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Positive solutions for a sixth-order boundary value problem with four parameters

Ravi P Agarwal^{1*}, B Kovacs² and D O'Regan³

*Correspondence:

Agarwal@tamuk.edu

¹Department of Mathematics, Texas

A&M University-Kingsville, 700

University Blvd., Kingsville,

78363-8202, USA

Full list of author information is available at the end of the article

Abstract

This paper investigates the existence and multiplicity of positive solutions of a sixth-order differential system with four variable parameters using a monotone iterative technique and an operator spectral theorem.

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1 Introduction

It is well known that boundary value problems for ordinary differential equations can be used to describe a large number of physical, biological and chemical phenomena. In recent years, boundary value problems for sixth-order ordinary differential equations, which arise naturally, for example, in sandwich beam deflection under transverse shear have been studied extensively, see [1–4] and the references therein. The deformation of the equilibrium state of an elastic circular ring segment with its two ends simply supported can be described by a boundary value problem involving a sixth-order ordinary differential equation

$$\begin{aligned}u^{(6)} + 2u^{(4)} + u'' &= f(t, u), \quad 0 < t < 1, \\u(0) = u(1) = u''(0) = u''(1) &= u^{(4)}(0) = u^{(4)}(1) = 0.\end{aligned}\tag{1}$$

Liu and Li [5] studied the existence and nonexistence of positive solutions of the nonlinear fourth-order beam equation

$$\begin{aligned}u^{(4)}(t) + \beta u''(t) - \alpha u(t) &= \lambda f(t, u(t)), \quad 0 < t < 1, \\u(0) = u(1) = u''(0) = u''(1) &= 0.\end{aligned}\tag{2}$$

They showed that there exists a $\lambda^* > 0$ such that the above boundary value problem has at least two, one, and no positive solutions for $0 < \lambda < \lambda^*$, $\lambda = \lambda^*$ and $\lambda > \lambda^*$, respectively.

In this paper, we discuss the existence of positive solutions for the sixth-order boundary value problem

$$\begin{aligned}-u^{(6)} + A(t)u^{(4)} + B(t)u'' + C(t)u &= (D(t) + u)\varphi + \lambda f(t, u), \quad 0 < t < 1, \\-\varphi'' + \kappa\varphi &= \mu u, \quad 0 < t < 1,\end{aligned}\tag{3}$$

$$u(0) = u(1) = u''(0) = u''(1) = u^{(4)}(0) = u^{(4)}(1) = 0,$$

$$\varphi(0) = \varphi(1) = 0.$$

For this, we shall assume the following conditions throughout

(H1) $f(t, u) : [0, 1] \times [0, \infty) \rightarrow [0, \infty)$ is continuous;

(H2) $a, b, c \in \mathbb{R}$, $a = \lambda_1 + \lambda_2 + \lambda_3 > -\pi^2$, $b = -\lambda_1\lambda_2 - \lambda_2\lambda_3 - \lambda_1\lambda_3 > 0$, $c = \lambda_1\lambda_2\lambda_3 < 0$

where $\lambda_1 \geq 0 \geq \lambda_2 \geq -\pi^2$, $0 \leq \lambda_3 < -\lambda_2$ and $\pi^6 + a\pi^4 - b\pi^2 + c > 0$, and

$A, B, C, D \in C[0, 1]$ with $a = \sup_{t \in [0, 1]} A(t)$, $b = \inf_{t \in [0, 1]} B(t)$ and $c = \sup_{t \in [0, 1]} C(t)$.

Let $K = \max_{0 \leq t \leq 1} [-A(t) + B(t) - C(t) - (-a + b - c)]$ and $\Gamma = \pi^6 + a\pi^4 - b\pi^2 + c$.

Assumption (H2) involves a three-parameter nonresonance condition.

More recently Li [6] studied the existence and multiplicity of positive solutions for a sixth-order boundary value problem with three variable coefficients. The main difference between our work and [6] is that we consider boundary value problem not only with three variable coefficients, but also with two positive parameters λ and μ , and the existence of the positive solution depends on these parameters. In this paper, we shall apply the monotone iterative technique [7] to boundary value problem (3) and then obtain several new existence and multiplicity results. In the special case, in [8] by using the fixed point theorem and the operator spectral theorem, we establish a theorem on the existence of positive solutions for the sixth-order boundary value problem (3) with $\lambda = 1$.

2 Preliminaries

Let $Y = C[0, 1]$ and $Y_+ = \{u \in Y : u(t) \geq 0, t \in [0, 1]\}$. It is well known that Y is a Banach space equipped with the norm $\|u\|_0 = \sup_{t \in [0, 1]} |u(t)|$. Set $X = \{u \in C^4[0, 1] : u(0) = u(1) = u''(0) = u''(1) = 0\}$. For given $\chi \geq 0$ and $\nu \geq 0$, we denote the norm $\|\cdot\|_{\chi, \nu}$ by

$$\|\cdot\|_{\chi, \nu} = \sup_{t \in [0, 1]} \{|u^{(4)}(t)| + \chi|u''(t)| + \nu|u(t)|\}, \quad u \in X.$$

We also need the space X , equipped with the norm

$$\|u\|_2 = \max\{\|u\|_0, \|u''\|_0, \|u^{(4)}\|_0\}.$$

In [8], it is shown that X is complete with the norm $\|\cdot\|_{\chi, \nu}$ and $\|u\|_2$, and moreover $\forall u \in X$, $\|u\|_0 \leq \|u''\|_0 \leq \|u^{(4)}\|_0$.

For $h \in Y$, consider the linear boundary value problem

$$\begin{aligned} -u^{(6)} + au^{(4)} + bu'' + cu &= h(t), \quad 0 < t < 1, \\ u(0) = u(1) = u''(0) = u''(1) = u^{(4)}(0) = u^{(4)}(1) &= 0, \end{aligned} \tag{4}$$

where a, b, c satisfy the assumption

$$\pi^6 + a\pi^4 - b\pi^2 + c > 0, \tag{5}$$

and let $\Gamma = \pi^6 + a\pi^4 - b\pi^2 + c$. Inequality (5) follows immediately from the fact that $\Gamma = \pi^6 + a\pi^4 - b\pi^2 + c$ is the first eigenvalue of the problem $-u^{(6)} + au^{(4)} + bu'' + cu = \lambda u$, $u(0) = u(1) = u''(0) = u''(1) = u^{(4)}(0) = u^{(4)}(1) = 0$, and $\phi_1(t) = \sin \pi t$ is the first eigenfunction, *i.e.*,

$\Gamma > 0$. Since the line $l_1 = \{(a, b, c) : \pi^6 + a\pi^4 - b\pi^2 + c = 0\}$ is the first eigenvalue line of the three-parameter boundary value problem $-u^{(6)} + au^{(4)} + bu'' + cu = 0, u(0) = u(1) = u''(0) = u''(1) = u^{(4)}(0) = u^{(4)}(1) = 0$, if (a, b, c) lies in l_1 , then by the Fredholm alternative, the existence of a solution of the boundary value problem (4) cannot be guaranteed.

Let $P(\lambda) = \lambda^2 + \beta\lambda - \alpha$, where $\beta < 2\pi^2, \alpha \geq 0$. It is easy to see that the equation $P(\lambda) = 0$ has two real roots $\lambda_1, \lambda_2 = \frac{-\beta \pm \sqrt{\beta^2 + 4\alpha}}{2}$ with $\lambda_1 \geq 0 \geq \lambda_2 > -\pi^2$. Let λ_3 be a number such that $0 \leq \lambda_3 < -\lambda_2$. In this case, (4) satisfies the decomposition form

$$-u^{(6)} + au^{(4)} + bu'' + cu = \left(-\frac{d^2}{dt^2} + \lambda_1\right)\left(-\frac{d^2}{dt^2} + \lambda_2\right)\left(-\frac{d^2}{dt^2} + \lambda_3\right)u, \quad 0 < t < 1. \quad (6)$$

Suppose that $G_i(t, s)$ ($i = 1, 2, 3$) is the Green's function associated with

$$-u'' + \lambda_i u = 0, \quad u(0) = u(1) = 0. \quad (7)$$

We need the following lemmas.

Lemma 1 [5, 9] *Let $\omega_i = \sqrt{|\lambda_i|}$, then $G_i(t, s)$ ($i = 1, 2, 3$) can be expressed as*

(i) *when $\lambda_i > 0$,*

$$G_i(t, s) = \begin{cases} \frac{\sinh \omega_i t \sinh \omega_i (1-s)}{\omega_i \sinh \omega_i}, & 0 \leq t \leq s \leq 1, \\ \frac{\sinh \omega_i s \sinh \omega_i (1-t)}{\omega_i \sinh \omega_i}, & 0 \leq s \leq t \leq 1 \end{cases};$$

(ii) *when $\lambda_i = 0$,*

$$G_i(t, s) = \begin{cases} t(1-s), & 0 \leq t \leq s \leq 1, \\ s(1-t), & 0 \leq s \leq t \leq 1 \end{cases};$$

(iii) *when $-\pi^2 < \lambda_i < 0$,*

$$G_i(t, s) = \begin{cases} \frac{\sin \omega_i t \sin \omega_i (1-s)}{\omega_i \sin \omega_i}, & 0 \leq t \leq s \leq 1, \\ \frac{\sin \omega_i s \sin \omega_i (1-t)}{\omega_i \sin \omega_i}, & 0 \leq s \leq t \leq 1 \end{cases}.$$

Lemma 2 [5] *$G_i(t, s)$ ($i = 1, 2, 3$) has the following properties*

(i) $G_i(t, s) > 0, \forall t, s \in (0, 1)$;

(ii) $G_i(t, s) \leq C_i G_i(s, s), \forall t, s \in [0, 1]$;

(iii) $G_i(t, s) \geq \delta_i G_i(t, t) G_i(s, s), \forall t, s \in [0, 1]$,

where $C_i = 1, \delta_i = \frac{\omega_i}{\sinh \omega_i}$, if $\lambda_i > 0$; $C_i = 1, \delta_i = 1$, if $\lambda_i = 0$; $C_i = \frac{1}{\sin \omega_i}, \delta_i = \omega_i \sin \omega_i$, if $-\pi^2 < \lambda_i < 0$.

In what follows, we let $D_i = \max_{t \in [0, 1]} \int_0^1 G_i(t, s) ds$.

Lemma 3 [10] *Let X be a Banach space, K a cone and Ω a bounded open subset of X . Let $\theta \in \Omega$ and $T : K \cap \bar{\Omega} \rightarrow K$ be condensing. Suppose that $Tx \neq \nu x$ for all $x \in K \cap \partial\Omega$ and $\nu \geq 1$. Then $i(T, K \cap \Omega, K) = 1$.*

Lemma 4 [10] *Let X be a Banach space, let K be a cone of X . Assume that $T : \bar{K}_r \rightarrow K$ (here $K_r = \{x \in K \mid \|x\| < r\}$, $r > 0$) is a compact map such that $Tx \neq x$ for all $x \in \partial K_r$. If $\|x\| \leq \|Tx\|$ for $x \in \partial K_r$, then $i(T, K_r, K) = 0$.*

Now, since

$$\begin{aligned} -u^{(6)} + au^{(4)} + bu'' + cu &= \left(-\frac{d^2}{dt^2} + \lambda_1\right) \left(-\frac{d^2}{dt^2} + \lambda_2\right) \left(-\frac{d^2}{dt^2} + \lambda_3\right) u \\ &= \left(-\frac{d^2}{dt^2} + \lambda_2\right) \left(-\frac{d^2}{dt^2} + \lambda_1\right) \left(-\frac{d^2}{dt^2} + \lambda_3\right) u = h(t), \end{aligned} \tag{8}$$

the solution of boundary value problem (4) can be expressed as

$$u(t) = \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, s) G_3(s, \tau) h(\tau) d\tau ds dv, \quad t \in [0, 1]. \tag{9}$$

Thus, for every given $h \in Y$, the boundary value problem (4) has a unique solution $u \in C^6[0, 1]$, which is given by (9).

We now define a mapping $T : C[0, 1] \rightarrow C[0, 1]$ by

$$(Th)(t) = \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, s) G_3(s, \tau) h(\tau) d\tau ds dv, \quad t \in [0, 1]. \tag{10}$$

Throughout this article, we shall denote $Th = u$ the unique solution of the linear boundary value problem (4).

Lemma 5 [8] *$T : Y \rightarrow (X, \|\cdot\|_{\chi, v})$ is linear completely continuous, where $\chi = \lambda_1 + \lambda_3$, $v = \lambda_1 \lambda_3$ and $\|T\| \leq D_2$. Moreover, $\forall h \in Y_+$, if $u = Th$, then $u \in X \cap Y_+$, and $u'' \leq 0$, $u^{(4)} \geq 0$.*

We list the following conditions for convenience

(H3) $f(t, u)$ is nondecreasing in u for $t \in [0, 1]$;

(H4) $f(t, 0) > \widehat{c} > 0$ for all $t \in [0, 1]$;

(H5) $f_\infty = \lim_{u \rightarrow \infty} \frac{f(t, u)}{u} = \infty$ uniformly for $t \in [0, 1]$;

(H6) $f(t, \rho u) \geq \rho^\alpha f(t, u)$ for $\rho \in (0, 1)$ and $t \in [0, 1]$, where $\alpha \in (0, 1)$ is independent of ρ and u .

Suppose that $G(t, s)$ is the Green's function of the linear boundary value problem

$$-u'' + \varkappa u = 0, \quad u(0) = u(1) = 0. \tag{11}$$

Then, the boundary value problem

$$-\varphi'' + \varkappa \varphi = \mu u, \quad \varphi(0) = \varphi(1) = 0,$$

can be solved by using Green's function, namely,

$$\varphi(t) = \mu \int_0^1 G(t, s) u(s) ds, \quad 0 < t < 1, \tag{12}$$

where $\varkappa > -\pi^2$. Thus, inserting (12) into the first equation in (3), yields

$$\begin{aligned}
 -u^{(6)} + A(t)u^{(4)} + B(t)u'' + C(t)u &= \mu(D(t) + u(t)) \int_0^1 G(t,s)u(s) ds + \lambda f(t, u), \\
 u(0) = u(1) = u''(0) = u''(1) = u^{(4)}(0) = u^{(4)}(1) &= 0.
 \end{aligned}
 \tag{13}$$

Let us consider the boundary value problem

$$\begin{aligned}
 -u^{(6)} + A(t)u^{(4)} + B(t)u'' + C(t)u &= h(t), \quad 0 < t < 1, \\
 u(0) = u(1) = u''(0) = u''(1) = u^{(4)}(0) = u^{(4)}(1) &= 0.
 \end{aligned}
 \tag{14}$$

Now, we consider the existence of a positive solution of (14). The function $u \in C^6(0, 1) \cap C^4[0, 1]$ is a positive solution of (14), if $u \geq 0$, $t \in [0, 1]$, and $u \neq 0$.

Let us rewrite equation (13) in the following form

$$\begin{aligned}
 -u^{(6)} + au^{(4)} + bu'' + cu &= -(A(t) - a)u^{(4)} - (B(t) - b)u'' - (C(t) - c)u \\
 &+ \mu(D(t) + u(t)) \int_0^1 G(t,s)u(s) ds + h(t).
 \end{aligned}
 \tag{15}$$

For any $u \in X$, let

$$Gu = -(A(t) - a)u^{(4)} - (B(t) - b)u'' - (C(t) - c)u + \mu D(t) \int_0^1 G(t,s)u(s) ds.$$

The operator $G : X \rightarrow Y$ is linear. By Lemmas 2 and 3 in [8], $\forall u \in X$, $t \in [0, 1]$, we have

$$\begin{aligned}
 |(Gu)(t)| &\leq [-A(t) + B(t) - C(t) - (-a + b - c)] \|u\|_2 + \mu Cd_1 \|u\|_0 \\
 &\leq (K + \mu Cd_1) \|u\|_2 \leq (K + \mu Cd_1) \|u\|_{\chi, \nu},
 \end{aligned}$$

where $C = \max_{t \in [0,1]} D(t)$, $K = \max_{t \in [0,1]} [-A(t) + B(t) - C(t) - (-a + b - c)]$, $d_1 = \max_{t \in [0,1]} \int_0^1 G(t,s) ds$, $\chi = \lambda_1 + \lambda_3 \geq 0$, $\nu = \lambda_1 \lambda_3 \geq 0$. Hence $\|Gu\|_0 \leq (K + \mu Cd_1) \|u\|_{\chi, \nu}$, and so $\|G\| \leq (K + \mu Cd_1)$. Also $u \in C^4[0, 1] \cap C^6(0, 1)$ is a solution of (13) if $u \in X$ satisfies $u = T(Gu + h_1)$, where $h_1(t) = \mu u(t) \int_0^1 G(t,s)u(s) ds + h(t)$, i.e.,

$$u \in X, \quad (I - TG)u = Th_1. \tag{16}$$

The operator $I - TG$ maps X into X . From $\|T\| \leq D_2$ together with $\|G\| \leq (K + \mu Cd_1)$ and the condition $D_2(K + \mu Cd_1) < 1$, and applying the operator spectral theorem, we find that $(I - TG)^{-1}$ exists and is bounded. Let $\mu \in (0, \frac{1 - D_2 K}{D_2 C d_1})$, where $1 - D_2 K > 0$, then the condition $D_2(K + \mu Cd_1) < 1$ is fulfilled. Let $L = D_2(K + \mu Cd_1)$, and let $\mu^{**} = \frac{1 - D_2 K}{D_2 C d_1}$.

Let $H = (I - TG)^{-1}T$. Then (16) is equivalent to $u = Hh_1$. By the Neumann expansion formula, H can be expressed by

$$H = (I + TG + \dots + (TG)^n + \dots)T = T + (TG)T + \dots + (TG)^n T + \dots. \tag{17}$$

The complete continuity of T with the continuity of $(I - TG)^{-1}$ guarantees that the operator $H : Y \rightarrow X$ is completely continuous.

Now $\forall h \in Y_+$, let $u = Th$, then $u \in X \cap Y_+$, and $u'' \leq 0$, $u^{(4)} \geq 0$. Thus, we have

$$(Gu)(t) = -(A(t) - a)u^{(4)} - (B(t) - b)u'' - (C(t) - c)u + \mu D(t) \int_0^1 G(t, s)u(s) ds \geq 0, \quad t \in [0, 1].$$

Hence

$$\forall h \in Y_+, \quad (GTh)(t) \geq 0, \quad t \in [0, 1], \tag{18}$$

and so, $(TG)(Th)(t) = T(GTh)(t) \geq 0$, $t \in [0, 1]$.

It is easy to see [11] that the following inequalities hold: $\forall h \in Y_+$,

$$\frac{1}{1-L}(Th)(t) \geq (Hh)(t) \geq (Th)(t), \quad t \in [0, 1], \tag{19}$$

and, moreover,

$$\|(Hh)\|_0 \leq \frac{1}{1-L} \|(Th)\|_0. \tag{20}$$

Lemma 6 [8] $H : Y \rightarrow (X, \|\cdot\|_{\chi, \nu})$ is completely continuous, where $\chi = \lambda_1 + \lambda_3$, $\nu = \lambda_1 \lambda_3$ and $\forall h \in Y_+$, $\frac{1}{1-L}(Th)(t) \geq (Hh)(t) \geq (Th)(t)$, $t \in [0, 1]$, and, moreover, $\|Th\|_0 \geq (1-L)\|Hh\|_0$.

For any $u \in Y_+$, define $Fu = \mu u(t) \int_0^1 G(t, s)u(s) ds + \lambda f(t, u)$. From (H1), we have that $F : Y_+ \rightarrow Y_+$ is continuous. It is easy to see that $u \in C^4[0, 1] \cap C^6(0, 1)$, being a positive solution of (13), is equivalent to $u \in Y_+$, being a nonzero solution of

$$u = HFu. \tag{21}$$

Let us introduce the following notations

$$\begin{aligned} T_{\lambda, \mu} u(t) &:= TFu(t) = \int_0^1 \int_0^1 \int_0^1 G_1(t, v)G_2(v, s)G_3(s, \tau) \\ &\quad \times \left(\mu u(\tau) \int_0^1 G(\tau, s)u(s) ds + \lambda f(\tau, u(\tau)) \right) d\tau ds dv, \\ Q_{\lambda, \mu} u &:= HFu = TFu + (TG)TFu + (TG)^2TFu + \dots + (TG)^nTFu + \dots \\ &= T_{\lambda, \mu} u + (TG)T_{\lambda, \mu} u + (TG)^2T_{\lambda, \mu} u + \dots + (TG)^nT_{\lambda, \mu} u + \dots, \end{aligned}$$

i.e., $Q_{\lambda, \mu} u = HFu$. Obviously, $Q_{\lambda, \mu} : Y_+ \rightarrow Y_+$ is completely continuous. We next show that the operator $Q_{\lambda, \mu}$ has a nonzero fixed point in Y_+ .

Let $P = \{u \in Y_+ : u(t) \geq \delta_1(1-L)g_1(t)\|u\|_0, t \in [\frac{1}{4}, \frac{3}{4}]\}$, where $g_1(t) = \frac{1}{C_1}G_1(t, t)$. It is easy to see that P is a cone in Y , and now, we show $Q_{\lambda, \mu}(P) \subset P$.

Lemma 7 $Q_{\lambda, \mu}(P) \subset P$ and $Q_{\lambda, \mu} : P \rightarrow P$ is completely continuous.

Proof It is clear that $Q_{\lambda,\mu} : P \rightarrow P$ is completely continuous. Now $\forall u \in P$, let $h_1 = Fu$, then $h_1 \in Y_+$. Using Lemma 6, i.e., $(Q_{\lambda,\mu}u)(t) = (HFu)(t) \geq (TFu)(t)$, $t \in [0, 1]$ and by Lemma 2, for all $u \in P$, we have

$$(TFu)(t) \leq C_1 \int_0^1 \int_0^1 \int_0^1 G_1(v, v)G_2(v, s)G_3(s, \tau)(Fu)(\tau) d\tau ds dv, \quad \forall t \in [0, 1].$$

Thus,

$$\int_0^1 \int_0^1 \int_0^1 G_1(v, v)G_2(v, s)G_3(s, \tau)(Fu)(\tau) d\tau ds dv \geq \frac{1}{C_1} \|TFu\|_0. \tag{22}$$

On the other hand, by Lemma 6 and (22), we have

$$\begin{aligned} (TFu)(t) &\geq \delta_1 G_1(t, t) \int_0^1 \int_0^1 \int_0^1 G_1(v, v)G_2(v, s)G_3(s, \tau)(Fu)(\tau) d\tau ds dv \\ &\geq \delta_1 G_1(t, t) \frac{1}{C_1} \|TFu\|_0 \geq \delta_1 G_1(t, t) \frac{1}{C_1} (1-L) \|Qu\|_0, \quad \forall t \in [0, 1]. \end{aligned}$$

Thus, $Q_{\lambda,\mu}(P) \subset P$. □

3 Main results

Lemma 8 *Let $f(t, u)$ be nondecreasing in u for $t \in [0, 1]$ and $f(t, 0) > \widehat{c} > 0$ for all $t \in [0, 1]$, where \widehat{c} is a constant and $L < 1$. Then there exists $\lambda^* > 0$ and $\mu^* > 0$ such that the operator $Q_{\lambda,\mu}$ has a fixed point u^* at (λ^*, μ^*) with $u^* \in P \setminus \{\theta\}$.*

Proof Set $\widehat{u}_1(t) = (Q_{\lambda^*, \mu^*} u_*)(t)$, where

$$u_*(t) = \frac{2}{1-L} \int_0^1 \int_0^1 \int_0^1 G_1(t, v)G_2(v, \tau)G_3(\tau, s) ds d\tau dv.$$

It is easy to see that $u_*(t) \in P$. Let $\lambda^* = M_{fu}^{-1}$ and $\mu^* = \min(N_{fu}^{-1}; \mu^{**})$, where $M_{fu} = \max_{t \in [0, 1]} f(t, u_*(t))$ and $N_{fu} = \max_{t \in [0, 1]} u_*(t) \int_0^1 G(t, s)u_*(s) ds$, respectively. Then $M_{fu} > 0$ and $N_{fu} > 0$, and from Lemma 6, we obtain

$$\begin{aligned} \widehat{u}_0(t) = u_*(t) &= \frac{2}{1-L} \int_0^1 \int_0^1 \int_0^1 G_1(t, v)G_2(v, \tau)G_3(\tau, s) ds d\tau dv \\ &\geq \frac{1}{1-L} \int_0^1 \int_0^1 \int_0^1 G_1(t, v)G_2(v, \tau)G_3(\tau, s) \\ &\quad \times \left(\lambda^* f(s, u_*(s)) + \mu^* u_*(t) \int_0^1 G(t, s)u_*(s) ds \right) ds d\tau dv \\ &= \frac{1}{1-L} (T_{\lambda^*, \mu^*} u_*)(t) \geq (Q_{\lambda^*, \mu^*} u_*)(t) = \widehat{u}_1(t). \end{aligned}$$

It is easy to see that

$$\begin{aligned} \widehat{u}_n(t) &= (Q_{\lambda^*, \mu^*} \widehat{u}_{n-1})(t) \\ &= (T_{\lambda^*, \mu^*} \widehat{u}_{n-1} + (TG)T_{\lambda^*, \mu^*} \widehat{u}_{n-1} + (TG)^2 T_{\lambda^*, \mu^*} \widehat{u}_{n-1} + \dots \end{aligned}$$

$$\begin{aligned}
 &+ (TG)^n T_{\lambda, \mu} * \widehat{u}_{n-1} + \dots) \\
 \geq &(T_{\lambda, \mu} * \widehat{u}_{n-2} + (TG)T_{\lambda, \mu} * \widehat{u}_{n-2} + (TG)^2 T_{\lambda, \mu} * \widehat{u}_{n-2} + \dots \\
 &+ (TG)^n T_{\lambda, \mu} * \widehat{u}_{n-2} + \dots) = \widehat{u}_{n-1}(t).
 \end{aligned}$$

Indeed, for $h_1, h_2 \in Y_+$, let $h_1(t) \geq h_2(t)$, then from (10), we have $u_1(t) = Th_1 \geq Th_2 = u_2(t)$. Using equation (4) and (6), we obtain

$$-u'' + \lambda_2 u = \int_0^1 \int_0^1 G_1(t, v) G_3(v, \tau) h(\tau) d\tau dv, \quad t \in [0, 1] \tag{23}$$

and

$$u_1^{(4)} - (\lambda_2 + \lambda_3)u'' + \lambda_2 \lambda_3 u = \int_0^1 G_1(t, v) h(v) dv, \quad t \in [0, 1]. \tag{24}$$

Then by (23), we have for $t \in [0, 1]$

$$u_1''(t) - u_2''(t) = \lambda_2(u_1(t) - u_2(t)) - \int_0^1 \int_0^1 G_1(t, v) G_3(v, \tau) (h_1(t) - h_2(t)) d\tau dv \leq 0,$$

because $\lambda_2 < 0$, and finally, from (24), we have

$$\begin{aligned}
 u_1^{(4)}(t) - u_2^{(4)}(t) &= (\lambda_2 + \lambda_3)(u_1''(t) - u_2''(t)) - \lambda_2 \lambda_3 (u_1(t) - u_2(t)) \\
 &+ \int_0^1 \int_0^1 G_1(t, v) (h_1(t) - h_2(t)) d\tau dv \geq 0, \quad t \in [0, 1]
 \end{aligned}$$

because $\lambda_2 + \lambda_3 \leq 0$ and $\lambda_2 \lambda_3 \leq 0$. From the equation

$$\begin{aligned}
 (Gu)(t) &= -(A(t) - a)u^{(4)} - (B(t) - b)u'' - (C(t) - c)u + \mu D(t) \int_0^1 G(t, s)u(s) ds \geq 0, \\
 t &\in [0, 1]
 \end{aligned}$$

we have

$$\begin{aligned}
 &(Gu_1)(t) - (Gu_2)(t) \\
 &= -(A(t) - a)(u_1^{(4)}(t) - u_2^{(4)}(t)) - (B(t) - b)(u_1''(t) - u_2''(t)) \\
 &- (C(t) - c)(u_1(t) - u_2(t)) + \mu D(t) \int_0^1 G(t, s)(u_1(s) - u_2(s)) ds \geq 0, \\
 &t \in [0, 1]
 \end{aligned} \tag{25}$$

i.e., $(Gu_1)(t) \geq (Gu_2)(t)$ for all $t \in [0, 1]$. Finally, if $h_1 = Fu_1$ and $h_2 = Fu_2$, then

$$\begin{aligned}
 (Hh_1)(t) &= T(h_1) + (TG)(Th_1) + (TG)^2(Th_1) + \dots + (TG)^n(Th_1) + \dots \\
 &\geq (Hh_2)(t) = T(h_2) + (TG)(Th_2) + (TG)^2(Th_2) + \dots + (TG)^n(Th_2) + \dots
 \end{aligned}$$

i.e.,

$$\begin{aligned}
 Q_{\lambda^*, \mu^*} u_1 &= (HFu_1)(t) = T(Fu_1) + (TG)(TFu_1) + (TG)^2(TFu_1) + \dots + (TG)^n(TFu_1) + \dots \\
 &\geq (HFu_2)(t) = T(Fu_2) + (TG)(TFu_2) + (TG)^2(TFu_2) + \dots + (TG)^n(TFu_2) + \dots \\
 &= Q_{\lambda^*, \mu^*} u_2,
 \end{aligned} \tag{26}$$

and from (26), it follows that for $u_1, u_2 \in Y_+$, if $u_1(t) \geq u_2(t)$ then, we have

$$Q_{\lambda^*, \mu^*} u_1 \geq Q_{\lambda^*, \mu^*} u_2. \tag{27}$$

Set $\widehat{u}_0(t) = u_*(t)$ and $\widehat{u}_n(t) = (Q_{\lambda^*, \mu^*} \widehat{u}_{n-1})(t)$, $n = 1, 2, \dots, t \in [0, 1]$. Then

$$\widehat{u}_0(t) = u_*(t) \geq \widehat{u}_1(t) \geq \dots \geq \widehat{u}_n(t) \geq \dots \geq L_1 G_1(t, t),$$

where

$$L_1 = \lambda^* \delta_1 \delta_2 \delta_3 \widehat{c} C_{23} C_{12} C_3. \quad \square$$

Indeed, by Lemma 6, we have

$$\begin{aligned}
 \widehat{u}_n(t) &= Q_{\lambda^*, \mu^*} \widehat{u}_{n-1} = (HF)(\widehat{u}_{n-1}) \geq (TF)(\widehat{u}_{n-1}) \\
 &\geq \lambda^* \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, \widehat{u}_{n-1}(s)) ds d\tau d\nu \\
 &\geq \lambda^* \widehat{c} \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) ds d\tau d\nu \\
 &\geq \lambda^* \widehat{c} \delta_1 \delta_2 \delta_3 C_{12} C_{23} C_3 G_1(t, t).
 \end{aligned}$$

Now, $f(t, u)$ nondecreasing in u for $t \in [0, 1]$, Lemma 2, and the Lebesgue convergence theorem guarantee that $\{u_n\}_{n=0}^\infty = \{Q_{\lambda^*, \mu^*} \widehat{u}_0\}_{n=0}^\infty$ decreases to a fixed point $u^* \in P \setminus \{\theta\}$ of the operator Q_{λ^*, μ^*} .

Lemma 9 Suppose that (H3)-(H5) hold, and $L < 1$. Set

$$S_{\lambda, \mu} = \{u \in P : Q_{\lambda, \mu} u = u, (\lambda, \mu) \in A\},$$

where $A \subset [a, \infty) \times [b, \infty)$ for some constants $a > 0, b > 0$. Then there exists a constant C_A such that $\|u\|_0 < C_A$ for all $u \in S_{\lambda, \mu}$.

Proof Suppose, to the contrary, that there exists a sequence $\{u_n\}_{n=1}^\infty$ such that $\lim_{n \rightarrow \infty} \|u_n\|_0 = +\infty$, where $u_n \in P$ is a fixed point of the operator $Q_{\lambda, \mu}$ at $(\lambda_n, \mu_n) \in A$ ($n = 1, 2, \dots$). Then

$$u_n(t) \geq k \|u_n\|_0 \quad \text{for } t \in \left[\frac{1}{4}, \frac{3}{4} \right],$$

where $k = \frac{\delta_1}{C_1} (1 - L) \min_{t \in [\frac{1}{4}, \frac{3}{4}]} G_1(t, t)$.

Choose $J_1 > 0$, so that

$$J_1 a \delta_1 \delta_2 \delta_3 C_{12} C_{23} m_1 m_2 k > 2,$$

and $l_1 > 0$ such that

$$f(t, u) \geq J_1 u \quad \text{for } u > l_1 \text{ and } t \in \left[\frac{1}{4}, \frac{3}{4} \right],$$

and N_0 , so that $\|u_{N_0}\| > \frac{l_1}{k}$. Now,

$$\begin{aligned} (Q_{\lambda_{N_0}, \mu_{N_0}} u_{N_0})\left(\frac{1}{2}\right) &\geq (TFu_{N_0})\left(\frac{1}{2}\right) \\ &\geq \lambda_{N_0} \int_0^1 \int_0^1 \int_0^1 G_1\left(\frac{1}{2}, \nu\right) G_2(\nu, \tau) G_3(\tau, s) f(s, u_{N_0}(s)) \, ds \, d\tau \, d\nu \\ &\geq \lambda_{N_0} \delta_1 \delta_2 \delta_3 C_{12} C_{23} G_1\left(\frac{1}{2}, \frac{1}{2}\right) \int_0^1 G_3(s, s) f(s, u_{N_0}(s)) \, ds \\ &\geq \lambda_{N_0} \delta_1 \delta_2 \delta_3 C_{12} C_{23} G_1\left(\frac{1}{2}, \frac{1}{2}\right) \int_{\frac{1}{4}}^{\frac{3}{4}} G_3(s, s) f(s, u_{N_0}(s)) \, ds \\ &\geq \frac{1}{2} a \delta_1 \delta_2 \delta_3 C_{12} C_{23} m_1 m_2 J_1 u_{N_0}(t) \\ &\geq \frac{1}{2} a \delta_1 \delta_2 \delta_3 C_{12} C_{23} m_1 m_2 J_1 k \|u_{N_0}\|_0 > \|u_{N_0}\|_0, \end{aligned}$$

and so,

$$\|u_{N_0}\|_0 = \|Q_{\lambda_{N_0}, \mu_{N_0}} u_{N_0}\|_0 \geq \|(TF)u_{N_0}\|_0 \geq (TFu_{N_0})\left(\frac{1}{2}\right) > \|u_{N_0}\|_0,$$

which is a contradiction. □

Lemma 10 *Suppose that $L < 1$, (H3) and (H4) hold and that the operator $Q_{\lambda, \mu}$ has a positive fixed point in P at $\widehat{\lambda} > 0$ and $\widehat{\mu} > 0$. Then for every $(\lambda_*, \mu_*) \in (0, \widehat{\lambda}) \times (0, \widehat{\mu})$ there exists a function $u_* \in P \setminus \{\theta\}$ such that $Q_{\lambda_*, \mu_*} u_* = u_*$.*

Proof Let $\widehat{u}(t)$ be a fixed point of the operator $Q_{\lambda, \mu}$ at $(\widehat{\lambda}, \widehat{\mu})$. Then

$$\widehat{u}(t) = Q_{\widehat{\lambda}, \widehat{\mu}} \widehat{u}(t) \geq Q_{\lambda_*, \mu_*} \widehat{u}(t),$$

where $0 < \lambda_* < \widehat{\lambda}$, $0 < \mu_* < \widehat{\mu}$. Hence

$$\begin{aligned} &\int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) \left(\widehat{\lambda} f(s, \widehat{u}(s)) + \widehat{\mu} \widehat{u}(s) \int_0^1 G(s, p) \widehat{u}(p) \, dp \right) \, ds \, d\tau \, d\nu \\ &\geq \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) \\ &\quad \times \left(\lambda_* f(s, \widehat{u}(s)) + \mu_* \widehat{u}(s) \int_0^1 G(s, p) \widehat{u}(p) \, dp \right) \, ds \, d\tau \, d\nu. \end{aligned}$$

Set

$$(T_{\lambda_*, \mu_*} u)(t) = \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) \\
 \times \left(\lambda_* f(s, u(s)) + \mu_* u(s) \int_0^1 G(s, p) u(p) dp \right) ds d\tau dv$$

and

$$(Q_{\lambda_*, \mu_*} u)(t) = T_{\lambda_*, \mu_*} u + (TG)T_{\lambda_*, \mu_*} u + (TG)^2 T_{\lambda_*, \mu_*} u + \dots + (TG)^n T_{\lambda_*, \mu_*} u + \dots$$

$u_0(t) = \widehat{u}(t)$ and $u_n(t) = Q_{\lambda_*, \mu_*} u_{n-1}$. Then

$$u_0(t) = \widehat{u}(t) = T_{\widehat{\lambda}, \widehat{\mu}} \widehat{u} + (TG)T_{\widehat{\lambda}, \widehat{\mu}} \widehat{u} + (TG)^2 T_{\widehat{\lambda}, \widehat{\mu}} \widehat{u} + \dots + (TG)^n T_{\widehat{\lambda}, \widehat{\mu}} \widehat{u} + \dots \\
 \geq T_{\lambda_*, \mu_*} \widehat{u} + (TG)T_{\lambda_*, \mu_*} \widehat{u} + (TG)^2 T_{\lambda_*, \mu_*} \widehat{u} + \dots + (TG)^n T_{\lambda_*, \mu_*} \widehat{u} + \dots = u_1(t)$$

and

$$u_n(t) = Q_{\lambda_*, \mu_*} u_{n-1} = T_{\lambda_*, \mu_*} u_{n-1} + (TG)T_{\lambda_*, \mu_*} u_{n-1} + (TG)^2 T_{\lambda_*, \mu_*} u_{n-1} + \dots \\
 + (TG)^n T_{\lambda_*, \mu_*} u_{n-1} + \dots \\
 \geq T_{\lambda_*, \mu_*} u_{n-2} + (TG)T_{\lambda_*, \mu_*} u_{n-2} + (TG)^2 T_{\lambda_*, \mu_*} u_{n-2} + \dots \\
 + (TG)^n T_{\lambda_*, \mu_*} u_{n-2} + \dots = u_{n-1}(t)$$

because $f(t, u)$ is nondecreasing in u for $t \in [0, 1]$ and $T_{\lambda_*, \mu_*} u$ is also nondecreasing in u . Thus

$$u_0(t) \geq u_1(t) \geq \dots \geq u_n(t) \geq u_{n+1}(t) \geq \dots \geq L_2 G_1(t, t), \tag{28}$$

where

$$L_2 = \lambda_* \widehat{c} \delta_1 \delta_2 \delta_3 C_{12} C_{23} C_3. \quad \square$$

Indeed, by Lemma 6, we have

$$u_n(t) = Q_{\lambda_*, \mu_*} u_{n-1} = (HF)(u_{n-1}) \geq T_{\lambda_*, \mu_*} (u_{n-1}) \\
 \geq \lambda_* \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) f(s, u_{n-1}(s)) ds d\tau dv \\
 \geq \lambda_* \widehat{c} \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) ds d\tau dv \geq \lambda_* \widehat{c} \delta_1 \delta_2 \delta_3 C_{12} C_{23} C_3 G_1(t, t).$$

Lemma 2 implies that $\{Q_{\lambda_*}^n u\}_{n=1}^\infty$ decreases to a fixed point $u_* \in P \setminus \{\theta\}$.

Lemma 11 *Suppose that $L < 1$, (H3)-(H5) hold. Let*

$$\Lambda = \{ \lambda > 0, \mu > 0 : Q_{\lambda, \mu} \text{ have at least one fixed point at } (\lambda, \mu) \text{ in } P \}.$$

Then Λ is bounded.

Proof Suppose, to the contrary, that there exists a fixed point sequence $\{u_n\}_{n=0}^\infty \subset P$ of $Q_{\lambda,\mu}$ at (λ_n, μ_n) such that $\lim_{n \rightarrow \infty} \lambda_n = \infty$ and $0 < \mu_n < \mu^{**}$. Then there are two cases to be considered: (i) there exists a subsequence $\{u_{n_i}\}_{n_i=0}^\infty$ such that $\lim_{i \rightarrow \infty} \|u_{n_i}\|_0 = \infty$, which is impossible by Lemma 9, so we only consider the next case: (ii) there exists a constant $H > 0$ such that $\|u_n\|_0 \leq H, n = 0, 1, 2, 3, \dots$. In view of (H3) and (H4), we can choose $l_0 > 0$ such that $f(t, 0) > l_0 H$, and further, $f(t, u_n) > l_0 H$ for $t \in [0, 1]$. We know that

$$u_n = Q_{\lambda_n, \mu_n} u_n \geq T_{\lambda_n, \mu_n} u_n.$$

Let $v_n(t) = T_{\lambda_n, \mu_n} u_n$, i.e., $u_n(t) \geq v_n(t)$. Then it follows that

$$-v_n^{(6)} + av_n^{(4)} + bv_n'' + cv_n = \lambda_n f(t, u_n) + \mu_n u_n(t) \int_0^1 G(t, p) u_n(p) dp, \quad 0 < t < 1. \quad (29)$$

Multiplying (29) by $\sin \pi t$ and integrating over $[0, 1]$, and then using integration by parts on the left side of (29), we have

$$\Gamma \int_0^1 v_n(t) \sin \pi t dt = \lambda_n \int_0^1 f(t, u_n) \sin \pi t dt + \mu_n \int_0^1 u_n(t) \sin \pi t \int_0^1 G(t, p) u_n(p) dp dt.$$

Next, assume that (ii) holds. Then

$$\begin{aligned} \Gamma \int_0^1 u_n(t) \sin \pi t dt &\geq \Gamma \int_0^1 v_n(t) \sin \pi t dt \\ &= \lambda_n \int_0^1 f(t, u_n) \sin \pi t dt + \mu_n \int_0^1 u_n(t) \sin \pi t \int_0^1 G(t, p) u_n(p) dp dt \end{aligned}$$

and

$$\begin{aligned} \Gamma H \int_0^1 \sin \pi t dt &\geq \Gamma \|u_n\|_0 \int_0^1 \sin \pi t dt \geq \Gamma \int_0^1 u_n(t) \sin \pi t dt \geq \Gamma \int_0^1 v_n(t) \sin \pi t dt \\ &= \lambda_n \int_0^1 f(t, u_n) \sin \pi t dt + \mu_n \int_0^1 u_n(t) \sin \pi t \int_0^1 G(t, p) u_n(p) dp dt \\ &\geq \lambda_n l_0 H \int_0^1 \sin \pi t dt \end{aligned}$$

lead to $\Gamma \geq \lambda_n l_0$, which is a contradiction. The proof is complete. \square

Lemma 12 *Suppose that $L < 1$, (H3)-(H4) hold. Let*

$$\Lambda_\mu = \{ \lambda > 0 : (\lambda, \mu) \in \Lambda \text{ and } \mu \text{ is fixed} \},$$

and let $\tilde{\lambda}_\mu = \sup \Lambda_\mu$. Then $\Lambda_\mu = (0, \tilde{\lambda}_\mu]$, where Λ is defined in Lemma 11.

Proof By Lemma 10, it follows that $(0, \tilde{\lambda}) \times (0, \mu) \subset \Lambda$. We only need to prove $(\tilde{\lambda}_\mu, \mu) \in \Lambda$. We may choose a distinct nondecreasing sequence $\{\lambda_n\}_{n=1}^\infty \subset \Lambda$ such that $\lim_{n \rightarrow \infty} \lambda_n = \tilde{\lambda}_\mu$. Set $u_n \in P$ as a fixed point of $Q_{\lambda_n, \mu}$ at (λ_n, μ) , $n = 1, 2, \dots$, i.e., $u_n = Q_{\lambda_n, \mu} u_n$. By Lemma 9,

$\{u_n\}_{n=1}^\infty$ is uniformly bounded, so it has a subsequence, denoted by $\{u_{n_k}\}_{k=1}^\infty$, converging to $\tilde{u} \in P$. Note that

$$\begin{aligned} u_n &= T_{\lambda_n, \mu} u_n + (TG)T_{\lambda_n, \mu} u_n + (TG)^2 T_{\lambda_n, \mu} u_n + \dots + (TG)^n T_{\lambda_n, \mu} u_n + \dots \\ &= Q_{\lambda_n, \mu} u_n. \end{aligned} \tag{30}$$

Taking the limit as $n \rightarrow \infty$ on both sides of (30), and using the Lebesgue convergence theorem, we have

$$\tilde{u} = T_{\tilde{\lambda}, \mu} \tilde{u} + (TG)T_{\tilde{\lambda}, \mu} \tilde{u} + (TG)^2 T_{\tilde{\lambda}, \mu} \tilde{u} + \dots + (TG)^n T_{\tilde{\lambda}, \mu} \tilde{u} + \dots$$

which shows that $Q_{\tilde{\lambda}, \mu}$ has a positive fixed point \tilde{u} at $(\tilde{\lambda}, \mu)$. □

Theorem 1 *Suppose that (H3)-(H5) hold, and $L < 1$. For fixed $\mu^* \in (0, \mu^{**})$, then there exists at $\lambda^* > 0$ such that (3) has at least two, one and has no positive solutions for $0 < \lambda < \lambda^*$, $\lambda = \lambda^*$ for $\lambda > \lambda^*$, respectively.*

Proof Suppose that (H3) and (H4) hold. Then there exists $\lambda^* > 0$ and $\mu^* > 0$ such that $Q_{\lambda, \mu}$ has a fixed point $u_{\lambda^*, \mu^*} \in P \setminus \{\theta\}$ at $\lambda = \lambda^*$ and $\mu = \mu^*$. In view of Lemma 12, $Q_{\lambda, \mu}$ also has a fixed point $u_{\underline{\lambda}, \underline{\mu}} < u_{\lambda^*, \mu^*}$, $u_{\underline{\lambda}, \underline{\mu}} \in P \setminus \{\theta\}$, and $0 < \underline{\lambda} < \lambda^*$, $0 < \underline{\mu} < \mu^*$, $\mu^* \in (0, \mu^{**})$. For $0 < \underline{\lambda} < \lambda^*$, there exists $\delta_0 > 0$ such that

$$f(t, u_{\lambda^*, \mu^*} + \delta) - f(t, u_{\lambda^*, \mu^*}) \leq f(t, 0) \left(\frac{\lambda^*}{\underline{\lambda}} - 1 \right)$$

for $t \in [0, 1]$, $0 < \delta \leq \delta_0$. In this case, it is easy to see that

$$\begin{aligned} T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) &= \underline{\lambda} \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) f(s, u_{\lambda^*, \mu^*}(s) + \delta) ds d\tau dv \\ &\quad + \underline{\mu} \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) (u_{\lambda^*, \mu^*}(s) + \delta) \\ &\quad \times \int_0^1 G(s, p) (u_{\lambda^*, \mu^*}(p) + \delta) dp ds d\tau dv \\ &\leq \lambda^* \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) f(s, u_{\lambda^*}(s)) ds d\tau dv \\ &\quad + \mu^* \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) u_{\lambda^*, \mu^*}(s) \\ &\quad \times \int_0^1 G(s, p) u_{\lambda^*, \mu^*}(p) dp ds d\tau dv = T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*}. \end{aligned}$$

Indeed, we have

$$\begin{aligned} &\underline{\lambda} \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) f(s, u_{\lambda^*}(s) + \delta) ds d\tau dv \\ &\quad - \lambda^* \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) f(s, u_{\lambda^*}(s)) ds d\tau dv \end{aligned}$$

$$\begin{aligned}
 &= \underline{\lambda} \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) \{f(s, u_{\lambda^*}(s) + \delta) - f(s, u_{\lambda^*}(s))\} ds d\tau d\nu \\
 &\quad - (\lambda^* - \underline{\lambda}) \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, u_{\lambda^*}(s)) ds d\tau d\nu \\
 &\leq (\lambda^* - \underline{\lambda}) \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, 0) ds d\tau d\nu \\
 &\quad - (\lambda^* - \underline{\lambda}) \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, u_{\lambda^*}(s)) ds d\tau d\nu \\
 &= (\lambda^* - \underline{\lambda}) \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) \{f(s, 0) - f(s, u_{\lambda^*}(s))\} ds d\tau d\nu \leq 0.
 \end{aligned}$$

Similarly, it is easy to see that

$$\begin{aligned}
 &\underline{\mu} \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) (u_{\lambda^*, \mu^*}(s) + \delta) \int_0^1 G(s, p) (u_{\lambda^*, \mu^*}(p) + \delta) dp ds d\tau d\nu \\
 &\quad - \mu^* \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) u_{\lambda^*, \mu^*}(s) \int_0^1 G(s, p) u_{\lambda^*, \mu^*}(p) dp ds d\tau d\nu \leq 0.
 \end{aligned}$$

Moreover, from (25), it follows that for $T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) \leq T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*}$ we have

$$G(T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta)) \leq G(T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*}).$$

Finally, we have

$$(TG)T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) \leq (TG)T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*}.$$

By induction, it is easy to see that

$$(TG)^n T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) \leq (TG)^n T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*}, \quad n = 1, 2, \dots \tag{31}$$

Hence, using (31), we have

$$\begin{aligned}
 Q_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) &= T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) + (TG)T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) \\
 &\quad + (TG)^2 T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) + \dots + (TG)^n T_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) + \dots \\
 &\leq T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*} + (TG)T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*} + (TG)^2 T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*} + \dots \\
 &\quad + (TG)^n T_{\lambda^*, \mu^*} u_{\lambda^*, \mu^*} + \dots \\
 &= Q_{\lambda^*, \mu^*}(u_{\lambda^*, \mu^*})
 \end{aligned}$$

i.e.,

$$Q_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) - Q_{\lambda^*, \mu^*}(u_{\lambda^*, \mu^*}) \leq 0,$$

so that

$$Q_{\underline{\lambda}, \underline{\mu}}(u_{\lambda^*, \mu^*} + \delta) \leq Q_{\lambda^*, \mu^*}(u_{\lambda^*, \mu^*}) = u_{\lambda^*, \mu^*} < u_{\lambda^*, \mu^*} + \delta.$$

Set $D_{u_{\lambda^*, \mu^*}} = \{u \in C[0, 1] : -\delta < u(t) < u_{\lambda^*, \mu^*} + \delta\}$. Then $Q_{\lambda, \mu} : P \cap D_{u_{\lambda^*, \mu^*}} \rightarrow P$ is completely continuous. Furthermore, $Q_{\lambda, \mu} u \neq \nu u$ for $\nu \geq 1$ and $u \in P \cap \partial D_{u_{\lambda^*, \mu^*}}$. Indeed set $u \in P \cap \partial D_{u_{\lambda^*, \mu^*}}$. Then there exists $t_0 \in [0, 1]$ such that $u(t_0) = \|u\|_0 = \|u_{\lambda^*, \mu^*} + \delta\|_0$ and

$$\begin{aligned} (Q_{\lambda, \mu} u)(t_0) &= (T_{\lambda, \mu} u) + (TG)T_{\lambda, \mu} u + (TG)^2 T_{\lambda, \mu} u + \dots + (TG)^n T_{\lambda, \mu} u + \dots)(t_0) \\ &\leq (T_{\lambda, \mu} (u_{\lambda^*, \mu^*} + \delta) + (TG)T_{\lambda, \mu} (u_{\lambda^*, \mu^*} + \delta) + (TG)^2 T_{\lambda, \mu} (u_{\lambda^*, \mu^*} + \delta) + \dots \\ &\quad + (TG)^n T_{\lambda, \mu} (u_{\lambda^*, \mu^*} + \delta) + \dots)(t_0) = Q_{\lambda, \mu} (u_{\lambda^*, \mu^*} + \delta)(t_0) \\ &< u_{\lambda^*, \mu^*}(t_0) + \delta = u(t_0) \leq \nu u(t_0), \quad \nu \geq 1. \end{aligned}$$

By Lemma 3, $i(Q_{\lambda, \mu}, P \cap \partial D_{u_{\lambda^*, \mu^*}}, P) = 1$.

Let k be such that

$$u(t) \geq k\|u\|_0 \quad \text{for } t \in \left[\frac{1}{4}, \frac{3}{4}\right].$$

We know that $\lim_{u \rightarrow \infty} \frac{f(t, u)}{u} = \infty$ uniformly for $t \in [0, 1]$, so we may choose $J_3 > 0$, so that

$$\lambda J_3 \delta_1 \delta_2 \delta_3 C_{12} C_{23} m_1 C_3 k > 2,$$

$l_3 > \|u_{\lambda^*, \mu^*} + \delta\|_0 > 0$, so that

$$f(t, u) \geq J_3 u \quad \text{for } u > l_3 \text{ and } t \in \left[\frac{1}{4}, \frac{3}{4}\right].$$

Set $R_1 = \frac{l_3}{k}$ and $P_{R_1} = \{u \in P : \|u\|_0 < R_1\}$. Then $Q_{\lambda, \mu} : \overline{P}_{R_1} \rightarrow P$ is completely continuous. It is easy to obtain

$$\begin{aligned} (Q_{\lambda, \mu} u)(t) &\geq (T_{\lambda, \mu} u)(t) \geq \lambda \int_0^1 \int_0^1 \int_0^1 G_1(t, v) G_2(v, \tau) G_3(\tau, s) f(s, u(s)) ds d\tau dv \\ &\geq \lambda \delta_1 \delta_2 \delta_3 C_{12} C_{23} G_1(t, t) \int_0^1 G_3(s, s) f(s, u(s)) ds \\ &\geq \lambda \delta_1 \delta_2 \delta_3 C_{12} C_{23} G_1(t, t) \int_{\frac{1}{4}}^{\frac{3}{4}} G_3(s, s) f(s, u(s)) ds \\ &\geq \frac{1}{2} \lambda \delta_1 \delta_2 \delta_3 C_{12} C_{23} m_1 C_3 J_3 u(t) \geq \frac{1}{2} \lambda \delta_1 \delta_2 \delta_3 C_{12} C_{23} m_1 C_3 J_3 k \|u\|_0 > \|u\|_0 \end{aligned}$$

for $t \in [0, 1]$ and $u \in \partial P_{R_1}$. Now $u(t) \geq k\|u\|_0 = kR_1 = l_3$, and so

$$\|Q_{\lambda, \mu} u\|_0 > \|u\|_0.$$

In view of Lemma 4, $i(Q_{\lambda, \mu}, P_{R_1}, P) = 0$. By the additivity of the fixed point index,

$$i(Q_{\lambda, \mu}, P_{R_1} \setminus \overline{P \cap D_{u_{\lambda^*, \mu^*}}}, P) = i(Q_{\lambda, \mu}, P_{R_1}, P) - i(Q_{\lambda, \mu}, P \cap D_{u_{\lambda^*, \mu^*}}, P) = -1.$$

Thus $Q_{\lambda, \mu}$ has a fixed point in $\{P \cap D_{u_{\lambda^*, \mu^*}}\} \setminus \{\theta\}$ and has another fixed point in $P_{R_1} \setminus P \cap D_{u_{\lambda^*, \mu^*}}$ by choosing $\lambda^* = \tilde{\lambda}$. \square

Let us introduce the notation $\mu = 0$ in the equation of (13), then we have

$$\begin{aligned}
 & -u^{(6)} + A(t)u^{(4)} + B(t)u'' + C(t)u = \lambda f(t, u), \\
 & u(0) = u(1) = u''(0) = u''(1) = u^{(4)}(0) = u^{(4)}(1) = 0.
 \end{aligned}
 \tag{32}$$

In this case, we can prove the following theorem, which is similar to Theorem 1.

Theorem 2 *Suppose that (H3)-(H5) hold, and $L < 1$. Then there exists at $\lambda^* > 0$ such that (32) has at least two, one and has no positive solutions for $0 < \lambda < \lambda^*$, $\lambda = \lambda^*$ for $\lambda > \lambda^*$, respectively.*

We follow exactly the same procedure, described in detail in the proof of Theorem 1 for $\mu = 0$.

Let us introduce the following notations for $\mu = 0$ and $\lambda = 1$

$$\begin{aligned}
 TFu(t) &= \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu)G_2(\nu, s)G_3(s, \tau)f(\tau, u(\tau)) \, d\tau \, ds \, d\nu, \\
 Qu := HFu &= TFu + (TG)TFu + (TG)^2TFu + \dots + (TG)^nTFu + \dots,
 \end{aligned}
 \tag{33}$$

i.e., $Qu = Q_{1,0}u = HFu$.

Lemma 13 *Suppose that (H3), (H4) and (H6) hold, and $L < 1$. Then for any $u \in C^+[0, 1] \setminus \{\theta\}$, there exist real numbers $S_u \geq s_u > 0$ such that*

$$s_u g(t) \leq (Qu)(t) \leq S_u g(t), \quad \text{for } t \in [0, 1],$$

where $g(t) = \int_0^1 \int_0^1 G_1(t, \tau)G_2(\tau, \nu)G_3(\nu, \nu) \, d\nu \, d\tau$.

Proof For any $u \in C^+[0, 1] \setminus \{\theta\}$ from Lemma 6, we have

$$\begin{aligned}
 (Qu)(t) &= (HFu)(t) \leq \frac{1}{1-L} \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu)G_2(\nu, \tau)G_3(\tau, s)f(s, u(s)) \, ds \, d\tau \, d\nu \\
 &\leq \frac{C_3}{1-L} \max_{s \in [0,1]} f(s, u(s)) \int_0^1 \int_0^1 G_1(t, \tau)G_2(\tau, \nu)G_3(\nu, \nu) \, d\nu \, d\tau \\
 &= \frac{C_3}{1-L} \max_{s \in [0,1]} f(s, u(s))g(t) = S_u g(t) \quad \text{for } t \in [0, 1].
 \end{aligned}$$

Note that for any $u \in C^+[0, 1] \setminus \{\theta\}$, there exists an interval $[a_1, b_1] \subset (0, 1)$ and a number $p > 0$ such that $u(t) \geq p$ for $t \in [a_1, b_1]$. In addition, by (H6), there exists $s_0 > 0$ and $u^0 \in (0, \infty)$ such that $f(t, u^0) \geq s_0$ for $t \in [a_1, b_1]$. If $p \geq u^0$, then $f(t, u) \geq f(t, p) \geq f(t, u^0) \geq s_0$; if $p < u^0$, then $f(t, u) \geq f(t, p) \geq f(t, \frac{p}{u^0}p) \geq (\frac{p}{u^0})^\alpha s_0$. Hence

$$\begin{aligned}
 (Qu)(t) &\geq (TFu)(t) \\
 &= \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu)G_2(\nu, \tau)G_3(\tau, s)f(s, u(s)) \, ds \, d\tau \, d\nu \\
 &\geq \delta_3 \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu)G_2(\nu, \tau)G_3(\tau, \tau)G_3(s, s)f(s, u(s)) \, ds \, d\tau \, d\nu
 \end{aligned}$$

$$\begin{aligned} &\geq \delta_3 g(t) \int_{a_1}^{b_1} G_3(s, s) f(s, u(s)) \, ds \, d\tau \, dv \\ &\geq (b_1 - a_1) \delta_3 g(t) m_G \left(\frac{p}{u^0} \right)^\alpha = s_u g(t), \end{aligned}$$

where $m_G = \min_{s \in [a_1, b_1]} G_3(s, s)$, $g(t) = \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, \tau) \, d\tau \, dv$, $s_u = (b_1 - a_1) \times \delta_3 m_G \left(\frac{p}{u^0} \right)^\alpha$. \square

Theorem 3 *Suppose that (H3), (H4) and (H6) hold, $L < 1$ and $\lambda = 1$. Then*

(i) (32) has a unique positive solution $u^* \in C^+[0, 1] \setminus \{\theta\}$ satisfying

$$m_u g(t) \leq u^*(t) \leq M_u g(t) \quad \text{for } t \in [0, 1],$$

where $0 < m_u < M_u$ are constants.

(ii) For any $u_0(t) \in C^+[0, 1] \setminus \{\theta\}$, the sequence

$$\begin{aligned} u_n(t) &= (Qu_{n-1})(t) = (HFu_{n-1})(t) \\ &= TFu_{n-1} + (TG)TFu_{n-1} + (TG)^2TFu_{n-1} + \dots + (TG)^nTFu_{n-1} + \dots \end{aligned}$$

($n = 1, 2, \dots$) converges uniformly to the unique solution u^* , and the rate of convergence is determined by

$$\|u_n(t) - u^*(t)\| = O(1 - d^{\alpha^n}),$$

where $0 < d < 1$ is a positive number.

Proof In view of (H3), (H4) and (H6), $Q : C^+[0, 1] \rightarrow C^+[0, 1]$ is a nondecreasing operator and satisfies $Q(\rho u) \geq \rho^\alpha Q(u)$ for $t \in [0, 1]$ and $u \in C^+[0, 1]$. Indeed, let $u_*(t) \leq u_{**}(t)$, $u_*, u_{**} \in C^+[0, 1]$, since $f(s, u)$ is nondecreasing in u , then by using $f(s, u_*(s)) \leq f(s, u_{**}(s))$, for $t \in [0, 1]$, it follows that

$$\begin{aligned} TFu_*(t) &= \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, u_*(s)) \, ds \, d\tau \, dv \\ &\leq \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, u_{**}(s)) \, ds \, d\tau \, dv = TFu_{**}(t). \end{aligned}$$

Moreover, from (25), it follows that for $TFu_*(t) \leq TFu_{**}(t)$

$$G(TFu_*)(t) \leq G(TFu_{**})(t) \quad \text{for } t \in [0, 1]. \tag{34}$$

Finally, since $f(s, u)$ is nondecreasing in u , then by using form (34), $f(s, G(TFu_*)(t)) \leq f(s, G(TFu_{**})(t))$, for $t \in [0, 1]$, we have

$$\begin{aligned} (TG)TFu_* &= \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, G(TFu_*)(s)) \, ds \, d\tau \, dv \\ &\leq \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, G(TFu_{**})(s)) \, ds \, d\tau \, dv \\ &= (TG)TFu_{**}, \end{aligned}$$

i.e.,

$$(TG)TF(u_\star) \leq (TG)TFu_{\star\star}.$$

By induction, it is easy to see that

$$(TG)^n TF(u_\star) \leq (TG)^n TFu_{\star\star}, \quad n = 1, 2, \dots \tag{35}$$

Hence, using (35), we have

$$\begin{aligned} Q(u_\star) &= TF(u_\star) + (TG)TF(u_\star) + (TG)^2 TF(u_\star) + \dots + (TG)^n TF(u_\star) + \dots \\ &\leq TF(u_{\star\star}) + (TG)TF(u_{\star\star}) + (TG)^2 TF(u_{\star\star}) + \dots + (TG)^n TF(u_{\star\star}) + \dots \\ &= Q(u_{\star\star}). \end{aligned} \tag{36}$$

Now, we show that $Q : C^+[0,1] \rightarrow C^+[0,1]$ satisfies $Q(\rho u) \geq \rho^\alpha Q(u)$ for $t \in [0,1]$ and $u \in C^+[0,1]$. Note that

$$\begin{aligned} TF(\rho u) &= \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, \rho u(s)) \, ds \, d\tau \, d\nu \\ &\geq \rho^\alpha \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, u(s)) \, ds \, d\tau \, d\nu \\ &= \rho^\alpha TF(u). \end{aligned}$$

Moreover, from (25), it follows that for $TF(\rho u) \geq \rho^\alpha TF(u)$,

$$\begin{aligned} G(TF\rho u)(t) &\geq G(\rho^\alpha TF(u))(t) \\ &= \rho^\alpha G(TF(u))(t) \quad \text{for } t \in [0,1]. \end{aligned}$$

Finally, we have

$$\begin{aligned} (TG)TF(\rho u)(t) &= \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, G(TF\rho u)(s)) \, ds \, d\tau \, d\nu \\ &\geq \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, \rho^\alpha G(TF(u))(s)) \, ds \, d\tau \, d\nu \\ &\geq \rho^{\alpha^2} \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, \tau) G_3(\tau, s) f(s, G(TF(u))(s)) \, ds \, d\tau \, d\nu \\ &= \rho^{\alpha^2} (TG)TF(u)(t), \end{aligned}$$

i.e.,

$$(TG)(TF\rho u)(t) \geq \rho^{\alpha^2} (TG)TF(u)(t).$$

By induction, it is easy to see that

$$(TG)^n (TF\rho u)(t) \geq \rho^{\alpha^{n+1}} (TG)TF(\rho u)(t), \quad n = 1, 2, \dots \tag{37}$$

Hence, using (35) and $\rho \in (0,1), \alpha \in (0,1)$, we have

$$\begin{aligned}
 Q(\rho u) &= TF(\rho u) + (TG)TF(\rho u) + (TG)^2TF(\rho u) + \dots + (TG)^nTF(\rho u) + \dots \\
 &\geq \rho^\alpha TF(u) + \rho^{\alpha^2} (TG)TF(u) + \rho^{\alpha^3} (TG)^2TF(u) + \dots + \rho^{\alpha^{n+1}} (TG)^nTF(u) + \dots \\
 &\geq \rho^\alpha TF(u) + \rho^\alpha (TG)TF(u) + \rho^\alpha (TG)^2TF(u) + \dots + \rho^\alpha (TG)^nTF(u) + \dots \\
 &= \rho^\alpha (TF(u) + (TG)TF(u) + (TG)^2TF(u) + \dots + (TG)^nTF(u) + \dots) \\
 &= \rho^\alpha Q(u).
 \end{aligned} \tag{38}$$

By Lemma 13, there exists $0 < s_g \leq S_g$ such that

$$s_u g(t) \leq Qg(t) \leq S_u g(t).$$

Let

$$s = \sup\{s_g : s_u g(t) \leq Qg(t)\}, \quad S = \inf\{S_g : Qg(t) \leq S_u g(t)\}.$$

Pick m_s and M_s such that

$$0 < m_s < \min\{1, s^{\frac{1}{1-\alpha}}\} \tag{39}$$

and

$$\max\{1, S^{\frac{1}{1-\alpha}}\} = M_s < \infty. \tag{40}$$

Set $u_0(t) = m_s g(t), v_0(t) = M_s g(t), u_n = Qu_{n-1}$, and $v_n = Qv_{n-1}, n = 1, 2, \dots$. From (36) and (38), we have

$$m_s g(t) = u_0(t) \leq u_1(t) \leq \dots \leq u_n(t) \leq \dots \leq v_n(t) \leq \dots \leq v_1(t) \leq v_0(t) = M_s g(t). \tag{41}$$

Indeed, from (39) $m_s < 1$, and $m_s^{\alpha-1} s > 1$, we have

$$\begin{aligned}
 u_1(t) &= Q(u_0) = Q(m_s g(t)) \geq m_s^\alpha Q(g(t)) \geq m_s^\alpha s g(t) \\
 &= m_s^{\alpha-1} s m_s g(t) = m_s^{\alpha-1} s u_0(t) \geq u_0(t),
 \end{aligned}$$

and by induction

$$u_{n+1}(t) = Q(u_n) \geq Q(u_{n-1}) = u_n(t).$$

From (40), $M_s > 1$, and $M_s^{\alpha-1} S < 1$, we have

$$\begin{aligned}
 v_1(t) &= Q(v_0) \leq M_s^\alpha Q(g(t)) = M_s^\alpha Q\left(\frac{1}{M_s} v_0\right) = M_s^\alpha Q(g) \\
 &\leq M_s^\alpha S g \leq S M_s^{\alpha-1} M_s g = S M_s^{\alpha-1} v_0(t) \leq v_0(t),
 \end{aligned}$$

and by induction

$$v_{n+1}(t) = Q(v_n) \leq Q(v_{n-1}) = v_n(t).$$

Let $d = \frac{m_s}{M_s}$. Then

$$u_n \geq d^{\alpha^n} v_n. \tag{42}$$

In fact $u_0 = dv_0$ is clear. Assume that (42) holds with $n = k$ (k is a positive integer), *i.e.*, $u_k \geq d^{\alpha^k} v_k$. Then

$$u_{k+1} = Q(u_k) \geq Q(d^{\alpha^k} v_k) \geq (d^{\alpha^k})^\alpha Q(v_k) = d^{\alpha^{k+1}} Q(v_k) = d^{\alpha^{k+1}} v_{k+1}.$$

By induction, it is easy to see that (42) holds. Furthermore, in view of (38), (41) and (42), we have

$$0 \leq u_{n+z} - u_n \leq v_n - u_n \leq (1 - d^{\alpha^n})v_0 = (1 - d^{\alpha^n})M_s g(t)$$

and

$$\|u_{n+z} - u_n\| \leq \|v_n - u_n\| \leq (1 - d^{\alpha^n})M_s \|g\|,$$

where z is a nonnegative integer. Thus, there exists $u^* \in C^+[0, 1]$ such that

$$\lim_{n \rightarrow \infty} u_n(t) = \lim_{n \rightarrow \infty} v_n(t) = u^*(t) \quad \text{for } t \in [0, 1]$$

and $u^*(t)$ is a fixed point of Q and satisfies

$$m_s g(t) \leq u^*(t) \leq M_s g(t).$$

This means that $u^* \in C_*^+[0, 1]$, where $C_*^+[0, 1] = \{u \in C^+[0, 1], u(t) > 0 \text{ for } t \in (0, 1)\}$.

Next we show that u^* is the unique fixed point of Q in $C_*^+[0, 1]$. Suppose, to the contrary, that there exists another $\bar{u} \in C_*^+[0, 1]$ such that $Q\bar{u} = \bar{u}$. We can suppose that

$$u^*(t) \leq \bar{u}(t), \quad u^*(t) \neq \bar{u}(t) \quad \text{for } t \in [0, 1].$$

Let $\hat{\tau} = \sup\{0 < \tau < 1 : \tau u^* \leq \bar{u} \leq \tau^{-1} u^*\}$. Then $0 < \hat{\tau} \leq 1$ and $\hat{\tau} u^* \leq \bar{u} \leq \hat{\tau}^{-1} u^*$. We assert $\hat{\tau} = 1$. Otherwise, $0 < \hat{\tau} < 1$, and then

$$\bar{u} = Q\bar{u} \geq Q(\hat{\tau} u^*) \geq \hat{\tau}^\alpha Q(u^*) = \hat{\tau}^\alpha u^*,$$

$$u^* = Qu^* \geq Q(\hat{\tau} \bar{u}) \geq \hat{\tau}^\alpha Q(\bar{u}) = \hat{\tau}^\alpha \bar{u}.$$

This means that $\hat{\tau}^\alpha u^* \leq \bar{u} \leq (\hat{\tau}^\alpha)^{-1} u^*$, which is a contradiction of the definition of $\hat{\tau}$, because $\hat{\tau} < \hat{\tau}^\alpha$.

Let us introduce the following notations for $\mu = 0$

$$T_\lambda u(t) := TFu(t) = \lambda \int_0^1 \int_0^1 \int_0^1 G_1(t, \nu) G_2(\nu, s) G_3(s, \tau) f(\tau, u(\tau)) d\tau ds d\nu,$$

$$Q_\lambda u := HFu = TFu + (TG)TFu + (TG)^2TFu + \dots + (TG)^nTFu + \dots$$

$$= T_\lambda u + (TG)T_\lambda u + (TG)^2T_\lambda u + \dots + (TG)^nT_\lambda u + \dots,$$

i.e., $Q_\lambda u = \lambda Qu$, where Q is given by (33). □

Theorem 4 Suppose that (H3), (H4), (H6) and $L < 1$ hold. Then (32) has a unique positive solution $u_\lambda(t)$ for any $0 < \lambda \leq 1$.

Proof Theorem 3 implies that for $\lambda = 1$, the operator Q_λ has a unique fixed point $u_1 \in C^+[0, 1]$, that is $Q_1 u_1 = u_1$. Then from Lemma 10, for every $\lambda_* \in (0, 1)$, there exists a function $u_* \in P \setminus \{\theta\}$ such that $Q_{\lambda_*} u_* = u_*$.

Thus, u_λ is a unique positive solution of (32) for every $0 < \lambda \leq 1$. □

4 Application

As an application of Theorem 1, consider the sixth-order boundary value problem

$$-u^{(6)} + (1 - 0.5t^2)u^{(4)} + (4.5 - 0.5 \sin \pi t)u'' + C(-5 + \cos 0.5\pi t)u$$

$$= (0.5t(1 - t) + u)\varphi + \lambda(1 + \sin \pi t + u^2), \quad 0 < t < 1,$$

$$-\varphi'' + 2\varphi = \mu u, \quad 0 < t < 1, \tag{43}$$

$$u(0) = u(1) = u''(0) = u''(1) = u^{(4)}(0) = u^{(4)}(1) = 0,$$

$$\varphi(0) = \varphi(1) = 0,$$

for a fixed $\lambda_1 = 2, \lambda_2 = -2, \lambda_3 = 1$ and $\varkappa = 2$. In this case, $a = \lambda_1 + \lambda_2 + \lambda_3 = 1, b = -\lambda_1\lambda_2 - \lambda_2\lambda_3 - \lambda_1\lambda_3 = 4$, and $c = \lambda_1\lambda_2\lambda_3 = -4$. We have $A(t) = 1 - 0.5t^2, B(t) = 4.5 - 0.5 \sin \pi t, C(t) = -5 + \cos 0.5\pi t, D(t) = 0.5t(1 - t)$ and $f(t, u) = 1 + \sin \pi t + u^2$. It is easy to see that $\pi^6 + a\pi^4 - b\pi^2 + c = 1,015.3 > 0, a = \sup_{t \in [0,1]} A(t), b = \inf_{t \in [0,1]} B(t)$ and $c = \sup_{t \in [0,1]} C(t)$. Note also that $K = \max_{0 \leq t \leq 1} [-A(t) + B(t) - C(t) - (-a + b - c)] = 2, D_2 = \max_{t \in [0,1]} \int_0^1 G_2(t, \nu) d\nu = 0.15768, C = \max_{t \in [0,1]} D(t) = 0.125, d_1 = \max_{t \in [0,1]} \int_0^1 G(t, s) ds = 0.10336, \mu^{**} = \frac{1 - D_2 K}{D_2 C d_1} = 336.1$ and $D_2 K = 0.3153 < 1$. Thus, if $0 < \mu < 336.1$, then the conditions of Theorem 1 (note $L = D_2(K + \mu C d_1) < 1$) are fulfilled (in particular, (H3)-(H5) are satisfied). As a result, Theorem 1 can be applied to (43).

Competing interests

The authors did not provide this information.

Authors' contributions

The authors did not provide this information.

Author details

¹Department of Mathematics, Texas A&M University-Kingsville, 700 University Blvd., Kingsville, 78363-8202, USA.

²Department of Analysis, University of Miskolc, Egyetemvaros, 3515, Hungary. ³School of Mathematics, Statistics and Applied Mathematics, National University of Ireland, Galway, Ireland.

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