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Concentrating standing waves for the fractional Schrödinger equation with critical nonlinearities

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Abstract

We study the following nonlocal Schrödinger equations:

$$\varepsilon^{2s}(-\Delta)^s u + V(x)u = W(x)f(u), \quad (I)$$

$$\varepsilon^{2s}(-\Delta)^s u + V(x)u = W(x)(f(u) + u^{2_s^*-1}), \quad (II)$$

for $u \in H^s(\mathbb{R}^N)$, where $f(u)$ is superlinear and subcritical, $2_s^* = \frac{2N}{N-2s}$ if $N > 2s$. $V(x)$ and $W(x)$ are sufficiently smooth potential with $\inf V(x) > 0$, $\inf W(x) > 0$, and $\varepsilon > 0$ is a small number. Under proper assumptions, we explore the existence, concentration phenomenon, convergence, and decay estimate of semiclassical solutions of (I) and (II), respectively. Compared with some existing issues, the most interesting results obtained here are therefore: the concentration phenomenon depends on competing potential functions; the nonlocal critical problem (II) is considered; unlike the classical case $s = 1$, the decay estimate of solution to (I) or (II) is of polynomial instead of exponential form, due to the nonlocal effect.

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1 Introduction and overview on main results

This paper is devoted to the study of the concentration phenomenon for the fractional Schrödinger equations with subcritical nonlinearity,

$$\varepsilon^{2s}(-\Delta)^s u + V(x)u = W(x)f(u), \quad x \in \mathbb{R}^N, \quad (1.1)$$

or critical nonlinearity,

$$\varepsilon^{2s}(-\Delta)^s u + V(x)u = W(x)(f(u) + u^{2_s^*-1}), \quad x \in \mathbb{R}^N, \quad (1.2)$$

where $V(x)$ and $W(x)$ are sufficiently smooth potentials with $\inf V(x) > 0$, $\inf W(x) > 0$, and $\varepsilon > 0$ is a small parameter, $2_s^* = \frac{2N}{N-2s}$ ($N > 2s$), f is superlinear and has subcritical growth at infinity.

A basic motivation for the study of (1.1) or (1.2) comes from looking for standing waves of the type

$$\psi(x, t) = e^{-\frac{iEt}{\varepsilon}} u(x),$$

for the following fractional nonlinear Schrödinger equation:

$$i\varepsilon\psi_t = \varepsilon^{2s}(-\Delta)^s\psi + (V(x) + E)\psi - W(x)f(\psi), \quad (t, x) \in \mathbb{R}_+ \times \mathbb{R}^N, \quad (1.3)$$

where $(-\Delta)^s$ ($0 < s < 1$) denotes the usual fractional Laplace operator, i is the imaginary unit, ε designates the usual Planck constant. Equation (1.3) was introduced by Laskin [1] as an extension of the classical nonlinear Schrödinger equation $s = 1$ in which the Brownian motion of the quantum paths is replaced by a Levy flight. Here $\psi = \psi(x, t)$ represents the quantum mechanical probability amplitude for a given unit-mass particle to have position x at time t (the corresponding probability density is $|\psi|^2$), under a confinement due to the potential functions $V(x)$, $W(x)$. The nonlinear self-coupling $f(\psi)$, which describes a self-interaction in quantum electrodynamics, gives a closer description of many particles found in the real world. Typical examples can be found in the self-interacting theories, where the nonlinear function f can be both a polynomial and nonpolynomial (this includes the cases $|\psi|^\lambda$, $\sin|\psi|$, *etc.*). We assume throughout the paper that f satisfies $f(e^{i\theta}\psi) = f(\psi)$ for all $\theta \in [0, 2\pi]$. The function $V(x)$ represents the potential acting on the particle and $W(x)$ represents a particle-interaction term, which avoids spreading of the wave packets, in the time-dependent version of the above equation. We refer to [1–3] for detailed physical discussions and motivation.

A solution ψ is referred to as a bound state of (1.3) if $\psi \rightarrow 0$ as $|x| \rightarrow \infty$. Bound states of (1.3) when $\varepsilon \ll 1$ are called semiclassical states, which are relevant for the links between classical and quantum mechanics. An important feature of semiclassical states u_ε is that they concentrate as $\varepsilon \rightarrow 0$.

In the classical case $s = 1$, there is a broad literature on the concentration phenomenon, for example, see [4–10] and the references therein. Investigations of the existence of solutions concentrating at certain points to nonlocal Schrödinger equations under different conditions have also appeared in [11–14]. In [11], Dávila *et al.* considered the following superlinear problem:

$$\varepsilon^{2s}(-\Delta)^s u + V(x)u = u^p, \quad \text{in } x \in \mathbb{R}^N,$$

and multi-peak solutions were obtained via a Lyapunov-Schmidt variational reduction.

In [12], for a smooth, bounded domain $\Omega \subset \mathbb{R}^N$, $p \in (1, \frac{N+2s}{N-2s})$, Dávila *et al.* constructed a family of solutions for the nonlocal equation

$$\varepsilon^{2s}(-\Delta)^s u + u = u^p, \quad \text{in } \Omega,$$

which shows concentration as $\varepsilon \rightarrow 0$ at an interior point of the domain Ω in the form of a scaling of the ground state in the entire space.

Concentrating solutions for fractional problems involving critical or almost critical exponents were considered in [14]. See also [15] for some concentration phenomena in

particular cases, and also [13] and the references therein for related problems about Schrödinger-type equations in a fractional setting.

The goal of this paper is to show, by variational techniques as developed by Rabinowitz [16], Wang [17], Ding and Liu [18] in the classical case, that semiclassical solutions concentrate around some certain points that depend on both linear and nonlinear potentials for the nonlocal superlinear problem (1.1) and the critical problem (1.2).

For any $p \in [1, +\infty)$, the fractional Sobolev space $W^{s,p}(\mathbb{R}^N)$ is defined as follows:

$$W^{s,p}(\mathbb{R}^N) := \left\{ u \in L^p(\mathbb{R}^N) : \frac{u(x) - u(y)}{|x - y|^{\frac{N}{p} + s}} \in L^p(\mathbb{R}^N \times \mathbb{R}^N) \right\},$$

endowed with the natural norm

$$\|u\|_{W^{s,p}(\mathbb{R}^N)} := \left(\int_{\mathbb{R}^N} |u|^p dx + \int_{\mathbb{R}^N} \int_{\mathbb{R}^N} \frac{|u(x) - u(y)|^p}{|x - y|^{N+sp}} dx dy \right)^{\frac{1}{p}},$$

where the term

$$[u]_{W^{s,p}(\mathbb{R}^N)} := \left(\int_{\mathbb{R}^N} \int_{\mathbb{R}^N} \frac{|u(x) - u(y)|^p}{|x - y|^{N+sp}} dx dy \right)^{\frac{1}{p}}$$

is the so-called Gagliardo (semi) norm of u .

For $p = 2$, we take into account the definition of the space $H^s(\mathbb{R}^N) = W^{s,2}(\mathbb{R}^N)$ via the Fourier transform. Precisely, we may define

$$\widehat{H}^s(\mathbb{R}^N) = \left\{ u \in L^2(\mathbb{R}^N) : \int_{\mathbb{R}^N} (1 + |\xi|^{2s}) |\hat{u}(\xi)|^2 d\xi < +\infty \right\},$$

where $\widehat{\cdot}$ denotes the Fourier transform. The dual space $H^{-s}(\mathbb{R}^N)$ is defined in the standard way. The natural place to look for a bound state of (1.1) or (1.2) is the space $H^s(\mathbb{R}^N)$. The fractional Laplace $(-\Delta)^s u$ of a function $u \in H^s(\mathbb{R}^N)$ is defined in terms of its Fourier transform by the relation

$$\widehat{(-\Delta)^s u} = |\xi|^{2s} \hat{u} \in L^2(\mathbb{R}^N).$$

To describe our results, set

$$\begin{aligned} \tau &:= \min V, & \mathcal{V} &:= \{x \in \mathbb{R}^N : V(x) = \tau\}, & \tau_\infty &:= \liminf_{|x| \rightarrow \infty} V(x); \\ \kappa &:= \max W, & \mathcal{W} &:= \{x \in \mathbb{R}^N : W(x) = \kappa\}, & \kappa_\infty &:= \limsup_{|x| \rightarrow \infty} W(x). \end{aligned}$$

Assume that the external linear and nonlinear potentials $V(x)$ and $W(x)$ satisfy:

(P₀) $V, W \in L^\infty(\mathbb{R}^N)$ are uniformly continuous and $\inf V > 0$, $\inf W > 0$.

(P₁) Either (i) $\tau < \tau_\infty$, and there exist $R > 0$, $x_\nu \in \mathcal{V}$ such that $W(x_\nu) \geq W(x)$ for all $|x| \geq R$; or (ii) $\kappa > \kappa_\infty$, and there exist $R > 0$, $x_w \in \mathcal{W}$ such that $V(x_w) \leq V(x)$ for all $|x| \geq R$.

Observe that, in case (P₁)(i) we can assume $W(x_\nu) = \max_{x \in \mathcal{V}} W(x)$ and set

$$\mathcal{A}_V := \{x \in \mathcal{V} : W(x) = W(x_\nu)\} \cup \{x \notin \mathcal{V} : W(x) > W(x_\nu)\};$$

in case (P₁)(ii) we can assume $V(x_w) = \min_{x \in \mathcal{W}} V(x)$ and set

$$\mathcal{A}_w := \{x \in \mathcal{W} : V(x) = V(x_w)\} \cup \{x \notin \mathcal{W} : V(x) < V(x_w)\}.$$

Obviously, \mathcal{A}_v and \mathcal{A}_w are bounded. Moreover, $\mathcal{A}_v = \mathcal{A}_w = \mathcal{V} \cap \mathcal{W}$ if $\mathcal{V} \cap \mathcal{W} \neq \emptyset$. In particular, $\mathcal{A}_v = \mathcal{V}$ if W is constant, and $\mathcal{A}_w = \mathcal{W}$ if V is constant.

For the nonlinear fields, by writing $F(t) := \int_0^t f(\tau) d\tau$, we begin with the superlinear case:

- (f₁) $f \in C^1(\mathbb{R}^+, \mathbb{R}^+)$, $f(t) = 0$ for $t \leq 0$, $f(t) = o(t)$;
- (f₂) $\frac{f(t)}{t}$ is nondecreasing with respect to $t > 0$;
- (f₃) there are $p \in (2, 2_s^*)$, $c_1 > 0$ such that $f(t) \leq c_1(1 + t^{p-1})$ for $t \geq 0$;
- (f₄) there exists $\mu > 2$ such that $0 < \mu F(t) \leq f(t)t$ for all $t > 0$.

Our first result reads as follows.

Theorem 1.1 *Let (P₀), (f₁)-(f₄) be satisfied.*

(A) *Suppose (P₁)(i) holds, then for sufficiently small $\varepsilon > 0$:*

- (i) (existence) *a positive solution $w_\varepsilon \in \bigcap_{q \geq 2} W^{s,q}(\mathbb{R}^N)$ to (1.1) exists;*
- (ii) (concentration) *w_ε possesses a (global) maximum point x_ε such that*

$$\lim_{\varepsilon \rightarrow 0} \text{dist}(x_\varepsilon, \mathcal{A}_v) = 0;$$

- (iii) (decay estimates) *there exist constants $0 < C_1 < C_2$ such that*

$$\varepsilon^{(N+2s)} C_1 |x - x_\varepsilon|^{-(N+2s)} \leq w_\varepsilon(x) \leq \varepsilon^{(N+2s)} C_2 |x - x_\varepsilon|^{-(N+2s)};$$

- (iv) (convergence) *setting $v_\varepsilon(x) := w_\varepsilon(\varepsilon x + x_\varepsilon)$, for any sequence $x_\varepsilon \rightarrow x_0$ ($\varepsilon \rightarrow 0$), $v_\varepsilon \rightarrow u$ in $H^s(\mathbb{R}^N)$ with $u(x)$ being a least energy solution of*

$$(-\Delta)^s v + V(x_0)v = W(x_0)f(v), \quad v > 0.$$

In particular if $\mathcal{V} \cap \mathcal{W} \neq \emptyset$, then $\lim_{\varepsilon \rightarrow 0} \text{dist}(x_\varepsilon, \mathcal{V} \cap \mathcal{W}) = 0$ and, up to a subsequence, $v_\varepsilon \rightarrow u$ in $H^s(\mathbb{R}^N)$ with $u(x)$ being a least energy solution of

$$(-\Delta)^s v + \tau v = \kappa f(v), \quad v > 0.$$

(B) *Suppose (P₁)(ii) holds, then all the conclusions of (A) (with \mathcal{A}_v replaced by \mathcal{A}_w) remain true.*

For the critical problem (1.2), we strengthen (f₄) as follows:

- (f'₄) *there exist $q > 2$, $\mu > 2$, and $c_0 > 0$ such that $c_0 t^q \leq F(t) \leq \frac{1}{\mu} f(t)t$ for all $t > 0$.*

Our result concerned with the nonlocal critical problem (1.2) is as follows.

Theorem 1.2 *Let (P₀), (f₁)-(f'₄) be satisfied.*

(A) *Suppose (P₁)(i) with $\tau \in (0, \tau_0)$ holds, then for sufficiently small $\varepsilon > 0$, all the conclusions as in Theorem 1.1(A)(i)-(iv) are valid.*

(B) Suppose $(P_1)(ii)$ with $\kappa > \kappa_0$ holds, then all the conclusions of (A) (with \mathcal{A}_v replaced by \mathcal{A}_w) remain true. (See the definition of τ_0, κ_0 in Section 4.)

In the case $s = 1$, Theorems 1.1 and 1.2 were found by Ding and Liu [18]. The case of $W(x) = 1$ was previously considered by Rabinowitz [16] and Wang [17].

The organization of this paper is as follows: In a preliminary section, Section 2, we describe the appropriate functional setting for the study of the problem (1.1) or (1.2), including the definition of an equivalent problem. In Section 3 and Section 4, we consider the superlinear problem (1.1) and the critical problem (1.2), respectively. The proof of the main results is variational and relies on an elementary idea entailing mountain-pass arguments.

2 Preliminaries and functional setting

Let $0 < s < 1$, as we have recalled in the introduction, for $\phi \in H^s(\mathbb{R}^N)$ the standard definition of the fractional Laplacian $(-\Delta)^s \phi$ is given via the Fourier transform $\widehat{\cdot}$. $(-\Delta)^s \phi \in L^2(\mathbb{R}^N)$ is defined by the formula

$$\widehat{(-\Delta)^s \phi} = |\xi|^{2s} \widehat{\phi(\xi)}. \quad (2.1)$$

When ϕ is assumed in addition sufficiently regular, we obtain the direct representation

$$(-\Delta)^s \phi(x) = C_{N,s} \int_{\mathbb{R}^N} \frac{\phi(x) - \phi(y)}{|x - y|^{N+2s}} dy, \quad (2.2)$$

for a suitable constant $C_{N,s}$ and the integral is understood in a principal value sense.

Another useful local representation, found by Caffarelli and Silvestre [19], is via the following boundary value problem in the half space $\mathbb{R}_+^{N+1} = \{(x, y) : x \in \mathbb{R}^N, y > 0\}$:

$$\begin{cases} \nabla \cdot (y^{1-2s} \nabla \tilde{\phi}) = 0, & \text{in } \mathbb{R}_+^{N+1}, \\ \tilde{\phi}(x, 0) = \phi(x), & \text{on } \mathbb{R}^N. \end{cases} \quad (2.3)$$

Here $\tilde{\phi}$ is called the s -harmonic extension of ϕ , the extension function belongs to the space $X_0^s(\mathbb{R}_+^{N+1}) = \overline{C_0^\infty(\mathbb{R}_+^{N+1})}^{\|\cdot\|_{X_0^s(\mathbb{R}_+^{N+1})}}$, with

$$\|\tilde{\phi}\|_{X_0^s(\mathbb{R}_+^{N+1})} = \left(k_s \int_{\mathbb{R}_+^{N+1}} y^{1-2s} |\nabla \tilde{\phi}|^2 dx dy \right)^{\frac{1}{2}},$$

where k_s is a normalization constant. With this constant, we have the extension operator to be an isometry between $H^s(\mathbb{R}^N)$ and $X_0^s(\mathbb{R}_+^{N+1})$. That is,

$$\|\tilde{\phi}\|_{X_0^s(\mathbb{R}_+^{N+1})} = \|\phi\|_{H^s(\mathbb{R}^N)} = \|(-\Delta)^{\frac{s}{2}} \phi\|_2.$$

Moreover, $\tilde{\phi}$ can be explicitly given as a convolution integral with the s -Poisson kernel $P_s(x, y)$,

$$\tilde{\phi}(x, y) = \int_{\mathbb{R}^N} P_s(x - z, y) \phi(z) dz, \quad (2.4)$$

where $P_s(x, y) = d_{N,s} \frac{y^{2s}}{(|x|^2 + |y|^2)^{\frac{N+2s}{2}}}$, and $d_{N,s}$ achieves $\int_{\mathbb{R}^N} P_s(x, y) dx = 1$. Then under suitable regularity, $(-\Delta)^s \phi$ is the Dirichlet-to-Neumann map for this problem, namely

$$\frac{1}{k_s} (-\Delta)^s \phi(x) = - \lim_{y \rightarrow 0^+} y^{1-2s} \partial_y \tilde{\phi}(x, y). \quad (2.5)$$

The characterizations (2.1), (2.2), and (2.4) are all equivalent, for instance, in Schwartz's space of rapidly decreasing smooth functions. The constants in (2.2), (2.4), and (2.5) satisfy the identity $2sd_{N,s}k_s = C_{N,s}$. Their explicit values can be consulted for instance in [20].

It is standard that (1.1) or (1.2), by setting $u(x) = w(\varepsilon x)$, respectively, is equivalent to

$$(-\Delta)^s u + V_\varepsilon(x)u = W_\varepsilon(x)f(u) \quad (2.6)$$

and

$$(-\Delta)^s u + V_\varepsilon(x)u = W_\varepsilon(x)h(u), \quad (2.7)$$

where $h(t) = f(t) + t^{2s^*-1}$, for $t \geq 0$, $h(t) = 0$ for $t < 0$, and $H(u) := F(u) + \frac{1}{2s^*} |u|^{2s^*}$, $V_\varepsilon(x) = V(\varepsilon x)$, $W_\varepsilon(x) = W(\varepsilon x)$. We will in the sequel focus on these equivalent problems.

In the following we will denote

$$\|u\|_\varepsilon := \left(\int_{\mathbb{R}^N} |(-\Delta)^{\frac{s}{2}} u|^2 dx + \int_{\mathbb{R}^N} V(\varepsilon x) u^2 dx \right)^{\frac{1}{2}}$$

as the norms in $H^s(\mathbb{R}^N)$, which are all equivalent to the standard norm $\|\cdot\|_{H^s}$ of $H^s(\mathbb{R}^N)$ because of the boundedness of $V(x)$ and $W(x)$. We will also denote by $|\cdot|_p$ the usual norm of $L^p(\mathbb{R}^N)$. Associated to the problem (2.6) or (2.7) we consider the energy functional I_ε or I_ε^* , respectively,

$$\begin{aligned} I_\varepsilon(u) &= \frac{1}{2} \int_{\mathbb{R}^N} |(-\Delta)^{\frac{s}{2}} u|^2 dx + \frac{1}{2} \int_{\mathbb{R}^N} V(\varepsilon x) u^2 dx - \int_{\mathbb{R}^N} W(\varepsilon x) F(u) dx, \\ I_\varepsilon^*(u) &= \frac{1}{2} \int_{\mathbb{R}^N} |(-\Delta)^{\frac{s}{2}} u|^2 dx + \frac{1}{2} \int_{\mathbb{R}^N} V(\varepsilon x) u^2 dx - \int_{\mathbb{R}^N} W(\varepsilon x) H(u) dx. \end{aligned}$$

These functionals are well defined in $H^s(\mathbb{R}^N)$, and, moreover, the critical points of I_ε and I_ε^* correspond to weak solutions to (2.6) and (2.7), respectively.

With the above extensions (2.3) and (2.5), we can reformulate our problem (2.6) or (2.7), respectively, as

$$\begin{cases} \nabla \cdot (y^{1-2s} \nabla \tilde{\phi}) = 0, & \text{in } \mathbb{R}_+^{N+1}, \\ \tilde{\phi}(x, 0) = \phi(x), & \text{on } \mathbb{R}^N, \\ -k_s \lim_{y \rightarrow 0^+} y^{1-2s} \partial_y \tilde{\phi}(x, y) = W(\varepsilon x) f(\tilde{\phi}) - V(\varepsilon x) \tilde{\phi}, & \text{in } \mathbb{R}_+^{N+1}. \end{cases} \quad (2.8)$$

$$\begin{cases} \nabla \cdot (y^{1-2s} \nabla \tilde{\phi}^*) = 0, & \text{in } \mathbb{R}_+^{N+1}, \\ \tilde{\phi}^*(x, 0) = \phi^*(x), & \text{on } \mathbb{R}^N, \\ -k_s \lim_{y \rightarrow 0^+} y^{1-2s} \partial_y \tilde{\phi}^*(x, y) = W(\varepsilon x) h(\tilde{\phi}^*) - V(\varepsilon x) \tilde{\phi}^*, & \text{in } \mathbb{R}_+^{N+1}. \end{cases} \quad (2.9)$$

An energy solution to problem (2.8) is a function $\tilde{\phi} \in X_0^s(\mathbb{R}_+^{N+1})$ such that

$$k_s \int_{\mathbb{R}_+^{N+1}} y^{1-2s} \langle \nabla \tilde{\phi}, \nabla \varphi \rangle dx dy + \int_{\mathbb{R}^N} V(\varepsilon x) \tilde{\phi} \varphi dx = \int_{\mathbb{R}^N} W(\varepsilon x) f(\tilde{\phi}) \varphi dx,$$

for all $\varphi \in X_0^s(\mathbb{R}_+^{N+1})$. For any energy solution $\tilde{\phi} \in X_0^s(\mathbb{R}_+^{N+1})$ of problem (2.8), the function $\phi = \tilde{\phi}(\cdot, 0)$ defined in the sense of traces, belongs to the space $H^s(\mathbb{R}^N)$ and is an energy solution to the problem (2.6). The converse is also true. Therefore, the formulations of (2.6) and (2.8) are equivalent. This is the same as for (2.7) and (2.9).

The associated energy functional to the problem (2.8) or (2.9) is, respectively,

$$J_\varepsilon(\tilde{\phi}) = \frac{k_s}{2} \int_{\mathbb{R}_+^{N+1}} y^{1-2s} |\nabla \tilde{\phi}|^2 dx dy + \frac{1}{2} \int_{\mathbb{R}^N} V(\varepsilon x) |\tilde{\phi}|^2 dx - \int_{\mathbb{R}^N} W(\varepsilon x) F(\tilde{\phi}) dx$$

or

$$\begin{aligned} J_\varepsilon^*(\tilde{\phi}^*) &= \frac{k_s}{2} \int_{\mathbb{R}_+^{N+1}} y^{1-2s} |\nabla \tilde{\phi}^*|^2 dx dy + \frac{1}{2} \int_{\mathbb{R}^N} V(\varepsilon x) |\tilde{\phi}^*|^2 dx \\ &\quad - \int_{\mathbb{R}^N} W(\varepsilon x) H(\tilde{\phi}^*) dx. \end{aligned}$$

Clearly, critical points of J_ε and J_ε^* in $X_0^s(\mathbb{R}_+^{N+1})$ correspond to critical points of I_ε and I_ε^* in $H^s(\mathbb{R}^N)$, respectively.

Remark 2.1 In the sequel, and in view of the above equivalence, we will find both formulations of the problem, in \mathbb{R}^N or in \mathbb{R}_+^{N+1} , whenever we may take some advantage. In particular, we will use the extension version (2.8) or (2.9) respectively, when dealing with the fractional operator acting on products of functions, since it is not clear how to calculate this action.

Another tool which is very useful in the following is the trace inequality,

$$\int_{\mathbb{R}_+^{N+1}} y^{1-2s} |\nabla z(x, y)|^2 dx dy \geq C_1 \left(\int_{\mathbb{R}^N} |z(x, 0)|^r dx \right)^{\frac{2}{r}}, \quad (2.10)$$

for any $1 \leq r \leq \frac{2N}{N-2s}$, $N > 2s$, and any $z \in X_0^s(\mathbb{R}_+^{N+1})$, where $C_1 = C_1(s, r, N) > 0$. It is equivalent to the fractional Sobolev inequality

$$\int_{\mathbb{R}^N} |(-\Delta)^{\frac{s}{2}} u|^2 dx \geq C_2 \left(\int_{\mathbb{R}^N} |u|^r dx \right)^{\frac{2}{r}}, \quad (2.11)$$

for any $1 \leq r \leq \frac{2N}{N-2s}$, $N > 2s$, and any $u \in H^s(\mathbb{R}^N)$. In the following we will denote the critical fractional Sobolev exponent $2_s^* = \frac{2N}{N-2s}$.

Remark 2.2 When $r = 2_s^*$, the best constant in (2.10) will be denoted by $S(s, N)$. This constant is explicit and independent of the domain; its exact value is

$$S(s, N) = \frac{2\pi^s \Gamma(\frac{N+2s}{2}) \Gamma(1-s) (\Gamma(\frac{N}{2}))^{\frac{2s}{N}}}{\Gamma(s) \Gamma(\frac{N-2s}{2}) (\Gamma(N))^s}.$$

So we have

$$\int_{\mathbb{R}_+^{N+1}} y^{1-2s} |\nabla z(x, y)|^2 dx dy \geq S(s, N) \left(\int_{\mathbb{R}^N} |z(x, 0)|^{\frac{2N}{N-2s}} dx \right)^{\frac{N-2s}{N}}, \quad (2.12)$$

for any $z \in X_0^s(\mathbb{R}_+^{N+1})$. This will be used in Section 4, the best constant in (2.11) is then $k_s S(s, N)$.

Recall that we say that $u \in H^s(\mathbb{R}^N)$ is a weak solution of (2.6) if

$$\int_{\mathbb{R}^N} (-\Delta)^{\frac{s}{2}} u (-\Delta)^{\frac{s}{2}} \varphi dx + \int_{\mathbb{R}^N} V(\varepsilon x) u \varphi dx = \int_{\mathbb{R}^N} W(\varepsilon x) f(u) \varphi dx, \quad (2.13)$$

for all $\varphi \in H^s(\mathbb{R}^N)$.

First of all, under our assumptions, we have the following lemma.

Lemma 2.1 *Any weak solution $u \in H^s(\mathbb{R}^N)$ of (2.6) or (2.7) is positive.*

Proof Since $f(t) = 0$ on \mathbb{R}^- , choosing $\varphi = u^- \in H^s(\mathbb{R}^N)$ in the variational formulation (2.13) yields

$$\begin{aligned} \int_{\mathbb{R}^N} (-\Delta)^{\frac{s}{2}} u (-\Delta)^{\frac{s}{2}} u^- dx &= - \int_{\mathbb{R}^N} V(\varepsilon x) u u^- dx + \int_{\mathbb{R}^N} W(\varepsilon x) f(u) u^- dx \\ &= \int_{\mathbb{R}^N} V(\varepsilon x) (u^-)^2 dx. \end{aligned}$$

Hence, it follows from the definition (2.2) of $(-\Delta)^s u$,

$$\begin{aligned} &\int_{\mathbb{R}^N} (-\Delta)^{\frac{s}{2}} u (-\Delta)^{\frac{s}{2}} u^- dx \\ &= \int_{\mathbb{R}^N} u^- (-\Delta)^s u^- dx - |(-\Delta)^{\frac{s}{2}} u^-|_2^2 \\ &= \frac{C_{N,s}}{2} \int_{\mathbb{R}^N} \int_{\mathbb{R}^N} \frac{(u^+(x) - u^+(y))(u^-(x) - u^-(y))}{|x - y|^{N+2s}} dx dy - |(-\Delta)^{\frac{s}{2}} u^-|_2^2 \\ &= -C_{N,s} \int_{\mathbb{R}^N} \int_{\mathbb{R}^N} \frac{u^+(x) u^-(y)}{|x - y|^{N+2s}} dx dy - |(-\Delta)^{\frac{s}{2}} u^-|_2^2 \leq -\|(-\Delta)^{\frac{s}{2}} u^-\|_2^2. \end{aligned}$$

In turn, we get $\|u^-\|_\varepsilon^2 = |(-\Delta)^{\frac{s}{2}} u^-|_2^2 + \int_{\mathbb{R}^N} V(\varepsilon x) (u^-)^2 dx \leq 0$, namely $u^- = 0$, hence the weak solution $u \in H^s(\mathbb{R}^N)$ for (2.6) is nonnegative. Moreover, u cannot vanish at an interior point as follows from the maximum principle [21]. This completes the proof. \square

3 Study of the nonlocal superlinear problem (1.1)

In this section, we will prove Theorem 1.1. We only need to give the details for (B) because the argument for (A) is similar to that for (B).

Suppose that (f_1) – (f_4) hold and let (P_0) and (P_1) (ii) be satisfied; without loss of generality, we assume that $x_w = 0 \in \mathcal{W}$ ($x_w = 0 \in \mathcal{V} \cap \mathcal{W}$ if $\mathcal{V} \cap \mathcal{W} \neq \emptyset$) and $a := V(0) = \min_{y \in \mathcal{W}} V(y) \leq V(x)$ for all $|x| \geq R$, then $V(0) = a$, $W(0) = \kappa$. We remark by (P_0) that $V_\varepsilon(x) \rightarrow V(0) = a$, $W_\varepsilon(x) \rightarrow W(0) = \kappa$ uniformly on bounded sets of \mathbb{R}^N as $\varepsilon \rightarrow 0$.

Before proving the main results, we denote the Nehari manifold, the critical set, the least energy, and the set of least energy solutions of I_ε as follows:

$$\mathcal{N}_\varepsilon := \{u \in H^s \setminus \{0\} : I'_\varepsilon(u)u = 0\},$$

$$\mathcal{H}_\varepsilon := \{u \in H^s : I'_\varepsilon(u) = 0\},$$

$$\gamma_\varepsilon := \inf_{u \in \mathcal{N}_\varepsilon} I_\varepsilon(u),$$

$$\mathcal{R}_\varepsilon := \{u \in \mathcal{H}_\varepsilon : I_\varepsilon(u) = \gamma_\varepsilon\}.$$

Observe that, in virtue of (f₄), we have

$$F(t) \geq a_1|t|^\mu - a_2|t|^2, \quad \text{for all } t \geq 0. \quad (3.1)$$

By (f₁) and (f₃), for any $\delta > 0$, there is $C_\delta > 0$ such that

$$F(t) \leq \delta|t|^2 + C_\delta|t|^p, \quad \text{for all } t \in \mathbb{R}. \quad (3.2)$$

These inequalities imply $\mu \leq p$. Setting $\widehat{F}(t) := \frac{1}{2}f(t)t - F(t)$, we have

$$\widehat{F}(t) \geq \frac{\mu-2}{2\mu}f(t)t \geq \frac{\mu-2}{2}F(t). \quad (3.3)$$

3.1 The function I_ε

In this subsection, we are going to establish some results for the function I_ε .

It is easy to check by (3.1) and (3.2) that functional I_ε possesses the mountain-pass structure.

Lemma 3.1 *There exist $\alpha > 0$ and an open set $B \subset H^s(\mathbb{R}^N)$ (both independent of ε), such that:*

- (i) $I_\varepsilon(u) \geq \alpha$ for $u \in \partial B$;
- (ii) $\lim_{t \rightarrow +\infty} I_\varepsilon(tu) = -\infty$ if $u(x) \geq 0$, $u \neq 0$.

Consequently, let us consider the family

$$\Gamma_\varepsilon := \{\gamma \in C([0,1], H^s(\mathbb{R}^N)) : \gamma(0) = 0, I_\varepsilon(\gamma(1)) < 0\},$$

and the minimax schemes $c_\varepsilon := \inf_{\gamma \in \Gamma_\varepsilon} \max_{t \in [0,1]} I_\varepsilon(\gamma(t))$. Moreover, there is $\bar{c} > 0$ independent of ε such that $\alpha \leq c_\varepsilon < \bar{c}$.

Using a standard argument as in the classical case in [18, 22], we have the following.

Lemma 3.2 $c_\varepsilon = \inf_{u \in H^s(\mathbb{R}^N) \setminus \{0\}} \max_{t \geq 0} I_\varepsilon(tu) = \inf_{u \in \mathcal{N}_\varepsilon} I_\varepsilon(u)$.

The following lemma is clear by the assumptions.

Lemma 3.3

- (i) For each $u \in H^s(\mathbb{R}^N) \setminus \{0\}$, there is a unique $t_\varepsilon = t_\varepsilon(u) > 0$ such that $t_\varepsilon u \in \mathcal{N}_\varepsilon$.
- (ii) Moreover, there is $T > 0$ independent of $\varepsilon > 0$ such that $t_\varepsilon < T$.

Proof Since the proof of (i) is standard, we only need to prove (ii).

Indeed, by (i), for any fixed $u \in H^s(\mathbb{R}^N) \setminus \{0\}$, there exists unique $t_\varepsilon u \in \mathcal{N}_\varepsilon$ so that

$$\begin{aligned} C_1 t_\varepsilon^2 \|u\|^2 &\geq \|t_\varepsilon u\|_\varepsilon^2 = \int_{\mathbb{R}^N} W(\varepsilon x) f(t_\varepsilon u) t_\varepsilon u \, dx \\ &\geq C_2 \inf W \cdot t_\varepsilon^\mu |u|_\mu^\mu - C_3 \inf W \cdot t_\varepsilon^2 |u|_2^2 \quad (\mu > 2). \end{aligned}$$

This proves that there is $T > 0$ only dependent of u such that $t_\varepsilon \leq T$. This completes the proof. \square

Lemma 3.4 *There is $\theta > 0$ independent of $\varepsilon \in (0, 1)$ such that $\|u\|_{H^s} \geq \theta$ for all $u \in \mathcal{N}_\varepsilon$.*

Proof Since $V(x) \geq \tau$, there is $\gamma_1 > 0$ independent of ε such that

$$\gamma_1 \|u\|_{H^s}^2 \leq \int_{\mathbb{R}^N} (|(-\Delta)^{\frac{s}{2}} u|^2 + V_\varepsilon(x) |u|^2) \, dx, \quad \text{for all } u \in H^s(\mathbb{R}^N).$$

Since $W(x) \leq \kappa$, it follows from (3.2) that, for any $\delta > 0$, there is C_δ independent of ε such that, for all $u \in H^s(\mathbb{R}^N)$,

$$\int_{\mathbb{R}^N} W_\varepsilon(x) f(u) \, dx \leq C_1 \delta \|u\|_{H^s}^2 + C_2 C_\delta \|u\|_{H^s}^p.$$

Now, for $u \in \mathcal{N}_\varepsilon$,

$$\gamma_1 \|u\|_{H^s}^2 \leq \|u\|_\varepsilon^2 = \int_{\mathbb{R}^N} W_\varepsilon(x) f(u) \, dx \leq C_1 \delta \|u\|_{H^s}^2 + C_2 C_\delta \|u\|_{H^s}^p,$$

taking $\delta = \frac{\gamma_1}{2C_1}$, there is $\theta > 0$ independent of ε such that $\|u\|_{H^s} \geq \theta$. Thus we complete the proof. \square

For any $a > 0$, $b > 0$, consider the constant coefficient equation

$$(-\Delta)^s u + au = bf(u), \quad u \in H^s(\mathbb{R}^N). \quad (3.4)$$

The solutions of (3.4) are critical points of the functional

$$I_{ab}(u) = \frac{1}{2} |(-\Delta)^{\frac{s}{2}} u|_2^2 + \frac{a}{2} |u|_2^2 - b \int_{\mathbb{R}^N} F(u) \, dx,$$

defined for $u \in H^s(\mathbb{R}^N)$. Let γ_{ab} be the mountain-pass level and \mathcal{N}_{ab} the Nehari manifold of I_{ab} .

The following lemma is similar to the one of [18].

Lemma 3.5 *For equation (3.4) we have:*

- (i) $\mathcal{H}_{ab} := \{u \in H^s(\mathbb{R}^N) \setminus \{0\} : I'_{ab}(u) = 0\} \neq \emptyset$.
- (ii) $\gamma_{ab} = \inf\{I_{ab}(u) : u \in \mathcal{N}_{ab}\} = \inf\{I_{ab}(u) : u \in \mathcal{H}_{ab} \setminus \{0\}\}$.
- (iii) γ_{ab} is attained.
- (iv) Let $a_j > 0$ and $b_j > 0$ ($j = 1, 2$) with $\min\{a_2 - a_1, b_1 - b_2\} \geq 0$, then $\gamma_{a_1 b_1} \leq \gamma_{a_2 b_2}$. If additionally, $\min\{a_2 - a_1, b_1 - b_2\} > 0$, then $\gamma_{a_1 b_1} < \gamma_{a_2 b_2}$.

Next, we state the regularity results whose proofs are the same as the ones in [23].

Lemma 3.6 *Suppose that $u \in H^s(\mathbb{R}^N)$ is a weak solution to (3.4) and f satisfies conditions (f_1) – (f_4) . Then $u \in L^q(\mathbb{R}^N)$ for all $q \in [2, +\infty)$ and $u \in C^{0,\mu}(\mathbb{R}^N)$ for some $\mu \in (0, 1)$. Moreover, $|u(x)| \rightarrow 0$ as $|x| \rightarrow \infty$.*

Using the same iterative argument as for Lemma 3.6, we obtain $u_\varepsilon \in \bigcap_{q \geq 2} W^{s,q}(\mathbb{R}^N)$.

Using Lemma 3.5, we have the following energy comparison between c_ε and γ_{ak} , which will be useful for the existence and concentration results.

Lemma 3.7 $\limsup_{\varepsilon \rightarrow 0} c_\varepsilon \leq \gamma_{ak}$.

Proof Denote $V^c(x) = \max\{c, V(x)\}$, $W^d(x) = \min\{d, W(x)\}$, $V_\varepsilon^c(x) = V^c(\varepsilon x)$, and $W_\varepsilon^d(x) = W^d(\varepsilon x)$, where c, d are positive constants.

Define the auxiliary functional as follows:

$$I_\varepsilon^{cd}(u) := \frac{1}{2} |(-\Delta)^{\frac{s}{2}} u|_2^2 + \frac{1}{2} \int_{\mathbb{R}^N} V_\varepsilon^c(x) |u|^2 dx - \int_{\mathbb{R}^N} W_\varepsilon^d(x) F(u) dx,$$

for any $u \in H^s(\mathbb{R}^N)$, which implies that $I_\varepsilon(u) \leq I_\varepsilon^{cd}(u)$, and thus $\gamma_{cd} \leq c_\varepsilon^{cd}$, where c_ε^{cd} is the least energy of I_ε^{cd} . By the definition of τ and κ , we get $V_\varepsilon^\tau(x) = V_\varepsilon(x)$, $W_\varepsilon^\kappa(x) = W_\varepsilon(x)$. Therefore,

$$I_\varepsilon^{\tau\kappa}(u) = I_\varepsilon(u), \quad (3.5)$$

and $V_\varepsilon^\tau(x) \rightarrow V(0) = a$, $W_\varepsilon^\kappa(x) \rightarrow W(0) = \kappa$ uniformly on bounded sets of x as $\varepsilon \rightarrow 0$.

Now, we claim $\limsup_{\varepsilon \rightarrow 0} I_\varepsilon^{\tau\kappa}(u) \leq \gamma_{ak}$.

Indeed, let e is a ground state of I_{ak} , that is, $I_{ak}(e) = \gamma_{ak}$, there exists $t_\varepsilon > 0$ such that $t_\varepsilon e \in \mathcal{N}_\varepsilon^{\tau\kappa}$ for sufficiently small ε , where $\mathcal{N}_\varepsilon^{\tau\kappa}$ is Nehari manifold for function $I_\varepsilon^{\tau\kappa}$. Thus

$$c_\varepsilon^{\tau\kappa} \leq I_\varepsilon^{\tau\kappa}(t_\varepsilon e) = \max_{t \geq 0} I_\varepsilon^{\tau\kappa}(te).$$

One has

$$I_\varepsilon^{\tau\kappa}(t_\varepsilon e) = I_{ak}(t_\varepsilon e) + \frac{1}{2} \int_{\mathbb{R}^N} (V_\varepsilon^\tau(x) - a) |t_\varepsilon e|^2 dx + \int_{\mathbb{R}^N} (\kappa - W_\varepsilon^\kappa(x)) F(t_\varepsilon e) dx. \quad (3.6)$$

We can assume that $t_\varepsilon \rightarrow t_0$ (as $\varepsilon \rightarrow 0$) by Lemma 3.3. This, together with the decay of $t_0 e$, implies

$$\int_{\mathbb{R}^N} (V_\varepsilon^\tau(x) - a) |t_\varepsilon e|^2 dx = o(1)$$

and

$$\int_{\mathbb{R}^N} (\kappa - W_\varepsilon^\kappa(x)) F(t_\varepsilon e) dx = o(1).$$

Notice from (3.6) that

$$I_\varepsilon^{\tau\kappa}(t_\varepsilon e) = I_{ak}(t_\varepsilon e) + o(1) \rightarrow I_{ak}(t_0 e) \quad \text{as } \varepsilon \rightarrow 0.$$

Consequently

$$c_\varepsilon^{\tau_K} \leq I_\varepsilon^{\tau_K}(t_\varepsilon e) \rightarrow I_{ak}(t_0 e) \leq \max_{t \geq 0} I_{ak}(te) = I_{ak}(e) = \gamma_{ak}.$$

From (3.5), we obtain $c_\varepsilon^{\tau_K} = c_\varepsilon$. Thus, we complete the proof. \square

3.2 Existence results

Lemma 3.8 c_ε is attained at some $u_\varepsilon \in \mathcal{R}_\varepsilon$ for all small $\varepsilon > 0$.

Proof Given $\varepsilon > 0$, let $u_k \in \mathcal{N}_\varepsilon$ be a minimizing sequence of I_ε , which is clearly a $(PS)_{c_\varepsilon}$ sequence for $I_\varepsilon: I_\varepsilon(u_k) \rightarrow c_\varepsilon$ and $I'_\varepsilon(u_k) \rightarrow 0$ as $k \rightarrow \infty$. It is easy to see that $\{u_k\}$ is bounded in $H^s(\mathbb{R}^N)$. Assume that $u_k \rightharpoonup u_\varepsilon \in \mathcal{H}_\varepsilon$ in $H^s(\mathbb{R}^N)$. If $u_\varepsilon \neq 0$, then clearly $I_\varepsilon(u_\varepsilon) = c_\varepsilon$.

Next we check that $u_\varepsilon \neq 0$ for all $\varepsilon > 0$ small.

Assume that there exists a sequence $\varepsilon_j \rightarrow 0$ with $u_{\varepsilon_j} = 0$, then $u_k \rightharpoonup 0$ in $H^s(\mathbb{R}^N)$, and thus $u_k \rightarrow 0$ in L^p_{loc} for $q \in (1, 2_s^*)$ and $u_k(x) \rightarrow 0$ a.e. in $x \in \mathbb{R}^N$.

Choose by (P₁)(ii) $b \in (\kappa_\infty, \kappa)$ and consider the functional I_ε^{ab} , let $t_k > 0$ be such that $t_k u_k \in \mathcal{N}_\varepsilon^{ab}$, this implies that $t_k \leq C$ for some constant $C > 0$. Assume $t_k \rightarrow t_0$ as $k \rightarrow \infty$. By (P₁)(ii), the set $O_\varepsilon := \{x \in \mathbb{R}^N : V_\varepsilon(x) < a \text{ or } W_\varepsilon(x) \geq b\}$ is bounded. Remark that $I_{\varepsilon_j}(t_k u_k) \leq I_{\varepsilon_j}(u_k)$. We obtain

$$\begin{aligned} c_{\varepsilon_j}^{ab} &\leq I_{\varepsilon_j}^{ab}(t_k u_k) \\ &= I_{\varepsilon_j}(t_k u_k) + \frac{1}{2} \int_{\mathbb{R}^N} (V_{\varepsilon_j}^a(x) - V_{\varepsilon_j}(x)) |t_k u_k|^2 dx \\ &\quad + \int_{\mathbb{R}^N} (W_{\varepsilon_j}(x) - W_{\varepsilon_j}^b(x)) F(t_k u_k) dx \\ &= I_{\varepsilon_j}(t_k u_k) + \frac{1}{2} \int_{O_{\varepsilon_j}} (a - V_{\varepsilon_j}(x)) |t_k u_k|^2 dx \\ &\quad + \int_{O_{\varepsilon_j}} (W_{\varepsilon_j}(x) - b) F(t_k u_k) dx \\ &\leq I_{\varepsilon_j}(t_k u_k) + o(1) \leq I_{\varepsilon_j}(u_k) + o(1) = c_{\varepsilon_j}. \end{aligned}$$

Notice that $\gamma_{ab} \leq c_{\varepsilon_j}^{ab}$, hence $\gamma_{ab} \leq c_{\varepsilon_j}$. In virtue of Lemma 3.7, letting $\varepsilon_j \rightarrow 0$ yields

$$\gamma_{ab} \leq \gamma_{ak},$$

which contradicts $\gamma_{ak} < \gamma_{ab}$ (see Lemma 3.5(iv)). Therefore, c_ε is attained at $0 \neq u_\varepsilon \in \mathcal{R}_\varepsilon$, which ends the proof. \square

3.3 Concentration and convergence of ground state

Lemma 3.9 Assume that (f₁)-(f₄), (P₀), (P₁)(ii) and for all ε sufficiently small, let $u_\varepsilon \in \mathcal{R}_\varepsilon$, then u_ε possesses a (global) maximum x_ε such that $\lim_{\varepsilon \rightarrow 0} \text{dist}(\varepsilon x_\varepsilon, \mathcal{A}_w) = 0$, and for any sequence $\varepsilon x_\varepsilon \rightarrow x_0$, $v_\varepsilon(x) := u_\varepsilon(x + x_\varepsilon)$ converges in $H^s(\mathbb{R}^N)$ to $u(x)$, which is a least energy solution of

$$(-\Delta)^s u + V(x_0)u = W(x_0)f(u).$$

In particular, $\mathcal{V} \cap \mathcal{W} \neq \emptyset$, then $\lim_{\varepsilon \rightarrow 0} \text{dist}(\varepsilon x_\varepsilon, \mathcal{V} \cap \mathcal{W}) = 0$, and up to subsequences, v_ε converges in $H^s(\mathbb{R}^N)$ to u being a least energy solution of

$$(-\Delta)^s u + \tau u = \kappa f(u).$$

Remark The proof of this lemma will be lengthy but will be along the main lines of the proof of the corresponding results in the classical case in [18, 22]. We shall first show that there exists a sequence of points $\{x_\varepsilon\}$ in \mathbb{R}^N such that (i) most of the ‘mass’ of u_ε is contained in a ball (of fixed size) centered at x_ε and (ii) $\varepsilon x_\varepsilon$ is bounded. This will be done in Step 1 and Step 2. Then in Step 3, we show that any limit point of $\varepsilon x_\varepsilon$ belongs to \mathcal{A}_W , and Step 4 together with Step 1 shows that $u_\varepsilon(x + x_\varepsilon)$ converges to the least energy solution of corresponding limit equation. Furthermore, Step 5 tells us such solution u_ε is at least a singular peak bound state.

Proof Step 1. Let $u_\varepsilon \in H^s(\mathbb{R}^N)$ be the critical point of I_ε so that $I_\varepsilon(u_\varepsilon) = c_\varepsilon$, we see that $\{u_\varepsilon\}$ is a bounded set in $H^s(\mathbb{R}^N)$. A concentration argument and Lemma 3.4 show that there exist a sequence $\{x_\varepsilon\} \subset \mathbb{R}^N$ and constants $R > 0$, $\sigma > 0$ such that $\lim_{\varepsilon \rightarrow 0} \int_{B_R(x_\varepsilon)} u_\varepsilon^2 \geq \sigma$.

Set $v_\varepsilon(x) := u_\varepsilon(x + x_\varepsilon)$, then v_ε satisfies

$$(-\Delta)^s v_\varepsilon + \widehat{V}_\varepsilon(x) v_\varepsilon = \widehat{W}_\varepsilon(x) f(v_\varepsilon), \quad (3.7)$$

where $\widehat{V}_\varepsilon(x) = V(\varepsilon(x + x_\varepsilon))$, $\widehat{W}_\varepsilon(x) = W(\varepsilon(x + x_\varepsilon))$, with energy

$$\begin{aligned} \widehat{I}_\varepsilon(v_\varepsilon) &= \frac{1}{2} |(-\Delta)^{\frac{s}{2}} v_\varepsilon|_2^2 + \frac{1}{2} \int_{\mathbb{R}^N} \widehat{V}_\varepsilon(x) v_\varepsilon^2 - \int_{\mathbb{R}^N} \widehat{W}_\varepsilon(x) F(v_\varepsilon) \\ &= \widehat{I}_\varepsilon(v_\varepsilon) - \frac{1}{2} \widehat{I}'_\varepsilon(v_\varepsilon) v_\varepsilon \\ &= \int_{\mathbb{R}^N} \widehat{W}_\varepsilon(x) \left(\frac{1}{2} f(v_\varepsilon) v_\varepsilon - F(v_\varepsilon) \right) \\ &= I_\varepsilon(u_\varepsilon) - \frac{1}{2} I'_\varepsilon(u_\varepsilon) u_\varepsilon = I_\varepsilon(u_\varepsilon) = c_\varepsilon. \end{aligned}$$

We may assume $v_\varepsilon \rightharpoonup u$ in $H^s(\mathbb{R}^N)$, and $v_\varepsilon \rightarrow u$ in L^q_{loc} for $q \in [1, 2^*)$ with $u \neq 0$.

By $V, W \in L^\infty$, without loss of generality, we may assume that $V(\varepsilon x_\varepsilon) \rightarrow V_0$ and $W(\varepsilon x_\varepsilon) \rightarrow W_0$ as $\varepsilon \rightarrow 0$. Furthermore, since V, W are uniformly continuous, for any $x \in B_r(0)$, one has

$$|V(\varepsilon(x + x_\varepsilon)) - V(\varepsilon x_\varepsilon)| \rightarrow 0 \quad \text{and} \quad |W(\varepsilon(x + x_\varepsilon)) - W(\varepsilon x_\varepsilon)| \rightarrow 0.$$

Therefore $\widehat{V}_\varepsilon(x) \rightarrow V_0$ and $\widehat{W}_\varepsilon(x) \rightarrow W_0$ as $\varepsilon \rightarrow 0$ uniformly on bounded sets of $x \in \mathbb{R}^N$. Consequently, by (3.7), for any $\varphi \in C_0^\infty(\mathbb{R}^N)$,

$$\begin{aligned} 0 &= \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^N} ((-\Delta)^s v_\varepsilon + \widehat{V}_\varepsilon(x) v_\varepsilon - \widehat{W}_\varepsilon(x) f(v_\varepsilon)) \varphi \, dx \\ &= \int_{\mathbb{R}^N} ((-\Delta)^s u + V_0 u - W_0 f(u)) \varphi \, dx, \end{aligned}$$

which implies that u solves

$$(-\Delta)^s u + V_0 u = W_0 f(u), \quad (3.8)$$

with the energy

$$\begin{aligned} I_{V_0 W_0}(u) &:= \frac{1}{2} |(-\Delta)^{\frac{s}{2}} u|_2^2 + \frac{1}{2} V_0 \int_{\mathbb{R}^N} u^2 - W_0 \int_{\mathbb{R}^N} F(u) \\ &= \int_{\mathbb{R}^N} W_0 \left(\frac{1}{2} f(u) u - F(u) \right) \geq \gamma_{V_0 W_0}. \end{aligned}$$

By Fatou's lemma and Lemma 3.7,

$$\begin{aligned} \gamma_{V_0 W_0} &\leq \int_{\mathbb{R}^N} W_0 \left(\frac{1}{2} f(u) u - F(u) \right) \\ &\leq \liminf_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^N} \widehat{W}_\varepsilon(x) \left(\frac{1}{2} f(v_\varepsilon) v_\varepsilon - F(v_\varepsilon) \right) \\ &= \liminf_{\varepsilon \rightarrow 0} \widehat{I}_\varepsilon(v_\varepsilon) \leq \limsup_{\varepsilon \rightarrow 0} I_\varepsilon(u_\varepsilon) \leq \gamma_{V_0 W_0}. \end{aligned}$$

Therefore,

$$\lim_{\varepsilon \rightarrow 0} \widehat{I}_\varepsilon(v_\varepsilon) = \lim_{\varepsilon \rightarrow 0} c_\varepsilon = I_{V_0 W_0} \quad \text{and} \quad \Gamma_{V_0 W_0}(u) = \gamma_{V_0 W_0}. \quad (3.9)$$

As a consequence, u is the least energy solution of the limit equation (3.8).

Step 2. $\{\varepsilon x_\varepsilon\}$ is bounded.

Assume that $\varepsilon |x_\varepsilon| \rightarrow +\infty$, by $V(\varepsilon x_\varepsilon) \rightarrow V_0$, $a = V(0) \leq V(x)$, $|x| \geq R$, and $W(\varepsilon x_\varepsilon) \rightarrow W_0$, $\kappa = \max W$, we deduce that $V_0 \geq a$ and $W_0 \leq \kappa$. So it follows from Lemma 3.5 that $\gamma_{V_0 W_0} > \gamma_{a\kappa}$.

However, by Step 1 and Lemma 3.7, $c_\varepsilon \rightarrow \gamma_{V_0 W_0} \leq \gamma_{a\kappa}$, a contradiction. Therefore, we can assume $\varepsilon x_\varepsilon \rightarrow x_0$ (as $\varepsilon \rightarrow 0$), then $V_0 = V(x_0)$, $W_0 = W(x_0)$, and we read (3.8) as

$$(-\Delta)^s u + V(x_0)u = W(x_0)f(u),$$

where u is the least energy solution.

Step 3. $\varepsilon x_\varepsilon \rightarrow \mathcal{A}_w$ as $\varepsilon \rightarrow 0$, that is, $x_0 \in \mathcal{A}_w$.

Assume that $x_0 \notin \mathcal{A}_w$, by the definition of \mathcal{A}_w , we have $V(x_0) > V(0) = a$, which, combined with $W(x_0) < \kappa$, leads to $\gamma_{V(x_0)W(x_0)} > \gamma_{a\kappa}$. However, by Lemma 3.7,

$$\lim_{\varepsilon \rightarrow 0} c_\varepsilon = \gamma_{V(x_0)W(x_0)} > \gamma_{a\kappa} \geq \lim_{\varepsilon \rightarrow 0} c_\varepsilon,$$

a contradiction.

Step 4. Let v_ε, u be defined in Step 1, then $v_\varepsilon \rightarrow u$ in $H^s(\mathbb{R}^N)$.

It suffices to prove that there is a subsequence $\{v_{\varepsilon_j}\}$ so that $v_{\varepsilon_j} \rightarrow u$ in $H^s(\mathbb{R}^N)$.

Recall that, as the argument shows, u is a least energy solution to

$$(-\Delta)^s u + V(x_0)u = W(x_0)f(u).$$

Let $\eta \in C_0^\infty(\mathbb{R}_+^{N+1})$ be a nonincreasing cut-off function verifying $\eta = 1$ in $B_1^+(0)$, $\eta = 0$ in $B_2^+(0)^c$. Let now $w_j(x, y) = \eta(\frac{2|x|}{j}, y)\tilde{u}(x, y)$, where $\text{Tr}(\tilde{u}) = u$. One has $w_j(x, 0) \rightarrow u(x)$ in $H^s(\mathbb{R}^N)$ and $w_j(x, 0) \rightarrow u(x)$ in L^q , $q \in [2, 2_s^*)$. Denote $\tilde{z}_j(x, y) = \tilde{v}_{\varepsilon_j}(x, y) - w_j(x, y)$, where $\text{Tr}(\tilde{z}_j) = z_j$, $\text{Tr}(\tilde{v}_{\varepsilon_j}) = v_{\varepsilon_j}$, $\text{Tr}(w_j) = w_j(x, 0)$.

Next we prove $z_j \rightarrow 0$ in $H^s(\mathbb{R}^N)$.

Firstly, we remark that $\{z_j\}$ is bounded in $H^s(\mathbb{R}^N)$ and using similar argument to [22], one has

$$\lim_{j \rightarrow \infty} \left| \int_{\mathbb{R}^N} \widehat{W}_{\varepsilon_j}(x) (F(\tilde{v}_{\varepsilon_j}) - F(\tilde{z}_j) - F(w_j)) dx \right| = 0 \quad (3.10)$$

and

$$\lim_{j \rightarrow \infty} \left| \int_{\mathbb{R}^N} \widehat{W}_{\varepsilon_j}(x) (f(\tilde{v}_{\varepsilon_j}) - f(\tilde{z}_j) - f(w_j)) \phi dx \right| = 0, \quad (3.11)$$

uniformly in $\phi \in X_0^s(R_+^{N+1})$ with $\|\phi\|_{X_0^s(\mathbb{R}_+^{N+1})} \leq 1$. By the decay of u , (3.10), (3.11), and the facts that $\widehat{V}_{\varepsilon_j}(x) \rightarrow V(x_0)$, $\widehat{W}_{\varepsilon_j}(x) \rightarrow W(x_0)$ as $j \rightarrow \infty$ uniformly on bounded sets of x , one checks directly the following:

$$\begin{aligned} \hat{J}_{\varepsilon_j}(\tilde{z}_j) &= \frac{k_s}{2} \int_{\mathbb{R}_+^{N+1}} y^{1-2s} \langle \nabla \tilde{z}_j, \nabla \tilde{z}_j \rangle dx dy + \frac{1}{2} \int_{\mathbb{R}^N} \widehat{V}_{\varepsilon_j}(x) \langle \tilde{z}_j, \tilde{z}_j \rangle dx \\ &\quad - \int_{\mathbb{R}^N} \widehat{W}_{\varepsilon_j}(x) F(\tilde{z}_j) dx \\ &= \frac{k_s}{2} \int_{\mathbb{R}_+^{N+1}} y^{1-2s} (|\nabla \tilde{v}_{\varepsilon_j}|^2 - 2 \langle \nabla \tilde{v}_{\varepsilon_j}, \nabla w_j \rangle + |\nabla w_j|^2) dx dy \\ &\quad + \frac{1}{2} \int_{\mathbb{R}^N} \widehat{V}_{\varepsilon_j}(x) (|\tilde{v}_{\varepsilon_j}|^2 - 2 \tilde{v}_{\varepsilon_j} w_j + w_j^2) dx - \int_{\mathbb{R}^N} \widehat{W}_{\varepsilon_j}(x) F(\tilde{z}_j) dx \\ &= \hat{J}_{\varepsilon_j}(\tilde{v}_{\varepsilon_j}) - \Gamma_{V_0 W_0}(\tilde{u}) + \int_{\mathbb{R}^N} \widehat{W}_{\varepsilon_j}(x) (F(\tilde{v}_{\varepsilon_j}) - F(\tilde{z}_j) - F(w_j)) dx \\ &\quad + o(1) = o(1) \end{aligned}$$

as $j \rightarrow \infty$, which implies that $\hat{J}_{\varepsilon_j}(\tilde{z}_j) \rightarrow 0$, and thus $\hat{I}_{\varepsilon_j}(z_j) \rightarrow 0$, where \hat{J}_{ε_j} is the extension function of the problem as in (2.7) corresponding to \hat{I}_{ε_j} .

Similarly,

$$\begin{aligned} \hat{J}'_{\varepsilon_j}(\tilde{z}_j)\phi &= k_s \int_{\mathbb{R}_+^{N+1}} y^{1-2s} \langle \nabla \tilde{z}_j, \nabla \phi \rangle dx dy + \int_{\mathbb{R}^N} \widehat{V}_{\varepsilon_j}(x) \langle \tilde{z}_j, \phi \rangle dx \\ &\quad - \int_{\mathbb{R}^N} \widehat{W}_{\varepsilon_j}(x) f(\tilde{z}_j) \phi dx \\ &= \hat{J}'_{\varepsilon_j}(\tilde{v}_{\varepsilon_j})\phi - k_s \int_{\mathbb{R}_+^{N+1}} y^{1-2s} \langle \nabla w_j, \nabla \phi \rangle dx dy - \int_{\mathbb{R}^N} \widehat{V}_{\varepsilon_j}(x) \langle w_j, \phi \rangle dx \\ &\quad + \int_{\mathbb{R}^N} \widehat{W}_{\varepsilon_j}(x) (f(\tilde{v}_{\varepsilon_j}) - f(\tilde{z}_j)) \phi dx \\ &= o(1) + \int_{\mathbb{R}^N} \widehat{W}_{\varepsilon_j}(x) (f(\tilde{v}_{\varepsilon_j}) - f(\tilde{z}_j) - f(w_j)) \phi dx = o(1) \end{aligned}$$

as $j \rightarrow \infty$ uniformly in $\|\phi\|_{X_0^s(\mathbb{R}^{N+1})} \leq 1$, which implies $\hat{J}'_{\varepsilon_j}(\tilde{z}_j) \rightarrow 0$, and thus $\hat{I}'_{\varepsilon_j}(z_j) \rightarrow 0$. Therefore,

$$o(1) = \hat{I}_{\varepsilon_j}(z_j) - \frac{1}{\mu} \hat{I}'_{\varepsilon_j}(z_j) z_j \geq \left(\frac{1}{2} - \frac{1}{\mu} \right) \|z_j\|_{\varepsilon}.$$

Consequently, $z_j \rightarrow 0$ in $H^s(\mathbb{R}^N)$.

Step 5. $v_{\varepsilon}(x) \rightarrow 0$ as $|x| \rightarrow \infty$ uniformly for all small ε .

Since $u, v_{\varepsilon} \in \bigcap_{q \geq 2} W^{s,q}(\mathbb{R}^N)$ and $v_{\varepsilon} \rightarrow u$ in $H^s(\mathbb{R}^N) = W^{s,2}(\mathbb{R}^N)$, for any $r \in (2, q)$, we infer that

$$\|v_{\varepsilon} - u\|_{L^r} \leq \|v_{\varepsilon} - u\|_{L^2}^{1-\lambda} \cdot \|v_{\varepsilon} - u\|_{L^q}^{\lambda},$$

where $\frac{1-\lambda}{2} + \frac{\lambda}{q} = \frac{1}{r}$.

Therefore,

$$\|v_{\varepsilon} - u\|_{W^{s,r}} \leq C \|v_{\varepsilon} - u\|_{W^{s,2}}^{\theta} \cdot \|v_{\varepsilon} - u\|_{W^{s,q}}^{1-\theta},$$

for some constant $C > 0$ and $\theta > 0$.

Consequently, $v_{\varepsilon} - u \rightarrow 0$ in $\bigcap_{q \geq 2} W^{s,q}(\mathbb{R}^N)$. Moreover, by a Sobolev embedding, $W^{s,q}(\mathbb{R}^N) \hookrightarrow C^{0,\alpha}(\mathbb{R}^N)$ (for q large enough), we deduce that $v_{\varepsilon} - u \rightarrow 0$ in $C^{0,\alpha}(\mathbb{R}^N)$, it follows from the decay of u that $|v_{\varepsilon}(x)| \rightarrow 0$ as $|x| \rightarrow \infty$ uniformly in $\varepsilon > 0$. Thus, we complete the proof. \square

By virtue of Step 5, it is clear that one may assume the sequence $\{x_{\varepsilon}\}$ in Step 1 to be the maximum points of u_{ε} . Moreover, from the above argument, we readily see that any sequence of such points satisfies $\varepsilon x_{\varepsilon}$ converging to some point in \mathcal{A}_w as $\varepsilon \rightarrow 0$.

3.4 Decay estimates

Step 5 in the previous lemma shows a uniform decay estimate; unlike the classical case $s = 1$, we find suitable comparison functions as in [23] based on the Bessel kernel \mathcal{K} to see that the solution v_{ε} has a power-type decay at infinity instead of exponential.

Lemma 3.10 *There exist $0 < C_1 \leq C_2$ and $R > 1$ such that, for all small $\varepsilon > 0$,*

$$\frac{C_1}{|x - x_{\varepsilon}|^{N+2s}} \leq u_{\varepsilon}(x) \leq \frac{C_2}{|x - x_{\varepsilon}|^{N+2s}},$$

for all $|x| \geq R$.

Before starting to give proof, let us consider for $m > 0$ and $g \in L^2(\mathbb{R}^N)$ the equation

$$(-\Delta)^s \phi + m\phi = g, \quad \text{in } \mathbb{R}^N.$$

Then in terms of the Fourier transform, this problem, for $\phi \in L^2$, reads

$$(|\xi|^{2s} + m)\hat{\phi} = \hat{g}$$

and has a unique solution $\phi \in H^s(\mathbb{R}^N)$ given by the convolution

$$\phi(x) = \mathcal{K} * g = \int_{\mathbb{R}^N} \mathcal{K}(x-z)g(z) dz,$$

where \mathcal{K} is the fundamental solution of $(-\Delta)^s + m$, called the Bessel kernel,

$$\widehat{\mathcal{K}(\xi)} = \frac{1}{|\xi|^{2s} + m}.$$

Moreover, the decay properties of the kernel are obtained in [23] using the basic idea of [24, 25], that is,

$$\frac{C_1}{|x|^{N+2s}} \leq \mathcal{K}(x) \leq \frac{C_2}{|x|^{N+2s}}, \quad (3.12)$$

for $|x| \geq 1$ and $C_2 > C_1 > 0$.

Proof of Lemma 3.10 First of all, we have the following claim.

(i) There is a continuous function v_1 in \mathbb{R}^N satisfying

$$(-\Delta)^s v_1 + a v_1 = 0, \quad \text{if } |x| > 1 \quad (3.13)$$

and

$$v_1(x) \geq \frac{C_1}{|x|^{N+2s}}, \quad (3.14)$$

for an appropriate $C_1 > 0$, where $a = \sup \widehat{V}_\varepsilon(x)$.

(ii) There is a continuous function v_2 in \mathbb{R}^N satisfying

$$(-\Delta)^s v_2 + \tau v_2 = 0, \quad \text{if } |x| > 1 \quad (3.15)$$

and

$$v_2(x) \leq \frac{C_2}{|x|^{N+2s}}, \quad (3.16)$$

for an appropriate $C_2 > 0$, where $\tau < \inf V(x)$.

Indeed, consider the function $v_1 = \mathcal{K}_1 * \mathcal{X}_{B_1}$, where \mathcal{X}_{B_1} is the characteristic function of the unit ball B_1 , and $\mathcal{K}_1 = \mathcal{F}^{-1}(\frac{1}{a+|\xi|^{2s}})$ is a fundamental solution of $(-\Delta)^s + a$. Clearly v_1 satisfies equation (3.13) outside B_1 and the decaying estimate (3.14) thanks to (3.12).

Similarly, we consider the function $v = \mathcal{K}_2 * \mathcal{X}_{B_r}$, where B_r is the ball of radius $r = \tau^{\frac{1}{2s}}$ and $\mathcal{K}_2 = \mathcal{F}^{-1}(\frac{1}{1+|\xi|^{2s}})$ is a fundamental solution of $(-\Delta)^s + 1$. Then, by scaling, $v_2(x) = v(rx)$ satisfies equation (3.15) and using (3.12), we obtain (3.16).

By the continuity of v_ε and v_1 , there exists a constant $C_1 > 0$ so that $w_\varepsilon(y) = v_\varepsilon(y) - C_1 v_1(y) \geq 0$ in ∂B_1 . Moreover, $((-\Delta)^s + a)w_\varepsilon(y) \geq 0$ in B_1^c . By the maximum principle [20] we can conclude that $w_\varepsilon(y) \geq 0$ in B_1^c . As a consequence, $v_\varepsilon(y) \geq \frac{C_1}{|y|^{N+2s}}$ for $|y| \geq 1$, that is,

$$u_\varepsilon(x) \geq \frac{C_1}{|x - x_\varepsilon|^{N+2s}}.$$

On the other hand, the uniform decay estimate of v_ε in Lemma 3.9, Step 5, and (f_1) allows us to take $R_1 > 0$ sufficiently large such that

$$(-\Delta)^s v_\varepsilon + \tau v_\varepsilon = \widehat{W}_\varepsilon(x) f(v_\varepsilon) + (\tau - \widehat{V}_\varepsilon(x)) v_\varepsilon \leq 0, \quad \text{in } B_{R_1}^c,$$

now we consider the function v_2 and the claim we found, which satisfies (3.15) in B_1^c and then in $B_{R_1}^c$.

In view of the continuity of v_ε and v_2 , there exist constants $C_2 > C_1 > 0$ such that

$$w_\varepsilon(y) := v_\varepsilon(y) - C_2 v_2(y) \leq 0, \quad \text{in } \partial B_{R_1}.$$

Moreover,

$$((-\Delta)^s + \tau) w_\varepsilon(y) \leq 0, \quad \text{in } B_{R_1}^c.$$

Using a similar comparison argument, we conclude that $u_\varepsilon(x) \leq \frac{C_2}{|x - z_\varepsilon|^{N+2s}}$ for $|x| \geq R_1$ and all $\varepsilon > 0$ small. The proof is completed. \square

Proof of Theorem 1.1 (B) Define $\omega_\varepsilon(x) = u_\varepsilon(\frac{x}{\varepsilon})$. Then ω_ε is a solution of (1.1) for all $\varepsilon > 0$. Since z_ε is a maximum point of $|\omega_\varepsilon|$, we have

$$\frac{C_1 \varepsilon^{N+2s}}{|x - z_\varepsilon|^{N+2s}} \leq \omega_\varepsilon(x) \leq \frac{C_2 \varepsilon^{N+2s}}{|x - z_\varepsilon|^{N+2s}},$$

for some constants $0 < C_1 < C_2$, and

$$\lim_{\varepsilon \rightarrow 0} \text{dist}(z_\varepsilon, \mathcal{A}_W) = 0.$$

Then we proceed similarly to (A). \square

4 Study of the nonlocal critical problem (1.2)

In this section, we will prove Theorem 1.2. We only need to give the details for (A) because the argument for (B) is similar to that for (A).

Suppose that (f_1) – (f'_4) hold and let (P_0) and (P_1) (i) be satisfied; without loss of generality, we assume that $x_v = 0 \in \mathcal{V}$ ($x_v = 0 \in \mathcal{W} \cap \mathcal{V}$ if $\mathcal{V} \cap \mathcal{W} \neq \emptyset$) and $b := W(0) = \min_{y \in \mathcal{V}} W(y) \leq W(x)$ for all $|x| \geq R$, then $V(0) = \tau$, $W(0) = b$. We remark by (P_0) that $V_\varepsilon(x) \rightarrow V(0) = \tau$, $W_\varepsilon(x) \rightarrow W(0) = b$ uniformly on bounded sets of \mathbb{R}^N as $\varepsilon \rightarrow 0$.

Plainly one only verifies that I_ε^* possesses the mountain-pass structure as Lemma 3.1. As in Section 3 we define replacing I_ε by I_ε^* the notations: mountain-pass level c_ε^* ; the Nehari manifold $\mathcal{N}_\varepsilon^*$; the critical set $\mathcal{H}_\varepsilon^*$, and the least energy solution set $\mathcal{R}_\varepsilon^*$. Observe that

$$c_\varepsilon^* = \inf \{ I_\varepsilon^*(u) : u \in \mathcal{N}_\varepsilon^* \}$$

and $0 < c_\varepsilon^* \leq c_\varepsilon$.

4.1 Autonomous equation

In this subsection, we give some results for the autonomous problem

$$\varepsilon^{2s}(-\Delta)^s u + au = bh(u), \quad u \in H^s(\mathbb{R}^N), \quad (4.1)$$

which are useful for the study of the nonlocal critical problem (1.2). Here $h(u) = f(u) + u^{2_s^*-1}$, f as before satisfies the assumptions (f_1) – (f_4) , $a, b > 0$ are constants.

Consider the functional $I_{ab}^* : H^s(\mathbb{R}^N) \rightarrow \mathbb{R}$ associated to this equation,

$$I_{ab}^*(u) := \frac{1}{2} |(-\Delta)^{\frac{s}{2}} u|_2^2 + \frac{a}{2} |u|_2^2 - b \int_{\mathbb{R}^N} F(u) dx - \frac{b}{2_s^*} |u|_{2_s^*}^{2_s^*},$$

then I_{ab}^* is of class C^1 on $H^s(\mathbb{R}^N)$.

Let c_{ab}^* be the mountain-pass level; \mathcal{N}_{ab}^* the Nehari manifold; \mathcal{H}_{ab}^* the critical set, γ_{ab}^* the least energy, and \mathcal{R}_{ab}^* the least energy solution set.

Let us notice that inequalities (3.1) and (3.2) imply that I_{ab}^* satisfies the mountain-pass conditions, we can define the mountain-pass level

$$c_{ab}^* := \inf_{\gamma \in \Gamma_{ab}^*} \max_{t \in [0,1]} I_{ab}^*(\gamma(t)),$$

where $\Gamma_{ab}^* := \{\gamma \in C([a, b], H^s), \gamma(0) = 0, I_{ab}^*(\gamma(1)) < 0\}$. It is easy to verify

$$c_{ab}^* = \inf_{u \in H^s \setminus \{0\}} \max_{t \geq 0} I_{ab}^*(tu) = \gamma_{ab}^*.$$

Next we show γ_{ab}^* is attained, under proper assumptions for $a, b > 0$.

Proposition 4.1 γ_{ab}^* is attained if $\gamma_{ab}^* < l_b := \frac{(S_0)^{\frac{N}{2s}} \cdot s}{N \cdot b^{\frac{N-2s}{2s}}}$, where $S_0 = k_s S(s, N)$ is the Sobolev constant as in (2.11).

Proof Since $\gamma_{ab}^* = \inf_{u \in \mathcal{N}_{ab}^*} I_{ab}^*(u)$, let $\{u_n\} \in \mathcal{N}_{ab}^*$ be a minimizing sequence of I_{ab}^* , which is clearly a $(PS)_{\gamma_{ab}^*}$ sequence: $I_{ab}^*(u_n) \rightarrow \gamma_{ab}^*$ and $I_{ab}^{\prime*}(u_n) \rightarrow 0$ as $n \rightarrow \infty$.

Remark that $2 < \mu < p < 2_s^*$ and

$$\gamma_{ab}^* + o(1) = I_{ab}^*(u_n) - \frac{1}{\mu} I_{ab}^{\prime*}(u_n) u_n \geq \left(\frac{1}{2} - \frac{1}{\mu} \right) \|u_n\|_{H^s}^2.$$

Thus, $\{u_n\}$ is bounded in $H^s(\mathbb{R}^N)$. By Lion's concentration principle, $\{u_n\}$ is either vanishing or non-vanishing. Assume that $\{u_n\}$ is vanishing, then $|u_n|_p \rightarrow 0$, $p \in (2, 2_s^*)$. Since $a > 0$, by (f_1) – (f_4') , one gets

$$o(1) = I_{ab}^{\prime*}(u_n) u_n \geq |(-\Delta)^{\frac{s}{2}} u_n|_2^2 - b |u_n|_{2_s^*}^{2_s^*} + o(1). \quad (4.2)$$

By the Sobolev embedding inequality (2.11),

$$S_0 |u_n|_{2_s^*}^2 \leq |(-\Delta)^{\frac{s}{2}} u_n|_2^2. \quad (4.3)$$

Note that

$$\gamma_{ab}^* + o(1) = I_{ab}^*(u_n) - \frac{1}{2} I_{ab}^{\prime*}(u_n) u_n \geq \frac{sb}{N} |u_n|_{2_s^*}^{2_s^*}. \quad (4.4)$$

It follows from (4.2)–(4.4) that

$$\gamma_{ab}^* \geq \frac{(S_0)^{\frac{N}{2s}} \cdot s}{N \cdot b^{\frac{N-2s}{2s}}},$$

a contradiction. Therefore, $\{u_n\}$ is non-vanishing, that is, there exist $\gamma, \delta > 0$, and $x_n \in \mathbb{R}^N$ such that, setting $v_n(x) = u_n(x + x_n)$, along a subsequence $\int_{B_r(0)} |v_n|^2 \geq \delta$. Without loss of generality we assume $v_n \rightharpoonup v$. Then $v \neq 0$ is a solution of (4.1), and so γ_{ab}^* is attained. Thus, we complete the proof. \square

Next we claim $\gamma_{ab}^* < l_b$ if $a < b\mathcal{R}_q$ where

$$\mathcal{R}_q := \left(\frac{2qc_0^{\frac{2}{q-2}} s(S_0)^{\frac{N}{2s}}}{S_q^{\frac{q}{q-2}} (q-2)N} \right)^{\frac{2s(q-2)}{2(sq+N)-Nq}} \quad (N > 2s, 2 < q < 2_s^*).$$

Indeed, let u be a ground state of

$$(-\Delta)^s u + au = bg(u) \quad (4.5)$$

with g as in (f₁), which is equivalent to

$$(-\Delta)^s z + z = \frac{b}{a} g(z), \quad (4.6)$$

after a change of variable, $z(x) = u(\frac{x}{a^{\frac{1}{2s}}})$, with the least energy

$$\begin{aligned} \gamma_{\frac{b}{a}} &= \frac{1}{2} |(-\Delta)^{\frac{s}{2}} z|_2^2 + \frac{1}{2} |z|_2^2 - \frac{b}{a} \int_{\mathbb{R}^N} G(z) dx \\ &= \frac{1}{2} \left| (-\Delta)^{\frac{s}{2}} u \left(\frac{x}{a^{\frac{1}{2s}}} \right) \right|_2^2 + \frac{1}{2} \left| u \left(\frac{x}{a^{\frac{1}{2s}}} \right) \right|_2^2 - \frac{b}{a} \int_{\mathbb{R}^N} G \left(u \left(\frac{x}{a^{\frac{1}{2s}}} \right) \right) dx \\ &= a^{\frac{N}{2s}-1} \gamma_{ab}. \end{aligned}$$

Denote

$$S_q := \inf_{u \in H^s \setminus \{0\}} \frac{|(-\Delta)^{\frac{s}{2}} u|_2^2 + |u|_2^2}{|u|_q^2}.$$

If $g(t) = c_0 t^{q-2}$, then by the mountain-pass theorem, the least energy corresponding to (4.6) denoted by $\gamma_{\frac{b}{a}}(q)$ satisfies

$$\gamma_{\frac{b}{a}}(q) \leq \frac{q-2}{2q} \left(\frac{a}{bc_0} \right)^{\frac{2}{q-2}} S_q^{\frac{q}{q-2}}.$$

This implies that the least energy corresponding to (4.5) denoted by $\gamma_{ab}(q)$ satisfies

$$\gamma_{ab}(q) = a^{\frac{2s-N}{2s}} \gamma_{\frac{b}{a}}(q) \leq \lambda(q, a, b) := a^{\frac{2s-N}{2s}} \cdot \frac{q-2}{2q} \left(\frac{a}{bc_0} \right)^{\frac{2}{q-2}} \cdot S_q^{\frac{q}{q-2}}. \quad (4.7)$$

Note that l_b is strictly decreasing with respect to $b > 0$, in virtue of (4.7), setting

$$\mathcal{R}_q := \left(\frac{2qc_0^{\frac{2}{q-2}} s \cdot (S_0)^{\frac{N}{2s}}}{S_q^{\frac{q}{q-2}} \cdot (q-2)N} \right)^{\frac{2s(q-2)}{2(sq+N)-Nq}},$$

if $a < b\mathcal{R}_q$, then $\gamma_{ab}(q) < l_b$. By (f'_4) , we have

$$\begin{aligned} I_{ab}^*(u) &\leq \frac{1}{2} |(-\Delta)^{\frac{s}{2}} u|_2^2 + \frac{a}{2} |u|_2^2 - bc_0 |u|_q^q - \frac{b}{2_s^*} |u|_{2_s^*}^{2_s^*} \\ &\leq \frac{1}{2} |(-\Delta)^{\frac{s}{2}} u|_2^2 + \frac{a}{2} |u|_2^2 - bc_0 |u|_q^q. \end{aligned}$$

This implies that $\gamma_{ab}^* \leq \gamma_{ab}(q)$ and thus $\gamma_{ab}^* < l_b$ if $a < b\mathcal{R}_q$.

In order to prove Theorem 1.2, next we will be concerned with $a \in [\tau, \tau_\infty]$ and $b \in [\kappa_\infty, \kappa]$. In particular we are looking for $\tau_0 > \tau$ and $\kappa_0 < \kappa$ such that

$$\gamma_{ab}(q) < l_k \leq l_b, \quad (4.8)$$

for either $a \in [\tau, \tau_0]$ and $b \in [\kappa_\infty, \kappa]$ or $a \in [\tau, \tau_\infty]$ and $b \in (\kappa_0, \kappa]$.

Observe that $\lambda(q, a, b) \leq \lambda(q, a, \kappa_\infty)$ and $l_b \geq l_k$ if $b \in [\kappa_\infty, \kappa]$. Furthermore, $\lambda(q, a, b) < l_k$ if

$$a < \tau_0 := \left(\frac{\kappa_\infty^{\frac{q-2}{2s}}}{\kappa^{\frac{N-2s}{2s}}} \right)^{\frac{2s(q-2)}{2(sq+N)-Nq}} \mathcal{R}_q.$$

Also $\lambda(q, a, b) \leq \lambda(q, \tau_\infty, b)$ and $l_b \geq l_k$ if $b \in [\kappa_\infty, \kappa]$. Also, $\lambda(q, \tau_\infty, b) < l_k$ if

$$b > \kappa_0 := \left(\frac{q-2}{2q} (\tau_\infty)^{\frac{2(sq+N)-Nq}{2s(q-2)}} S_q^{\frac{q}{q-2}} \cdot \frac{N\kappa^{\frac{N-2s}{2s}}}{(S_0)^{\frac{N}{2s}} \cdot s} c_0^{\frac{2}{2-q}} \right)^{\frac{q-2}{2}}.$$

In conclusion, (4.8) holds if either $\tau < \tau_0$, $a \in [\tau, \tau_0]$, and $b \in [\kappa_\infty, \kappa]$, or $\kappa > \kappa_0$, $b \in (\kappa_0, \kappa]$ and $a \in [\tau, \tau_\infty]$.

From the above argument and Proposition 4.1, we have the following results.

Lemma 4.1 *If $\tau < \tau_0$, $a \in [\tau, \tau_0]$, and $b \in [\kappa_\infty, \kappa]$, or $\kappa > \kappa_0$, $b \in (\kappa_0, \kappa]$, and $a \in [\tau, \tau_\infty]$, then $\gamma_{ab}^* < l_b$ and, consequently, $\mathcal{R}_{ab}^* \neq \emptyset$, γ_{ab}^* is attained.*

The following comparison result is similar to the one in Lemma 3.5(iv).

Lemma 4.2 *Let for $j = 1, 2$, either $\tau < \tau_0$, $a_j \in [\tau, \tau_0]$, and $b_j \in [\kappa_\infty, \kappa]$ or $\kappa > \kappa_0$, $b_j \in (\kappa_0, \kappa]$, $a_j \in [\tau, \tau_\infty]$. Assume $\min\{a_2 - a_1, b_1 - b_2\} \geq 0$, then $\gamma_{a_1 b_1}^* \leq \gamma_{a_2 b_2}^*$.*

4.2 The function I_ε^*

In this subsection, we will discuss the properties of the functional I_ε^* .

Plainly one easily verifies that I_ε^* possesses the mountain-pass structure and

$$c_\varepsilon^* := \inf_{\gamma \in \Gamma_\varepsilon^*} \max_{t \in [0,1]} I_\varepsilon^*(\gamma(t)) = \inf_{u \in H^s \setminus \{0\}} \max_{t \geq 0} I_\varepsilon^*(tu) = \inf_{u \in \mathcal{N}_\varepsilon^*} I_\varepsilon^*(u),$$

where c_ε^* is the mountain-pass minimax value associated with I_ε^* , $\Gamma_\varepsilon^* = \{\gamma \in C([0,1], H^s(\mathbb{R}^N)) : \gamma(0) = 0, I_\varepsilon^*(\gamma(1)) < 0\}$.

Similar to the proof of Lemma 3.6, we also have the following energy comparison between c_ε^* and $\gamma_{\tau b}$.

Lemma 4.3 *If $\tau \in (0, \tau_0)$, $b \in [\kappa_\infty, \kappa]$, then $\limsup_{\varepsilon \rightarrow 0} c_\varepsilon^* \leq \gamma_{\tau b}^* < l_k \leq l_b$.*

4.3 Existence results

Lemma 4.4 *If $\tau \in (0, \tau_0)$, c_ε^* is attained at some $u_\varepsilon^* \in \mathcal{R}_\varepsilon$ for all small $\varepsilon > 0$.*

Proof Given $\varepsilon > 0$, let $u_k^* \in \mathcal{N}_\varepsilon^*$ be a minimizing sequence of I_ε^* , which is clearly a $(PS)_{c_\varepsilon^*}$ sequence for I_ε^* . It is easy to see that $\{u_k^*\}$ is bounded in $H^s(\mathbb{R}^N)$. Assume that $u_k^* \rightharpoonup u_\varepsilon^* \in \mathcal{H}_\varepsilon^*$ in $H^s(\mathbb{R}^N)$. If $u_\varepsilon^* \neq 0$, then clearly $I_\varepsilon^*(u_\varepsilon^*) = c_\varepsilon^*$.

Next we check that $u_\varepsilon^* \neq 0$ for all $\varepsilon > 0$ small.

Assume that there exists a sequence $\varepsilon_j \rightarrow 0$ with $u_{\varepsilon_j}^* = 0$, then $u_k^* \rightharpoonup 0$ in $H^s(\mathbb{R}^N)$ and thus $u_k^* \rightarrow 0$ in L_{loc}^p for $q \in (1, 2_s^*)$ and $u_k^*(x) \rightarrow 0$ a.e. in $x \in \mathbb{R}^N$.

Since $\tau < \tau_\infty$ and $\tau < \tau_0$ by the assumptions, choose $\min\{\tau_\infty, \tau_0\} > a > \tau$, and consider the functional I_ε^{*ab} as in Lemma 3.7, let $t_k > 0$ be such that $t_k u_k^* \in \mathcal{N}_\varepsilon^{*ab}$, then $\{t_k\}$ is bounded and we may assume $t_k \rightarrow t_0$ as $k \rightarrow \infty$. By (P_0) , $(P_1)(i)$, the set $O_\varepsilon := \{x \in \mathbb{R}^N : V_\varepsilon(x) \leq a \text{ or } W_\varepsilon(x) > b\}$ is bounded. Remark that $I_{\varepsilon_j}^*(t_k u_k^*) \leq I_{\varepsilon_j}^*(u_k^*)$. We obtain

$$\begin{aligned} c_{\varepsilon_j}^{*ab} &\leq I_{\varepsilon_j}^{*ab}(t_k u_k^*) \\ &\leq I_{\varepsilon_j}^*(t_k u_k^*) + \frac{1}{2} \int_{O_{\varepsilon_j}} (a - V_{\varepsilon_j}(x)) |t_k u_k^*|^2 dx \\ &\quad + \int_{O_{\varepsilon_j}} (W_{\varepsilon_j}(x) - b) H(t_k u_k^*) dx \\ &\leq I_{\varepsilon_j}^*(t_k u_k^*) + o(1) = c_{\varepsilon_j}^* \end{aligned}$$

as $k \rightarrow \infty$, hence $c_{\varepsilon_j}^{*ab} \leq c_{\varepsilon_j}^*$. Notice that $\gamma_{ab}^* \leq c_{\varepsilon_j}^{*ab}$, hence $\gamma_{ab}^* \leq c_{\varepsilon_j}^*$. In virtue of Lemma 4.3, letting $\varepsilon_j \rightarrow 0$ yields

$$\gamma_{ab}^* \leq \gamma_{\tau b}^*,$$

which contradicts with $\gamma_{\tau b}^* < \gamma_{ab}^*$ (see Lemma 4.2). Therefore, c_ε^* is attained at $0 \neq u_\varepsilon^* \in \mathcal{R}_\varepsilon^*$, which ends the proof. \square

4.4 Concentration and convergence of ground state

Lemma 4.5 *Assuming (f_1) – (f_4) , (P_0) , $(P_1)(i)$ with $\tau < \tau_0$, and, for all ε sufficiently small, let $u_\varepsilon^* \in \mathcal{R}_\varepsilon^*$, then u_ε^* possesses a (global) maximum x_ε such that $\lim_{\varepsilon \rightarrow 0} \text{dist}(\varepsilon x_\varepsilon, \mathcal{A}_W) = 0$, and for any sequence $\varepsilon x_\varepsilon \rightarrow x_0$, $v_\varepsilon^*(x) := u_\varepsilon^*(x + x_\varepsilon)$ converges in $H^s(\mathbb{R}^N)$ to $u^*(x)$, which is a least energy solution of*

$$(-\Delta)^s u + V(x_0)u = W(x_0)h(u),$$

note that $h(u) = f(u) + u^{2_s^-1}$. In particular, $\mathcal{V} \cap \mathcal{W} \neq \emptyset$, then $\lim_{\varepsilon \rightarrow 0} \text{dist}(\varepsilon x_\varepsilon, \mathcal{V} \cap \mathcal{W}) = 0$, and up to subsequences, v_ε^* converges in $H^s(\mathbb{R}^N)$ to u^* being a least energy solution of*

$$(-\Delta)^s u + \tau u = \kappa h(u).$$

The proof of this lemma will be along the main lines of the proof of Theorem 1.1. We argue step by step.

Proof Step 1. Let $u_\varepsilon^* \in H^s(\mathbb{R}^N)$ be the critical point of I_ε^* so that $I_\varepsilon^*(u_\varepsilon^*) = c_\varepsilon^*$, we see that $\{u_\varepsilon^*\}$ is a bounded set in $H^s(\mathbb{R}^N)$. Then $\{u_\varepsilon^*\}$ is non-vanishing.

Indeed, assume $\{u_\varepsilon^*\}$ is vanishing, then $|u_\varepsilon^*|_p \rightarrow 0$ for $p \in (2, 2_s^*)$. By (f_1) – (f_4) , one gets

$$o(1) = I_\varepsilon^{*'}(u_\varepsilon^*)u_\varepsilon^* \geq |(-\Delta)^{\frac{s}{2}} u_\varepsilon^*|_2^2 - \int_{\mathbb{R}^N} W_\varepsilon(x) |u_\varepsilon^*|^{2_s^*} dx. \quad (4.9)$$

On the other hand

$$c_\varepsilon^* + o(1) = I_\varepsilon^*(u_\varepsilon^*) - \frac{1}{2} I_\varepsilon^{*'}(u_\varepsilon^*)u_\varepsilon^* \geq \frac{s}{N} \int_{\mathbb{R}^N} W_\varepsilon(x) |u_\varepsilon^*|^{2_s^*} dx. \quad (4.10)$$

Recall that

$$\int_{\mathbb{R}^N} |(-\Delta)^{\frac{s}{2}} u_\varepsilon^*|^2 dx \geq S_0 \left(\int_{\mathbb{R}^N} |u_\varepsilon^*|^{2_s^*} dx \right)^{\frac{2}{2_s^*}}. \quad (4.11)$$

It follows from (4.9)–(4.11) that

$$\liminf_{\varepsilon \rightarrow 0} c_\varepsilon^* \geq l_k = \frac{N}{s} S_0^{\frac{N}{2s}} \kappa^{\frac{2s-N}{2s}},$$

contradicting Lemma 4.3. Therefore $\{u_\varepsilon^*\}$ is non-vanishing, that is, there exist a sequence $\{x_\varepsilon\} \subset \mathbb{R}^N$ and constant $R > 0$, $\sigma > 0$ such that $\lim_{\varepsilon \rightarrow 0} \int_{B_R(x_\varepsilon)} |u_\varepsilon^*|^2 \geq \sigma$.

Set $v_\varepsilon^*(x) := u_\varepsilon^*(x + x_\varepsilon)$, then v_ε^* satisfies

$$(-\Delta)^s v_\varepsilon^* + \widehat{V}_\varepsilon(x) v_\varepsilon^* = \widehat{W}_\varepsilon(x) h(v_\varepsilon^*), \quad (4.12)$$

where $\widehat{V}_\varepsilon(x) = V(\varepsilon(x + x_\varepsilon))$, $\widehat{W}_\varepsilon(x) = W(\varepsilon(x + x_\varepsilon))$, with energy

$$\begin{aligned} \widehat{I}_\varepsilon^*(v_\varepsilon^*) &= \frac{1}{2} |(-\Delta)^{\frac{s}{2}} v_\varepsilon^*|_2^2 + \frac{1}{2} \int_{\mathbb{R}^N} \widehat{V}_\varepsilon(x) v_\varepsilon^{*2} - \int_{\mathbb{R}^N} \widehat{W}_\varepsilon(x) H(v_\varepsilon^*) \\ &= \widehat{I}_\varepsilon^*(v_\varepsilon^*) - \frac{1}{2} \widehat{I}_\varepsilon^{*'}(v_\varepsilon^*) v_\varepsilon^* \\ &= \int_{\mathbb{R}^N} \widehat{W}_\varepsilon(x) \left[\left(\frac{1}{2} f(v_\varepsilon^*) v_\varepsilon^* - F(v_\varepsilon^*) \right) + \left(\frac{1}{2} - \frac{1}{2_s^*} \right) |v_\varepsilon^*|^{2_s^*} \right] \\ &= I_\varepsilon^*(u_\varepsilon^*) - \frac{1}{2} I_\varepsilon^{*'}(u_\varepsilon^*) u_\varepsilon^* = I_\varepsilon^*(u_\varepsilon^*) = c_\varepsilon^*. \end{aligned}$$

We may assume $v_\varepsilon^* \rightharpoonup u^*$ in $H^s(\mathbb{R}^N)$, and $v_\varepsilon^* \rightarrow u^*$ in L_{loc}^q for $q \in [1, 2_s^*)$ with $u^* \neq 0$.

Since $V, W \in L^\infty$, without loss of generality, we assume that $V(\varepsilon x_\varepsilon) \rightarrow V_0$ and $W(\varepsilon x_\varepsilon) \rightarrow W_0$ as $\varepsilon \rightarrow 0$. It is easy to check that $\widehat{V}_\varepsilon(x) \rightarrow V_0$ and $\widehat{W}_\varepsilon(x) \rightarrow W_0$ as $\varepsilon \rightarrow 0$ uniformly on bounded sets of $x \in \mathbb{R}^N$.

Consequently, by (4.12), for any $\varphi \in C_0^\infty(\mathbb{R}^N)$,

$$\begin{aligned} 0 &= \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^N} ((-\Delta)^s v_\varepsilon^* + \widehat{V}_\varepsilon(x) v_\varepsilon^* - \widehat{W}_\varepsilon(x) h(v_\varepsilon^*)) \varphi dx \\ &= \int_{\mathbb{R}^N} ((-\Delta)^s u^* + V_0 u^* - W_0 h(u^*)) \varphi dx, \end{aligned}$$

which implies that u^* solves

$$(-\Delta)^s u^* + V_0 u^* = W_0 h(u^*), \quad (4.13)$$

with the energy

$$\begin{aligned} \Gamma_{V_0 W_0}^*(u^*) &:= \frac{1}{2} |(-\Delta)^{\frac{s}{2}} u^*|_2^2 + \frac{1}{2} V_0 \int_{\mathbb{R}^N} u^{*2} - W_0 \int_{\mathbb{R}^N} H(u^*) \\ &= \int_{\mathbb{R}^N} W_0 \left[\left(\frac{1}{2} f(u^*) u^* - F(u^*) \right) + \left(\frac{1}{2} - \frac{1}{2_s^*} \right) |u^*|^{2_s^*} \right] \geq \gamma_{V_0 W_0}^* \end{aligned}$$

by Fatou's lemma and Lemma 4.3,

$$\begin{aligned} \gamma_{V_0 W_0}^* &\leq \int_{\mathbb{R}^N} W_0 \left[\left(\frac{1}{2} f(u^*) u^* - F(u^*) \right) + \left(\frac{1}{2} - \frac{1}{2_s^*} \right) |u^*|^{2_s^*} \right] \\ &\leq \liminf_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^N} \widehat{W}_\varepsilon(x) \left[\left(\frac{1}{2} f(v_\varepsilon^*) v_\varepsilon^* - F(v_\varepsilon^*) \right) + \left(\frac{1}{2} - \frac{1}{2_s^*} \right) |v_\varepsilon^*|^{2_s^*} \right] \\ &= \liminf_{\varepsilon \rightarrow 0} \widehat{I}_\varepsilon^*(v_\varepsilon^*) \leq \limsup_{\varepsilon \rightarrow 0} I_\varepsilon^*(u_\varepsilon^*) \leq \gamma_{V_0 W_0}^*. \end{aligned}$$

Therefore,

$$\lim_{\varepsilon \rightarrow 0} \widehat{I}_\varepsilon^*(v_\varepsilon^*) = \lim_{\varepsilon \rightarrow 0} c_\varepsilon^* = \gamma_{V_0 W_0}^* \quad \text{and} \quad \Gamma_{V_0 W_0}^*(u^*) = \gamma_{V_0 W_0}^*.$$

As a consequence, u^* is the least energy solution of the limit equation (4.4).

Step 2. $\{\varepsilon x_\varepsilon\}$ is bounded.

Assume that $\varepsilon |x_\varepsilon| \rightarrow +\infty$, by $W(\varepsilon x_\varepsilon) \rightarrow W_0$, $b = W(0) \geq W(x)$, $|x| \geq R$, and $V(\varepsilon x_\varepsilon) \rightarrow V_0$, we deduce that $V_0 \geq \tau$ and $W_0 < b$. So it follows from Lemma 4.2 that $\gamma_{V_0 W_0}^* > \gamma_{\tau b}^*$.

However, by Step 1 and Lemma 4.3, $c_\varepsilon^* \rightarrow \gamma_{V_0 W_0}^* \leq \gamma_{\tau b}^*$, a contradiction. Therefore, we can assume $\varepsilon x_\varepsilon \rightarrow x_0$ (as $\varepsilon \rightarrow 0$), then $V_0 = V(x_0)$, $W_0 = W(x_0)$, and we read (4.13) as

$$(-\Delta)^s u^* + V(x_0) u^* = W(x_0) h(u^*),$$

where u^* is the least energy solution.

Step 3. $\varepsilon x_\varepsilon \rightarrow \mathcal{A}_V$ as $\varepsilon \rightarrow 0$, that is, $x_0 \in \mathcal{A}_V$.

Assume that $x_0 \notin \mathcal{A}_V$, by the definition of \mathcal{A}_V , we have $W(x_0) < W(0) = b$, which combined with $V(x_0) > \tau$, leads to $\gamma_{V(x_0)W(x_0)}^* > \gamma_{a\kappa}^*$. However, by Lemma 4.3,

$$\lim_{\varepsilon \rightarrow 0} c_\varepsilon^* = \gamma_{V(x_0)W(x_0)}^* > \gamma_{\tau b}^* \geq \lim_{\varepsilon \rightarrow 0} c_\varepsilon^*,$$

a contradiction.

Step 4. Let v_ε^* , u^* be defined in Step 1, then $v_\varepsilon^* \rightarrow u^*$ in $H^s(\mathbb{R}^N)$. See Step 4 of the proof of Lemma 3.9.

Step 5. $v_\varepsilon(x) \rightarrow 0$ as $|x| \rightarrow \infty$ uniformly for all small ε . See Step 5 of the proof of Lemma 3.9. \square

4.5 Decay estimates

Now repeating the arguments of Lemma 3.10 we obtain the following lemma.

Lemma 4.6 *There exist $0 < C_1 \leq C_2$ and $R > 1$ such that, for all small $\varepsilon > 0$,*

$$\frac{C_1}{|x - x_\varepsilon|^{N+2s}} \leq u_\varepsilon(x) \leq \frac{C_2}{|x - x_\varepsilon|^{N+2s}},$$

for all $|x| \geq R$.

Proof of Theorem 1.2 (A) Define $\omega_\varepsilon(x) = u_\varepsilon(\frac{x}{\varepsilon})$, then ω_ε is a solution of (1.2) for all $\varepsilon > 0$.

Since z_ε is a maximum point of $|\omega_\varepsilon|$, we have

$$\frac{C_1 \varepsilon^{N+2s}}{|x - z_\varepsilon|^{N+2s}} \leq \omega_\varepsilon(x) \leq \frac{C_2 \varepsilon^{N+2s}}{|x - z_\varepsilon|^{N+2s}},$$

for some constants $0 < C_1 < C_2$, and

$$\lim_{\varepsilon \rightarrow 0} \text{dist}(z_\varepsilon, \mathcal{A}_V) = 0.$$

Proceed similar to (B). □

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

SL and YD carried out the proofs of the theorems. YC carried out the check of the manuscript. All authors read and approved the final manuscript.

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