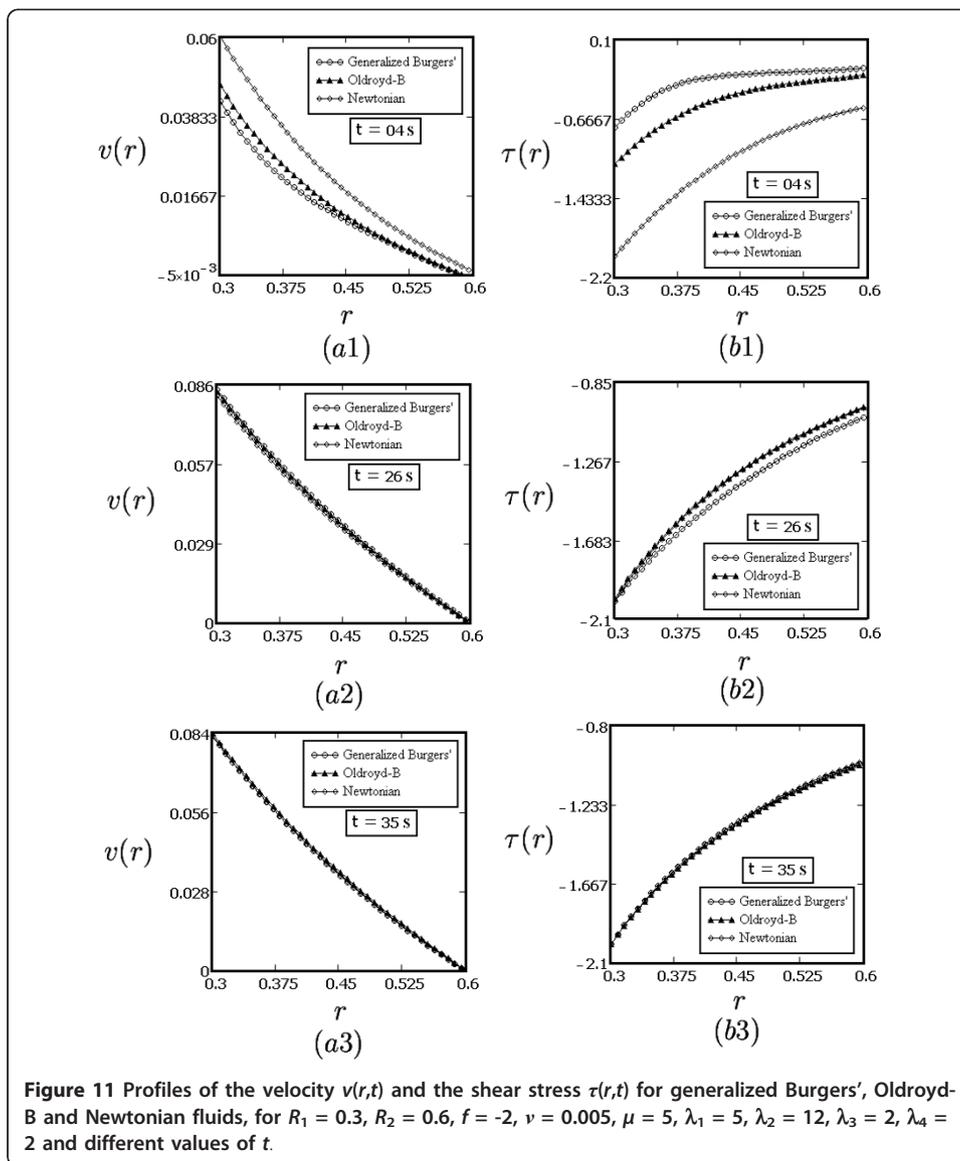
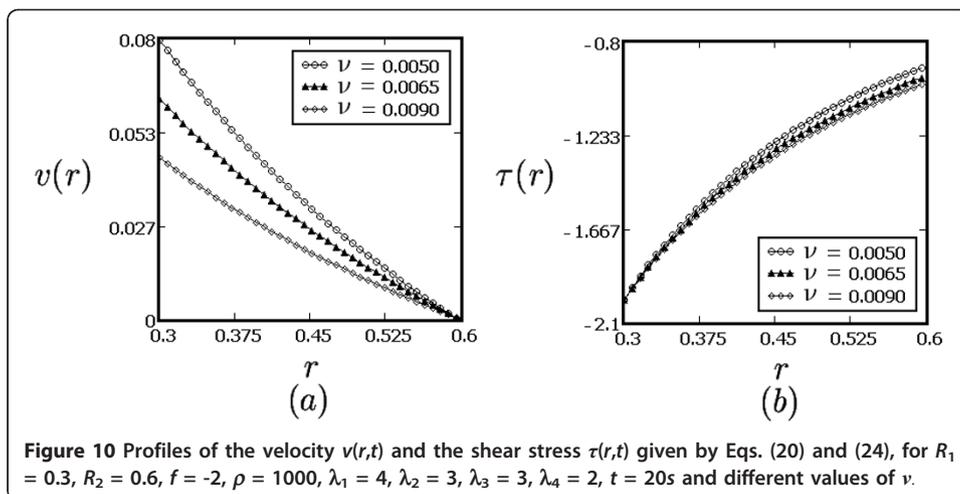
the boundary. However, this is not a surprise because, for large times, the boundary shear stress corresponding to rate type fluids, as it results from Eqs. (8) and (29), tends to the same constant f corresponding to Newtonian and second grade fluids.

From Figures 1 and 2 it also results that both the velocity and the shear stress (in absolute value) are increasing functions with respect to t . Moreover, they are decreasing functions with respect to r . Figures 6 and 7 are prepared to show the influence of the relaxation time λ_1 and the rheological parameter, λ_2 on the fluid motion. The two parameters, as expected, have opposite effects on the fluid motion. Both the velocity field and the shear stress (in absolute value) are decreasing functions with respect to relaxation time λ_1 and increasing ones with respect to λ_2 on the whole flow domain. Figures 8 and 9 are depicted to show the effects of retardation time λ_3 and rheological parameter λ_4 on the fluid motion. It is observed that greater the retardation time λ_3 , the more rapidly decay the velocity, however the shear stress is grown up faster. The influence of the rheological parameter λ_4 on the fluid motion is shown by Figure 9. Its effect is opposite to that of λ_3 . The influence of the kinematic viscosity ν on the fluid motion is shown in Figure 10. From these figures, we can see that the velocity decreases and the shear stress increases by increasing ν .

Finally, for comparison, the profiles of velocity and shear stress corresponding to the motion of the three types of fluids (Newtonian, Oldroyd-B and generalized Burgers) are together depicted in Figure 11 for different values of t and of common material parameters. The Newtonian fluid, as it results from Figure 11a1, is the swiftest and the generalized Burgers' fluid is the slowest on the whole flow domain. The shear stress corresponding to the Newtonian fluid in absolute value is also higher on the whole flow domain. Moreover, Figure 11-a2,b2,a3,b3 show that for large values of t , the velocity as well as the shear stress corresponding to generalized Burgers and Oldroyd-B fluids, as it was to be expected, are going to those belonging to a Newtonian fluid. Consequently, the non-Newtonian effects disappear in time. The units of the material constants are SI units in all figures and the roots r_n have been approximated by $(2n - 1)\pi/[2(R_2 - R_1)]$.







6 Concluding remarks

In this article, the velocity $v(r,t)$ and the shear stress $\tau(r,t)$ corresponding to the flow of an incompressible generalized Burgers' fluid, between two infinite coaxial circular cylinders, have been determined by means of Laplace and finite Hankel transforms. The motion of the fluid is produced by the inner cylinder that, after the initial moment, applies a time dependent longitudinal shear to the fluid. The solutions that have been obtained, written in series form in terms of Bessel functions $J_0(\bullet)$, $J_1(\bullet)$, $Y_0(\bullet)$, and $Y_1(\bullet)$, satisfy all imposed initial and boundary conditions. They can easily be reduced to the similar solutions for Burgers fluids. For large values of t , all solutions are going to the steady solutions $v_S(r)$ and $\tau_S(r)$, which are the same for all kinds of fluids. The following conclusions may be extracted from graphical results.

- The required time to reach the steady-state increases with respect to λ_1 and decreases with regard to λ_3 and v . Consequently, the required time to reach the steady state for Newtonian fluids is lower/higher in comparison with Maxwell, respectively, second grade fluids.
- For small values of λ_3 and λ_4 or λ_1 , λ_2 , λ_3 , and λ_4 the general solutions (20) and (24), as expected, are equivalent to those corresponding to Oldroyd-B, respectively, Newtonian fluids.
- The relaxation parameters λ_1 and λ_2 , as well as the retardation parameters λ_3 and λ_4 , have opposite effects on the fluid motion. More exactly, the velocity $v(r,t)$ and the shear stress $\tau(r,t)$ in absolute value are decreasing functions with respect to λ_1 and λ_3 and increasing ones with regard to λ_2 and λ_4 .
- It is observed that the increase of the kinematic viscosity v leads to a decay of velocity and grown up the shear stress.
- The Newtonian fluid is the swiftest and the generalized Burgers' fluid is the slowest.
- The non-Newtonian effects disappear in time.

Appendix

$$\begin{aligned}
 & \mathcal{L}^{-1} \left\{ \frac{\lambda_2 q^2 + (\lambda_1 + \lambda_4 v r_n^2) q + 1 + \lambda_3 v r_n^2}{\lambda_2 q^3 + (\lambda_1 + \lambda_4 v r_n^2) q^2 + (1 + \lambda_3 v r_n^2) q + v r_n^2} \right\} \\
 &= \frac{1}{\lambda_2} \mathcal{L}^{-1} \left\{ \frac{\lambda_2 q^2 + (\lambda_1 + \lambda_4 v r_n^2) q + 1 + \lambda_3 v r_n^2}{(q - q_{1n})(q - q_{2n})(q - q_{3n})} \right\} \\
 &= \frac{1}{\lambda_2} \mathcal{L}^{-1} \left\{ \frac{\lambda_2 q_{1n}^2 + (\lambda_1 + \lambda_4 v r_n^2) q_{1n} + 1 + \lambda_3 v r_n^2}{(q_{1n} - q_{2n})(q_{1n} - q_{3n})(q - q_{1n})} + \frac{\lambda_2 q_{2n}^2 + (\lambda_1 + \lambda_4 v r_n^2) q_{2n} + 1 + \lambda_3 v r_n^2}{(q_{2n} - q_{1n})(q_{2n} - q_{3n})(q - q_{2n})} \right. \\
 &\quad \left. + \frac{\lambda_2 q_{3n}^2 + (\lambda_1 + \lambda_4 v r_n^2) q_{3n} + 1 + \lambda_3 v r_n^2}{(q_{3n} - q_{1n})(q_{3n} - q_{2n})(q - q_{3n})} \right\} \\
 &= \frac{-v r_n^2}{\lambda_2} \left[\frac{e^{q_{1n} t}}{q_{1n}(q_{1n} - q_{2n})(q_{1n} - q_{3n})} + \frac{e^{q_{2n} t}}{q_{2n}(q_{2n} - q_{1n})(q_{2n} - q_{3n})} \right. \\
 &\quad \left. + \frac{e^{q_{3n} t}}{q_{3n}(q_{3n} - q_{1n})(q_{3n} - q_{2n})} \right],
 \end{aligned} \tag{A1}$$

$$\frac{d}{dr} B(r, r_n) = -r_n \tilde{B}(r, r_n), \tag{A2}$$

$$\begin{aligned}
 & \mathcal{L}^{-1} \left\{ \frac{1}{q(\lambda_2 q^2 + \lambda_1 q + 1)} \right\} \\
 &= \frac{1}{\lambda_2} \mathcal{L}^{-1} \left\{ \frac{1}{q(q-p_1)(q-p_2)} \right\} \\
 &= \frac{1}{\lambda_2} \mathcal{L}^{-1} \left\{ \frac{1}{p_1 p_2 q} + \frac{1}{p_1(p_1-p_2)(q-p_1)} + \frac{1}{p_2(p_2-p_1)(q-p_2)} \right\} \\
 &= 1 - \frac{p_2 e^{p_1 t} - p_1 e^{p_2 t}}{p_2 - p_1},
 \end{aligned} \tag{A3}$$

$$\begin{aligned}
 & \mathcal{L}^{-1} \left\{ \frac{1}{\lambda_2 q^3 + (\lambda_1 + \lambda_4 v r_n^2) q^2 + (1 + \lambda_3 v r_n^2) q + v r_n^2} \right\} \\
 &= \frac{1}{\lambda_2} \mathcal{L}^{-1} \left\{ \frac{1}{(q-q_{1n})(q-q_{2n})(q-q_{3n})} \right\} \\
 &= \frac{1}{\lambda_2} \mathcal{L}^{-1} \left\{ \frac{1}{(q_{1n}-q_{2n})(q_{1n}-q_{3n})(q-q_{1n})} + \frac{1}{(q_{2n}-q_{1n})(q_{2n}-q_{3n})(q-q_{2n})} \right. \\
 & \quad \left. + \frac{1}{(q_{3n}-q_{1n})(q_{3n}-q_{2n})(q-q_{3n})} \right\} \\
 &= \frac{1}{\lambda_2} \left\{ \frac{e^{q_{1n} t}}{(q_{1n}-q_{2n})(q_{1n}-q_{3n})} + \frac{e^{q_{2n} t}}{(q_{2n}-q_{1n})(q_{2n}-q_{3n})} \right. \\
 & \quad \left. + \frac{e^{q_{3n} t}}{(q_{3n}-q_{1n})(q_{3n}-q_{2n})} \right\},
 \end{aligned} \tag{A4}$$

$$\begin{aligned}
 & \mathcal{L}^{-1} \left\{ \frac{\lambda_1 q + 1 + \lambda_3 v r_n^2}{\lambda_1 q^2 + (1 + \lambda_3 v r_n^2) q + v r_n^2} \right\} \\
 &= \frac{1}{\lambda_1} \mathcal{L}^{-1} \left\{ \frac{\lambda_1 q + 1 + \lambda_3 v r_n^2}{(q-q_7)(q-q_8)} \right\} \\
 &= \frac{1}{\lambda_1} \mathcal{L}^{-1} \left\{ \frac{\lambda_1 q_{1n} + 1 + \lambda_3 v r_n^2}{(q_{7n}-q_{8n})(q-q_{7n})} + \frac{\lambda_1 q_2 + 1 + \lambda_3 v r_n^2}{(q_{8n}-q_{7n})(q-q_{8n})} \right\} \\
 &= \frac{q_{8n} e^{q_{7n} t} - q_{7n} e^{q_{8n} t}}{q_{8n} - q_{7n}},
 \end{aligned} \tag{A5}$$

$$\mathcal{L}^{-1} \left\{ \frac{1}{q(1 + \lambda_1 q)} \right\} = \mathcal{L}^{-1} \left\{ \frac{1}{q} - \frac{\lambda_1}{1 + \lambda_1 q} \right\} = 1 - e^{-\frac{t}{\lambda_1}}, \tag{A6}$$

$$\begin{aligned}
 & \mathcal{L}^{-1} \left\{ \frac{1}{\lambda_1 q^2 + (1 + \lambda_3 v r_n^2) q + v r_n^2} \right\} \\
 &= \frac{1}{\lambda_1} \mathcal{L}^{-1} \left\{ \frac{1}{(q-q_{7n})(q-q_{8n})} \right\} \\
 &= \frac{1}{\lambda_1} \mathcal{L}^{-1} \left\{ \frac{-1}{(q_{8n}-q_{7n})(q-q_{7n})} + \frac{1}{(q_{8n}-q_{7n})(q-q_{8n})} \right\} \\
 &= \frac{1}{\lambda_1} \frac{e^{q_{8n} t} - e^{q_{7n} t}}{q_{8n} - q_{7n}}.
 \end{aligned} \tag{A7}$$

Acknowledgements

The authors would like to express their sincere gratitude to the referees for their careful assessment and fruitful remarks and suggestions regarding the initial version of the manuscript. The author Muhammad Jamil highly thankful

and grateful to the Abdus Salam School of Mathematical Sciences, GC University, Lahore, Pakistan; Department of Mathematics, NED University of Engineering & Technology, Karachi-75270, Pakistan and also Higher Education Commission of Pakistan for generous supporting and facilitating this research study.

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Authors' contributions

Qualitatively, the authors' contribution for this paper is as follows: MJ (Muhammad Jamil) 60% and CF (Constantin Fetecau) 40%. Both authors participated in the design of the study and performed the statistical analysis. MJ has had a special contribution to get the simplest form of solutions. CF participated in the sequence alignment and drafted the manuscript. MJ prepared all graphical illustrations and CF participated at conclusions and discussion. Both authors read and approved the final manuscript.

Competing interests

The authors declare that they have no competing interests.

Received: 28 March 2011 Accepted: 10 February 2012 Published: 10 February 2012

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doi:10.1186/1687-2770-2012-14

Cite this article as: Jamil and Fetecau: Starting solutions for the motion of a generalized Burgers' fluid between coaxial cylinders. *Boundary Value Problems* 2012 **2012**:14.